

KV-Topics
2/25/25

Toward Zimmer super-rigidity,

Prepared ingredients

① The "long" lemma: (done already)

$\omega: P \rightarrow V$ is A -inv., H -equiv.

If G is semisimple, α is a root,

$G_\alpha = \langle U_\alpha, U_{-\alpha} \rangle$, then

"

$\omega|_{G_\alpha}$ is induced from a

homomorphism $G_\alpha \rightarrow Q_\alpha \cap W_\alpha \subseteq V$

II Homomorphisms from
semisimple Lie groups are
always $\mathbb{R}$ -algebraic.

← (Today)
III $G_{\mathbb{R}}$ is semisimple
(& root classification for the
layperson)

Setting: $\mathfrak{g}$ a Lie algebra over $\mathbb{C}$
(or split algebra over $\mathbb{R}$)

• $\mathfrak{a} \subseteq \mathfrak{g}$ is a Cartan subalgebra if
(or maximal torus)

- 1) $\mathfrak{a}$ is abelian
- 2) $\forall X \in \mathfrak{a}$: ad_X is diagonalizable
- 3) $\mathfrak{a}$ is maximal with 1) & 2).

Construction of Cartan subalgebras:

$$\begin{aligned} X \in \mathfrak{g} \text{ generic, } & \leftarrow \text{(from an open dense subset)} \\ \sigma = \mathbb{Z}_{\mathfrak{g}}(X). \end{aligned}$$

• The decomposition

$$\mathfrak{g} = \sigma \oplus \bigoplus_{\lambda \in \Delta} \mathfrak{g}_{\lambda}$$

is called the root space decomp.

- $\Delta \subseteq \sigma^*$ finite,
- $H \in \sigma, X \in \mathfrak{g}_{\lambda}$
 $\Rightarrow [H, X] = \lambda(H) \cdot X.$

$$\text{Lem: } [\mathfrak{g}_\lambda, \mathfrak{g}_\mu] \subseteq \mathfrak{g}_{\lambda+\mu}.$$

$$\text{Lem: If } \lambda + \mu \neq 0, \text{ then } \mathfrak{g}_\lambda \perp_K \mathfrak{g}_\mu$$

(i.e. $\forall X \in \mathfrak{g}_\lambda, \forall Y \in \mathfrak{g}_\mu:$
 $K(X, Y) = 0$)

(Killing form)

Before proof: $K([A, B], C) = K(A, [B, C])$

comes from $\uparrow$ (associativity)

$$\begin{aligned} K([A, B], C) &= \text{tr}(\text{ad}_{[A, B]} \text{ad}_C) \\ &= \text{tr}([\text{ad}_A, \text{ad}_B] \text{ad}_C) \end{aligned}$$

use $\text{tr}(AB) = \text{tr}(BA)$ to finish.

Pf of Lemma:

$$K(X, Y) = K\left(\frac{1}{\lambda(H)} [H, \bar{X}], Y\right)$$

$$= -\frac{1}{\lambda(H)} K([X, H], Y)$$

$$= -\frac{1}{\lambda(H)} K(X, [H, \bar{Y}])$$

$$= -\frac{1}{\lambda(H)} K(X, \mu(H) Y)$$

$$= -\frac{\mu(H)}{\lambda(H)} K(X, Y)$$

$$\Rightarrow -\frac{\mu(H)}{\lambda(H)} = 1$$

$$\Rightarrow \lambda(H) + \mu(H) = 0 \quad \text{unless } K(X, Y) = 0.$$

Cor: $K|_{\sigma}$ is nondegenerate.

pf: Given $\sigma = \sigma_0$, the 0-eigenspace.

Then by lemma, $\sigma \perp_K \sigma_\lambda, \forall \lambda \neq 0$.

Since K is non-degenerate,

$$\forall X \in \sigma, \exists Y \in \sigma : K(X, Y) \neq 0.$$

• By duality, $\forall \theta \in \sigma^*, \exists H_\theta$ such that
 $\theta(H) = K(H, H_\theta), \forall H \in \sigma$.

Theorem: (a) $\alpha \in \Delta \Rightarrow -\alpha \in \Delta$.

(b) If $X \in \sigma_\alpha, Y \in \sigma_{-\alpha}$, then

$$[X, Y] = K(X, Y) \cdot H_\alpha$$

(c) $K(H_\alpha, H_\alpha) \neq 0$

↳

(d) $\forall X \in \mathfrak{g}_\alpha, \exists Y \in \mathfrak{g}_{-\alpha}$ such that
if $\hat{H}_\alpha = \frac{2H_\alpha}{K(H_\alpha, H_\alpha)}$, then

$$\left. \begin{aligned} [X, Y] &= \hat{H}_\alpha, \\ [\hat{H}_\alpha, X] &= 2X, \\ [\hat{H}_\alpha, Y] &= -2Y. \end{aligned} \right\} (\mathfrak{sl}_2\text{-triple})$$

Pf: (a) since $\mathfrak{g}_\alpha \perp_K \mathfrak{g}$ and

$\mathfrak{g}_\alpha \perp_K \mathfrak{g}_\beta \quad \forall \beta \neq -\alpha$, if K is
nondegenerate, $-\alpha \in \Delta$. (associativity)

$$\begin{aligned} (b) \quad \forall H \in \mathfrak{g}, \quad K(H, [X, Y]) &\stackrel{\downarrow}{=} K([H, X], Y) \\ &= \alpha(H) K(X, Y) = K(H_\alpha, H) \cdot K(X, Y) \end{aligned}$$

$\hookrightarrow$

$$= K(K(X, Y) H_\alpha, H)$$

$$= K(H, K(X, Y) H_\alpha)$$

$$\Rightarrow [X, Y] = K(X, Y) H_\alpha$$

by nondegeneracy of $K|_{\mathfrak{g}}$.

(c) Assume, for a contradiction, that

$$K(H_\alpha, H_\alpha) = 0$$

$$\Rightarrow \alpha(H_\alpha) = 0$$

$$\Rightarrow [H_\alpha, X] = 0, \quad \forall X \in \mathfrak{g}_\alpha$$

$$[H_\alpha, Y] = 0, \quad \forall Y \in \mathfrak{g}_{-\alpha} \quad \left(H_\alpha \text{ commutes with } \mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha} \right)$$

$\exists X \in \mathfrak{g}_\alpha, \exists Y \in \mathfrak{g}_{-\alpha}$ such that

$$K(X, Y) = 1 \Rightarrow [X, Y] = H_\alpha.$$

$\hookrightarrow$

(b)

$$\Rightarrow \langle X, Y, H_\alpha \rangle \cong_{\text{Lie}} (\mathfrak{heis}) = \begin{pmatrix} 0 & * & * \\ 0 & 0 & * \\ 0 & 0 & 0 \end{pmatrix}$$

Since $H_\alpha = [X, Y]$ and belongs to an ad-nilpotent subalgebra, it is nilpotent.

But H_α is a (co)securing sample;
nilpotent + securing sample $\Rightarrow H_\alpha = 0$,
a contradiction.

(d) Fix $X \in \mathfrak{g}_\alpha$, and choose $Y \in \mathfrak{g}_{-\alpha}$ such that

$$K(X, Y) = \frac{2}{K(H_\alpha, H_\alpha)} = \frac{2}{\alpha(H_\alpha)}.$$

$$\begin{aligned} \Rightarrow [X, Y] &= K(X, Y) H_\alpha \\ &= \frac{2}{\alpha(H_\alpha)} H_\alpha = \hat{H}_\alpha \end{aligned}$$

Exr: If $\mathfrak{h} \subseteq \mathfrak{g}$ is nilpotent,
 $X = [Y, Z], Y, Z \in \mathfrak{h}$
 $\Rightarrow \text{ad}_X : \mathfrak{g} \rightarrow \mathfrak{g}$ is nilpotent.

$$[\hat{H}_\alpha, X] = \frac{2}{\alpha(H_\alpha)} [H_\alpha, X] = \frac{2}{\alpha(H_\alpha)} \text{ad}(H_\alpha)X \\ = 2X.$$

$$\text{Similarly, } [\hat{H}_\alpha, Y] = -2X.$$

• Fix a generic $H \in \mathfrak{g}$

$$(\text{i.e., } \alpha(H) \neq 0, \forall \alpha \in \Delta, \\ \alpha(H) \neq \beta(H), \forall \alpha \neq \beta \in \Delta)$$

$$\text{Let } \Delta^+(H) = \{\alpha \in \Delta \mid \alpha(H) > 0\} \\ (\text{positive roots}) \sim \text{unstable dir.}$$

$$\Delta_S(H) = \left\{ \alpha \in \Delta^+(H) \mid \alpha \neq \beta_1 + \beta_2, \right. \\ \left. \begin{array}{l} \text{(simple roots)} \\ \beta_1 + \beta_2 \in \Delta^+(H) \end{array} \right\}$$

Then: $\Delta_S(H)$ "generates" $\Delta^+(H)$

Ex: $\mathcal{H}(3, \mathbb{R})$, $H = \begin{pmatrix} x_1 & & \\ & x_2 & \\ & & x_3 \end{pmatrix}$
 $x_1 > x_2 > x_3$

$$\Rightarrow \Delta^+(H) = \{t_1 - t_2, t_2 - t_3, t_1 - t_3\}$$

$$\Delta_S(H) = \{t_1 - t_2, t_2 - t_3\}$$

Thm: $\Delta_S(H)$ is a basis of $\mathfrak{a}^*$.

List the elements of $\Delta_S(H)$:

$\{\alpha_1, \dots, \alpha_\ell\}$. Define the matrix

$$C_{ij} = \frac{2 K(H\alpha_i, H\alpha_j)}{K(H\alpha_i, H\alpha_i)} \quad \leftarrow \text{(Cartan matrix)}$$

Thm: The Cartan matrix $C = (C_{ij})$
 has integer entries, and
 determines $\mathfrak{g}$ up to isomorphism.

Ex: $\mathfrak{sl}(3, \mathbb{R}) = \mathfrak{g}$.

$$\Delta_S = \{t_1 - t_2, t_2 - t_3\}$$

~~$$H_{t_1 - t_2} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad H_{t_2 - t_3} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$~~

$$K(H_{t_1 - t_2}, \begin{pmatrix} t_1 & 0 & 0 \\ 0 & t_2 & 0 \\ 0 & 0 & t_3 \end{pmatrix})$$

$$= t_1 - t_2$$

Exr: If G is a matrix
 group, then
 $K(X, Y) = \text{tr}(XY)$.

$$\Rightarrow H_{t_1 - t_2} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix},$$

↪

$$H_{t_2-t_3} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & - \\ 0 & 0 & -1 \end{pmatrix}.$$

$$C_{12} = \frac{2 K(H_{t_1-t_2}, H_{t_1-t_3})}{K(H_{t_1-t_2}, H_{t_1-t_2})} = \frac{2 \cdot (-1)}{2} = -1.$$

$$C_{11} = C_{12} = 2 \Rightarrow C = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

Σ_2 $sl(d, \mathbb{R}) = \mathfrak{of}.$

$$\Rightarrow C = \begin{pmatrix} 2 & -1 & & & & \\ & -1 & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & -1 \\ & & & & & -1 & 2 \end{pmatrix}$$

Ex: $\mathfrak{g} = \mathfrak{so}(2, 2)$.

$$\begin{pmatrix} t_1 \square & 0 & \Delta \\ -\square & t_2 & \Delta & 0 \\ \hline 0 & -\Delta & -t_1 & -\square \\ -\Delta & 0 & \square & -t_2 \end{pmatrix}$$

say H has $t_1 > t_2 > 0$.

$$\Delta^+(H) = \{t_1 - t_2, t_1 + t_2\} = \Delta_S(H).$$

$$H_{t_1 - t_2} = \begin{pmatrix} \frac{1}{2} & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & 0 & 0 \\ \hline 0 & 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 & \frac{1}{2} \end{pmatrix}$$

$$H_{t_1 + t_2} = \begin{pmatrix} \frac{1}{2} & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ \hline 0 & 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 & -\frac{1}{2} \end{pmatrix}$$

↪

$$\Rightarrow \kappa(H_{t_1-t_2}, H_{t_1+t_2}) = 0.$$

$$\Rightarrow C = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}.$$

$$\Rightarrow \mathfrak{so}(2, 4) = \mathfrak{sl}(4) \oplus \mathfrak{sl}(2).$$

Ex: $\mathfrak{g} = \mathfrak{so}(2, 3)$

t_1 □	$\bigcirc$	△	★
t_2	△	$\bigcirc$	▽
	$-t_1$		
	□	$-t_2$	
	★	▽	$\bigcirc$

$\left(\begin{matrix} \mathfrak{so}(3-2) \\ = \mathfrak{so}(1) = 0 \end{matrix} \right)$

H be so that $t_1 > t_2 > 0$.

$$\Delta^+(H) = \{t_1, t_2, t_1 - t_2, t_1 + t_2\}$$

$$\Delta_-(H) = \{t_2, t_1 - t_2\}$$

$$H_{t_2} = \left(\begin{array}{cc|c} 0 & 1/2 & 0 \\ \hline & & -1/2 \\ \hline & & 0 \end{array} \right)$$

$$H_{t_1-t_2} = \left(\begin{array}{cc|c} 1/2 & -1/2 & 0 \\ \hline & & -1/2 \\ \hline & & 1/2 \\ \hline & & 0 \end{array} \right)$$

$$C_{12} = \frac{2 \cdot (-1/2)}{1/2} = -2$$

$$C_{21} = \frac{2 \cdot (-1/2)}{1} = -1$$

$$\Rightarrow C = \begin{pmatrix} 2 & -2 \\ -1 & 2 \end{pmatrix}$$