

<p>COPYRIGHT &amp; LICENSE</p> <p><i>Copyright © 2007 Jason Underdown Some rights reserved.</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>statement</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>sentential connectives</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>negation</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>conjunction</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>disjunction</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>implication or conditional</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>antecedant &amp; consequent hypothesis &amp; conclusion</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>equivalence</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>negation of a conjunction</i></p> <p>REAL ANALYSIS I</p>

<p>A sentence that can unambiguously be classified as true or false.</p>	<p>These flashcards and the accompanying <math>\text{\LaTeX}</math> source code are licensed under a Creative Commons Attribution–NonCommercial–ShareAlike 3.0 License. For more information, see <a href="http://creativecommons.org">creativecommons.org</a>. You can contact the author at:</p> <p style="text-align: center;">jasonu at physics utah edu</p> <p style="text-align: center;">File last updated on Thursday 2<sup>nd</sup> August, 2007, at 02:18</p>																														
<p>Let <math>p</math> stand for a statement, then <math>\sim p</math> (read <i>not p</i>) represents the logical opposite or <b>negation</b> of <math>p</math>.</p>	<p style="text-align: center;">not, and, or, if ... then, if and only if</p>																														
<p>If <math>p</math> and <math>q</math> are statements, then the statement <math>p</math> or <math>q</math> (called the <b>disjunction</b> of <math>p</math> and <math>q</math> and denoted <math>\mathbf{p} \vee \mathbf{q}</math>) is true unless both <math>p</math> and <math>q</math> are false.</p> <table style="margin-left: auto; margin-right: auto; border-collapse: collapse;"> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>p</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>q</math></td> <td style="padding: 2px 5px;"><math>p \vee q</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="padding: 2px 5px;"><math>T</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="padding: 2px 5px;"><math>T</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="padding: 2px 5px;"><math>T</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="padding: 2px 5px;"><math>F</math></td> </tr> </table>	$p$	$q$	$p \vee q$	$T$	$T$	$T$	$T$	$F$	$T$	$F$	$T$	$T$	$F$	$F$	$F$	<p>If <math>p</math> and <math>q</math> are statements, then the statement <math>p</math> and <math>q</math> (called the <b>conjunction</b> of <math>p</math> and <math>q</math> and denoted <math>\mathbf{p} \wedge \mathbf{q}</math>) is true only when both <math>p</math> and <math>q</math> are true, and false otherwise.</p> <table style="margin-left: auto; margin-right: auto; border-collapse: collapse;"> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>p</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>q</math></td> <td style="padding: 2px 5px;"><math>p \wedge q</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="padding: 2px 5px;"><math>T</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="padding: 2px 5px;"><math>F</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="padding: 2px 5px;"><math>F</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="padding: 2px 5px;"><math>F</math></td> </tr> </table>	$p$	$q$	$p \wedge q$	$T$	$T$	$T$	$T$	$F$	$F$	$F$	$T$	$F$	$F$	$F$	$F$
$p$	$q$	$p \vee q$																													
$T$	$T$	$T$																													
$T$	$F$	$T$																													
$F$	$T$	$T$																													
$F$	$F$	$F$																													
$p$	$q$	$p \wedge q$																													
$T$	$T$	$T$																													
$T$	$F$	$F$																													
$F$	$T$	$F$																													
$F$	$F$	$F$																													
<p style="text-align: center;">If <math>p</math>, then <math>q</math>.</p> <p>In the above, the statement <math>p</math> is called the <b>antecedent</b> or <b>hypothesis</b>, and the statement <math>q</math> is called the <b>consequent</b> or <b>conclusion</b>.</p>	<p>A statement of the form</p> <p style="text-align: center;"><i>if p then q</i></p> <p>is called an <b>implication</b> or <b>conditional</b>.</p> <table style="margin-left: auto; margin-right: auto; border-collapse: collapse;"> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>p</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>q</math></td> <td style="padding: 2px 5px;"><math>p \Rightarrow q</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="padding: 2px 5px;"><math>T</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="padding: 2px 5px;"><math>F</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>T</math></td> <td style="padding: 2px 5px;"><math>T</math></td> </tr> <tr> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="border-right: 1px solid black; padding: 2px 5px;"><math>F</math></td> <td style="padding: 2px 5px;"><math>T</math></td> </tr> </table>	$p$	$q$	$p \Rightarrow q$	$T$	$T$	$T$	$T$	$F$	$F$	$F$	$T$	$T$	$F$	$F$	$T$															
$p$	$q$	$p \Rightarrow q$																													
$T$	$T$	$T$																													
$T$	$F$	$F$																													
$F$	$T$	$T$																													
$F$	$F$	$T$																													
<p style="text-align: center;"><math>\sim (p \wedge q) \Leftrightarrow (\sim p) \vee (\sim q)</math></p>	<p>A statement of the form “<math>p</math> if and only if <math>q</math>” is the conjunction of two implications and is called an <b>equivalence</b>.</p>																														

<p>DEFINITION</p> <p><i>negation of a disjunction</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>negation of an implication</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>tautology</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>universal quantifier</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>existential quantifier</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>contrapositive</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>converse</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>inverse</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>contradiction</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>subset</i></p> <p>REAL ANALYSIS I</p>

$\sim (p \Rightarrow q) \Leftrightarrow p \wedge (\sim q)$	$\sim (p \vee q) \Leftrightarrow (\sim p) \wedge (\sim q)$
$\forall x, p(x)$ <p>In the above statement, the <b>universal quantifier</b> denoted by <math>\forall</math> is read “for all”, “for each”, or “for every”.</p>	<p>A sentence whose truth table contains only T is called a <b>tautology</b>. The following sentences are examples of tautologies (<math>c \equiv</math> contradiction):</p> $(p \Leftrightarrow q) \Leftrightarrow (p \Rightarrow q) \wedge (q \Rightarrow p)$ $(p \Rightarrow q) \Leftrightarrow (\sim q \Rightarrow \sim p)$ $(p \Rightarrow q) \Leftrightarrow [(p \wedge \sim q) \Rightarrow c]$
<p>The implication <math>p \Rightarrow q</math> is logically equivalent with its <b>contrapositive</b>:</p> $\sim q \Rightarrow \sim p$	$\exists x \ni p(x)$ <p>In the above statement, the <b>existential quantifier</b> denoted by <math>\exists</math> is read “there exists ...”, “there is at least one ...”. The symbol <math>\ni</math> is just shorthand for “such that”.</p>
<p>Given the implication <math>p \Rightarrow q</math> then its <b>inverse</b> is</p> $\sim p \Rightarrow \sim q$ <p>An implication is <i>not</i> logically equivalent to its inverse. The inverse is the contrapositive of the converse.</p>	<p>Given the implication <math>p \Rightarrow q</math> then its <b>converse</b> is</p> $q \Rightarrow p$ <p>But they are <i>not</i> logically equivalent.</p>
<p>Let <math>A</math> and <math>B</math> be sets. We say that <math>A</math> is a <b>subset</b> of <math>B</math> if every element of <math>A</math> is an element of <math>B</math>. In symbols, this is denoted</p> $A \subseteq B \text{ or } B \supseteq A$	<p>A <b>contradiction</b> is a statement that is always false. Contradictions are symbolized by the letter <math>c</math> or by two arrows pointing directly at each other.</p> $\Rightarrow \Leftarrow$

<p>DEFINITION</p> <p><i>proper subset</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>set equality</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>union, intersection, complement, disjoint</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>indexed family of sets</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>pairwise disjoint</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>ordered pair</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>Cartesian product</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>relation</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>equivalence relation</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>equivalence class</i></p> <p>REAL ANALYSIS I</p>

<p>Let <math>A</math> and <math>B</math> be sets. We say that <math>A</math> is a <b>equal</b> to <math>B</math> if <math>A</math> is a subset of <math>B</math> and <math>B</math> is a subset of <math>A</math>.</p> $A = B \Leftrightarrow A \subseteq B \text{ and } B \subseteq A$	<p>Let <math>A</math> and <math>B</math> be sets. <math>A</math> is a <b>proper subset</b> of <math>B</math> if <math>A</math> is a subset of <math>B</math> and there exists an element in <math>B</math> that is not in <math>A</math>.</p>
<p>If for each element <math>j</math> in a nonempty set <math>J</math> there corresponds a set <math>A_j</math>, then</p> $\mathcal{A} = \{A_j : j \in J\}$ <p>is called an <b>indexed family of sets</b> with <math>J</math> as the index set.</p>	<p>Let <math>A</math> and <math>B</math> be sets.</p> $A \cup B = \{x : x \in A \text{ or } x \in B\}$ $A \cap B = \{x : x \in A \text{ and } x \in B\}$ $A \setminus B = \{x : x \in A \text{ and } x \notin B\}$ <p>If <math>A \cap B = \emptyset</math> then <math>A</math> and <math>B</math> are said to be <b>disjoint</b>.</p>
<p>The <b>ordered pair</b> <math>(a, b)</math> is the set whose members are <math>\{a\}</math> and <math>\{a, b\}</math>.</p> $(a, b) = \{\{a\}, \{a, b\}\}$	<p>If <math>\mathcal{A}</math> is a collection of sets, then <math>\mathcal{A}</math> is called <b>pairwise disjoint</b> if</p> $\forall A, B \in \mathcal{A}, \text{ where } A \neq B \text{ then } A \cap B = \emptyset$
<p>Let <math>A</math> and <math>B</math> be sets. A <b>relation</b> between <math>A</math> and <math>B</math> is any subset <math>R</math> of <math>A \times B</math>.</p> $aRb \Leftrightarrow (a, b) \in R$	<p>If <math>A</math> and <math>B</math> are sets, then the <b>Cartesian product</b> or <b>cross product</b> of <math>A</math> and <math>B</math> is the set of all ordered pairs <math>(a, b)</math> such that <math>a \in A</math> and <math>b \in B</math>.</p> $A \times B = \{(a, b) : a \in A \text{ and } b \in B\}$
<p>The <b>equivalence class</b> of <math>x \in S</math> with respect to an equivalence relation <math>R</math> is the set</p> $E_x = \{y \in S : yRx\}$	<p>A relation <math>R</math> on a set <math>S</math> is an <b>equivalence relation</b> if for all <math>x, y, z \in S</math> it satisfies the following criteria:</p> <ol style="list-style-type: none"> <li>1. <math>xRx</math> reflexivity</li> <li>2. <math>xRy \Rightarrow yRx</math> symmetry</li> <li>3. <math>xRy</math> and <math>yRz \Rightarrow xRz</math> transitivity</li> </ol>

<p>THEOREM</p> <p><i>partition</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>function between A and B</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>domain</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>range &amp; codomain</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>surjective or onto</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>injective or 1-1</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>bijective</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>characteristic or indicator function</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>image and pre-image</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>composition of functions</i></p> <p>REAL ANALYSIS I</p>

<p>Let <math>A</math> and <math>B</math> be sets. A <b>function between <math>A</math> and <math>B</math></b> is a nonempty relation <math>f \subseteq A \times B</math> such that</p> $[(a, b) \in f \text{ and } (a, b') \in f] \implies b = b'$	<p>A <b>partition</b> of a set <math>S</math> is a collection <math>\mathcal{P}</math> of nonempty subsets of <math>S</math> such that</p> <ol style="list-style-type: none"> <li>1. Each <math>x \in S</math> belongs to some subset <math>A \in \mathcal{P}</math>.</li> <li>2. For all <math>A, B \in \mathcal{P}</math>, if <math>A \neq B</math>, then <math>A \cap B = \emptyset</math></li> </ol> <p>A member of a set <math>\mathcal{P}</math> is called a <b>piece</b> of the partition.</p>
<p>Let <math>A</math> and <math>B</math> be sets, and let <math>f \subseteq A \times B</math> be a function between <math>A</math> and <math>B</math>. The <b>range</b> of <math>f</math> is the set of all second elements of members of <math>f</math>.</p> $\text{rng } f = \{b \in B : \exists a \in A \ni (a, b) \in f\}$ <p>The set <math>B</math> is referred to as the <b>codomain</b> of <math>f</math>.</p>	<p>Let <math>A</math> and <math>B</math> be sets, and let <math>f \subseteq A \times B</math> be a function between <math>A</math> and <math>B</math>. The <b>domain</b> of <math>f</math> is the set of all first elements of members of <math>f</math>.</p> $\text{dom } f = \{a \in A : \exists b \in B \ni (a, b) \in f\}$
<p>The function <math>f : A \rightarrow B</math> is <b>injective</b> or (1-1) if:</p> $\forall a, a' \in A, \quad f(a) = f(a') \implies a = a'$	<p>The function <math>f : A \rightarrow B</math> is <b>surjective</b> or <b>onto</b> if <math>B = \text{rng } f</math>. Equivalently,</p> $\forall b \in B, \quad \exists a \in A \ni b = f(a)$
<p>Let <math>A</math> be a nonempty set and let <math>S \subseteq A</math>, then the <b>characteristic function</b> <math>\chi_S : A \rightarrow \{0, 1\}</math> is defined by</p> $\chi_S(a) = \begin{cases} 0 & a \notin S \\ 1 & a \in S \end{cases}$	<p>A function <math>f : A \rightarrow B</math> is said to be <b>bijective</b> if <math>f</math> is both surjective and injective.</p>
<p>Suppose <math>f : A \rightarrow B</math> and <math>g : B \rightarrow C</math>, then the <b>composition</b> of <math>g</math> with <math>f</math> denoted by <math>g \circ f : A \rightarrow C</math> is given by</p> $(g \circ f)(x) = g(f(x))$ <p>In terms of ordered pairs this means</p> $g \circ f = \{(a, c) \in A \times C : \exists b \in B \ni (a, b) \in f \wedge (b, c) \in g\}$	<p>Suppose <math>f : A \rightarrow B</math>, and <math>C \subseteq B</math>, then the <b>image</b> of <math>C</math> under <math>f</math> is</p> $f(C) = \{f(x) : x \in C\}$ <p>If <math>D \subseteq B</math> then the <b>pre-image</b> of <math>D</math> in <math>f</math> is</p> $f^{-1}(D) = \{x \in A : f(x) \in D\}$



<p>DEFINITION</p> <p><i>inverse function</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>identity function</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>equinumerous</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>finite &amp; infinite sets</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>cardinal number &amp; transfinite</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>denumerable</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>countable &amp; uncountable</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>power set</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>continuum hypothesis</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>algebraic &amp; transcendental</i></p> <p>REAL ANALYSIS I</p>

<p>A function that maps a set <math>A</math> onto itself is called the <b>identity function</b> on <math>A</math>, and is denoted <math>i_A</math>.</p> <p>If <math>f : A \rightarrow B</math> is a bijection, then</p> $f^{-1} \circ f = i_A$ $f \circ f^{-1} = i_B$	<p>Let <math>f : A \rightarrow B</math> be bijective. The <b>inverse function</b> of <math>f</math> is the function <math>f^{-1} : B \rightarrow A</math> given by</p> $f^{-1} = \{(y, x) \in B \times A : (x, y) \in f\}$
<p>A set <math>S</math> is said to be <b>finite</b> if <math>S = \emptyset</math> or if there exists an <math>n \in \mathbb{N}</math> and a bijection</p> $f : \{1, 2, \dots, n\} \rightarrow S.$ <p>If a set is not finite, it is said to be <b>infinite</b>.</p>	<p>Two sets <math>S</math> and <math>T</math> are <b>equinumerous</b>, denoted <math>S \sim T</math>, if there exists a bijection from <math>S</math> onto <math>T</math>.</p>
<p>A set <math>S</math> is said to be <b>denumerable</b> if there exists a bijection</p> $f : \mathbb{N} \rightarrow S$	<p>Let <math>I_n = \{1, 2, \dots, n\}</math>. The <b>cardinal number</b> of <math>I_n</math> is <math>n</math>. Let <math>S</math> be a set. If <math>S \sim I_n</math> then <math>S</math> has <math>n</math> elements.</p> <p>The cardinal number of <math>\emptyset</math> is defined to be 0.</p> <p>Finally, if a cardinal number is not finite, it is said to be <b>transfinite</b>.</p>
<p>Given any set <math>S</math>, the <b>power set</b> of <math>S</math> denoted by <math>\mathcal{P}(S)</math> is the collection of all possible subsets of <math>S</math>.</p>	<p>If a set is finite or denumerable, then it is <b>countable</b>.</p> <p>If a set is not countable, then it is <b>uncountable</b>.</p>
<p>A real number is said to be <b>algebraic</b> if it is a root of a polynomial with integer coefficients.</p> <p>If a number is not algebraic, it is called <b>transcendental</b>.</p>	<p>Given that <math> \mathbb{N}  = \aleph_0</math> and <math> \mathbb{R}  = c</math>, we know that <math>c &gt; \aleph_0</math>, but is there any set with cardinality say <math>\lambda</math> such that <math>\aleph_0 &lt; \lambda &lt; c</math>?</p> <p>The conjecture that there is no such set was first made by Cantor and is known as the <b>continuum hypothesis</b>.</p>

<p>AXIOM</p> <p><i>well-ordering property of <math>\mathbb{N}</math></i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>basis for induction, induction step, induction hypothesis</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>recursion relation or recurrence relation</i></p> <p>REAL ANALYSIS I</p>	<p>AXIOM</p> <p><i>field axioms</i></p> <p>REAL ANALYSIS I</p>
<p>AXIOM</p> <p><i>order axioms</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>absolute value</i></p> <p>REAL ANALYSIS I</p>
<p>THEOREM</p> <p><i>triangle inequality</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>ordered field</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>irrational number</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>upper &amp; lower bound</i></p> <p>REAL ANALYSIS I</p>

<p>In the <i>Principle of Mathematical Induction</i>, part (1) which refers to <math>P(1)</math> being true is known as the <b>basis for induction</b>.</p> <p>Part (2) where one must show that <math>\forall k \in \mathbb{N}, P(k) \Rightarrow P(k+1)</math> is known as the <b>induction step</b>.</p> <p>Finally, the assumption in part (2) that <math>P(k)</math> is true is known as the <b>induction hypothesis</b>.</p>	<p>If <math>S</math> is a nonempty subset of <math>\mathbb{N}</math>, then there exists an element <math>m \in S</math> such that <math>\forall k \in S, m \leq k</math>.</p>
<p>A1 Closure under addition  A2 Addition is commutative  A3 Addition is associative  A4 Additive identity is 0  A5 Unique additive inverse of <math>x</math> is <math>-x</math>  M1 Closure under multiplication  M2 Multiplication is commutative  M3 Multiplication is associative  M4 Multiplicative identity is 1  M5 If <math>x \neq 0</math>, then the unique multiplicative inverse is <math>1/x</math>  DL <math>\forall x, y, z \in \mathbb{R}, x(y+z) = xy + xz</math></p>	<p>A <b>recurrence relation</b> is an equation that defines a sequence recursively: each term of the sequence is defined as a function of the preceding terms.</p> <p>The Fibonacci numbers are defined using the linear recurrence relation:</p> $\begin{aligned} F_n &= F_{n-2} + F_{n-1} \\ F_1 &= 1 \\ F_2 &= 1 \end{aligned}$
<p>If <math>x \in \mathbb{R}</math>, then the <b>absolute value</b> of <math>x</math>, is denoted <math> x </math> and defined to be</p> $ x  = \begin{cases} x & x \geq 0 \\ -x & x < 0 \end{cases}$	<p>O1 <math>\forall x, y \in \mathbb{R}</math> exactly one of the relations <math>x = y, x &lt; y, x &gt; y</math> holds. (trichotomy)</p> <p>O2 <math>\forall x, y, z \in \mathbb{R}, x &lt; y</math> and <math>y &lt; z \Rightarrow x &lt; z</math>. (transitivity)</p> <p>O3 <math>\forall x, y, z \in \mathbb{R}, x &lt; y \Rightarrow x + z &lt; y + z</math></p> <p>O4 <math>\forall x, y, z \in \mathbb{R}, x &lt; y</math> and <math>z &gt; 0 \Rightarrow xz &lt; yz</math>.</p>
<p>If <math>S</math> is a field and satisfies (O1–O4) of the order axioms, then <math>S</math> is an <b>ordered field</b>.</p>	<p>Let <math>x, y \in \mathbb{R}</math> then</p> $ x + y  \leq  x  +  y $ <p>alternatively,</p> $ a - b  \leq  a - c  +  c - b $
<p>Let <math>S</math> be a subset of <math>\mathbb{R}</math>. If there exists an <math>m \in \mathbb{R}</math> such that <math>m \geq s \quad \forall s \in S</math>, then <math>m</math> is called an <b>upper bound</b> of <math>S</math>.</p> <p>Similarly, if <math>m \leq s \quad \forall s \in S</math>, then <math>m</math> is called a <b>lower bound</b> of <math>S</math>.</p>	<p>Suppose <math>x \in \mathbb{R}</math>. If <math>x \neq \frac{m}{n}</math> for some <math>m, n \in \mathbb{Z}</math>, then <math>x</math> is <b>irrational</b>.</p>

<p>DEFINITION</p> <p><i>bounded</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>maximum &amp; minimum</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>supremum</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>infimum</i></p> <p>REAL ANALYSIS I</p>
<p>AXIOM</p> <p><i>Completeness Axiom</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>Archimedean ordered field</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>dense</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>extended real numbers</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>neighborhood &amp; radius</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>deleted neighborhood</i></p> <p>REAL ANALYSIS I</p>

<p>If <math>m</math> is an upper bound of <math>S</math> and also in <math>S</math>, then <math>m</math> is called the <b>maximum</b> of <math>S</math>.</p> <p>Similarly, if <math>m</math> is a lower bound of <math>S</math> and also in <math>S</math>, then <math>m</math> is called the <b>minimum</b> of <math>S</math>.</p>	<p>A set <math>S</math> is said to be <b>bounded</b> if it is bounded above and bounded below.</p>
<p>Let <math>S</math> be a nonempty subset of <math>\mathbb{R}</math>. If <math>S</math> is bounded below, then the <b>greatest lower bound</b> is called the <b>infimum</b>, and is denoted <math>\inf S</math>.</p> <p><math>m = \inf S \Leftrightarrow</math></p> <p>(a) <math>m \leq s, \forall s \in S</math> and</p> <p>(b) if <math>m' &gt; m</math>, then <math>\exists s' \in S \ni s' &lt; m'</math></p>	<p>Let <math>S</math> be a nonempty subset of <math>\mathbb{R}</math>. If <math>S</math> is bounded above, then the <b>least upper bound</b> is called the <b>supremum</b>, and is denoted <math>\sup S</math>.</p> <p><math>m = \sup S \Leftrightarrow</math></p> <p>(a) <math>m \geq s, \forall s \in S</math> and</p> <p>(b) if <math>m' &lt; m</math>, then <math>\exists s' \in S \ni s' &gt; m'</math></p>
<p>An ordered field <math>F</math> has the <b>Archimedean property</b> if</p> $\forall x \in F \quad \exists n \in \mathbb{N} \ni x < n$	<p>Every nonempty subset <math>S</math> of <math>\mathbb{R}</math> that is bounded above has a least upper bound. That is, <math>\sup S</math> exists and is a real number.</p>
<p>For convenience, we extend the set of real numbers with two symbols <math>\infty</math> and <math>-\infty</math>, that is <math>\mathbb{R} \cup \{\infty, -\infty\}</math>.</p> <p>Then for example if a set <math>S</math> is not bounded above, then we can write</p> $\sup S = \infty$	<p>A set <math>S</math> is <b>dense</b> in a set <math>T</math> if</p> $\forall t_1, t_2 \in T \quad \exists s \in S \ni t_1 < s < t_2$
<p>Let <math>x \in \mathbb{R}</math> and <math>\varepsilon &gt; 0</math>, then a <b>deleted neighborhood</b> of <math>x</math> is</p> $N^*(x; \varepsilon) = \{y \in \mathbb{R} : 0 <  y - x  < \varepsilon\}$	<p>Let <math>x \in \mathbb{R}</math> and <math>\varepsilon &gt; 0</math>, then a <b>neighborhood</b> of <math>x</math> is</p> $N(x; \varepsilon) = \{y \in \mathbb{R} :  y - x  < \varepsilon\}$ <p>The number <math>\varepsilon</math> is referred to as the <b>radius</b> of <math>N(x; \varepsilon)</math>.</p>

<p>DEFINITION</p> <p><i>interior point</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>boundary point</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>closed and open sets</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>accumulation point</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>isolated point</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>closure of a set</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>open cover</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>subcover</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>compact set</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>sequence</i></p> <p>REAL ANALYSIS I</p>

<p>A point <math>x \in \mathbb{R}</math> is a <b>boundary point</b> of <math>S</math> if</p> <p><math>\forall \varepsilon &gt; 0, N(x; \varepsilon) \cap S \neq \emptyset</math> and <math>N(x; \varepsilon) \cap (\mathbb{R} \setminus S) \neq \emptyset</math></p> <p>In other words, every neighborhood of a boundary point must intersect the set <math>S</math> and the complement of <math>S</math> in <math>\mathbb{R}</math>.</p> <p>The set of all boundary points of <math>S</math> is denoted <math>\text{bd } S</math>.</p>	<p>Let <math>S \subseteq \mathbb{R}</math>. A point <math>x \in \mathbb{R}</math> is an <b>interior point</b> of <math>S</math> if there exists a neighborhood <math>N(x; \varepsilon)</math> such that <math>N \subseteq S</math>.</p> <p>The set of all interior points of <math>S</math> is denoted <math>\text{int } S</math>.</p>
<p>Suppose <math>S \subseteq \mathbb{R}</math>, then a point <math>x \in \mathbb{R}</math> is called an <b>accumulation point</b> of <math>S</math> if</p> $\forall \varepsilon > 0, N^*(x; \varepsilon) \cap S \neq \emptyset$ <p>In other words, every deleted neighborhood of <math>x</math> contains a point in <math>S</math>.</p> <p>The set of all accumulation points of <math>S</math> is denoted <math>S'</math>.</p>	<p>Let <math>S \subseteq \mathbb{R}</math>. If <math>\text{bd } S \subseteq S</math>, then <math>S</math> is said to be <b>closed</b>.</p> <p>If <math>\text{bd } S \subseteq \mathbb{R} \setminus S</math>, then <math>S</math> is said to be <b>open</b>.</p>
<p>Let <math>S \subseteq \mathbb{R}</math>. The <b>closure</b> of <math>S</math> is defined by</p> $\text{cl } S = S \cup S'$ <p>In other words, the closure of a set is the set itself unioned with its set of accumulation points.</p>	<p>Let <math>S \subseteq \mathbb{R}</math>. If <math>x \in S</math> and <math>x \notin S'</math>, then <math>x</math> is called an <b>isolated point</b> of <math>S</math>.</p>
<p>Suppose <math>\mathcal{G} \subseteq \mathcal{F}</math> are both families of indexed sets that cover a set <math>S</math>, then since <math>\mathcal{G}</math> is a subset of <math>\mathcal{F}</math> it is called a <b>subcover</b> of <math>S</math>.</p>	<p>An <b>open cover</b> of a set <math>S</math> is a family or collection of sets whose union contains <math>S</math>.</p> $S \subseteq \mathcal{F} = \{F_n : n \in \mathbb{N}\}$
<p>A <b>sequence</b> <math>s</math> is a function whose domain is <math>\mathbb{N}</math>. However, instead of denoting the value of <math>s</math> at <math>n</math> by <math>s(n)</math>, we denote it <math>s_n</math>. The ordered set of all values of <math>s</math> is denoted <math>(s_n)</math>.</p>	<p>A set <math>S</math> is <b>compact</b> iff <i>every</i> open cover of <math>S</math> contains a finite subcover of <math>S</math>.</p> <p>Note: This is a difficult definition to use because to show that a set is compact you must show that <i>every</i> open cover contains a finite subcover.</p>



<p>DEFINITION</p> <p><i>converge &amp; diverge</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>bounded sequence</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>diverge to <math>+\infty</math></i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>diverge to <math>-\infty</math></i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>nondecreasing, nonincreasing &amp; monotone</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>increasing &amp; decreasing</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>Cauchy sequence</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>subsequence</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>subsequential limit</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>lim sup &amp; lim inf</i></p> <p>REAL ANALYSIS I</p>

<p>A sequence is said to be <b>bounded</b> if its range <math>\{s_n : n \in \mathbb{N}\}</math> is bounded. Equivalently if,</p> $\exists M \geq 0 \text{ such that } \forall n \in \mathbb{N},  s_n  \leq M$	<p>A sequence <math>(s_n)</math> is said to <b>converge</b> to <math>s \in \mathbb{R}</math>, denoted <math>(s_n) \rightarrow s</math> if</p> $\forall \varepsilon > 0, \exists N \text{ such that } \forall n \in \mathbb{N},$ $n > N \Rightarrow  s_n - s  < \varepsilon$ <p>If a sequence does not converge, it is said to <b>diverge</b>.</p>
<p>A sequence <math>(s_n)</math> is said to diverge to <math>-\infty</math> if</p> $\forall M \in \mathbb{R}, \exists N \text{ such that}$ $n > N \Rightarrow s_n < M$	<p>A sequence <math>(s_n)</math> is said to diverge to <math>+\infty</math> if</p> $\forall M \in \mathbb{R}, \exists N \text{ such that}$ $n > N \Rightarrow s_n > M$
<p>A sequence <math>(s_n)</math> is <b>increasing</b> if</p> $s_n < s_{n+1} \quad \forall n \in \mathbb{N}$ <p>A sequence <math>(s_n)</math> is <b>decreasing</b> if</p> $s_n > s_{n+1} \quad \forall n \in \mathbb{N}$	<p>A sequence <math>(s_n)</math> is <b>nondecreasing</b> if</p> $s_n \leq s_{n+1} \quad \forall n \in \mathbb{N}$ <p>A sequence <math>(s_n)</math> is <b>nonincreasing</b> if</p> $s_n \geq s_{n+1} \quad \forall n \in \mathbb{N}$ <p>A sequence is <b>monotone</b> if it is either nondecreasing or nonincreasing.</p>
<p>If <math>(s_n)</math> is any sequence and <math>(n_k)</math> is any strictly increasing sequence, then the sequence <math>(s_{n_k})</math> is called a <b>subsequence</b> of <math>(s_n)</math>.</p>	<p>A sequence <math>(s_n)</math> is said to be a <b>Cauchy sequence</b> if</p> $\forall \varepsilon > 0, \exists N \text{ such that}$ $m, n > N \Rightarrow  s_n - s_m  < \varepsilon$
<p>Suppose <math>S</math> is the set of all subsequential limits of a sequence <math>(s_n)</math>. The <b>lim sup</b> <math>(s_n)</math>, shorthand for the limit superior of <math>(s_n)</math> is defined to be</p> $\lim \sup (s_n) = \sup S$ <p>The <b>lim inf</b> <math>(s_n)</math>, shorthand for the limit inferior of <math>(s_n)</math> is defined to be</p> $\lim \inf (s_n) = \inf S$	<p>A <b>subsequential limit</b> of a sequence <math>(s_n)</math> is the limit of some subsequence of <math>(s_n)</math>.</p>

<p>DEFINITION</p> <p><i>oscillating sequence</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>limit of a function</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>sum, product, multiple, &amp; quotient of functions</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>right-hand limit</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>left-hand limit</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>continuous function at a point</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>continuous on <math>S</math> continuous</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>bounded function</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>uniform continuity</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>extension of a function</i></p> <p>REAL ANALYSIS I</p>

<p>Suppose <math>f : D \rightarrow \mathbb{R}</math> where <math>D \subseteq \mathbb{R}</math>, and suppose <math>c</math> is an accumulation point of <math>D</math>. Then the <b>limit of <math>f</math> at <math>c</math> is <math>L</math></b> is denoted by</p> $\lim_{x \rightarrow c} f(x) = L$ <p>and defined by</p> $\forall \varepsilon > 0, \quad \exists \delta > 0 \text{ such that}$ $ x - c  < \delta \Rightarrow  f(x) - L  < \varepsilon$	<p>If <math>\liminf (s_n) &lt; \limsup (s_n)</math>, then we say that the sequence <math>(s_n)</math> <b>oscillates</b>.</p>
<p>Let <math>f : (a, b) \rightarrow \mathbb{R}</math>, then the <b>right-hand limit</b> of <math>f</math> at <math>a</math> is denoted</p> $\lim_{x \rightarrow a^+} f(x) = L$ <p>and defined by</p> $\forall \varepsilon > 0, \quad \exists \delta > 0 \text{ such that}$ $a < x < a + \delta \Rightarrow  f(x) - L  < \varepsilon$	<p>Let <math>f : D \rightarrow \mathbb{R}</math> and <math>g : D \rightarrow \mathbb{R}</math>, then we define:</p> <ol style="list-style-type: none"> <li>1. <b>sum</b> <math>(f + g)(x) = f(x) + g(x)</math></li> <li>2. <b>product</b> <math>(fg)(x) = f(x)g(x)</math></li> <li>3. <b>multiple</b> <math>(kf)(x) = kf(x) \quad k \in \mathbb{R}</math></li> <li>4. <b>quotient</b> <math>\left(\frac{f}{g}\right) = \frac{f(x)}{g(x)}</math> if <math>g(x) \neq 0 \quad \forall x \in D</math></li> </ol>
<p>Let <math>f : D \rightarrow \mathbb{R}</math> where <math>D \subseteq \mathbb{R}</math>, and suppose <math>c \in D</math>, then <math>f</math> is <b>continuous</b> at <math>c</math> if</p> $\forall \varepsilon > 0, \quad \exists \delta > 0 \text{ such that}$ $ x - c  < \delta \Rightarrow  f(x) - f(c)  < \varepsilon$	<p>Let <math>f : (a, b) \rightarrow \mathbb{R}</math>, then the <b>left-hand limit</b> of <math>f</math> at <math>b</math> is denoted</p> $\lim_{x \rightarrow b^-} f(x) = L$ <p>and defined by</p> $\forall \varepsilon > 0, \quad \exists \delta > 0 \text{ such that}$ $b - \delta < x < b \Rightarrow  f(x) - L  < \varepsilon$
<p>A function is said to be <b>bounded</b> if its range is bounded. Equivalently, <math>f : D \rightarrow \mathbb{R}</math> is bounded if</p> $\exists M \in \mathbb{R} \text{ such that } \forall x \in D,  f(x)  \leq M$	<p>Let <math>f : D \rightarrow \mathbb{R}</math> where <math>D \subseteq \mathbb{R}</math>. If <math>f</math> is continuous at each point of a subset <math>S \subseteq D</math>, then <math>f</math> is said to be <b>continuous on <math>S</math></b>.</p> <p>If <math>f</math> is continuous on its entire domain <math>D</math>, then <math>f</math> is simply said to be <b>continuous</b>.</p>
<p>Suppose <math>f : (a, b) \rightarrow \mathbb{R}</math>, then the <b>extension of <math>f</math></b> is denoted <math>\tilde{f} : [a, b] \rightarrow \mathbb{R}</math> and defined by</p> $\tilde{f}(x) = \begin{cases} u & x = a \\ f(x) & a < x < b \\ v & x = b \end{cases}$ <p>where <math>\lim_{x \rightarrow a} f(x) = u</math> and <math>\lim_{x \rightarrow b} f(x) = v</math>.</p>	<p>A function <math>f : D \rightarrow \mathbb{R}</math> is <b>uniformly continuous on <math>D</math></b> if</p> $\forall \varepsilon > 0, \quad \exists \delta > 0 \text{ such that}$ $ x - y  < \delta \Rightarrow  f(x) - f(y)  < \varepsilon$

<p>DEFINITION</p> <p><i>differentiable at a point</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>strictly increasing function</i> <i>strictly decreasing function</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>limit at <math>\infty</math></i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>tends to <math>\infty</math></i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>Taylor polynomials for <math>f</math> at <math>x_0</math></i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>Taylor series</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>partition of an interval</i> <i>refinement of a partition</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>upper sum</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>lower sum</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>upper integral</i> <i>lower integral</i></p> <p>REAL ANALYSIS I</p>

<p>A function <math>f : D \rightarrow \mathbb{R}</math> is said to be <b>strictly increasing</b> if</p> $\forall x_1, x_2 \in D, \quad x_1 < x_2 \Rightarrow f(x_1) < f(x_2)$ <p>A function <math>f : D \rightarrow \mathbb{R}</math> is said to be <b>strictly decreasing</b> if</p> $\forall x_1, x_2 \in D, \quad x_1 < x_2 \Rightarrow f(x_1) > f(x_2)$	<p>Suppose <math>f : I \rightarrow \mathbb{R}</math> where <math>I</math> is an interval containing the point <math>c</math>. Then <math>f</math> is <b>differentiable at <math>c</math></b> if the limit</p> $\lim_{x \rightarrow c} \frac{f(x) - f(c)}{x - c}$ <p>exists and is finite. Whenever this limit exists and is finite, we denote the <b>derivative of <math>f</math> at <math>c</math></b> by</p> $f'(c) = \lim_{x \rightarrow c} \frac{f(x) - f(c)}{x - c}$
<p>Suppose <math>f : (a, \infty) \rightarrow \mathbb{R}</math>, then we say <math>f</math> <b>tends to <math>\infty</math></b> as <math>x \rightarrow \infty</math> and denote it by</p> $\lim_{x \rightarrow \infty} f(x) = \infty$ <p>iff</p> $\forall M \in \mathbb{R}, \quad \exists N > a \text{ such that}$ $x > N \Rightarrow f(x) > M$	<p>Suppose <math>f : (a, \infty) \rightarrow \mathbb{R}</math>, then the <b>limit at infinity</b> of <math>f</math> denoted</p> $\lim_{x \rightarrow \infty} f(x) = L$ <p>iff</p> $\forall \varepsilon > 0, \quad \exists N > a \text{ such that}$ $x > N \Rightarrow  f(x) - L  < \varepsilon$
<p>If <math>f</math> has derivatives of all orders in a neighborhood of <math>x_0</math>, then the limit of the Taylor polynomials is an infinite series called the <b>Taylor series</b> of <math>f</math> at <math>x_0</math>.</p> $f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(x_0)}{n!} (x - x_0)^n$ $= f(x_0) + f'(x_0)(x - x_0) + \frac{f''(x_0)}{2!} (x - x_0)^2 + \dots$	$p_0(x) = f(x_0)$ $p_1(x) = f(x_0) + f'(x_0)(x - x_0)$ $p_2(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{f''(x_0)}{2!} (x - x_0)^2$ $\vdots$ $p_n(x) = f(x_0) + f'(x_0)(x - x_0) + \dots + \frac{f^{(n)}(x_0)}{n!} (x - x_0)^n$
<p>Suppose <math>f</math> is a bounded function on <math>[a, b]</math> and <math>P = \{x_0, \dots, x_n\}</math> is a partition of <math>[a, b]</math>. For each <math>i \in \{1, \dots, n\}</math> let</p> $M_i(f) = \sup\{f(x) : x \in [x_{i-1}, x_i]\}.$ <p>We define the <b>upper sum</b> of <math>f</math> with respect to <math>P</math> to be</p> $U(f, P) = \sum_{i=1}^n M_i \Delta x_i$ <p>where <math>\Delta x_i = x_i - x_{i-1}</math>.</p>	<p>A <b>partition</b> of an interval <math>[a, b]</math> is a finite set of points <math>P = \{x_0, x_1, x_2, \dots, x_n\}</math> such that</p> $a = x_0 < x_1 < \dots < x_n = b$ <p>If <math>P</math> and <math>P'</math> are two partitions of <math>[a, b]</math> where <math>P \subset P'</math> then <math>P'</math> is called a <b>refinement</b> of <math>P</math>.</p>
<p>Suppose <math>f</math> is a bounded function on <math>[a, b]</math>. We define the <b>upper integral</b> of <math>f</math> on <math>[a, b]</math> to be</p> $U(f) = \inf\{U(f, P) : P \text{ any partition of } [a, b]\}.$ <p>Similarly, we define the <b>lower integral</b> of <math>f</math> on <math>[a, b]</math> to be</p> $L(f) = \sup\{L(f, P) : P \text{ any partition of } [a, b]\}.$	<p>Suppose <math>f</math> is a bounded function on <math>[a, b]</math> and <math>P = \{x_0, \dots, x_n\}</math> is a partition of <math>[a, b]</math>. For each <math>i \in \{1, \dots, n\}</math> let</p> $m_i(f) = \inf\{f(x) : x \in [x_{i-1}, x_i]\}.$ <p>We define the <b>lower sum</b> of <math>f</math> with respect to <math>P</math> to be</p> $L(f, P) = \sum_{i=1}^n m_i \Delta x_i$ <p>where <math>\Delta x_i = x_i - x_{i-1}</math>.</p>

<p>DEFINITION</p> <p><i>Riemann integrable</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>monotone function</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>proper integral</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>improper integral</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>integral convergence</i> <i>integral divergence</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>infinite series</i> <i>partial sum</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>convergent series</i> <i>sum</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>divergent series</i> <i>diverge to <math>+\infty</math></i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>harmonic series</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>geometric series</i></p> <p>REAL ANALYSIS I</p>

<p>A function is said to be <b>monotone</b> if it is either increasing or decreasing.</p> <p>A function is increasing if <math>x &lt; y \Rightarrow f(x) \leq f(y)</math>.  A function is decreasing if <math>x &lt; y \Rightarrow f(x) \geq f(y)</math>.</p>	<p>Let <math>f : [a, b] \rightarrow \mathbb{R}</math> be a bounded function. If <math>L(f) = U(f)</math>, then we say <math>f</math> is <b>Riemann integrable</b> or just <b>integrable</b>. Furthermore,</p> $\int_a^b f = \int_a^b f(x)dx = L(f) = U(f)$ <p>is called the <b>Riemann integral</b> or just the <b>integral</b> of <math>f</math> on <math>[a, b]</math>.</p>
<p>An <b>improper integral</b> is the limit of a definite integral, as an endpoint of the interval of integration approaches either a specified real number or <math>\infty</math> or <math>-\infty</math> or, in some cases, as both endpoints approach limits.</p> <p>Let <math>f : (a, b] \rightarrow \mathbb{R}</math> be integrable on <math>[c, b] \forall c \in (a, b]</math>. If <math>\lim_{c \rightarrow a^+} \int_c^b f</math> exists then</p> $\int_a^b f = \lim_{c \rightarrow a^+} \int_c^b f$	<p>When a function <math>f</math> is bounded and the interval over which it is integrated is bounded, then if the integral exists it is called a <b>proper integral</b>.</p>
<p>Let <math>(a_k)</math> be a sequence of real numbers, then we can create a new sequence of numbers <math>(s_n)</math> where each <math>s_n</math> in <math>(s_n)</math> corresponds to the sum of the first <math>n</math> terms of <math>(a_k)</math>. This new sequence of sums is called an <b>infinite series</b> and is denoted by <math>\sum_{n=0}^{\infty} a_n</math>.</p> <p>The <math>n</math>-th <b>partial sum</b> of the series, denoted by <math>s_n</math> is defined to be</p> $s_n = \sum_{k=0}^n a_k$	<p>Suppose <math>f : (a, b] \rightarrow \mathbb{R}</math> is integrable on <math>[c, b] \forall c \in (a, b]</math>, furthermore let <math>L = \lim_{c \rightarrow a^+} \int_c^b f</math>. If <math>L</math> is finite, then the improper integral <math>\int_a^b f</math> is said to <b>converge</b> to <math>L</math>.</p> <p>If <math>L = \infty</math> or <math>L = -\infty</math>, then the improper integral is said to <b>diverge</b>.</p>
<p>If a series does not converge then it is <b>divergent</b>.</p> <p>If the <math>\lim_{n \rightarrow \infty} s_n = +\infty</math> then the series is said to <b>diverge to <math>+\infty</math></b>.</p>	<p>If <math>(s_n)</math> converges to a real number say <math>s</math>, then we say that the series <math>\sum_{n=0}^{\infty} a_n = s</math> is <b>convergent</b>.</p> <p>Furthermore, we call <math>s</math> the <b>sum</b> of the series.</p>
<p>The <b>geometric series</b> is given by</p> $\sum_{n=0}^{\infty} x^n = 1 + x + x^2 + x^3 + \dots$ <p>The geometric series converges to <math>\frac{1}{1-x}</math> for <math> x  &lt; 1</math>, and diverges otherwise.</p>	<p>The <b>harmonic series</b> is given by</p> $\sum_{n=1}^{\infty} \frac{1}{n} = 1 + \frac{1}{2} + \frac{1}{3} + \frac{1}{4} + \dots$ <p>The harmonic series diverges to <math>+\infty</math>.</p>



<p>DEFINITION</p> <p><i>converge absolutely</i> <i>converge conditionally</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>power series</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>radius of convergence</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>interval of convergence</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p><i>converges pointwise</i></p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p><i>converges uniformly</i></p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p>REAL ANALYSIS I</p>
<p>DEFINITION</p> <p>REAL ANALYSIS I</p>	<p>DEFINITION</p> <p>REAL ANALYSIS I</p>

<p>Given a sequence <math>(a_n)</math> of real numbers, then the series</p> $\sum_{n=0}^{\infty} a_n x^n = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$ <p>is called a <b>power series</b>. The number <math>a_n</math> is called the <b><math>n</math>th coefficient</b> of the series.</p>	<p>If <math>\sum  a_n </math> converges then the series <math>\sum a_n</math> is said to <b>converge absolutely</b>.</p> <p>If <math>\sum a_n</math> converges, but <math>\sum  a_n </math> diverges, then the series <math>\sum a_n</math> is said to <b>converge conditionally</b>.</p>
<p>The <b>interval of convergence</b> of a power series is the set of all <math>x \in \mathbb{R}</math> such that <math>\sum_{n=0}^{\infty} a_n x^n</math> converges.</p> <p>By theorem we see that (for a power series centered at 0) this set will either be <math>\{0\}</math>, <math>\mathbb{R}</math> or a bounded interval centered at 0.</p>	<p>The <b>radius of convergence</b> of a power series <math>\sum a_n x^n</math> is an extended real number <math>R</math> such that (for a power series centered at <math>x_0</math>)</p> $ x - x_0  < R \Rightarrow \sum a_n x^n \text{ converges.}$ <p>Note that <math>R</math> may be 0, <math>+\infty</math> or any number between.</p>
<p>Let <math>(f_n)</math> be a sequence of functions defined on a subset <math>S</math> of <math>\mathbb{R}</math>. Then <math>(f_n)</math> <b>converges uniformly</b> on <math>S</math> to a function <math>f</math> defined on <math>S</math> if</p> $\forall \varepsilon > 0, \quad \exists N \text{ such that } \forall x \in S$ $n > N \Rightarrow  f_n(x) - f(x)  < \varepsilon$	<p>Let <math>(f_n)</math> be a sequence of functions defined on a subset <math>S</math> of <math>\mathbb{R}</math>. Then <math>(f_n)</math> <b>converges pointwise</b> on <math>S</math> if for each <math>x \in S</math> the sequence of numbers <math>(f_n(x))</math> converges. If <math>(f_n)</math> converges pointwise on <math>S</math>, then we define <math>f : S \rightarrow \mathbb{R}</math> by</p> $f(x) = \lim_{n \rightarrow \infty} f_n(x)$ <p>for each <math>x \in S</math>, and we say that <math>(f_n)</math> converges to <math>f</math> pointwise on <math>S</math>.</p>