

Dynamical Interpretation of the Adjoint Representation Ad:

G : Lie group

$\Gamma \subseteq G$ lattice

Put a metric on G/Γ ?

Choose a right invariant metric on G
and project it to G/Γ .

Each $g \in G$ induces a dynamical
system on $G/\Gamma = \{g\Gamma \mid g \in G\}$

by left multiplication.

$$\zeta_g : G/\Gamma \rightarrow G/\Gamma, x\Gamma \mapsto gx\Gamma$$

What does the derivative transformation dL_g look like?

$$dL_g: T_h G \rightarrow T_{gh} G$$



the same space.

$$\phi: T(G/\Gamma) \rightarrow G/\Gamma \times T_e G$$

$$\underbrace{(v, g\Gamma)}_{v \in T_{g\Gamma}(G/\Gamma)} \mapsto (g\Gamma, dR_{\bar{g}^{-1}}(v))$$

HW: Check that this is a well defined vector bundle isomorphism.

$$\begin{array}{ccc}
 dL_g(v, h\Gamma) & = & (dL_g(v), gh\Gamma) \\
 \underbrace{\text{trivialization}} \downarrow & & \downarrow \\
 dR_{h^{-1}}(v) & & dR_{(gh)^{-1}} dL_g(v) \\
 & & dR_{h^{-1}} dR_{\bar{g}^{-1}} dL_g(v)
 \end{array}$$

$$\text{Ad}(g) = dR_{g^{-1}} dL_g$$

Thus the derivative is determined by $\text{Ad}(g)$.

Supersession E_a from Last time.

$$\mathbb{Z} \subseteq \mathbb{R}, \quad A \in \text{SL}(2, \mathbb{Z})$$

$$A = \exp(X)$$

$$(\mathbb{R} \rtimes_X \mathbb{R}^2) / (\mathbb{Z} \rtimes_A \mathbb{Z}^2).$$

HW: show that for $H = \mathbb{R} \rtimes_X \mathbb{R}^2$,

$$\left[\begin{array}{l} H \cong \left\{ \left(\begin{array}{c|c} A^t & \begin{smallmatrix} 0 \\ 0 \end{smallmatrix} \\ \hline v & 1 \end{array} \right) \mid \begin{array}{l} t \in \mathbb{R} \\ v \in \mathbb{R}^2 \end{array} \right\} \text{ and} \\ \text{Lie}(H) = \text{Lie algebra of } H = \left\{ \left(\begin{array}{c|c} tX & \begin{smallmatrix} 0 \\ 0 \end{smallmatrix} \\ \hline v & a \end{array} \right) \right\} \end{array} \right.$$

$$\text{Ad}(A)(X) = 0$$

$$\text{Ad}(A)(v) = Av$$

Solvable group?

H is called solvable if

$$\left(\begin{array}{l} H_0 = H \\ H_1 = [H_0, H_0] \\ H_{n+1} = [H_n, H_n] \end{array} \right) \quad H_0 \rightarrow H_1 \rightarrow H_2 \rightarrow H_3 \rightarrow e$$

$(H_n = H_n^{\text{solr}})$

HW: The above group H is solvable.

Nilpotent group?

H is called nilpotent if

$$\left(\begin{array}{l} H^0 = H \\ H^1 = [H, H^0] \\ H^{n+1} = [H, H^n] \end{array} \right)$$

$$H^0 \rightarrow H^1 \rightarrow H^2 \rightarrow H^3 \rightarrow e$$

$$H^0 \rightarrow H^1 \rightarrow H^2 \rightarrow H^3 \rightarrow e$$

$(H^n = H_n^{\text{nil}})$

HW: show that H is nilpotent

$\Leftrightarrow$ the only eigenvalue of X is 0 .

(e.g. Heisenberg).

Ex: $H = \begin{pmatrix} * & & \\ & \ddots & \\ 0 & & * \end{pmatrix}$

upper triangular matrices are solvable.

$[\text{Lie}(H), \text{Lie}(H)] = \begin{pmatrix} 0 & & \\ & \ddots & \\ 0 & & 0 \end{pmatrix} \stackrel{Y/H \text{ solv}}{=} \begin{pmatrix} 0 & & \\ & \ddots & \\ 0 & & 0 \end{pmatrix}$

$\text{Lie}(H_2^{\text{solv}}) = \begin{pmatrix} 0 & 0 & \\ 0 & 0 & * \\ 0 & 0 & 0 \end{pmatrix}$

Ex: $H = \begin{pmatrix} * & & * \\ 0 & & \\ | & \diagdown & | \\ 0 & & 0 \end{pmatrix}$

upper triangular
matrices are
not nilpotent.

$\text{Lie}(H_1^{\text{nil}}) = \text{Lie}(H_2^{\text{nil}}) \dots$

* Solvability and nilpotence are
hereditary.

Ex: $G = \begin{pmatrix} 1 & * & \\ 0 & & \\ | & \diagdown & | \\ 0 & & 1 \end{pmatrix}$

is nilpotent.

HW: Prove this

(useful fact: $[E_{ij}, E_{jk}] = E_{ik}$)

Thm (Lie): Every solvable ~~group~~ ^{Lie} group is
isomorphic to a closed subgroup of
 $H_{\mathbb{C}} =$ upper triangulars with complex
entries.

Thm (Engel): Every nilpotent ^{s.c.} Lie group
is isomorphic to a closed subgroups
of G

(more on Lie & Engel thms later).

Killing Form: (following Helgason).

Let $\mathfrak{g}$ be a Lie algebra.

$$X \in \mathfrak{g} \leadsto \text{ad}_X : \mathfrak{g} \rightarrow \mathfrak{g} \quad \text{"little ad!"}$$
$$Y \mapsto [X, Y].$$

Def: The Killing form on $\mathfrak{g}$ is a
bilinear form defined by

$$B(X, Y) = \text{Tr}(\text{ad}_X \text{ad}_Y).$$

HW: • B is bilinear

• B is symmetric

• $\forall \sigma \in \text{Aut}(\mathfrak{g}) : B(\sigma X, \sigma Y) = B(X, Y)$

HW: Find the Killing forms for ...

• $\mathbb{R}^3$

• $\mathbb{R} \ltimes_{\times} \mathbb{R}^2$

• ~~$\mathfrak{so}(3)$~~ $\mathfrak{so}(3)$

• $\mathfrak{sl}(2, \mathbb{R})$

• $\mathfrak{h} \subseteq \mathfrak{g}$ is an ideal if

$$[\mathfrak{g}, \mathfrak{h}] \subseteq \mathfrak{h}.$$

Lemma: If $\mathfrak{h}$ is an ideal in $\mathfrak{g}$,

then $B_{\mathfrak{g}}|_{\mathfrak{h}} = B_{\mathfrak{h}}.$

Pf: Pick a basis $\underbrace{X_1, \dots, X_n}_{\mathfrak{h}}, \underbrace{X_{n+1}, \dots, X_m}_{\text{transverse to } \mathfrak{h}}$ of $\mathfrak{g}$

$$B_{\mathfrak{g}}(X_i, X_j) = \text{tr}(\text{ad}_{X_i} \text{ad}_{X_j})$$

$$= \sum_{k=1}^n X_k^*([X_i, [X_j, X_k]])$$

$$+ \sum_{k=n+1}^m \text{---} \text{---} \text{---}$$

$$= B_{\mathfrak{h}}(X_i, X_j)$$

← vanishes.
for $X_i, X_j \in \mathfrak{h}$

Def: $\mathfrak{g}$ is called semisimple if $B_{\mathfrak{g}}$ is a nondegenerate bilinear form.

FACT: Every simple Lie algebra ($\neq 0$) is semisimple.

Lemma: $\mathfrak{oj}$ is compact and center-free
 [iff B is negative definite.

Pf: $(\Leftarrow)$ B is negative def

$\Leftrightarrow -B$ is a metric

$\Rightarrow O(B) = \left\{ \begin{array}{l} \text{transformations} \\ \text{preserving } B \end{array} \right\}$

is compact group.

$\langle \exp(\text{ad}_X) \mid X \in \mathfrak{oj} \rangle \subseteq O(B)$
 closed.

$(\Rightarrow)$ (harder direction)

Case: $\text{Ad}(\mathfrak{oj}) \subseteq \text{SO}(Q)$

(adjoint group of $\mathfrak{oj}$)

for some
quadratic
form Q .

$\Rightarrow \mathfrak{oj} \subseteq \mathfrak{so}(Q)$

$\Rightarrow$ Every ad_X is skew-symmetric
 w/r/t $X_1, X_2, \dots, X_n$, a basis.

$\mathfrak{oj}$ is compact
 if $\{ \exp(\text{ad}_X) \mid X \in \mathfrak{oj} \}$
 is compact.

$$B(X, X) = \text{tr}(\text{ad}_X \text{ad}_X) \quad \left(a_{ij} : \text{entries of } \text{ad}_X. \right)$$

$$= \sum_{i,j=1}^n a_{ij} a_{ji} = \sum_{i,j=1}^n -a_{ij}^2 < 0$$

(by the center-free assumption.)

Def: $X \in \mathfrak{g}$ is called F -semisimple ($F = \mathbb{R}$ or $F = \mathbb{C}$) if ad_X is diagonalizable over F .

$\mathfrak{h} \subseteq \mathfrak{g}$ is an (F -split) Cartan subalgebra if it is ~~not~~ abelian, every $X \in \mathfrak{h}$ is F -semisimple, and $\mathfrak{h}$ is maximal among such subalgebras.

Ex: $\mathfrak{g} = \mathfrak{sl}(n, \mathbb{C})$

$\mathfrak{a} \subseteq \mathfrak{g}, \quad \mathfrak{a} = \left\{ \begin{pmatrix} t_1 & & 0 \\ & \ddots & \\ 0 & & t_n \end{pmatrix} \mid t_i \in \mathbb{R}, \sum t_i = 0 \right\}$

is an $\mathbb{R}$ -split Cartan subalgebra.

$\mathfrak{b} \subseteq \mathfrak{g}, \quad \mathfrak{b} = \left\{ \begin{pmatrix} z_1 & & 0 \\ & \ddots & \\ 0 & & z_n \end{pmatrix} \mid z_i \in \mathbb{C}, \sum z_i = 0 \right\}$

is a $\mathbb{C}$ -split Cartan subalgebra.

$X = \text{diag}(t_1, \dots, t_n) \in \mathfrak{sl}(n, \mathbb{C})$

$\text{ad}_X(E_{ij}) = \underbrace{(t_i - t_j)}_{\gamma_{ij}(X)} E_{ij}$

$\gamma_{ij}(X) \leftarrow$ important function
(Lyapunov exponent)

$\text{Ad}(\exp(tX)) = \exp(t \text{ad}_X).$

Preview :

A : $\mathbb{R}$ -split Cartan.

$$\Sigma(A) = \underset{\substack{\uparrow \\ \text{compact}}}{M} \times A$$

$$A \cap M \backslash G / \Gamma$$

has the
most amount
of hyperbolicity.