## Introduction to Algebraic and Geometric Topology Week 10

Domingo Toledo

University of Utah

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# Recall: Quotient Topology

- Let
  - 1.  $(X, \mathcal{T}_X)$  be a topological space,
  - 2. *Y* a set
  - 3.  $f: X \to Y$  a surjective map.

The *quotient topology*  $\mathcal{T}_Y$  on Y, is defined as

$$T_{Y} = \{ \bigcup_{X \in X} C(X) \mid f^{-1}(U) \in \mathcal{T}_{X} \}$$

T<sub>Y</sub> is the largest topology on Y that makes f continuous.



#### Recall: Identification

Definition

Let

- 1.  $f:(X,\mathcal{T}_X),(Y,\mathcal{T}_Y)$  be topological spaces.
- 2.  $f: X \rightarrow Y$  a surjective map.

f is called an *identification* if and only if  $T_Y$  is the quotient topology just defined:

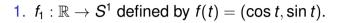
$$T_Y = \{U \subset Y \mid f^{-1}(U) \in \mathcal{T}_X\}$$

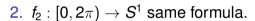
► Equivalent statements: A surjective map f : X → Y is an identification if and only if

U open in 
$$Y \iff f^{-1}(U)$$
 is open in  $X$ 

$$F \text{ closed in } Y \iff f^{-1}(F) \text{ is closed in } X$$

## Recall: Examples





3. 
$$f_3:[0,2\pi]\to S^1$$
 same formula.

1) and 3) are identifications, 2 is not.



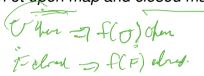






### Sufficient Conditions for Identification

1. Recall definition of open map and closed map



2.  $f: X \to Y$  continuous, surjective and open  $\Longrightarrow$  identification.

3.  $f: X \to Y$  continuous, surjective and *closed*  $\Longrightarrow$  identification.

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## Checking Identifications

- Useful facts:
- ▶ Suppose  $f: X \rightarrow Y$ ,  $A \subset X$ ,  $B \subset Y$ . Then
  - **1.**  $f(f^{-1}(B))$  ⊂ B
  - 2. If f is surjective,  $f(f^{-1}(B)) \equiv B$
  - 3.  $A \subset f^{-1}(f(A))$ .
  - 4. If f is surjective, then

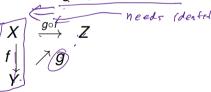
$$A = f^{-1}(B) \text{ for some } B \subset Y \iff A = f^{-1}(f(A))$$
 and, in this case,  $B = f(A)$ .





## Continuous Maps

- ► *X*, *Y*, *Z* topological spaces.
- ▶  $f: X \rightarrow Y$  identification,
- $g: Y \to Z$  a map.
- ▶ Then g is continuous  $\iff g \circ f$  is continuous



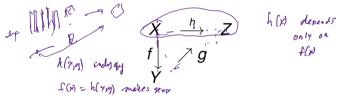
- Proof:
- ▶ If  $U \subset Z$ , then

$$(g \circ f)^{-1}(U) = f^{-1}(g^{-1}(U))$$

▶ Thus, if  $U \subset Z$ ,

$$\underbrace{g^{-1}(U)}_{\text{former}} \text{ is open} \iff (g \circ f)^{-1}(U)_{\text{former}} \text{ is open}$$
Thus  $g \text{ continuous} \iff g \circ f \text{ is continuous}.$ 

- Equivalent Formulation:
- ▶ X, Y, Z topological spaces, f : X → Y an identification.
- ▶  $h: X \to Z$  a map that is constant on the fibers  $f^{-1}(y)$  of f.
- ▶ Then the map *g* in the following diagram is defined:



▶ g is continuous  $\iff$  h is continuous.

▶ Example: Periodic functions  $h: \mathbb{R} \to \mathbb{R}$ 

Example. Periodic functions 
$$H : \mathbb{R} \to \mathbb{R}$$

$$f(x \mapsto \pi \cdot y) = f(x)$$

$$f \neq g$$

$$f \neq g$$

$$f \neq g$$

$$f(x) = f(t) = e^{ct} = x$$

where  $f(t) = (\cos t, \sin t)$ .

- ► Example: Doubly periodic functions  $h : \mathbb{R}^2 \to \mathbb{R}$  $h(s+2\pi,t) = h(s,t)$  and  $h(s,t+2\pi) = h(s,t) \, \forall (s,t) \in \mathbb{R}^2$
- ▶ Let *T* be the *torus*  $S^1 \times S^1$

$$T = \{(x_1, x_2, x_3, x_4) \in \mathbb{R}^4 \mid x_1^2 + x_2^2 = x_3^2 + x_4^2 = 1\}$$
  
and  $f : \mathbb{R}^2 \to T$  be defined by  $f(s, t) = (\cos s, \sin s, \cos t, \sin t).$ 

► Then f is an identification and h is continuous ⇔ g is continuous:

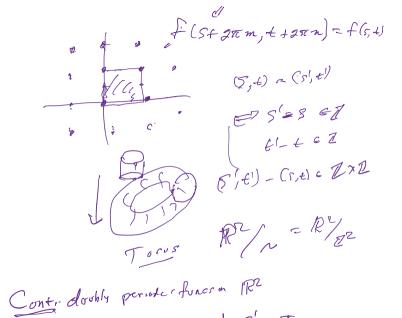
$$\mathbb{R}^{2} \xrightarrow{n} \mathbb{R}$$

$$f \not \nearrow g$$

$$T$$

$$f (\mathfrak{F}+2\pi)+1=f(s,t)$$

$$f (s_{f}+1\pi)=f(s,t)$$



es Cont function 51x5' = Torus.

## **Equivalence Relations**

•  $f: X \to Y$  surjective map of sets  $\iff$ 

equivalence relation on X:

They eyes 
$$x_1 \sim x_2 \iff f(x_1) = f(x_2)$$
.

They eyes  $f: y \to Set \circ f$ 

egov closes

•  $f: X \to Y$  surjective map of sets  $\iff$ 

Partition of X into disjoint subsets

$$X = \prod_{y \in Y} f^{-1}(y)$$

$$\Rightarrow \begin{cases} x_{e+1} & \text{if e gon clesses} \end{cases}$$

## **Connected Components**



▶ Let *X* be a topological space. Define a relation

$$x \sim y \iff \exists$$
 a connected  $C \subset X$  with  $x, y \in C$ 

- ► Theorem

  The relation just defined is an equivalence relation.
- Proof.

  Clearly  $(x \sim x)$  and  $x \sim y \iff y \sim x$ .

  Transitivity  $x \sim y$  and  $y \sim z \implies x \sim z$  follows from the next lemma.

Lemma

If  $C_1, C_2 \subset X$  are connected and  $C_1 \cap C_2 \neq \emptyset$ , then  $C_1 \cup C_2$  is connected.

let 
$$\varphi: C_1 \cup C_2 \longrightarrow \{o_1i\}$$

conf fonc.

 $\varphi|C_1 = conf \subset C_1$ 
 $\varphi|C_2 = conf \subset C_2$ 
 $\varphi: C_1 \cap C_2 \longrightarrow \varphi(x) = \emptyset$ 
 $\exists C_2 = \varphi(x)$ 
 $\exists C_3 = c_2 = \varphi(x)$ 

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#### Better Lemma:

#### Lemma

- Let  $\{C_{\alpha}\}_{{\alpha}\in A}$  be a collection of connected subsets of X indexed by a set A. Suppose that  $\bigcap_{\alpha} C_{\alpha} \neq \emptyset$ . Then  $|\cup_{lpha} \mathcal{C}_{lpha}$  is connected.
- Suppose  $C \subset X$  is connected. Then its closure  $\overline{C}$  is

#### Definition

The equivalence classes of the equivalence relation just defined are called the *connected components* of X.

▶ If  $x \in X$ , let  $C_x$  be the connected component of Xcontaining x.

#### Theorem

•  $C_x$  is the largest connected subset of X containing x.
•  $C_x$  is closed in X.

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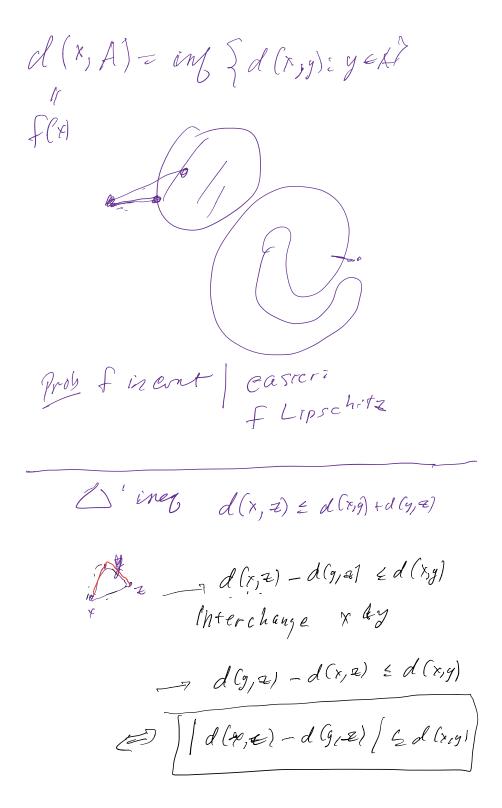
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&\mathcal{J}(x) - \mathcal{G}(x) = \mathcal{A}(x, y)
\end{aligned}$$

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&\mathcal{J}(x, 3) = \inf_{x \in A} \left\{ \mathcal{J}_{x}(x) : z \in A \right\}
\end{aligned}$$

$$\begin{aligned}
&\mathcal{J}(x, 4) = \inf_{x \in A} \left\{ \mathcal{J}_{x}(x) : z \in A \right\}
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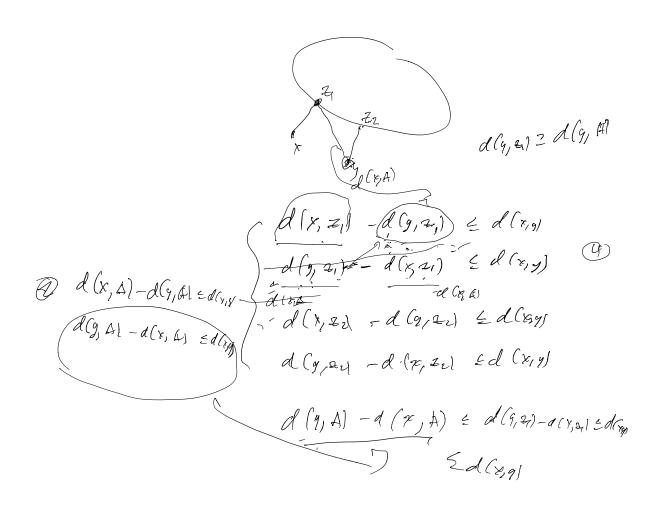
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$$\end{aligned}$$

d(x, A) d(x, A) - d(y, A)  $Suppose d(x, A) = d(x, Z_1)$   $d(y, A) = d(y, Z_2)$ 



Connected Components of (XX)

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Show x,y = C

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#### **Definition**

Let  $\pi_0(X)$  denote the set of connected components of X.

There is a surjective map  $\pi: X \to \pi_0(X)$  defined by

$$\pi(x) = C_x,$$

the connected component of X containing x.

- $\widehat{card}(\pi_0(X)) = 1 \iff X \text{ is connected.}$
- ▶ In general,  $card(\pi_0(X))$  is the number of connected components of X.
- $\star$   $\pi_0(X)$  is a topological space, with the quotient topology.



▶ If  $f: X \to Y$  is continuous, there is a map, first of sets,

$$f_*:\pi_0(X) o\pi_0(Y)$$

defined by

$$f_*(C_x^X) \to C_{f(x)}^Y$$

where  $C_x^X$  and  $C_y^Y$  denote the connected components of x in X and of y in Y respectively.

► Exercise 1: f<sub>\*</sub> is well-defined:

$$X \sim X' \Longrightarrow C_{f(X)}^{Y} = C_{f(X')}^{Y}.$$

- ▶ Reason:  $x \sim x' \iff C_x^X = C_{x'}^X$  and  $f(C_x^X)$  is a connected subset of Y containing f(x), hence  $f(C_x^X) \subset C_{f(x)}^Y$ .
- Exercise 2: f homeomorphism  $\Longrightarrow f_*$  bijective.
- Exercise 3: f\* is continuous.
- ► Exercise 4: f homeomorphism ⇒ f, homeomorphism.

## Examples

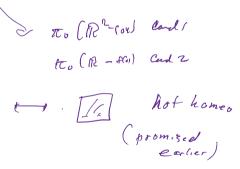
- $\sqrt{\pi_0(\mathbb{R}^n)}$  has cardinality one for  $n=1,2,\ldots$
- ▶ If X is discrete  $\pi: X \to \pi_0(X)$  is a homeomorphism.
- ► Homework Problem : X locally connected  $\Longrightarrow \pi_0(X)$  is discrete.

#### **Theorem**

For  $n \geq 2$ ,  $\mathbb{R}$  is not homeomorphic to  $\mathbb{R}^{\widehat{n}}$ .

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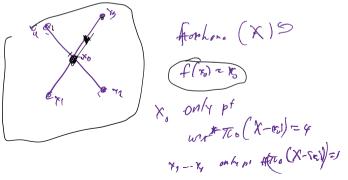
- Same argument: the unit interval *I* is not homeomorphic to *I* × *I*.
- ► This was used in the proof that the Euclidean and taxi-cab metrics not being isometric.

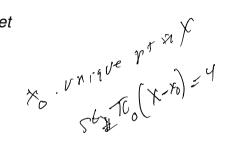


#### **Theorem**

Let X be the subspace of  $\mathbb{R}^2$  of the letter "X". Let  $x_0$  be the junction point of the four "branches" of X, and let  $x_1, x_2, x_3, x_4$  be the other endpoints of the branches. Let  $f: X \to X$  be a homeomorphism.

Then  $f(x_0) = x_0$  and f permutes the points  $x_1, \ldots, x_4$ .

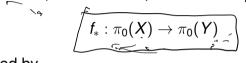






- ▶ If X is the Cantor set, what is  $\pi_0(X)$ ?
- ▶ Some information in the homework.

- ▶ Let's go back to the definition of *f*<sub>∗</sub>:
- ▶ If  $f: X \rightarrow Y$  is continuous, there is a map, first of sets,



defined by

$$f_*(C_{\scriptscriptstyle X}^{\scriptscriptstyle X}) o C_{f({\scriptscriptstyle X})}^{\scriptscriptstyle Y}$$

where  $C_x^X$  and  $C_y^Y$  denote the connected components of x in X and of y in Y respectively.

► Exercise 1:  $f_*$  is well-defined:  $x \sim x' \Longrightarrow C_{f(x)}^Y = C_{f(x')}^Y$ .

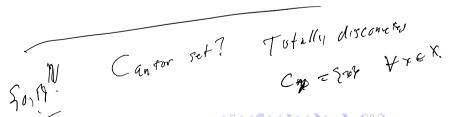
Better to first say:

#### **Theorem**

- 1. The connected components of X are the maximal connected subsets of X.
- 2. Every non-empty connected subset of X is contained in a unique maximal connected subset.

# Connected, Max

- ► Then  $C_{f(x)}^{Y}$  is *the* maximal connected subspace of Y containing  $f(C_{X})$ .
- So is  $C_{f(x')}^{Y}$  for any  $x' \in C_x$ .



- ▶ In the same spirit as looking at homeomorhisms of the letter *X*:
- ► Exercise: Classify the (capital) letters A, B, C, ... Z of the Roman alphabet up to homeomorphism.



HW X char Hausdiot A, BCX chal subts A 11B = 0 = 3 yensets U,V ACTOBET (Inv=+ Quutient Tupology Connered Component

> Quotients of Hausdorff Spaces need not be Hausdorff

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Another Exi

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Y+ r e P (U) treg



Definition  $\underline{\mathcal{L}}$  A topological surface is a Hausdorff space with a countable basis that is locally homeomorphic to  $\mathbb{R}^2$ .

(connected) Surface - locally home to 12 Y locally home to the Y a. R. Y & St. V from Va. R. Countible basis = no more

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#### Examples

- ▶ An open subset of  $\mathbb{R}^2$
- ▶ The unit sphere  $S^2 \subset \mathbb{R}^3$

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Let  $u \subset \mathbb{R}^3$  be open, let f  $U \to \mathbb{R}$  be a function of class  $C^1$ , and suppose that the gradient  $\nabla_x f \neq 0$  at any point x where f(x) = 0. Then

$$\{x\in\mathbb{R}^3\mid f(x)=0\}$$

is a topological surface.

Reason: The implicit function theorem. (Will review and prove)

# Surfaces as Identification Spaces

**Example: Torus** (x,y).~ (x/y/)

 $\xi = \frac{1}{2} \left( \frac{1}{2} - \frac{1}{2} \right)^2 = \frac{1}{2} \left( \frac{1}{2} - \frac{1$ 

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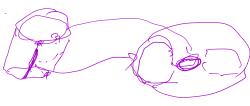
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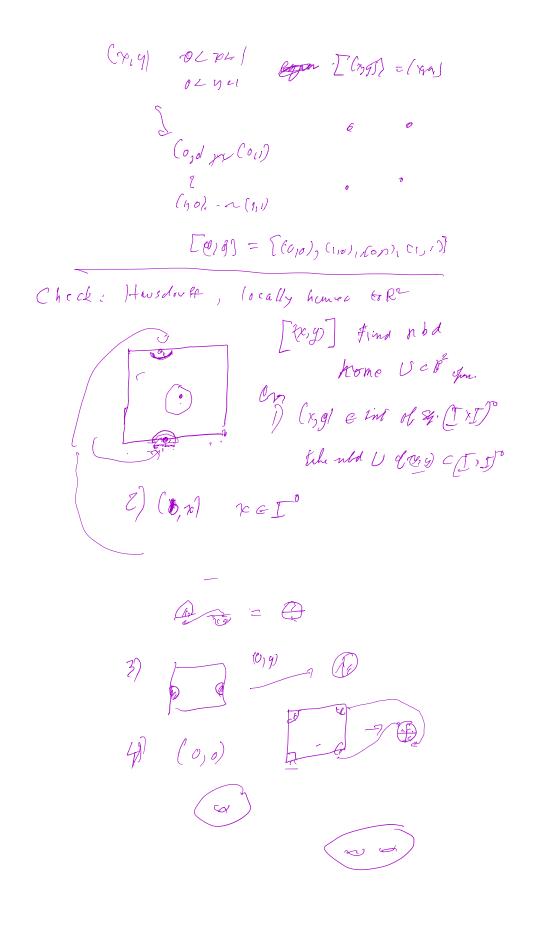
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(oh 5'x5)

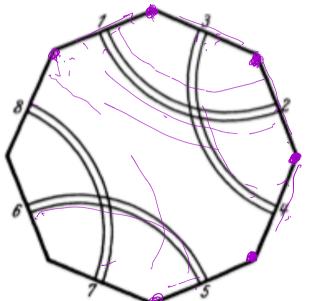
Surface: [0,1x20]

 $\begin{array}{c|c}
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(^{2}y) & (^{1}y) \\
(^{2}y) & (^{1}y)
\end{array}$ 



### Surface of Genus Two

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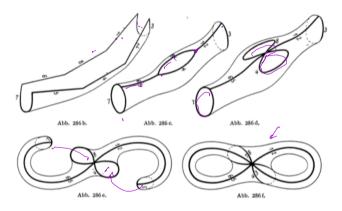


Figure: Surface of Genus Two

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# Non-Hausdorff Quotient Spaces

#### A non-Hausdorff "Surface"

# Existence theorems based on connectedness

► The intermediate value theorem.

$$X \text{ tom}, f: X \rightarrow R \text{ bot}$$

$$A = b$$

$$A = b$$

$$A = b$$

$$A = f(x) = a$$

$$f(x) = b$$

$$A = f(x) = b$$

$$A = f(x) = c$$

$$A = f(x) = c$$

The implicit function theorem. Alford on Mg f(x,g) f(0,0) = (0,0)  $C^2$ - 2f (0,0) ≠ 0 # 8 7, 8 Cal}