

Fourteen

Chain Rule:

$$(f \circ g)'(x) = f'(g(x)) \cdot g'(x)$$

Example:

$$\frac{d}{dx} \cos(x^2) = (-\sin(x^2)) \cdot (2x)$$

- ① Matrices
- ② Jacobian matrices
- ③ The purpose of Jacobian matrices
- ④ Chain rule
- ⑤ The chain rule in practice

① Matrices

A $k \times n$ matrix is a matrix
with k rows and n columns.

1×1 :

8

1×2 :

(4, 6)

1×3 :

(3, 7, 8)

2×1 :

$\begin{pmatrix} 3 \\ 5 \end{pmatrix}$

2×2 :

$\begin{pmatrix} 3 & 4 \\ 7 & 2 \end{pmatrix}$

2×3 :

$\begin{pmatrix} 6 & 7 & 1 \\ 3 & 4 & 2 \end{pmatrix}$

3×1 :

$\begin{pmatrix} 2 \\ 4 \\ 7 \end{pmatrix}$

3×2 :

$\begin{pmatrix} 5 & 2 \\ 4 & 7 \\ 3 & 1 \end{pmatrix}$

3×3 :

$\begin{pmatrix} 1 & 3 & 4 \\ 5 & 7 & 2 \\ 3 & 4 & 1 \end{pmatrix}$

Matrices are functions

$$\begin{pmatrix} 2 & 3 \\ 4 & 7 \end{pmatrix} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} 2 & 3 \\ 4 & 7 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2x+3y \\ 4x+7y \end{pmatrix}$$

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$$(4, 3, 5) : \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$(4, 3, 5) \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 4x+3y+5z$$

$$\begin{pmatrix} 2 & 3 & 5 \\ 4 & 7 & 8 \end{pmatrix} : \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} 2 & 3 & 5 \\ 4 & 7 & 8 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2x+3y+5z \\ 4x+7y+8z \end{pmatrix}$$

$$\begin{pmatrix} 1 & 3 \\ 4 & 8 \\ 9 & 2 \end{pmatrix} : \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$\begin{pmatrix} 1 & 3 \\ 4 & 8 \\ 9 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+3y \\ 4x+8y \\ 9x+2y \end{pmatrix}$$

Matrices are functions

$$\underline{2 \times 2} \begin{pmatrix} 2 & 3 \\ 4 & 7 \end{pmatrix} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} 2 & 3 \\ 4 & 7 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2x+3y \\ 4x+7y \end{pmatrix}$$

$$\underline{1 \times 3} (4, 3, 5) : \mathbb{R}^3 \rightarrow \mathbb{R}^1$$

$$(4, 3, 5) \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 4x+3y+5z$$

$$\underline{2 \times 3} \begin{pmatrix} 2 & 3 & 5 \\ 4 & 7 & 8 \end{pmatrix} : \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} 2 & 3 & 5 \\ 4 & 7 & 8 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2x+3y+5z \\ 4x+7y+8z \end{pmatrix}$$

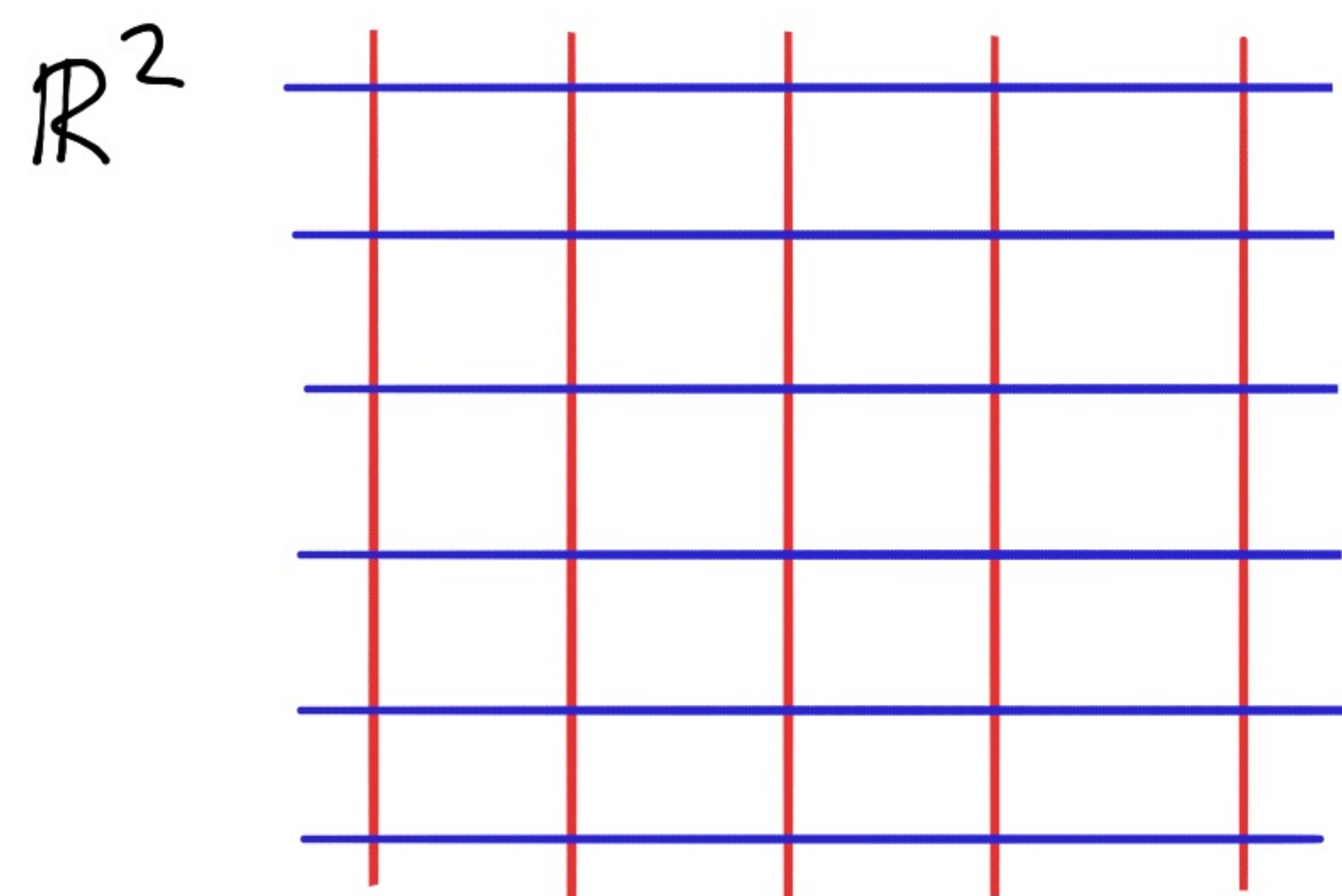
$$\underline{3 \times 2} \begin{pmatrix} 1 & 3 \\ 4 & 8 \\ 9 & 2 \end{pmatrix} : \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

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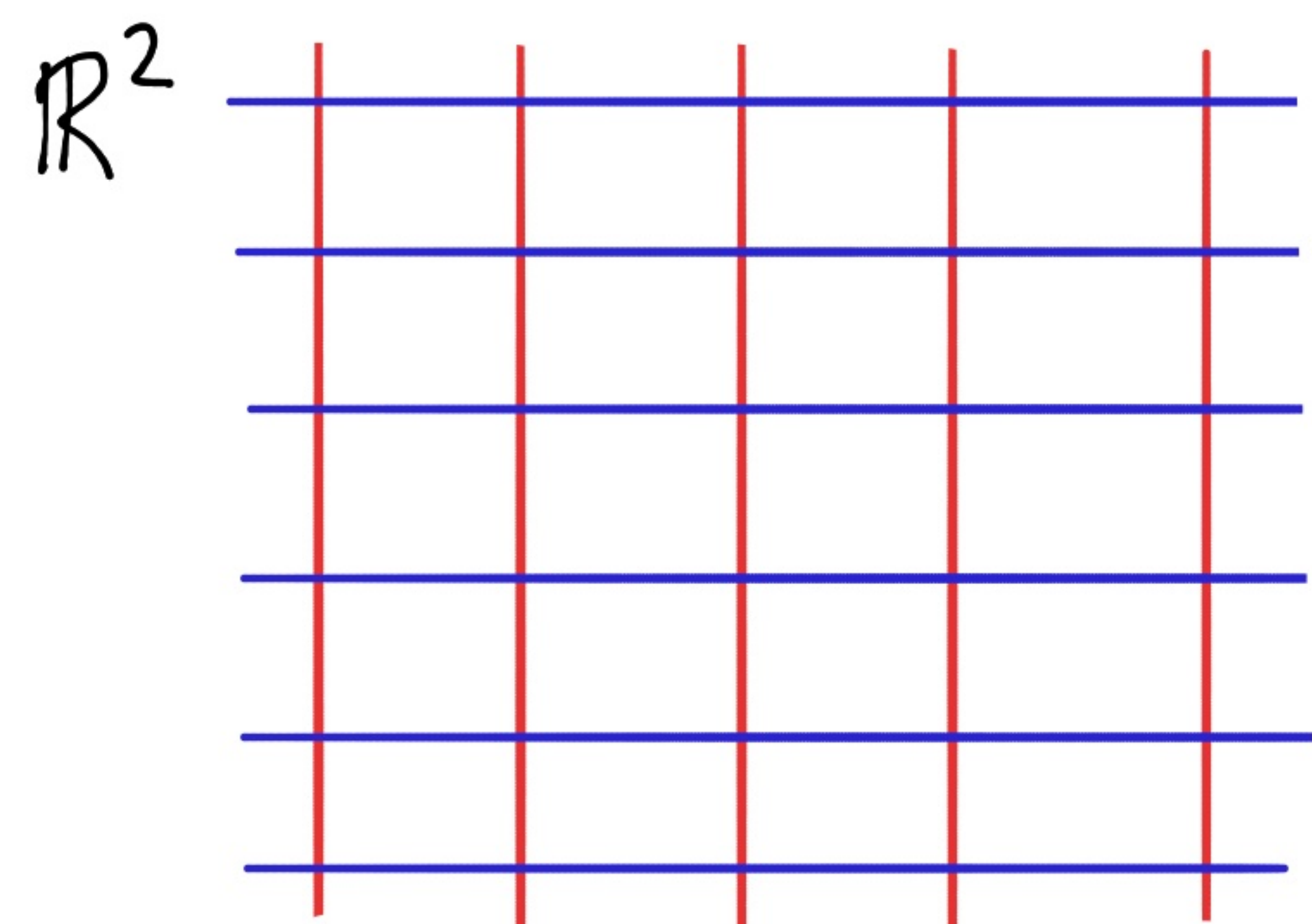
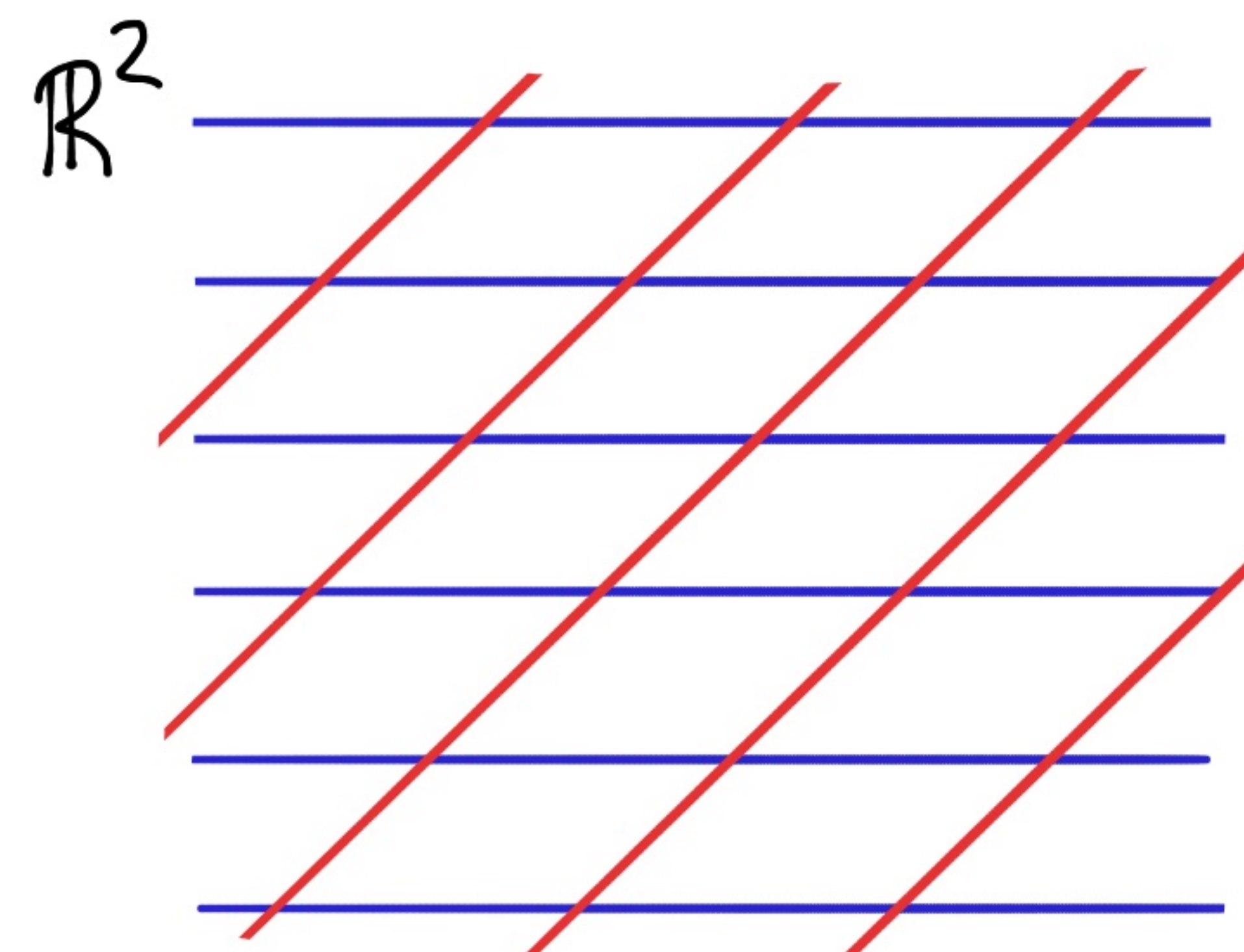
A $k \times n$ matrix is a
function $\mathbb{R}^n \rightarrow \mathbb{R}^k$

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"straight" function $\mathbb{R}^n \rightarrow \mathbb{R}^k$

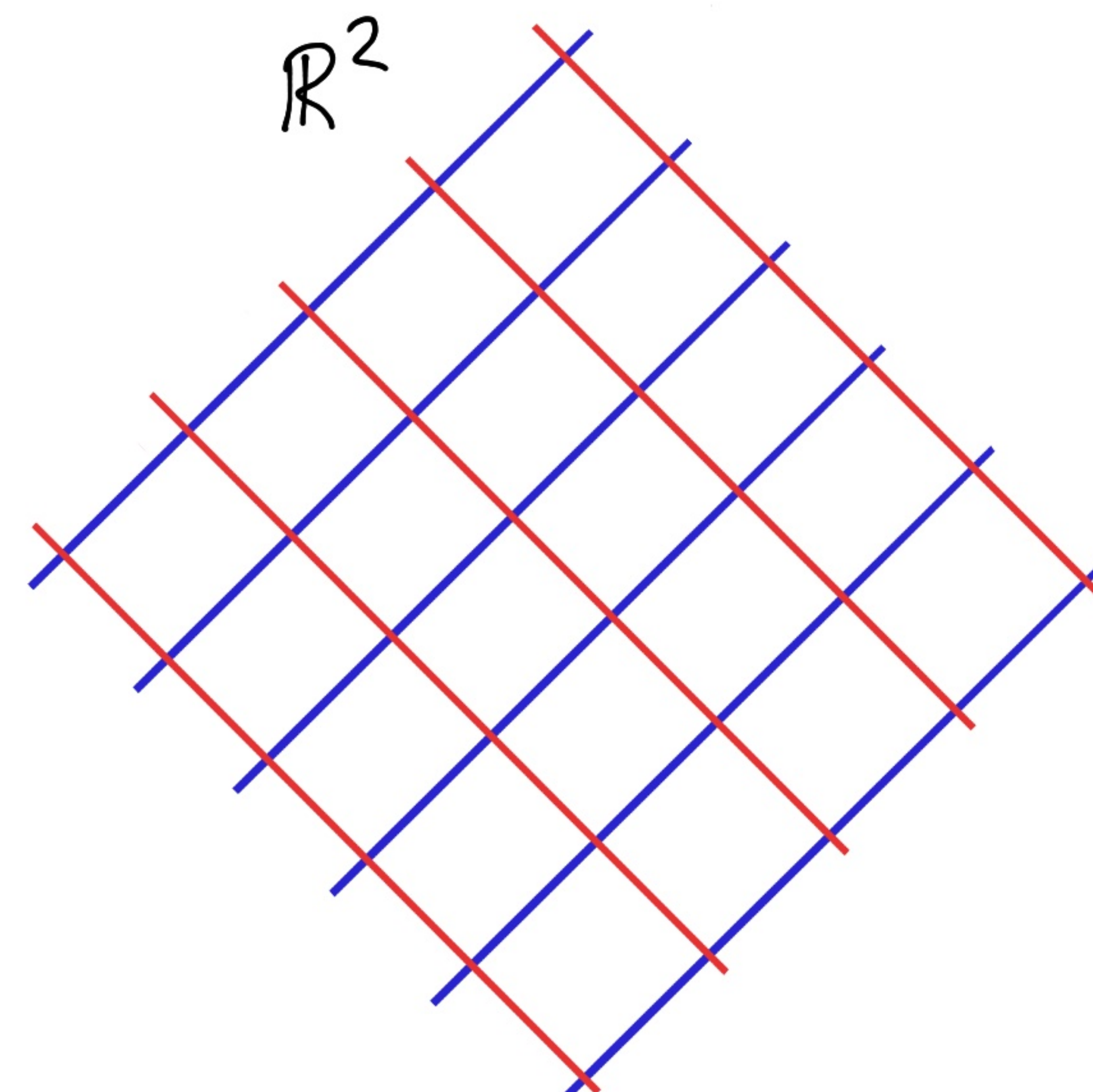
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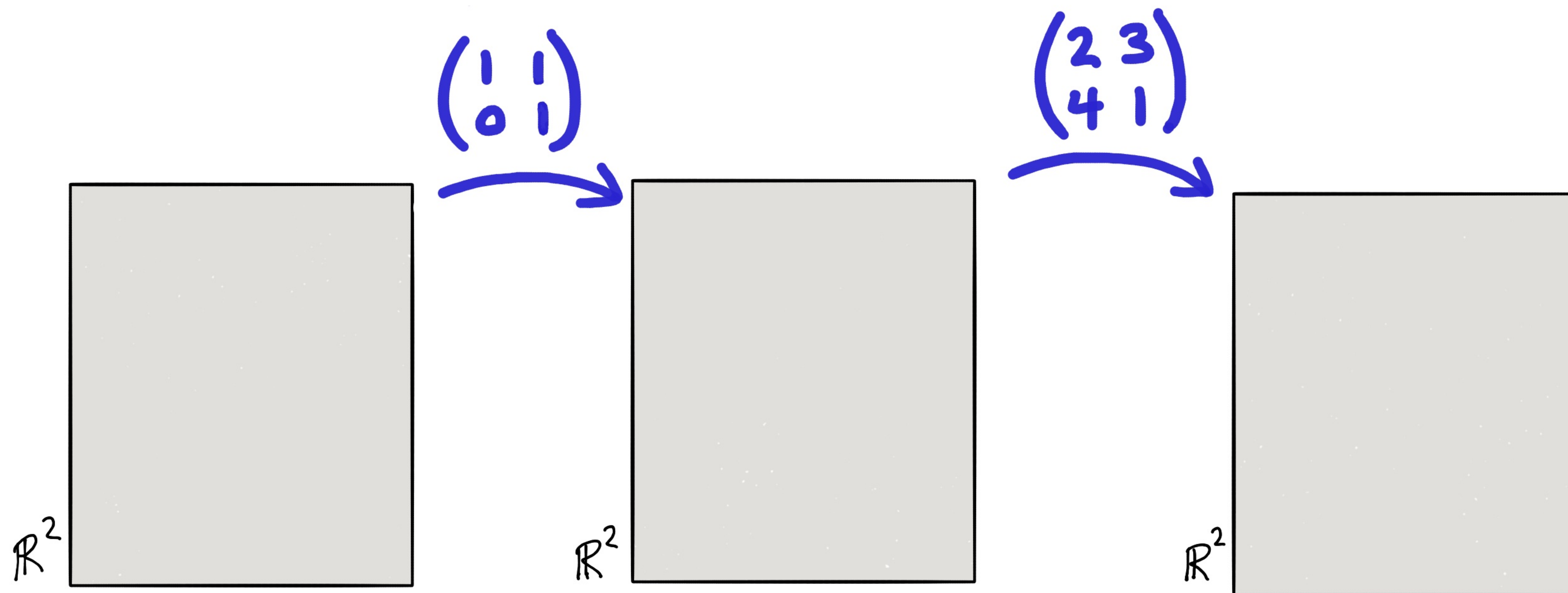
$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

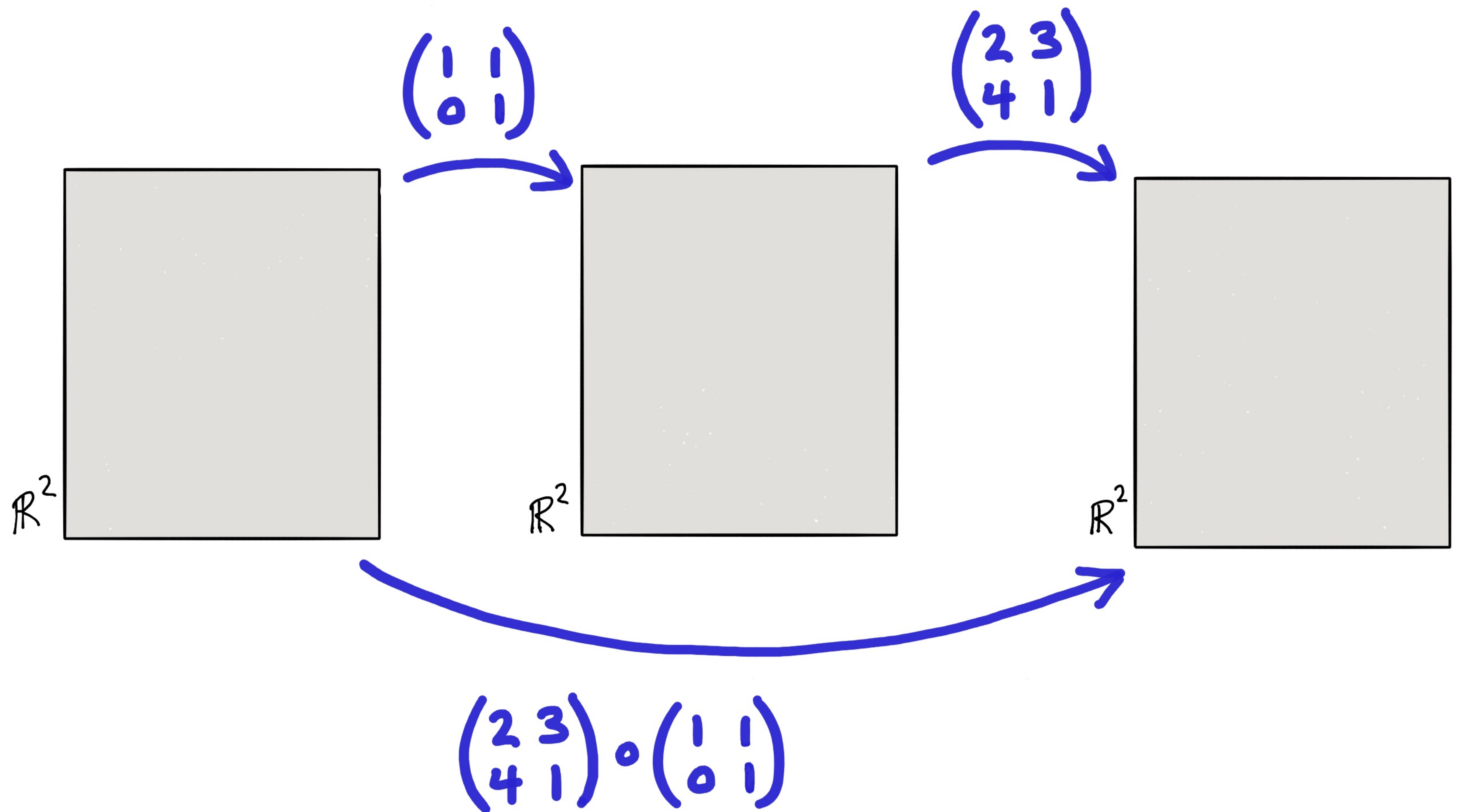
$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

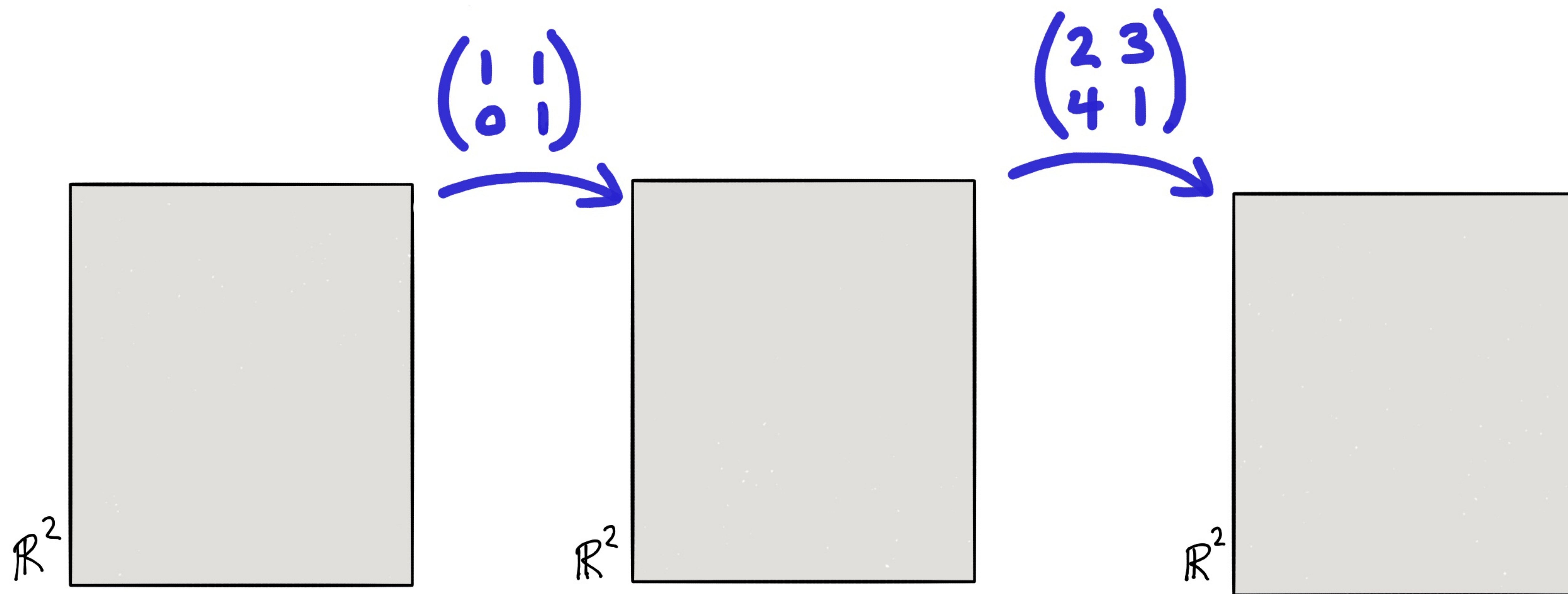
Matrix multiplication
is function composition



Matrix multiplication
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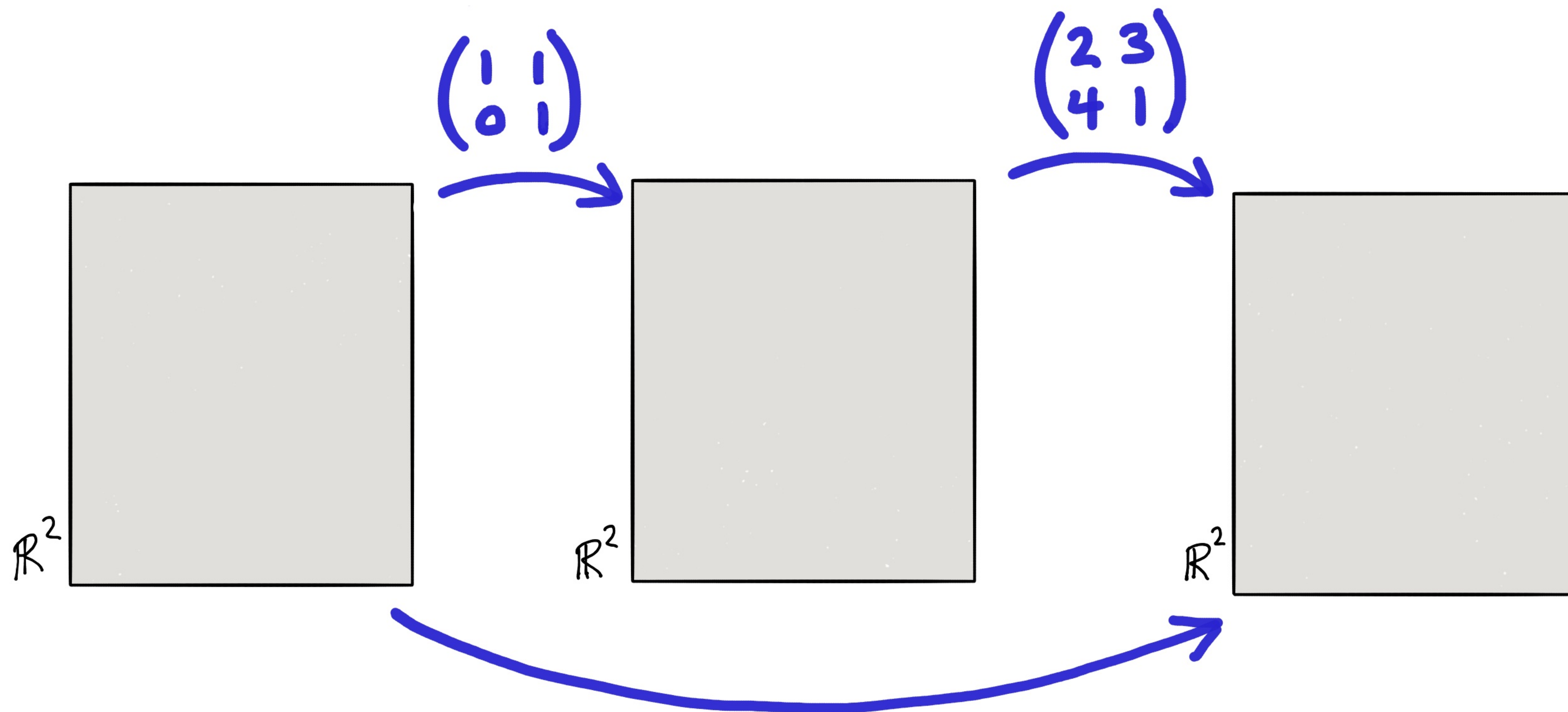


Matrix multiplication
is function composition



$$\begin{pmatrix} 2 & 3 \\ 4 & 1 \end{pmatrix} \circ \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

Matrix multiplication
is function composition



$$\begin{pmatrix} 2 & 3 \\ 4 & 1 \end{pmatrix} \circ \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 5 \\ 4 & 5 \end{pmatrix}$$

② Jacobian matrices

$$f: \mathbb{R}^3 \rightarrow \mathbb{R} \quad f(x, y, z) = w$$

$x \ y \ z$ w

Jacobian matrix:

$$D_p f = \left(\frac{\partial w}{\partial x} \Big|_p, \frac{\partial w}{\partial y} \Big|_p, \frac{\partial w}{\partial z} \Big|_p \right)$$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$x \ y \ z$
 w

$$f(x, y, z) = w$$

Jacobian matrix:

$$D_p f = \overset{\substack{\text{output} \\ \text{variable}}}{\downarrow} \quad w \quad \left(\frac{\partial w}{\partial x} \Big|_p, \frac{\partial w}{\partial y} \Big|_p, \frac{\partial w}{\partial z} \Big|_p \right)$$

x
 y
 z

input variables $\longrightarrow$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$x \ y \ z$
 w

$$f(x, y, z) = w$$

Jacobian matrix:

$$D_p f = \overset{\substack{\text{output} \\ \text{variable}}}{\downarrow} \quad w \quad \left(\underset{x}{\frac{\partial w}{\partial x}} \Big|_p, \quad \underset{y}{\frac{\partial w}{\partial y}} \Big|_p, \quad \underset{z}{\frac{\partial w}{\partial z}} \Big|_p \right)$$

input variables $\longrightarrow$

$$f: \underset{t}{\mathbb{R}} \rightarrow \underset{x \ y \ z}{\mathbb{R}^3} \quad f(\underset{t}{t}) = (\underset{x}{x}, \underset{y}{y}, \underset{z}{z})$$

Jacobian matrix:

output variables $\downarrow$

$$D_p f = \begin{matrix} x \\ y \\ z \end{matrix} \left(\begin{array}{c|c} \frac{\partial x}{\partial t} & | \\ \frac{\partial y}{\partial t} & | \\ \frac{\partial z}{\partial t} & | \end{array} \right)_p \begin{matrix} t \\ \end{matrix}$$

input variable $\longrightarrow$

$$f: \underset{t}{\mathbb{R}} \rightarrow \underset{x \ y \ z}{\mathbb{R}^3} \quad f(\underset{t}{t}) = (\underset{x}{x}, \underset{y}{y}, \underset{z}{z})$$

Jacobian matrix:

output variables $\downarrow$

$$D_p f = \begin{matrix} x \\ y \\ z \end{matrix} \begin{pmatrix} \frac{\partial x}{\partial t} \big|_p \\ \frac{\partial y}{\partial t} \big|_p \\ \frac{\partial z}{\partial t} \big|_p \end{pmatrix}$$

$\underset{t}{t}$
input variable $\longrightarrow$

$$f: \underset{t}{\mathbb{R}} \rightarrow \underset{x \ y \ z}{\mathbb{R}^3} \quad f(\underset{t}{t}) = (\underset{x}{x}, \underset{y}{y}, \underset{z}{z})$$

Jacobian matrix:

output variables $\downarrow$

$$D_p f = \begin{matrix} x \\ y \\ z \end{matrix} \begin{pmatrix} \frac{dx}{dt} \big|_p \\ \frac{dy}{dt} \big|_p \\ \frac{dz}{dt} \big|_p \end{pmatrix}$$

$\underset{t}{t}$
input variable $\longrightarrow$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad f(\underset{\Delta \ t}{}) = (\underset{x \ y}{})$$

Jacobian matrix:

$$D_p f = \begin{matrix} \text{output} \\ \text{variables} \\ \downarrow \end{matrix} \begin{matrix} x \\ y \end{matrix} \begin{pmatrix} \frac{\partial}{\partial} \big|_p & \frac{\partial}{\partial} \big|_p \\ \frac{\partial}{\partial} \big|_p & \frac{\partial}{\partial} \big|_p \end{pmatrix} \begin{matrix} \Delta & t \\ \text{input variables} \longrightarrow \end{matrix}$$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$\Delta \quad t$
 $\quad x \quad y$

$$f(\Delta, t) = (x, y)$$

Jacobian matrix:

output
variables

↓

$$D_p f = \begin{pmatrix} \frac{\partial x}{\partial \Delta} \Big|_p & \frac{\partial x}{\partial t} \Big|_p \\ \frac{\partial y}{\partial \Delta} \Big|_p & \frac{\partial y}{\partial t} \Big|_p \end{pmatrix}$$

Δ
 t

input variables →

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

Δ t x y

$$f(\Delta, t) = (x, y)$$

Jacobian matrix:

output
variables

↓ x

$$D_p f = \begin{pmatrix} \frac{\partial x}{\partial \Delta} \big|_p & \frac{\partial x}{\partial t} \big|_p \\ \frac{\partial y}{\partial \Delta} \big|_p & \frac{\partial y}{\partial t} \big|_p \end{pmatrix}$$

y

Δ t

input variables →

Example: If $f(x, y) = (2xy, xy^3)$, then

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$$= \begin{pmatrix} 2y \Big|_{(1,3)} & 2x \Big|_{(1,3)} \\ y^3 \Big|_{(1,3)} & 3xy^2 \Big|_{(1,3)} \end{pmatrix}$$

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$$= \begin{pmatrix} 2y \Big|_{(1,3)} & 2x \Big|_{(1,3)} \\ y^3 \Big|_{(1,3)} & 3xy^2 \Big|_{(1,3)} \end{pmatrix}$$

$$= \begin{pmatrix} 6 & 2 \\ 27 & 27 \end{pmatrix}$$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}^2 \quad f(\underset{x \ y \ z}{x, y, z}) = (\underset{u \ w}{u, w})$$

Jacobian matrix:

$$D_p f = \begin{matrix} \text{output} \\ \text{variables} \\ \downarrow \\ u \\ w \end{matrix} \begin{pmatrix} \frac{\partial u}{\partial x} \big|_p & \frac{\partial u}{\partial y} \big|_p & \frac{\partial u}{\partial z} \big|_p \\ \frac{\partial w}{\partial x} \big|_p & \frac{\partial w}{\partial y} \big|_p & \frac{\partial w}{\partial z} \big|_p \end{pmatrix} \begin{matrix} x & y & z \\ \text{input variables} \longrightarrow \end{matrix}$$

$$f: \underset{t}{\mathbb{R}} \rightarrow \underset{z}{\mathbb{R}} \quad f(\underset{t}{t}) = \underset{z}{z}$$

Jacobian matrix:

$$D_p f = \overset{\substack{\text{output} \\ \text{variable}}}{\downarrow} z \quad \frac{\partial z}{\partial \underset{t}{t}} \bigg|_p$$

input variable $\longrightarrow$

$$f: \underset{t}{\mathbb{R}} \rightarrow \underset{z}{\mathbb{R}} \quad f(\underset{t}{t}) = \underset{z}{z}$$

Jacobian matrix:

$$D_p f = \overset{\substack{\text{output} \\ \text{variable}}}{\downarrow} \underset{z}{z} \quad \underset{\underset{t}{\text{input variable}}}{\frac{\partial z}{\partial t}} \bigg|_p = \frac{dz}{dt} \bigg|_p = f'(p)$$

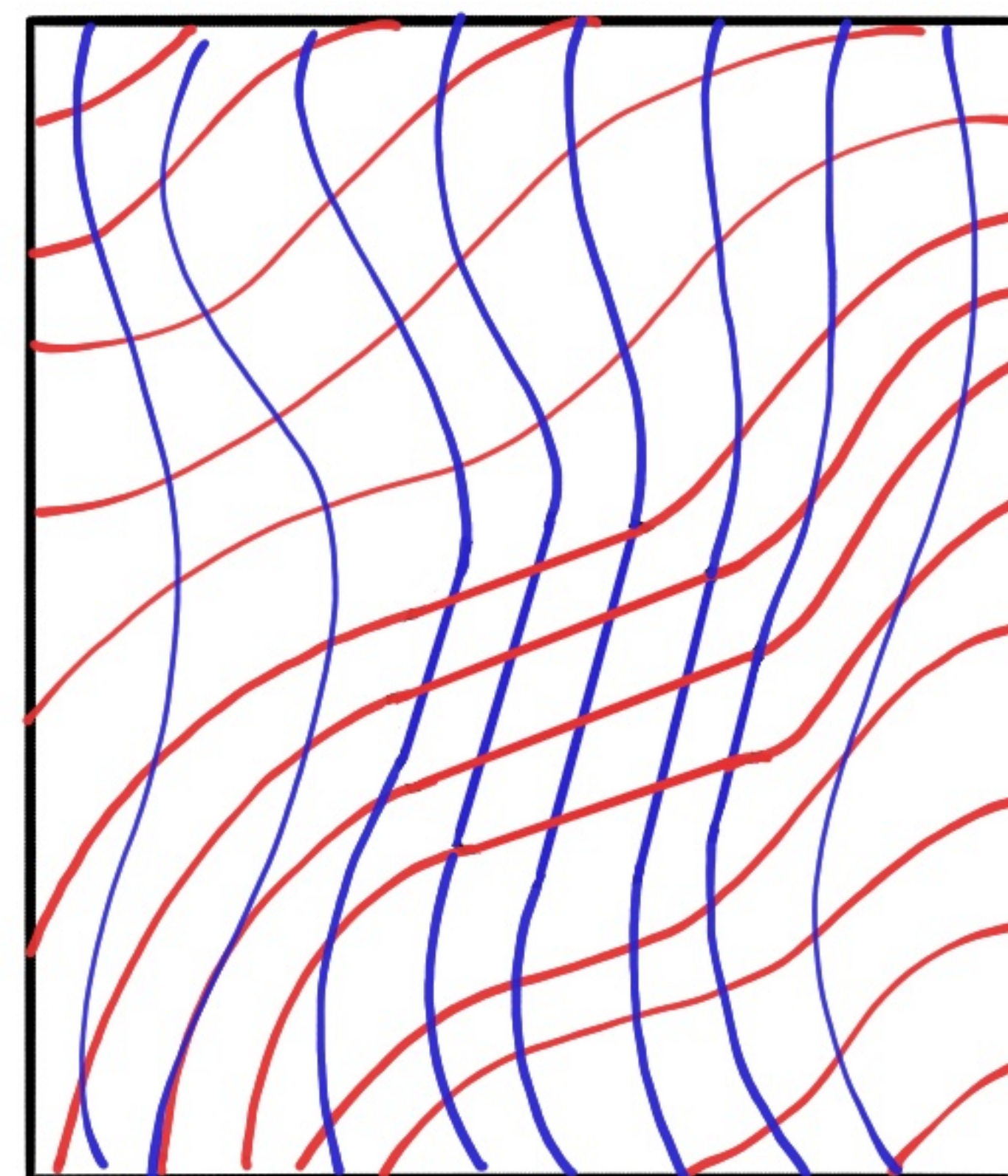
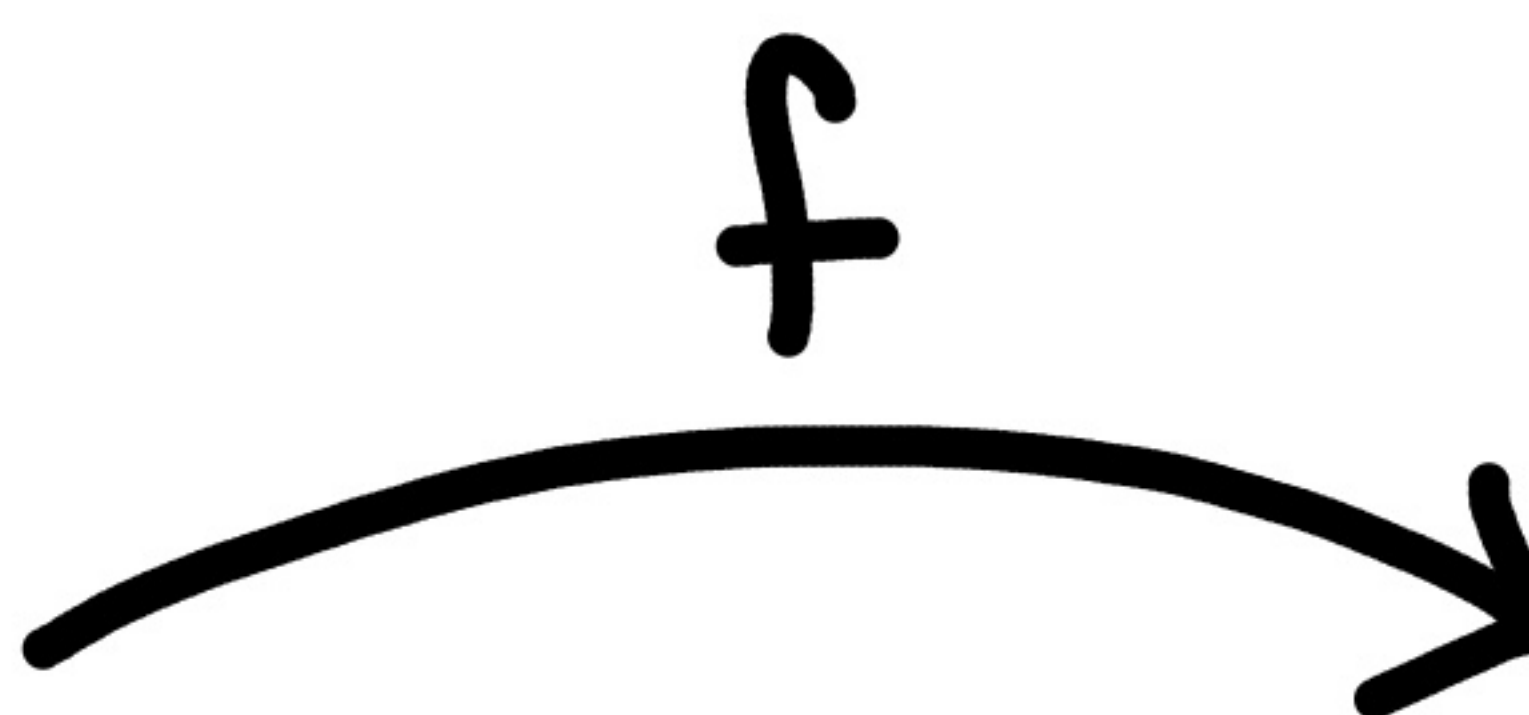
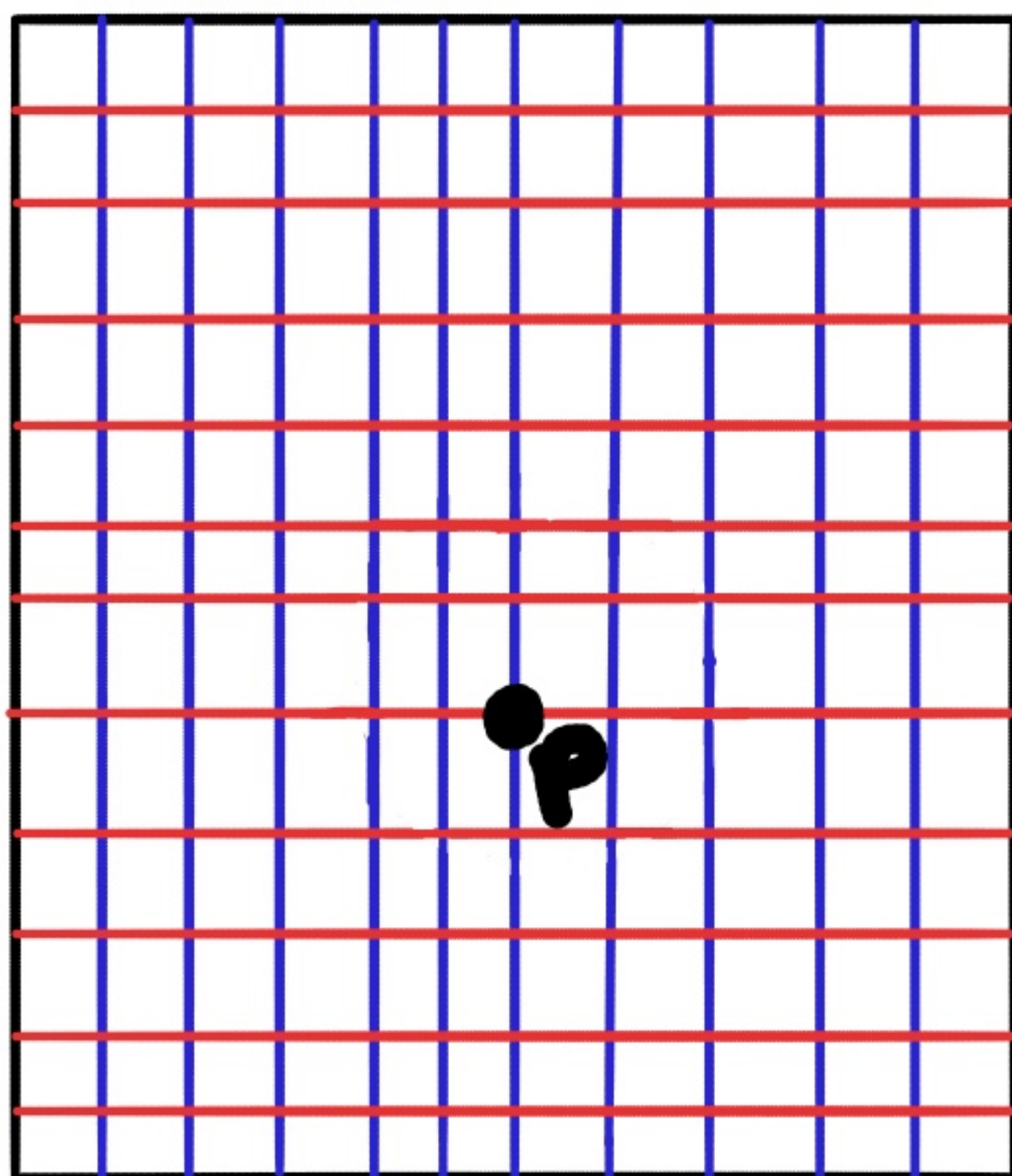
If $f: \mathbb{R}^n \rightarrow \mathbb{R}^k$,

and $p \in \mathbb{R}^n$,

then $D_p f: \mathbb{R}^n \rightarrow \mathbb{R}^k$

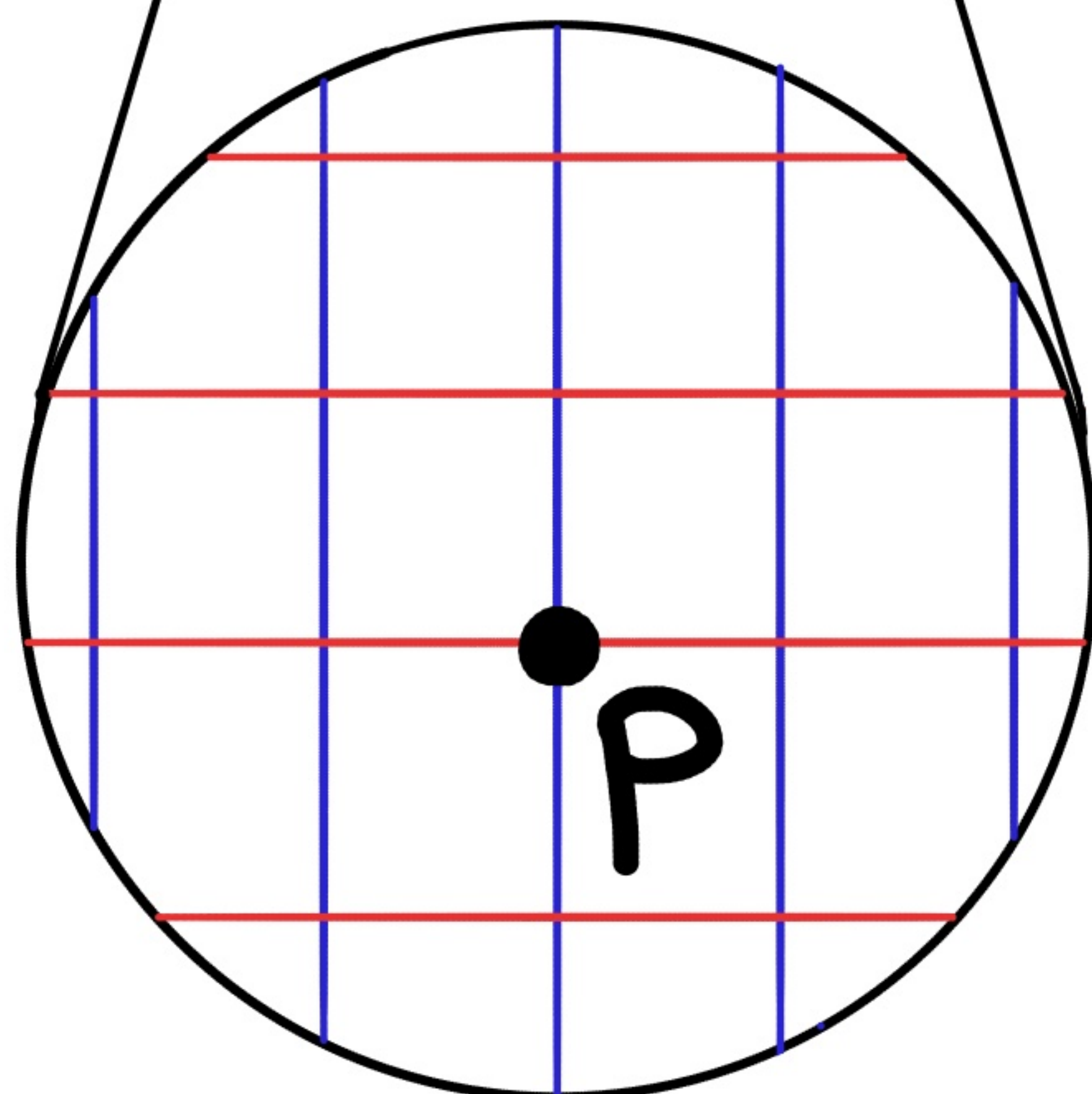
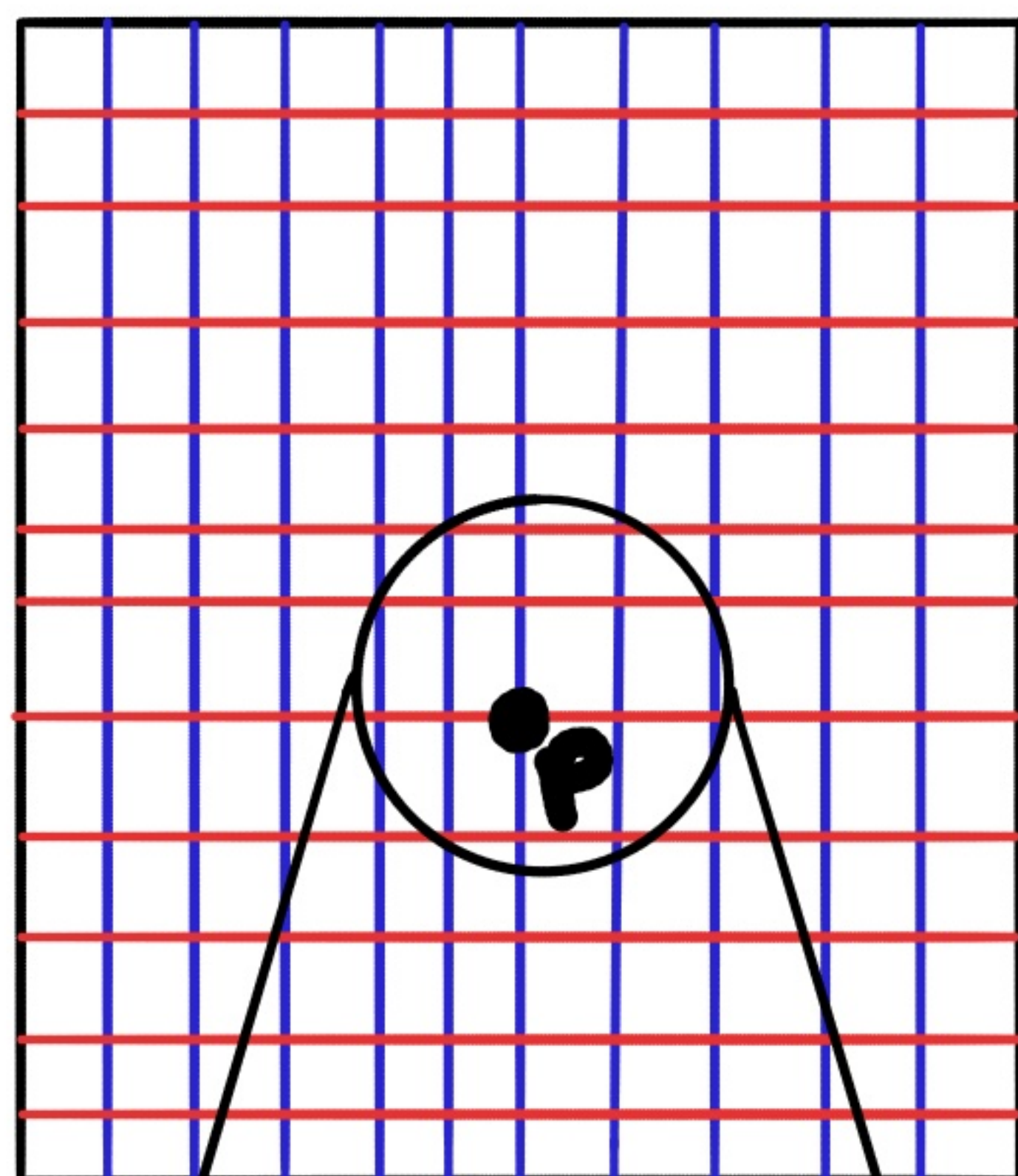
③ The purpose
of Jacobian matrices

$\mathbb{R}^n$



$\mathbb{R}^k$

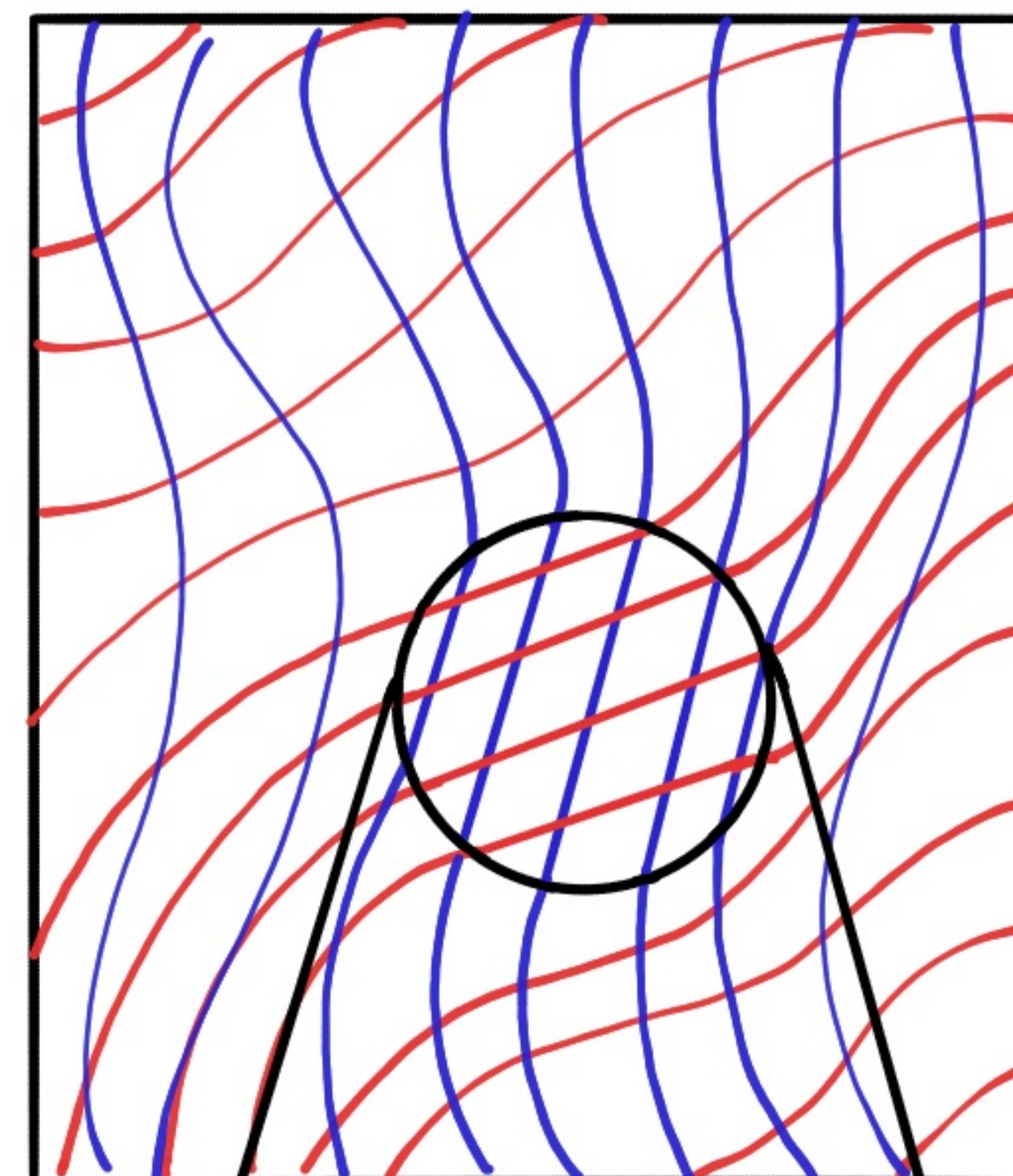
$\mathbb{R}^n$



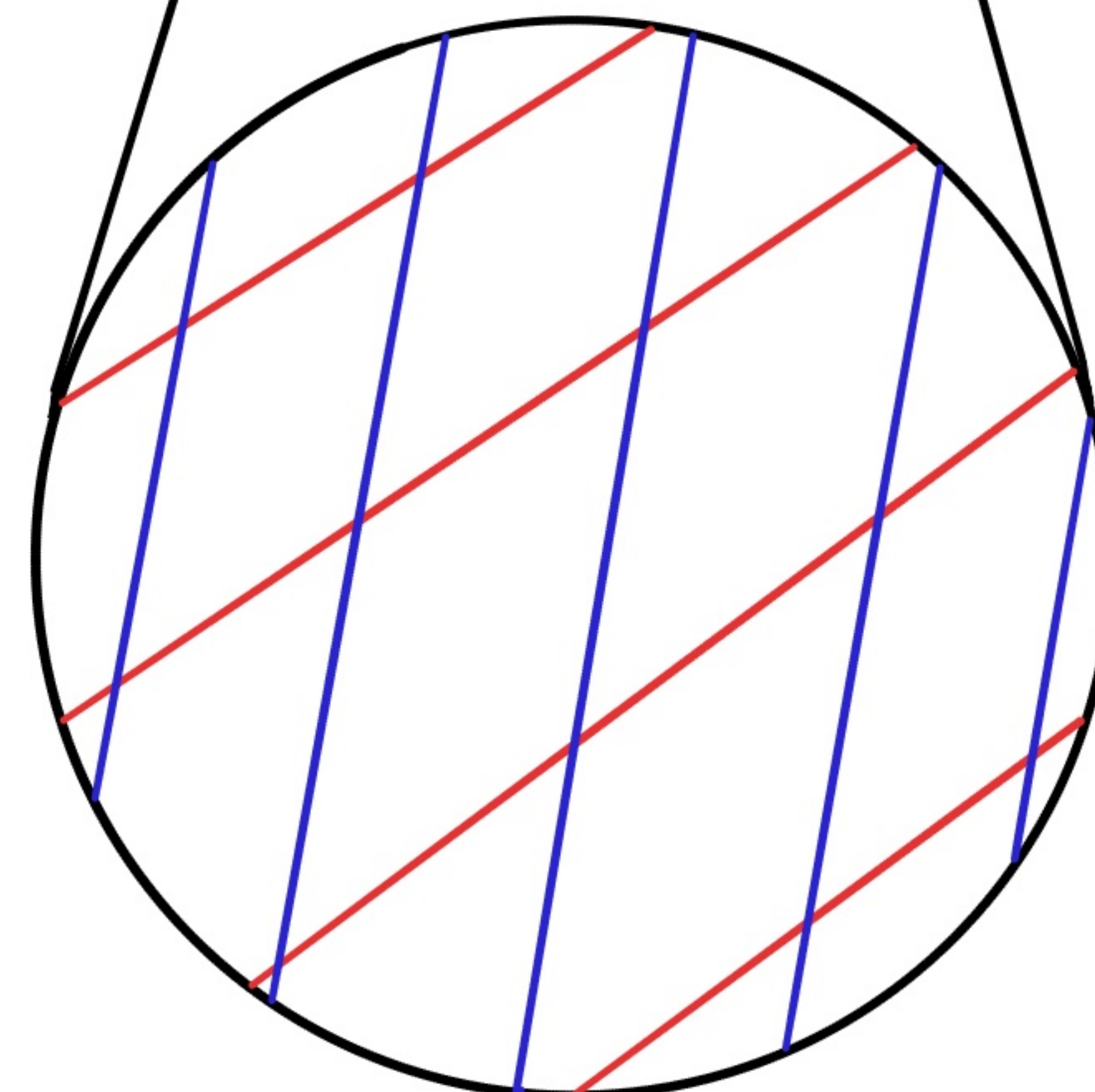
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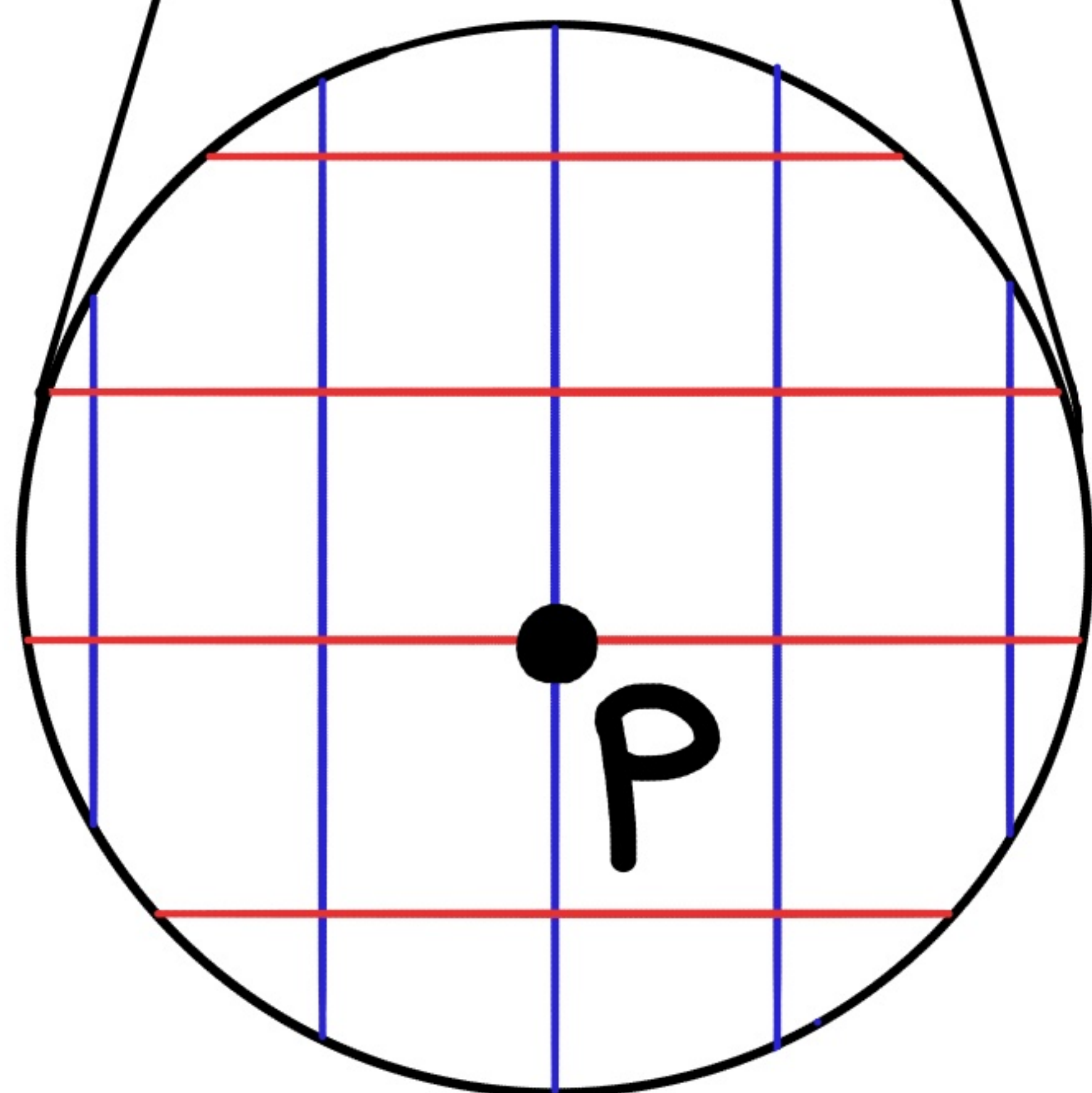
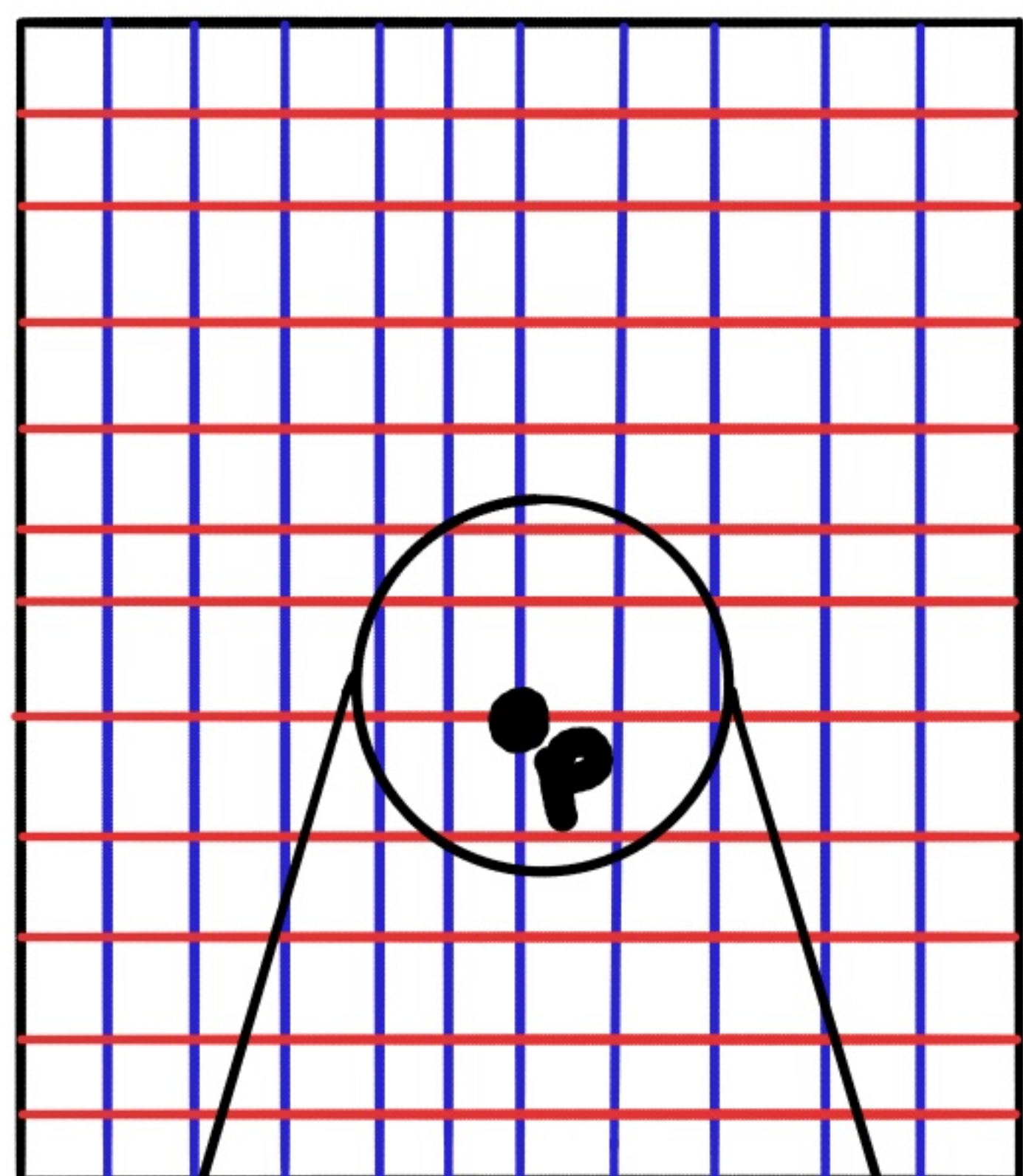
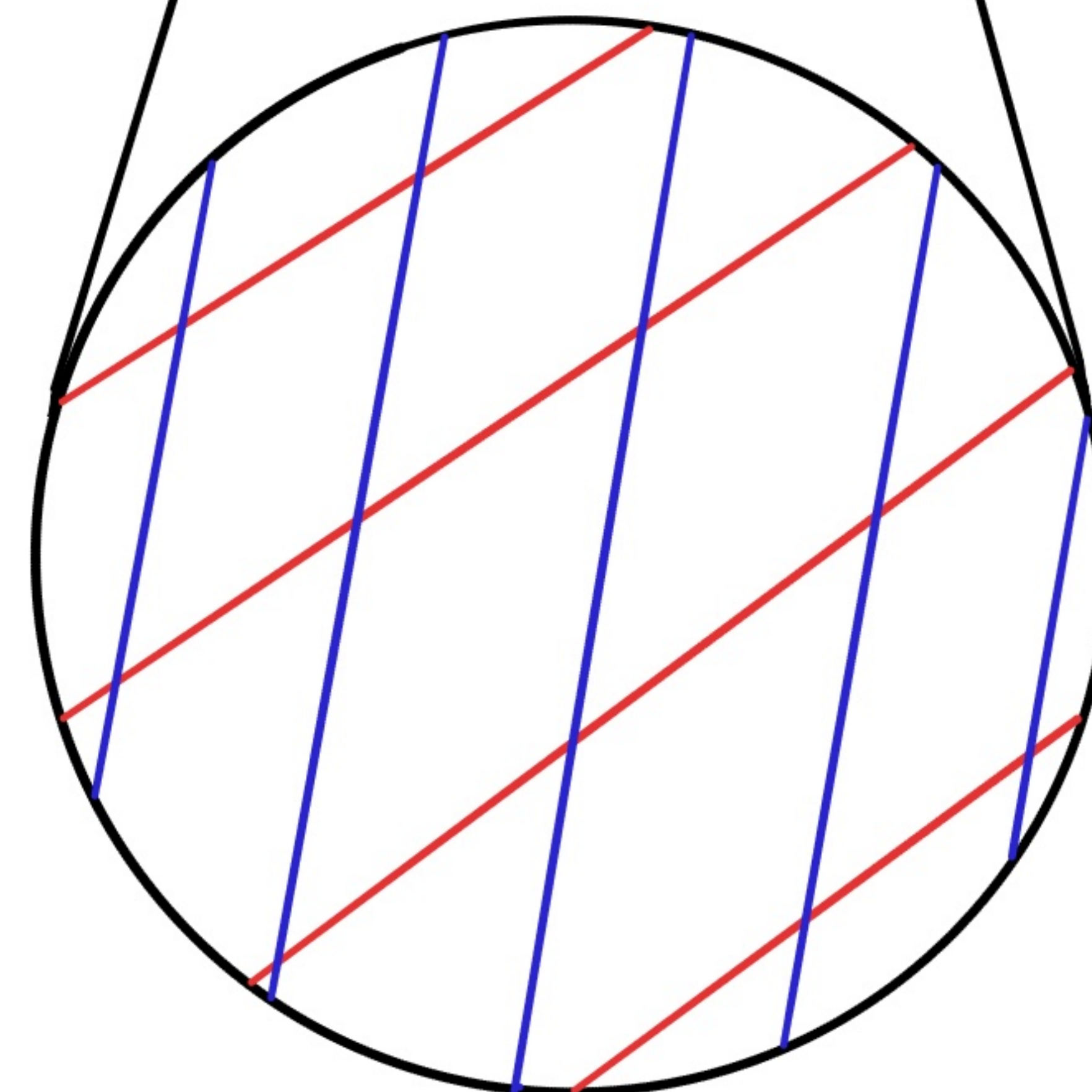
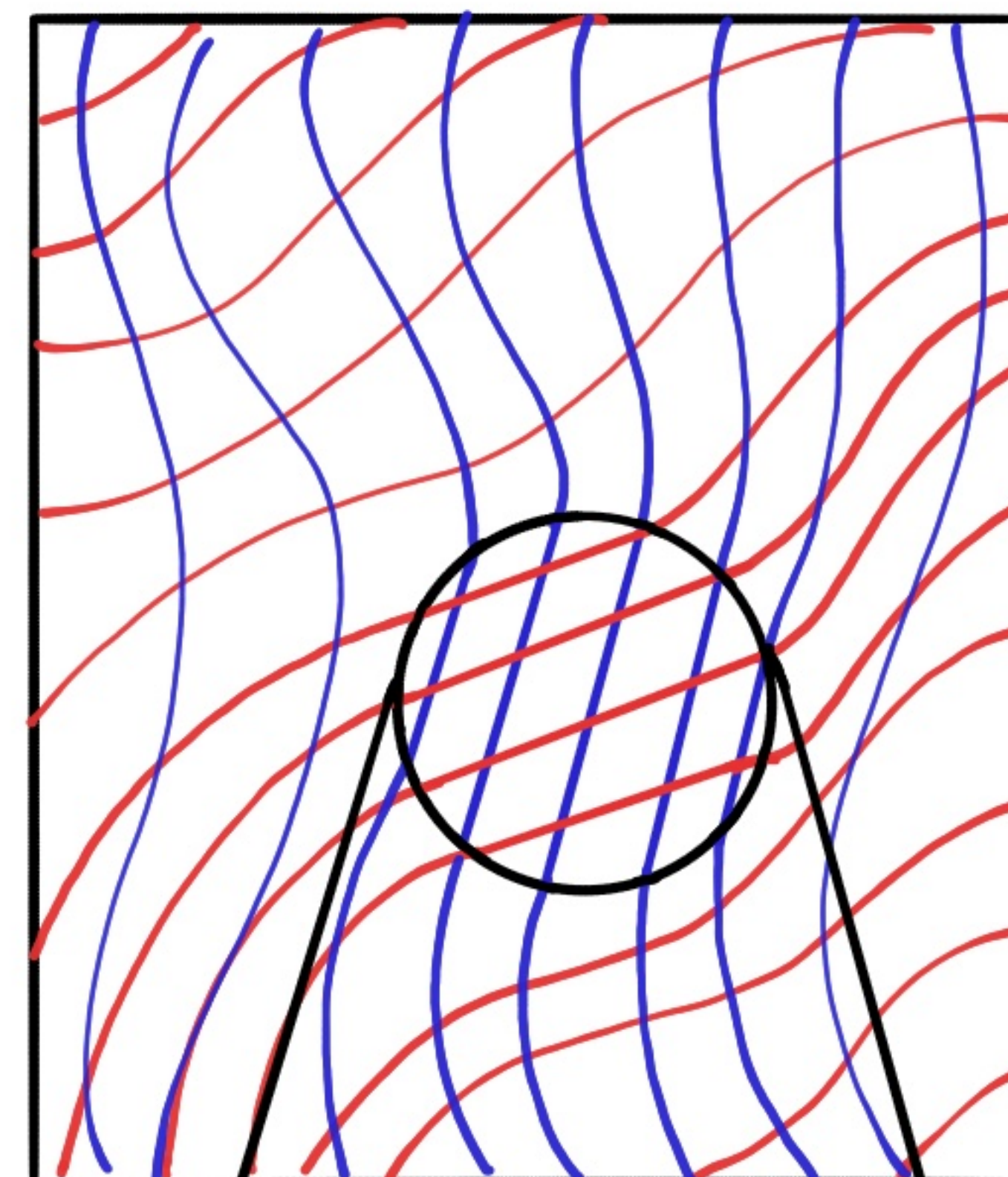


$\mathbb{R}^k$



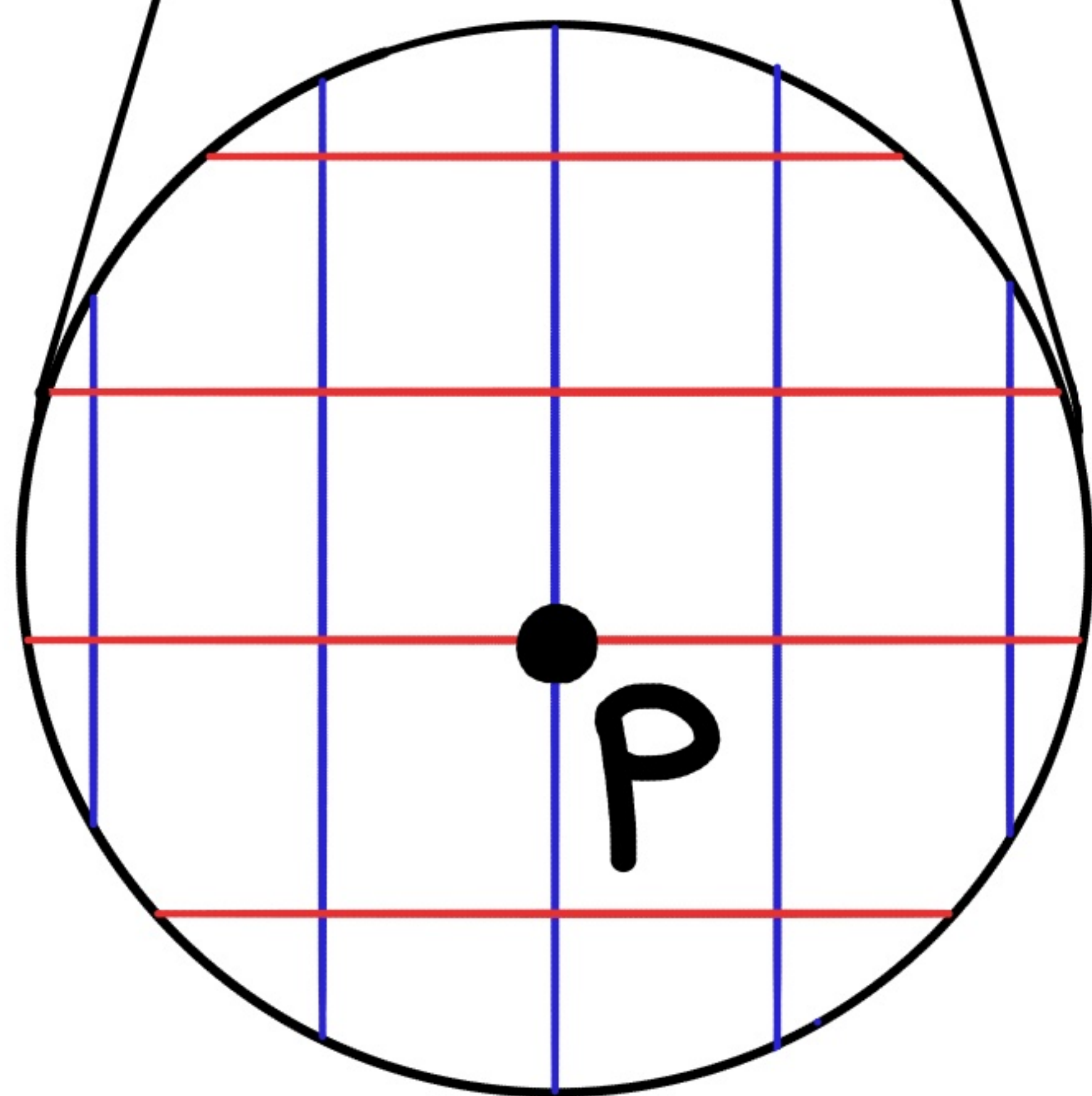
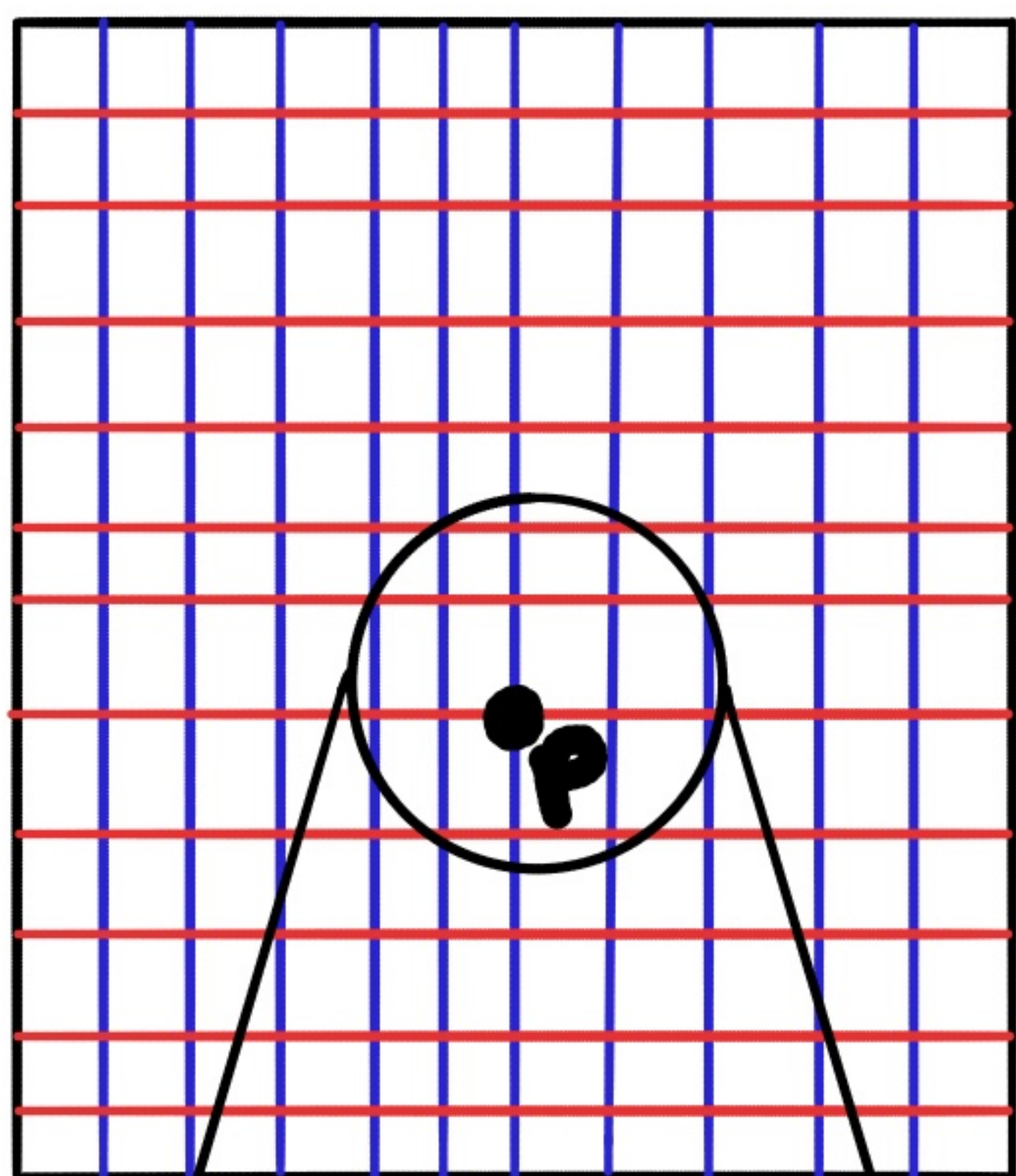
f



$\mathbb{R}^n$  f  $\mathbb{R}^k$  $f \approx D_P f$ 

Near p , $D_p f$ approximates f

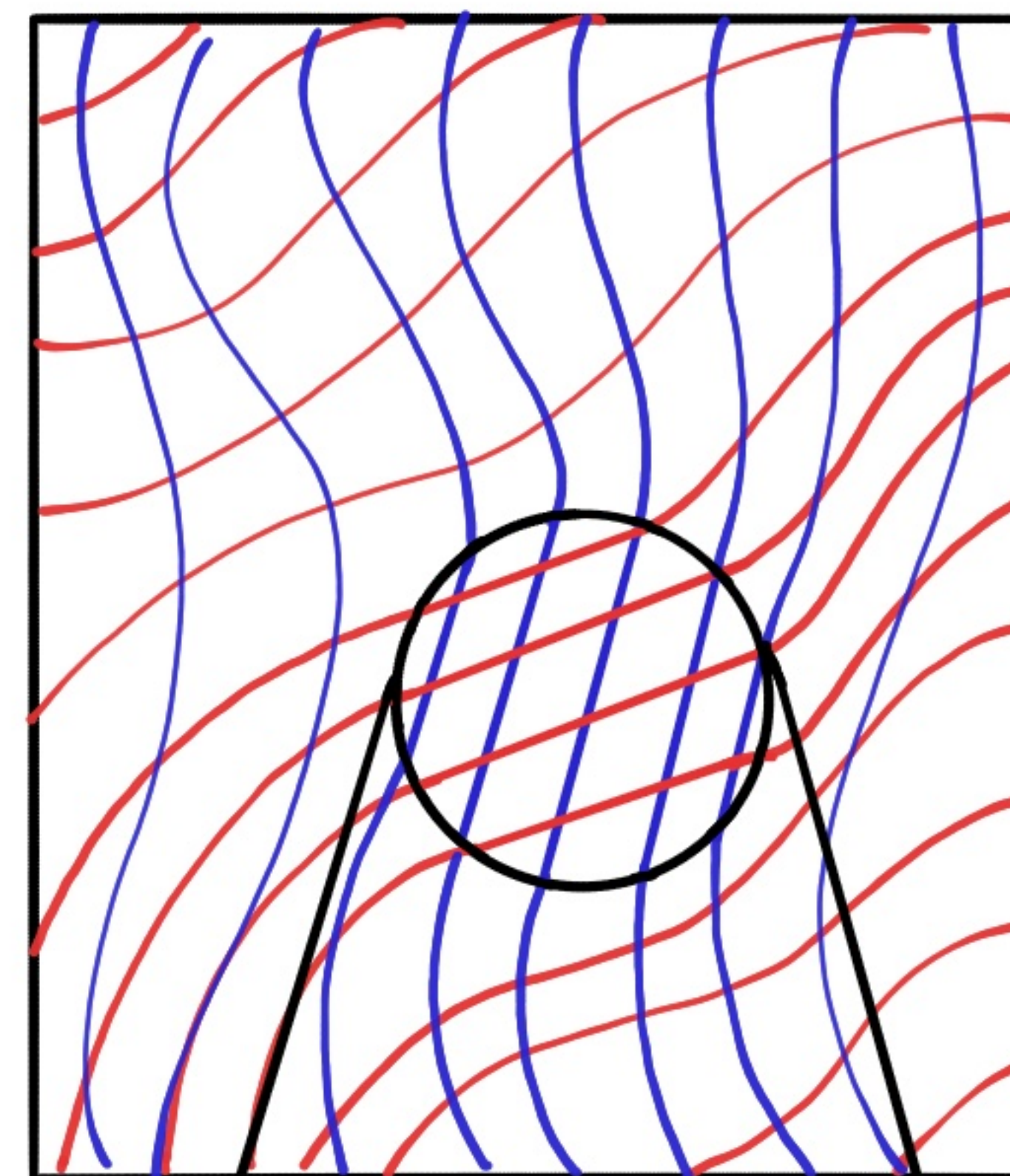
$\mathbb{R}^n$



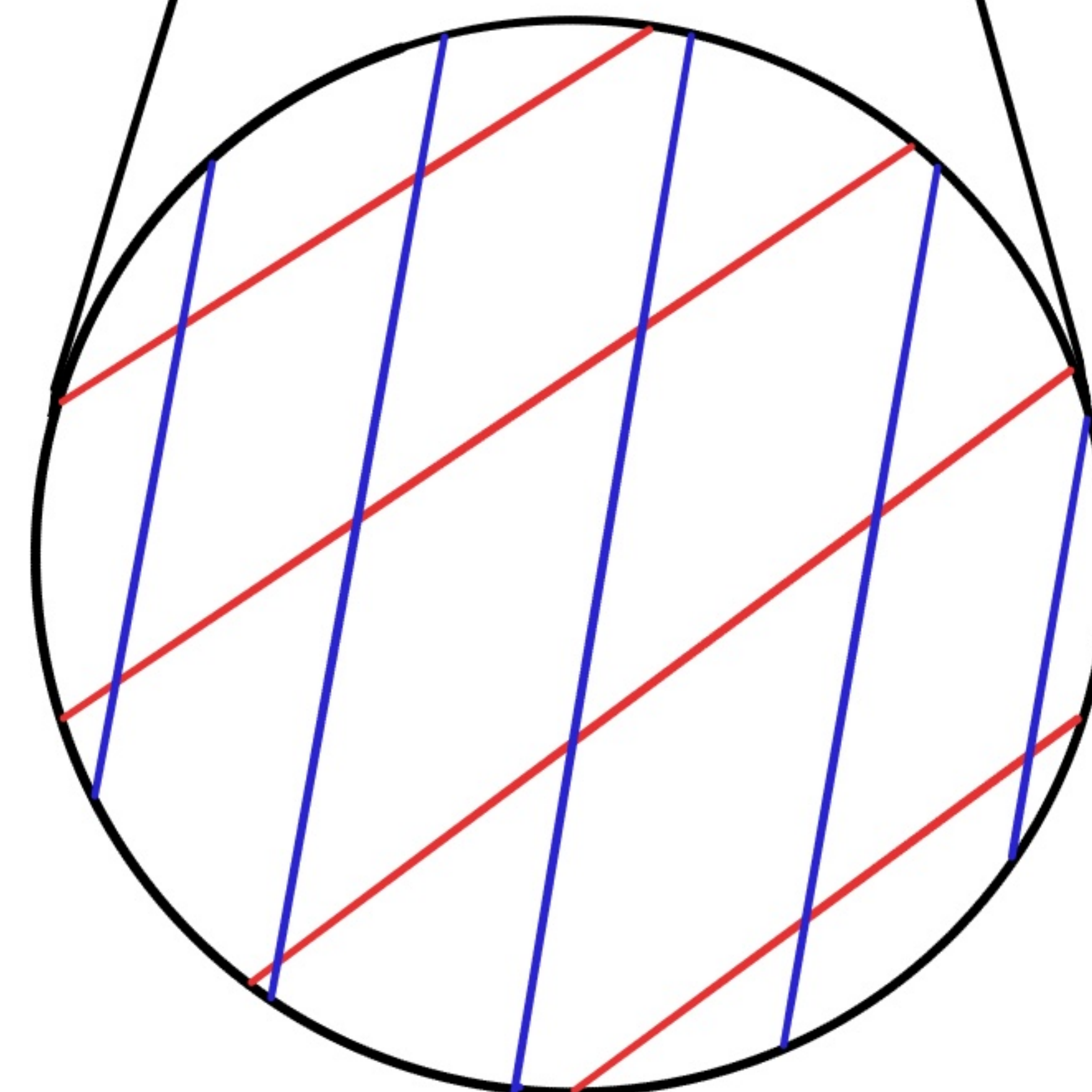
f



$\mathbb{R}^k$

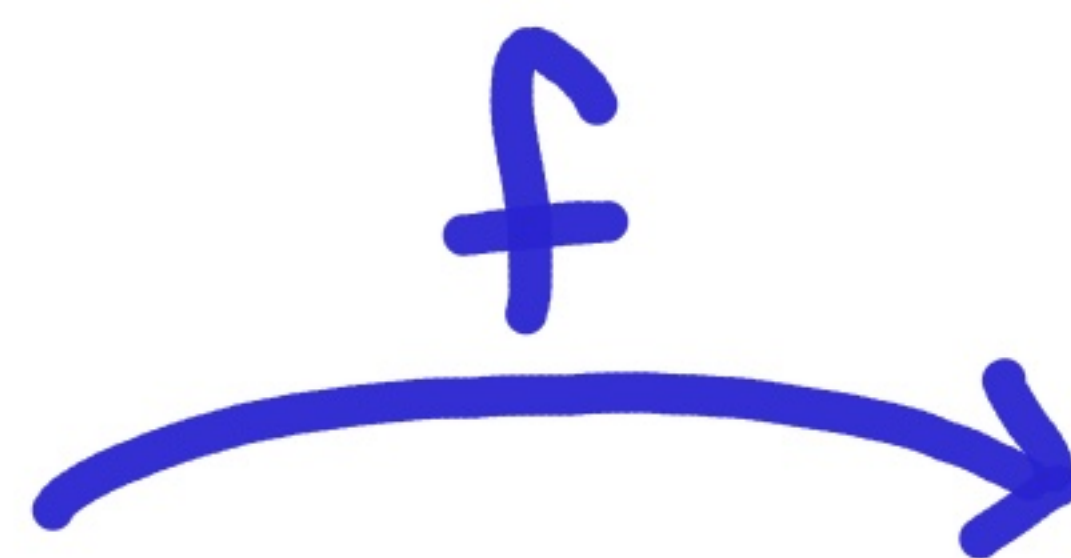
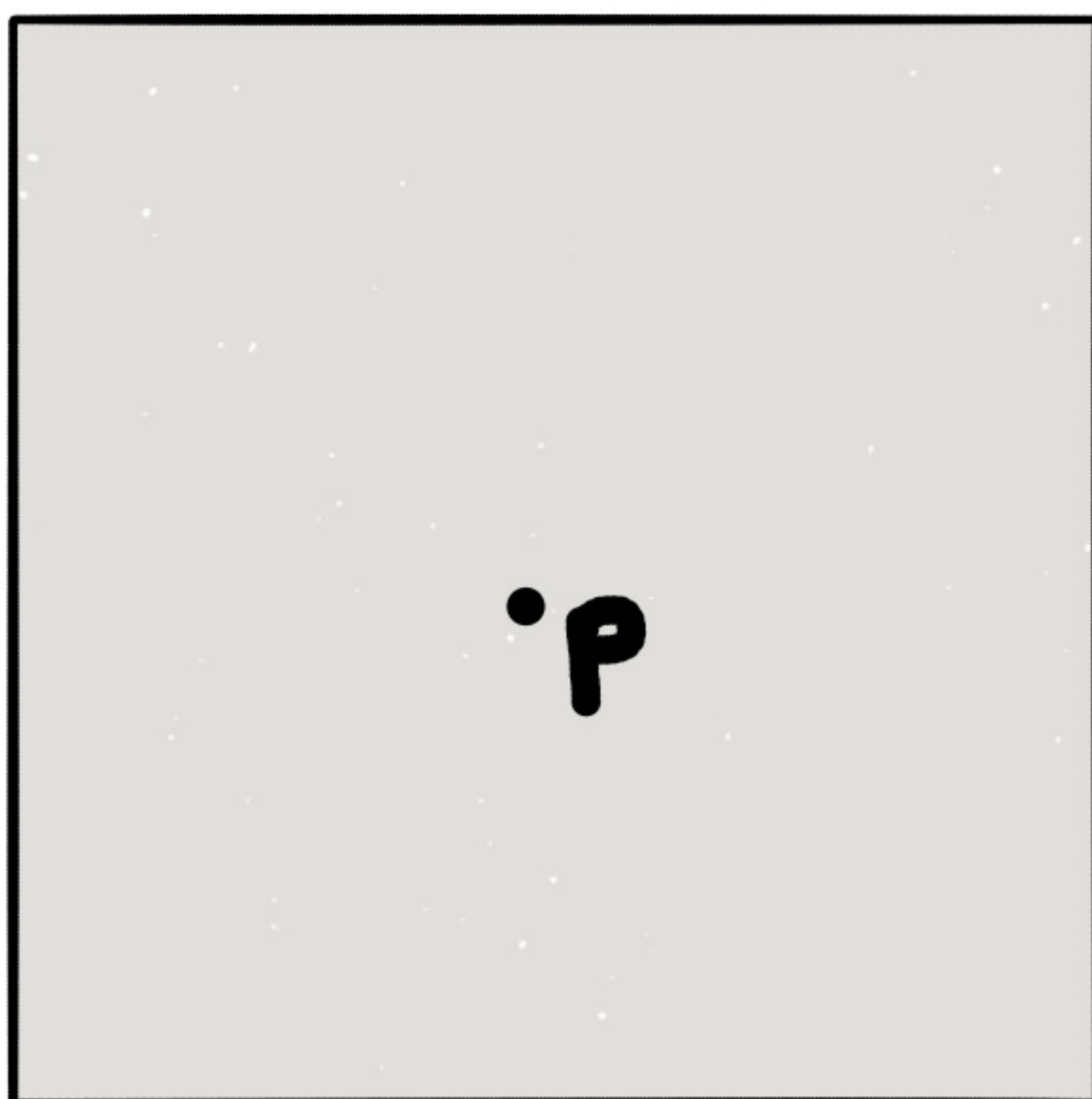


$f \approx D_p f$

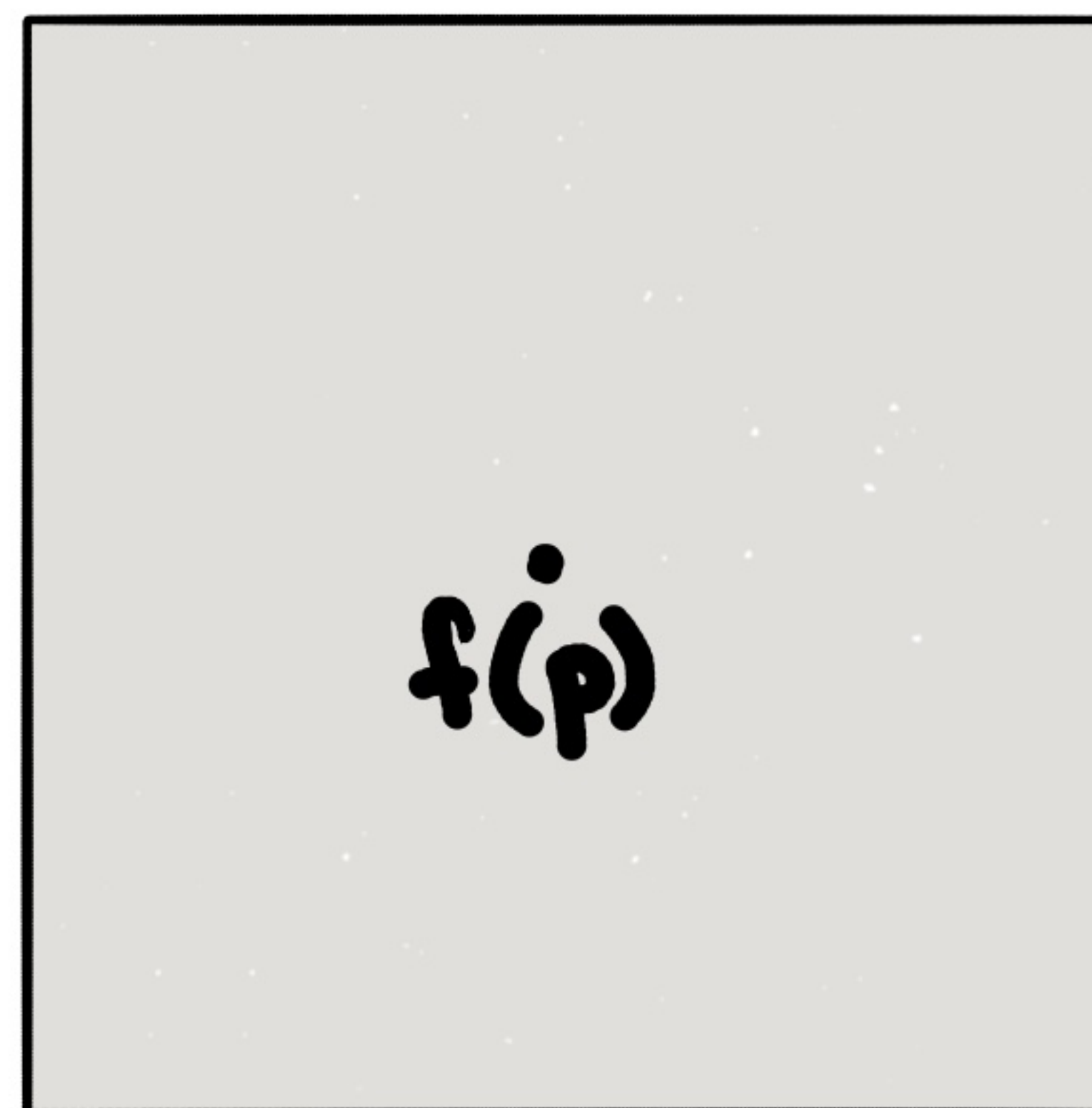


Near p , $D_p f$ approximates f

$\mathbb{R}^n$

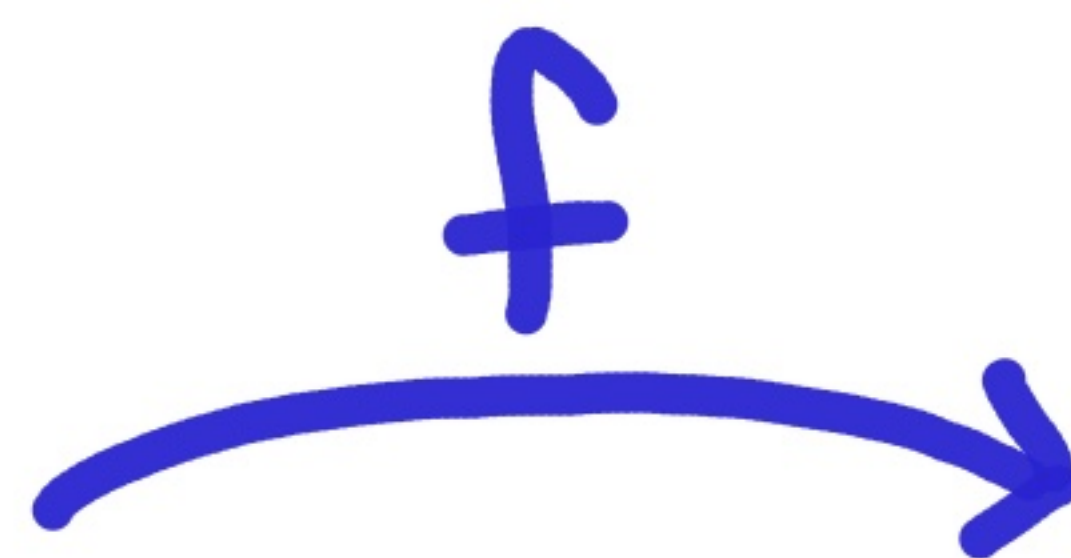
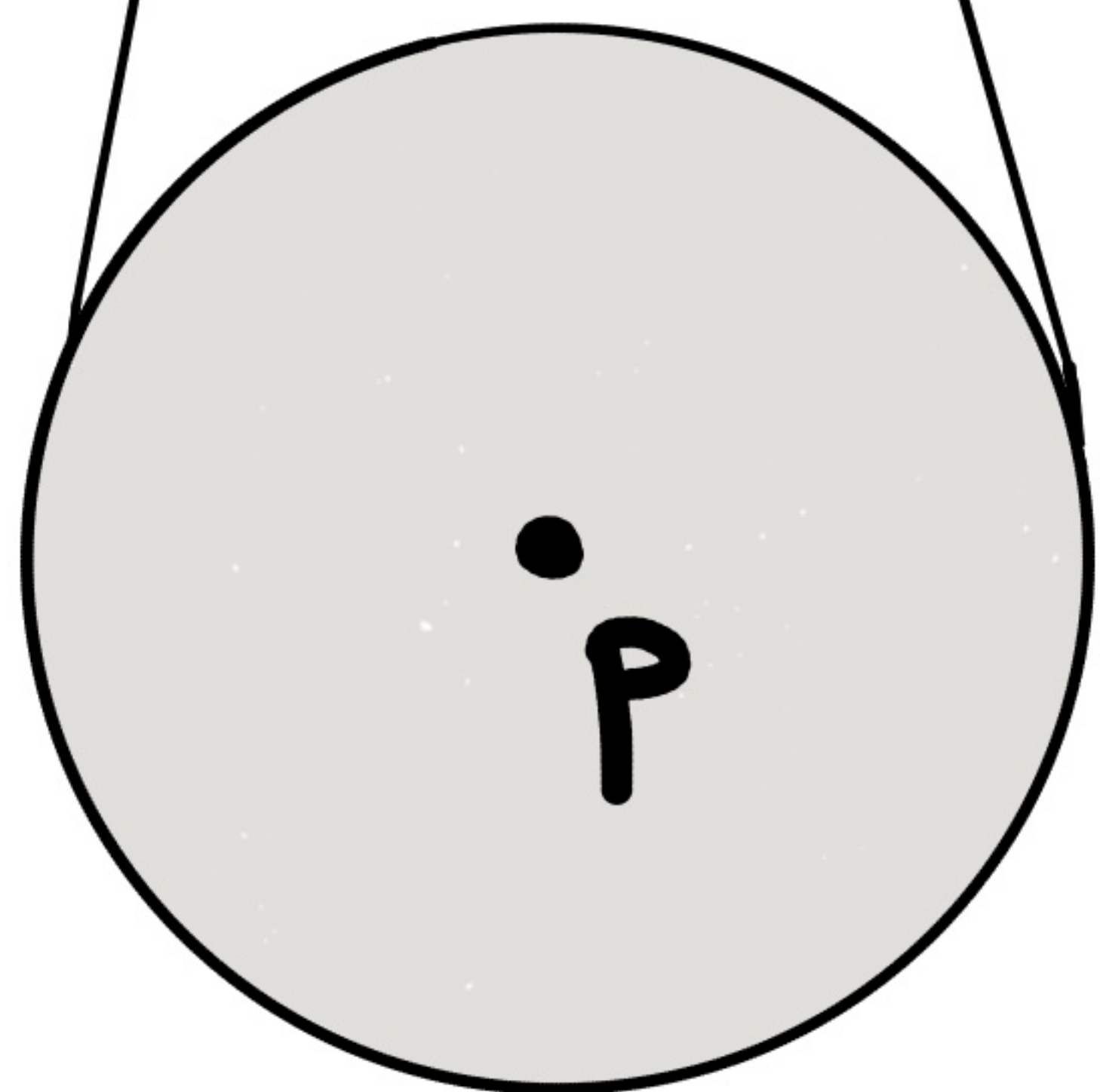
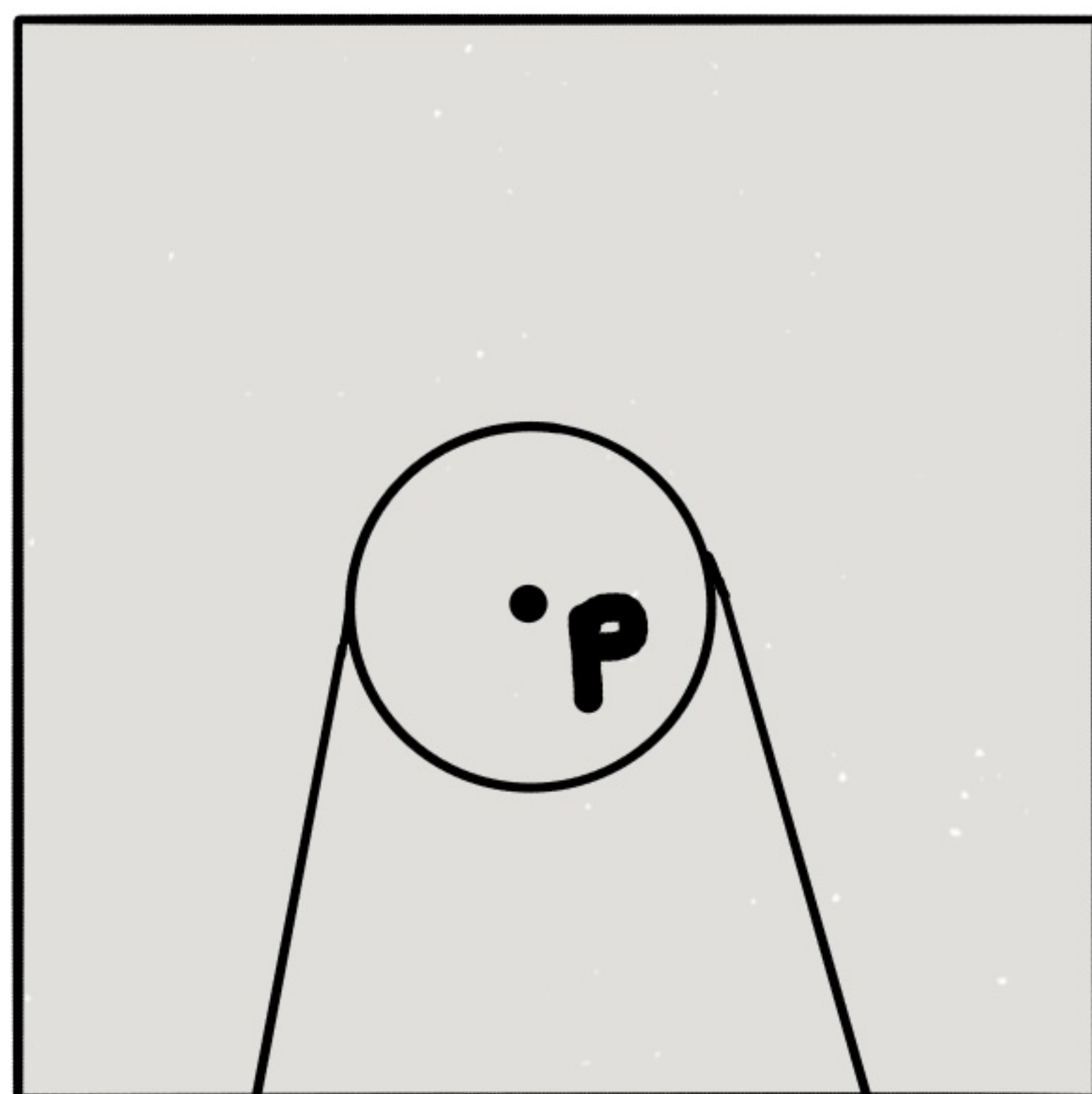


$\mathbb{R}^k$

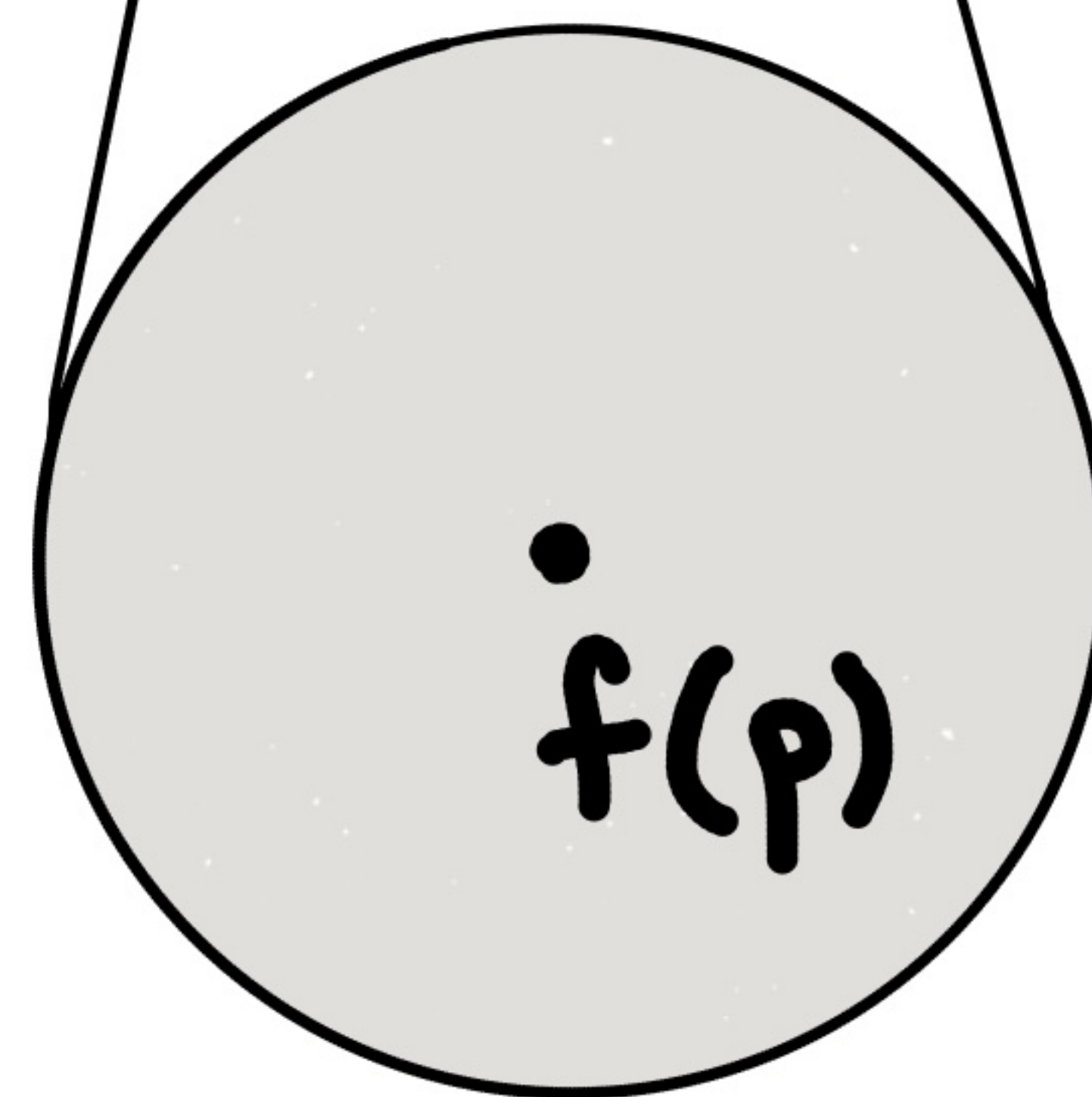
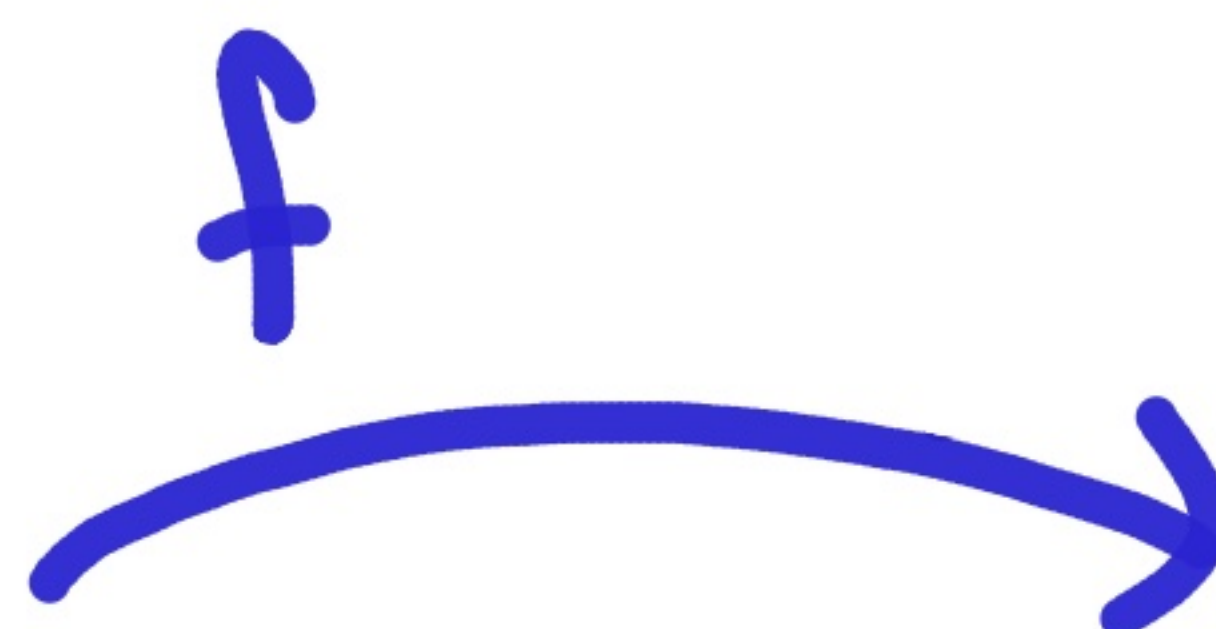
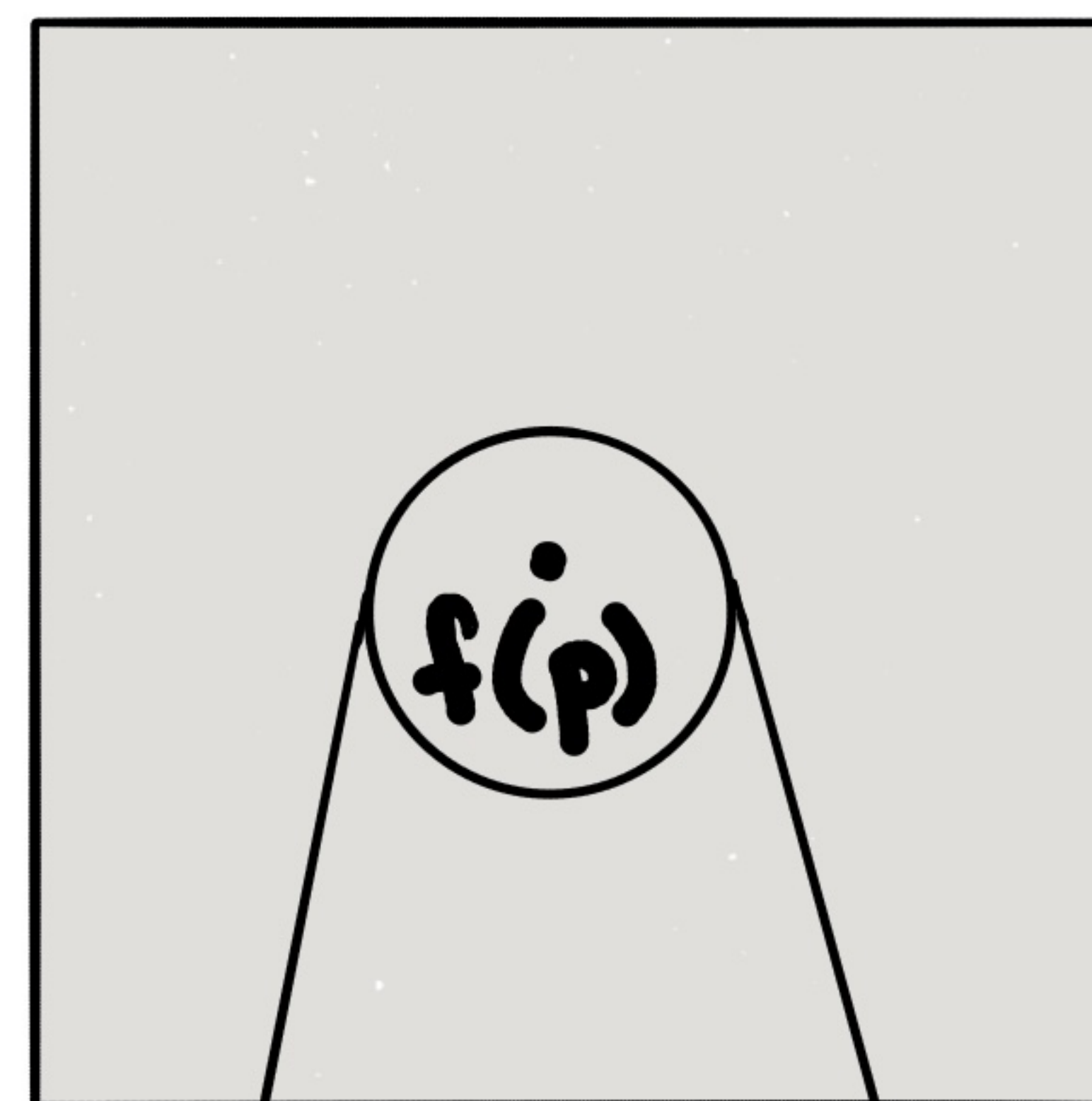


Near p , $D_p f$ approximates f

$\mathbb{R}^n$

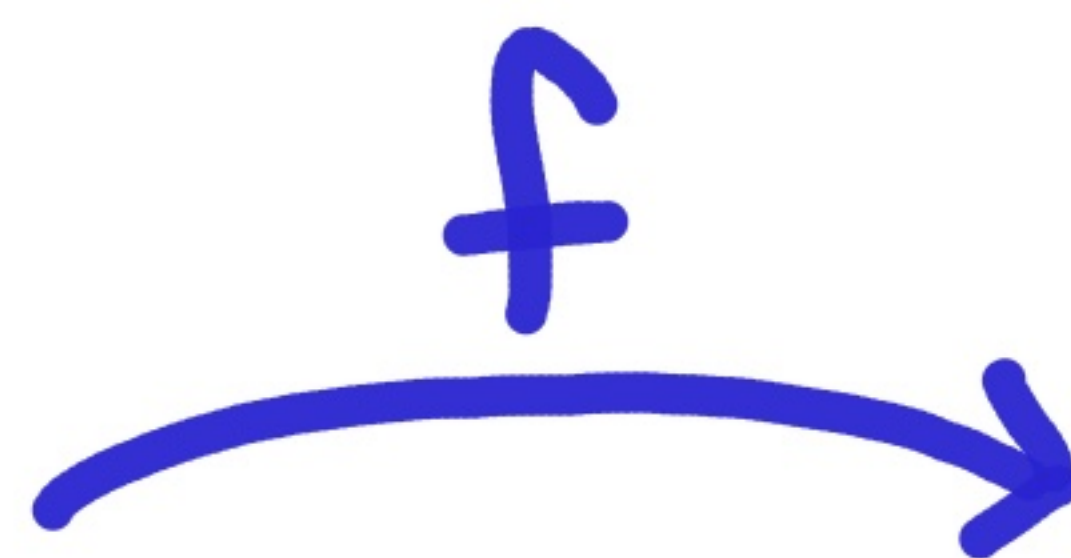
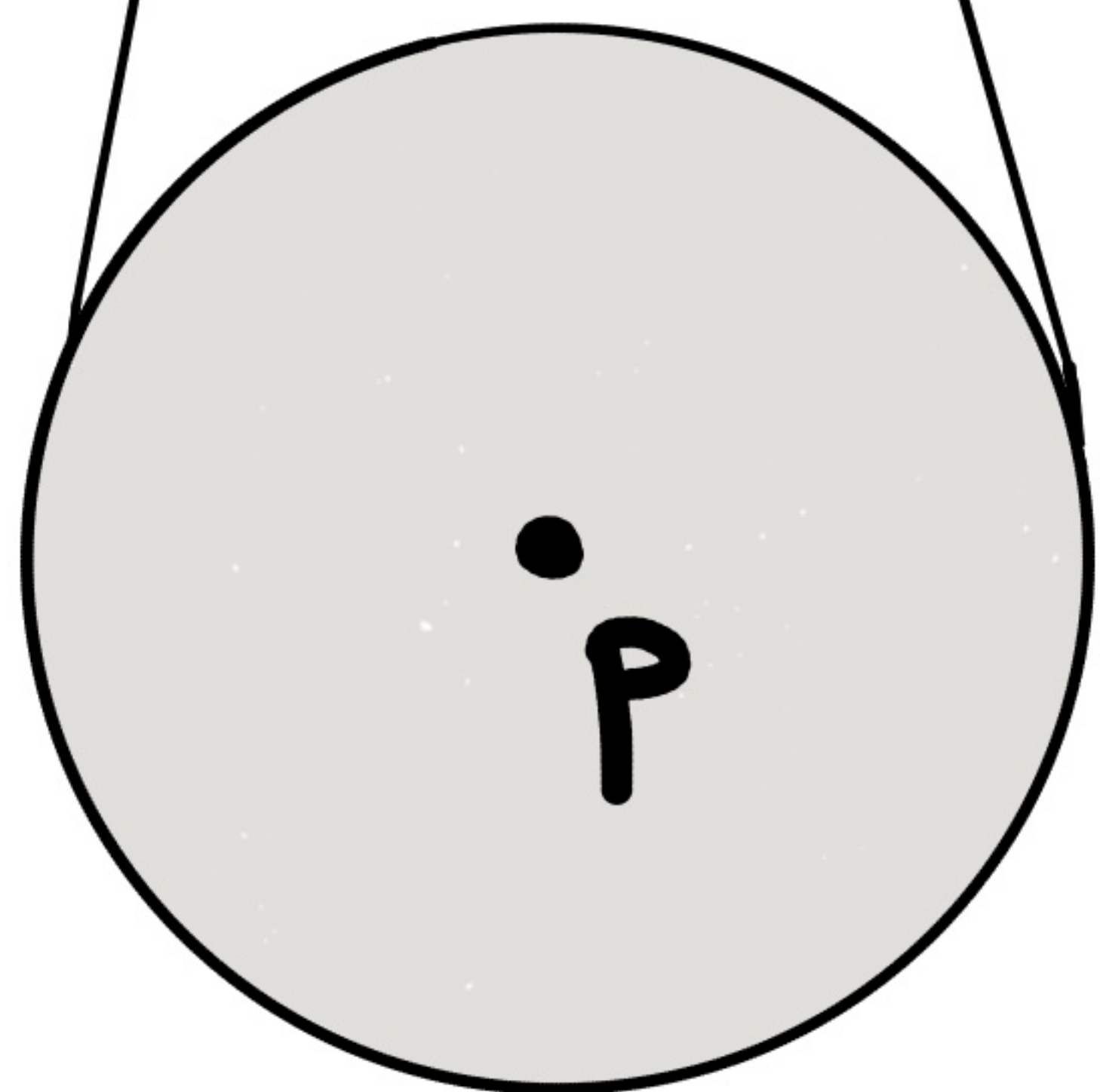
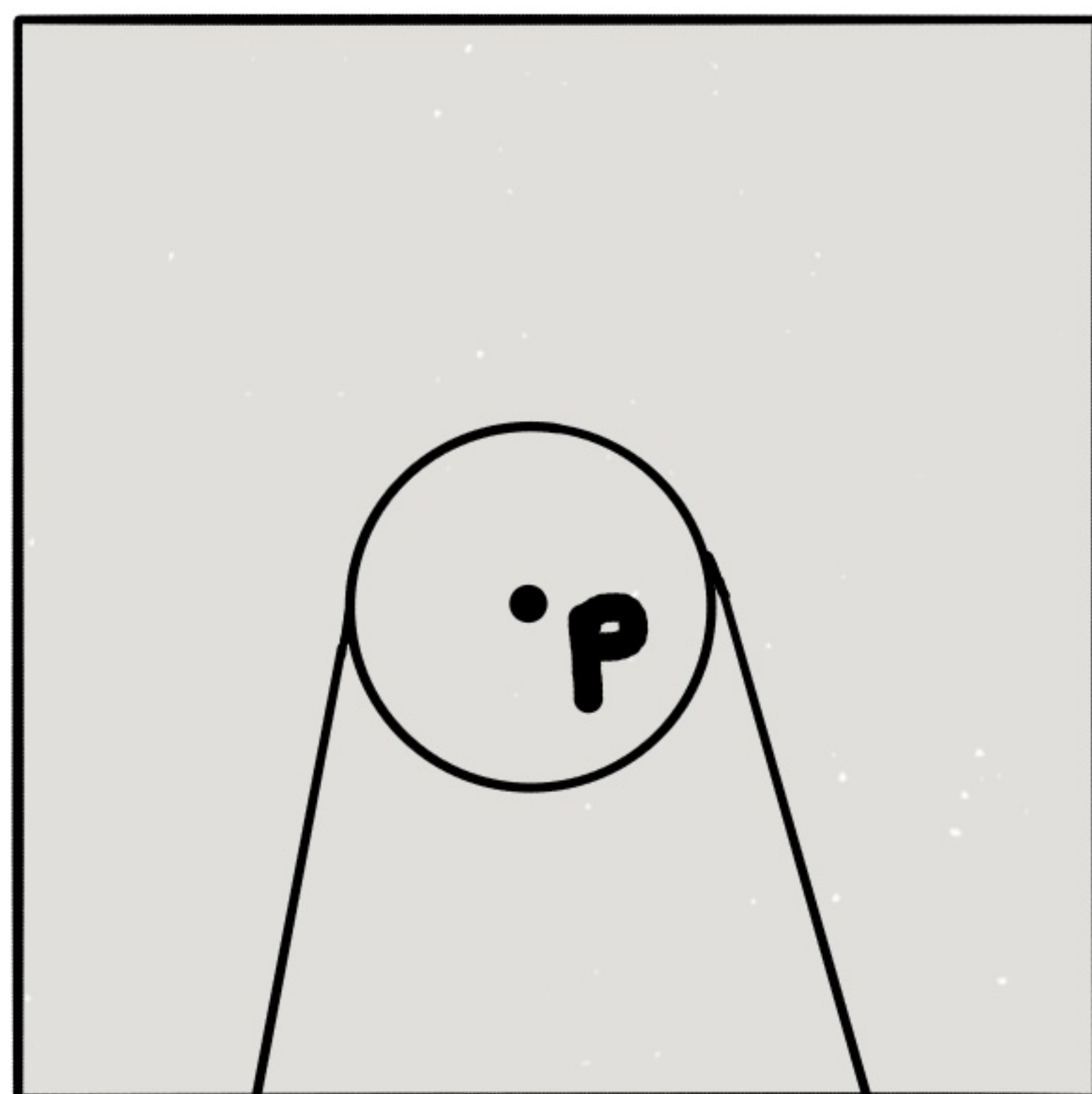


$\mathbb{R}^k$

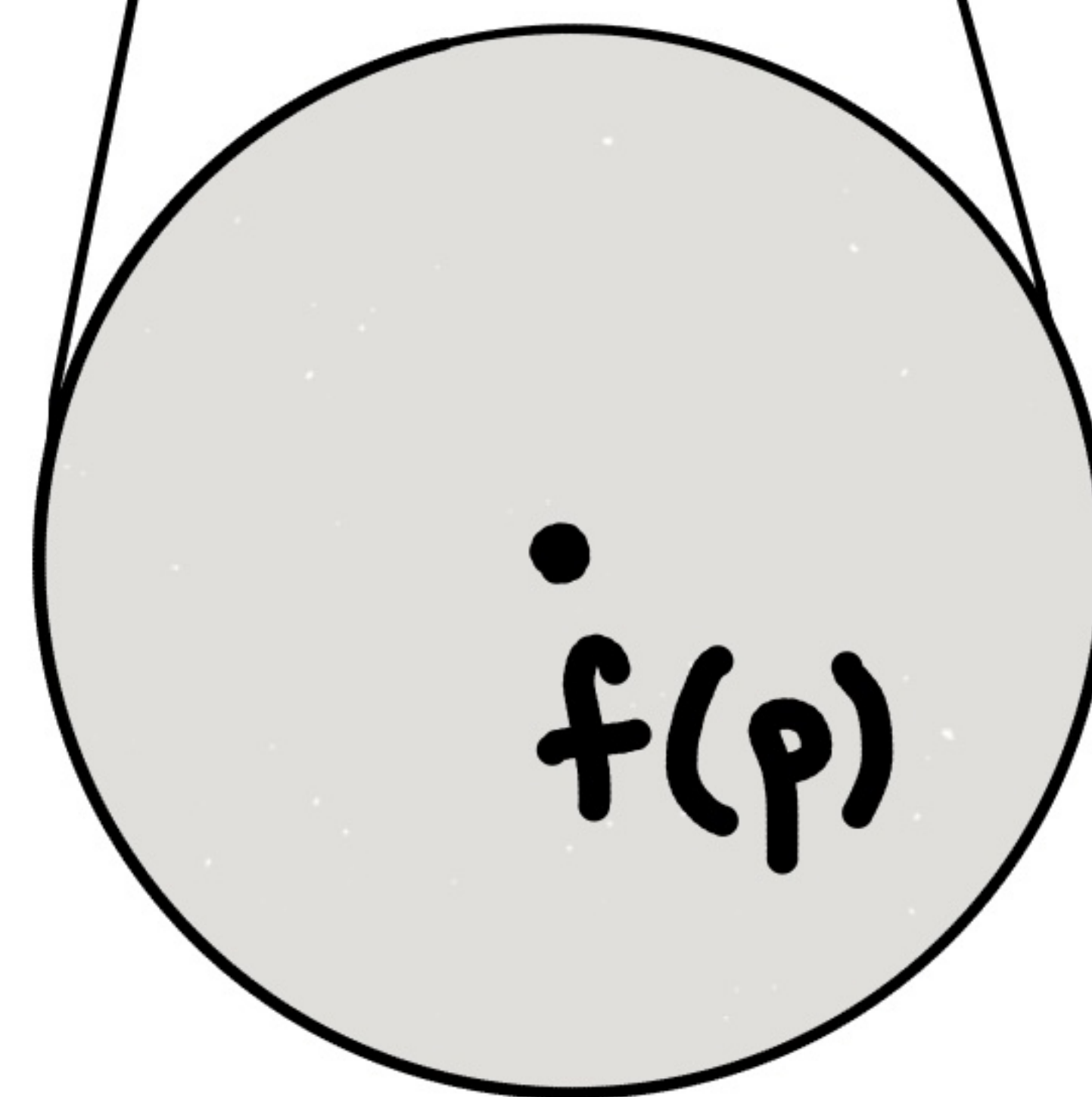
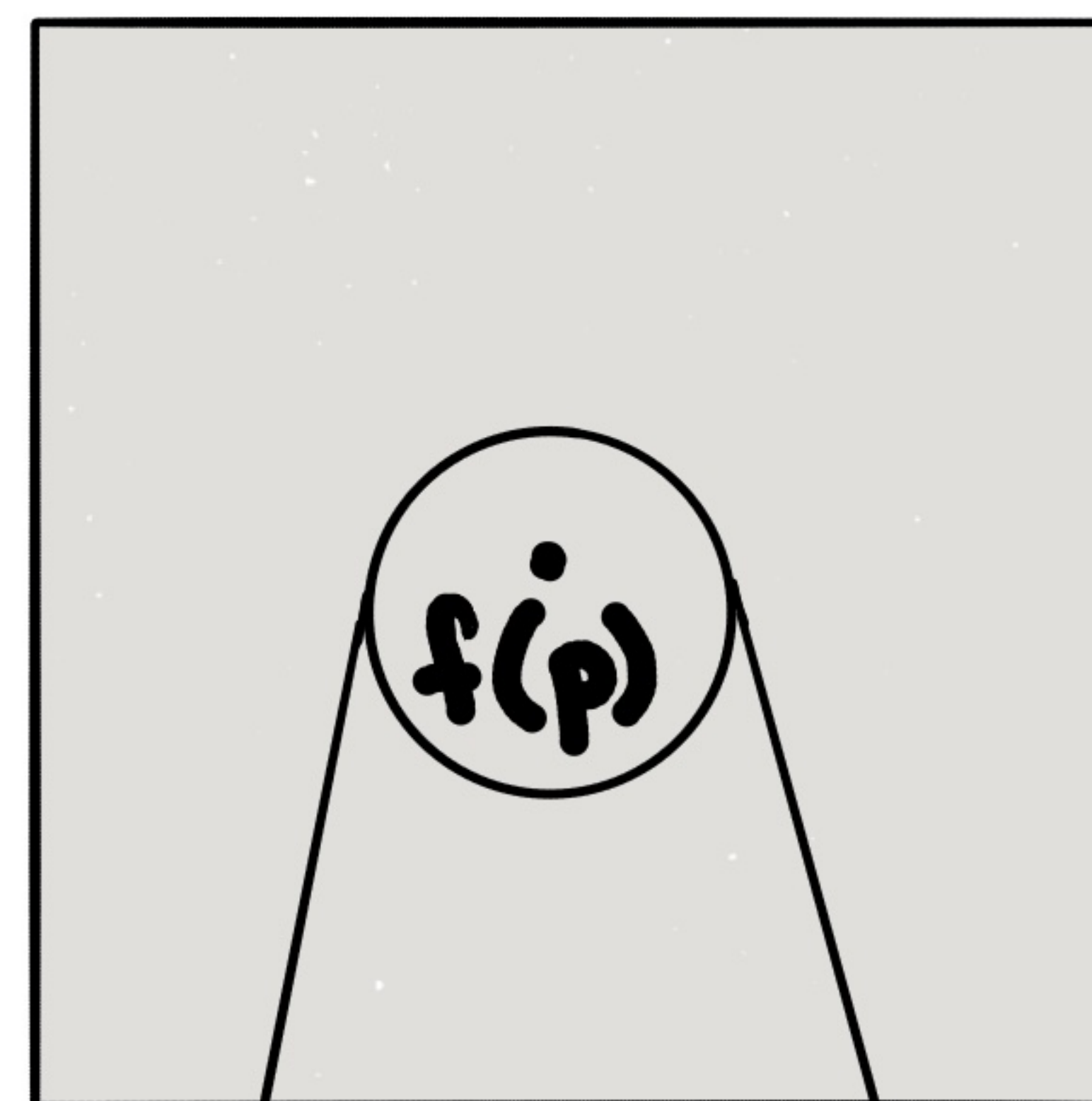


Near p , $D_p f$ approximates f

$\mathbb{R}^n$

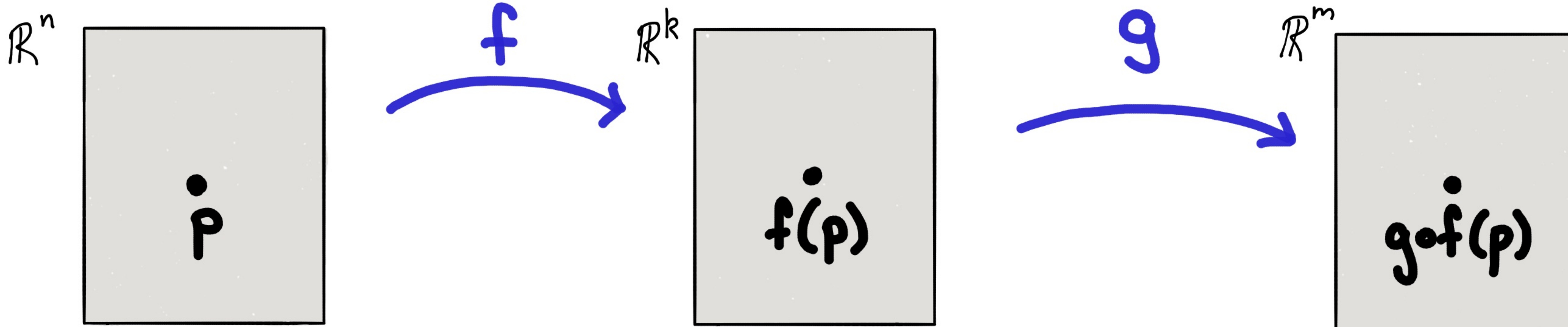


$\mathbb{R}^k$

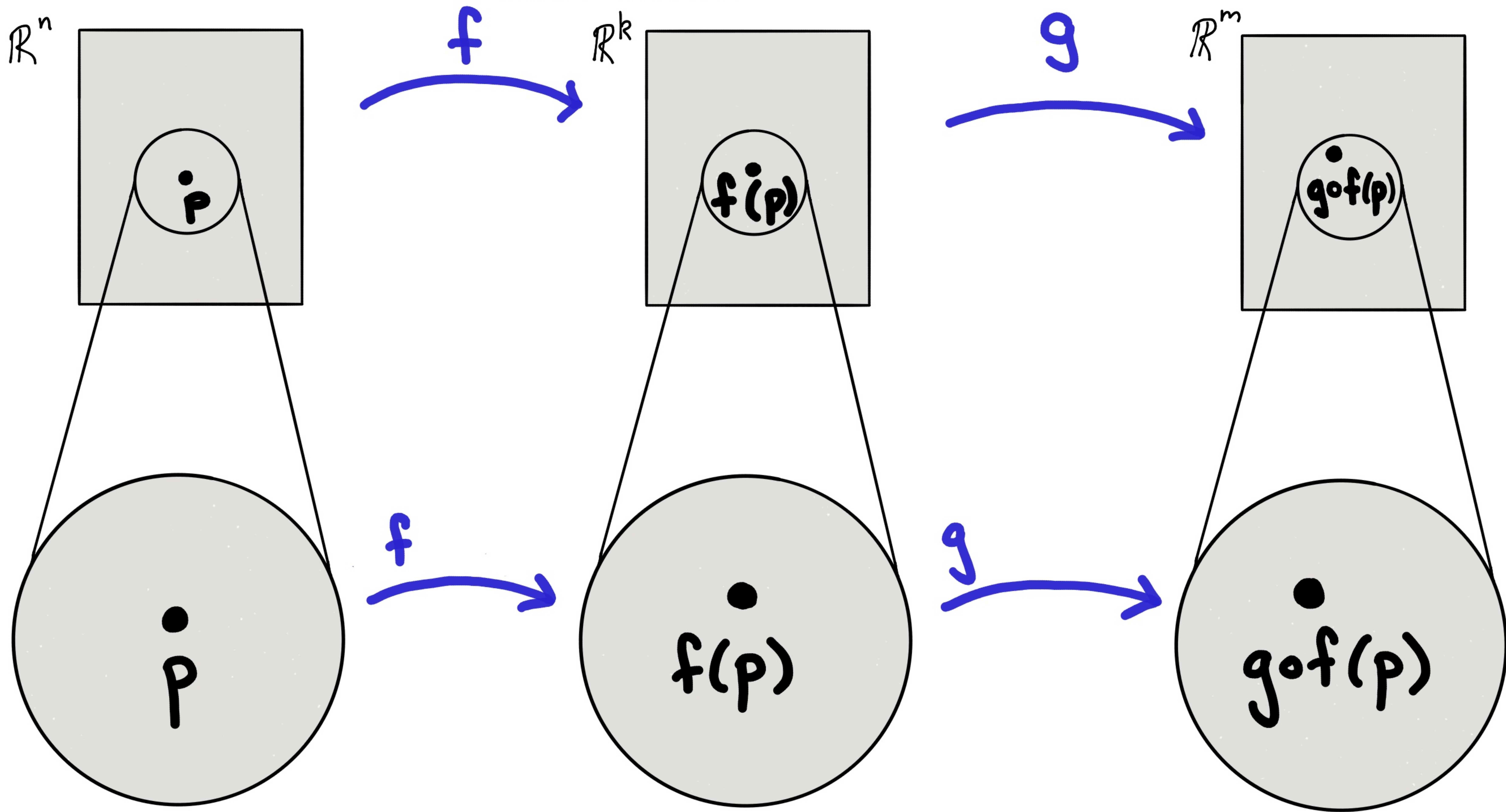


④ Chain rule

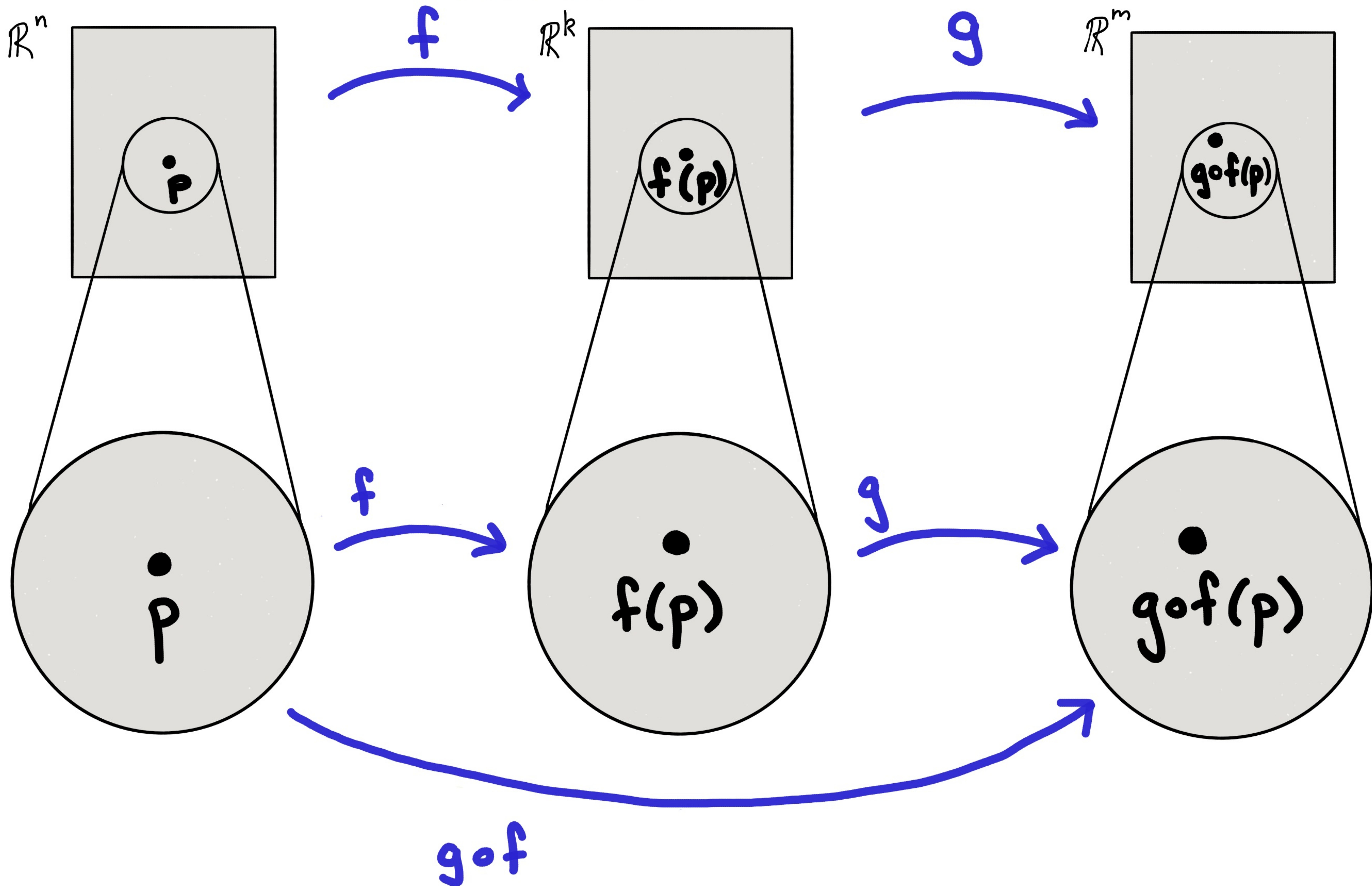
Chain Rule



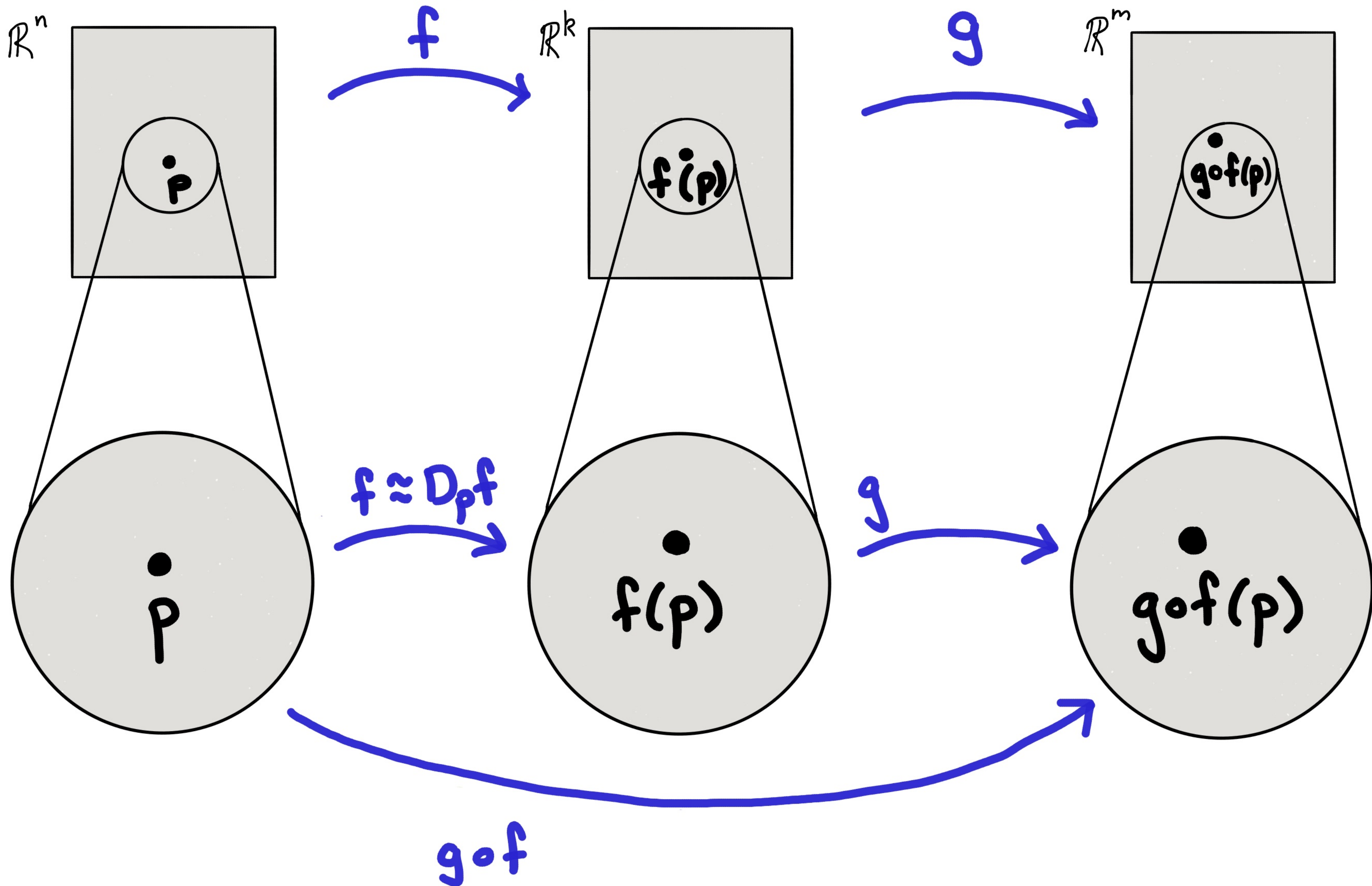
Chain Rule



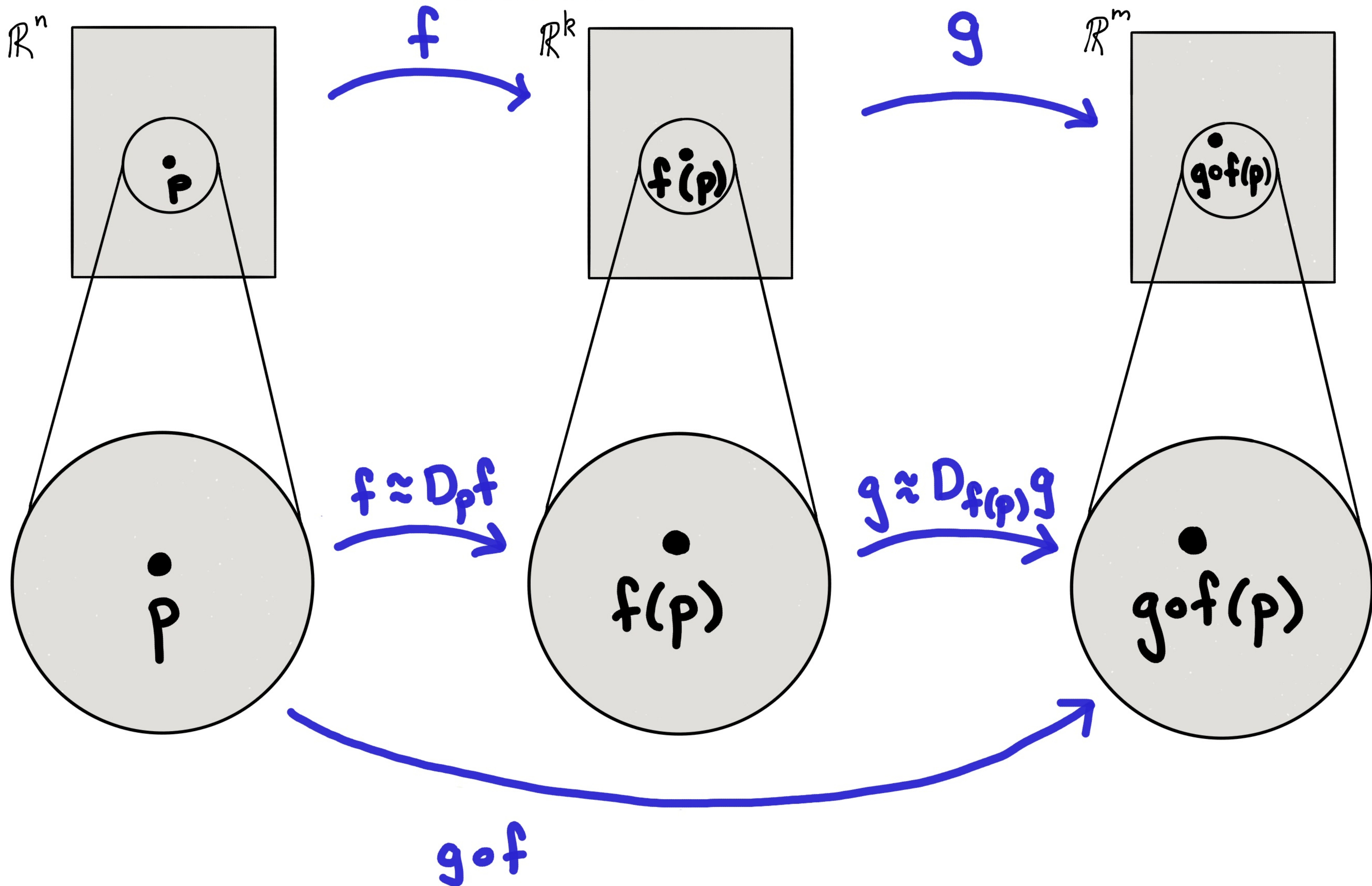
Chain Rule



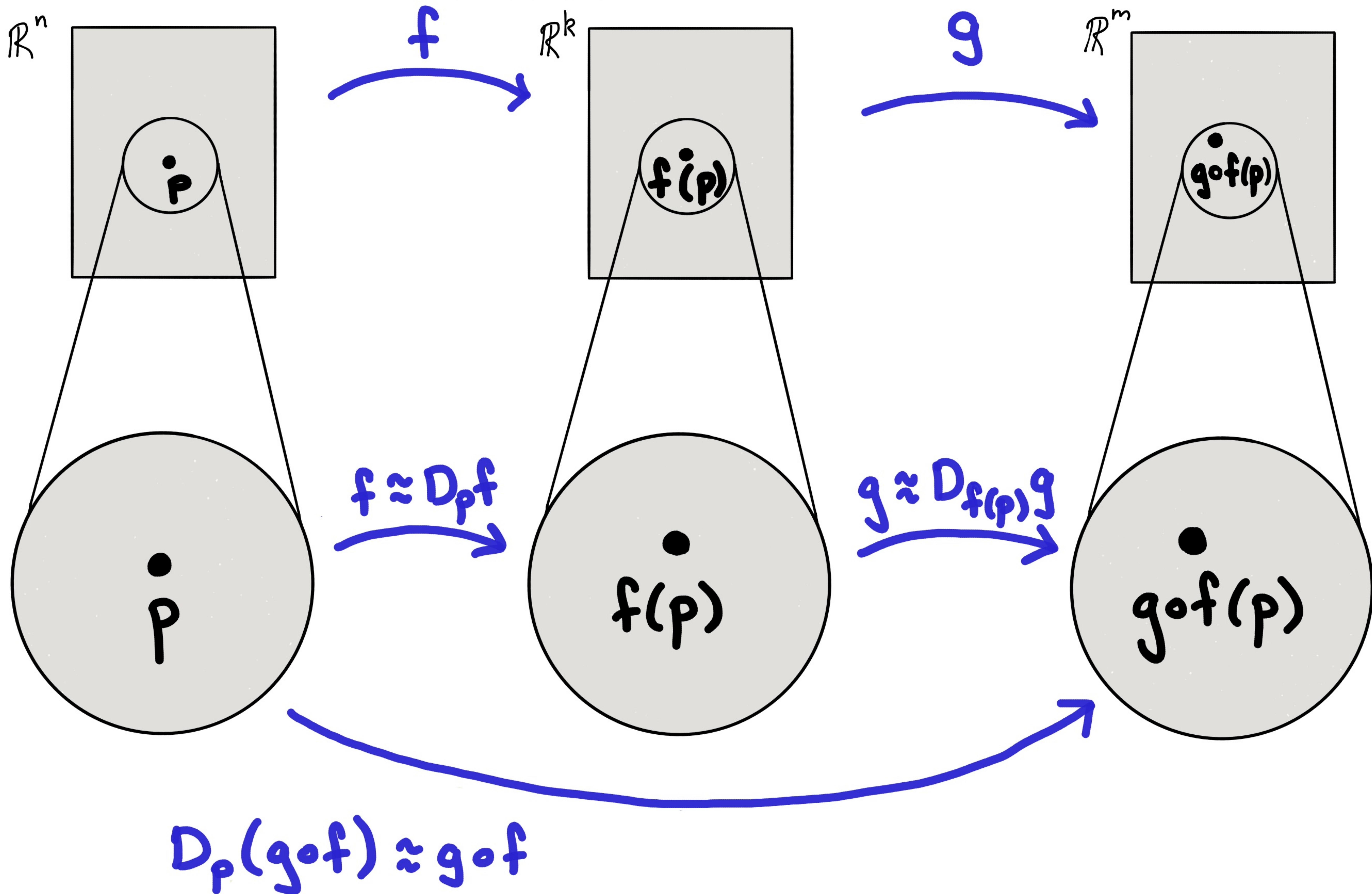
Chain Rule



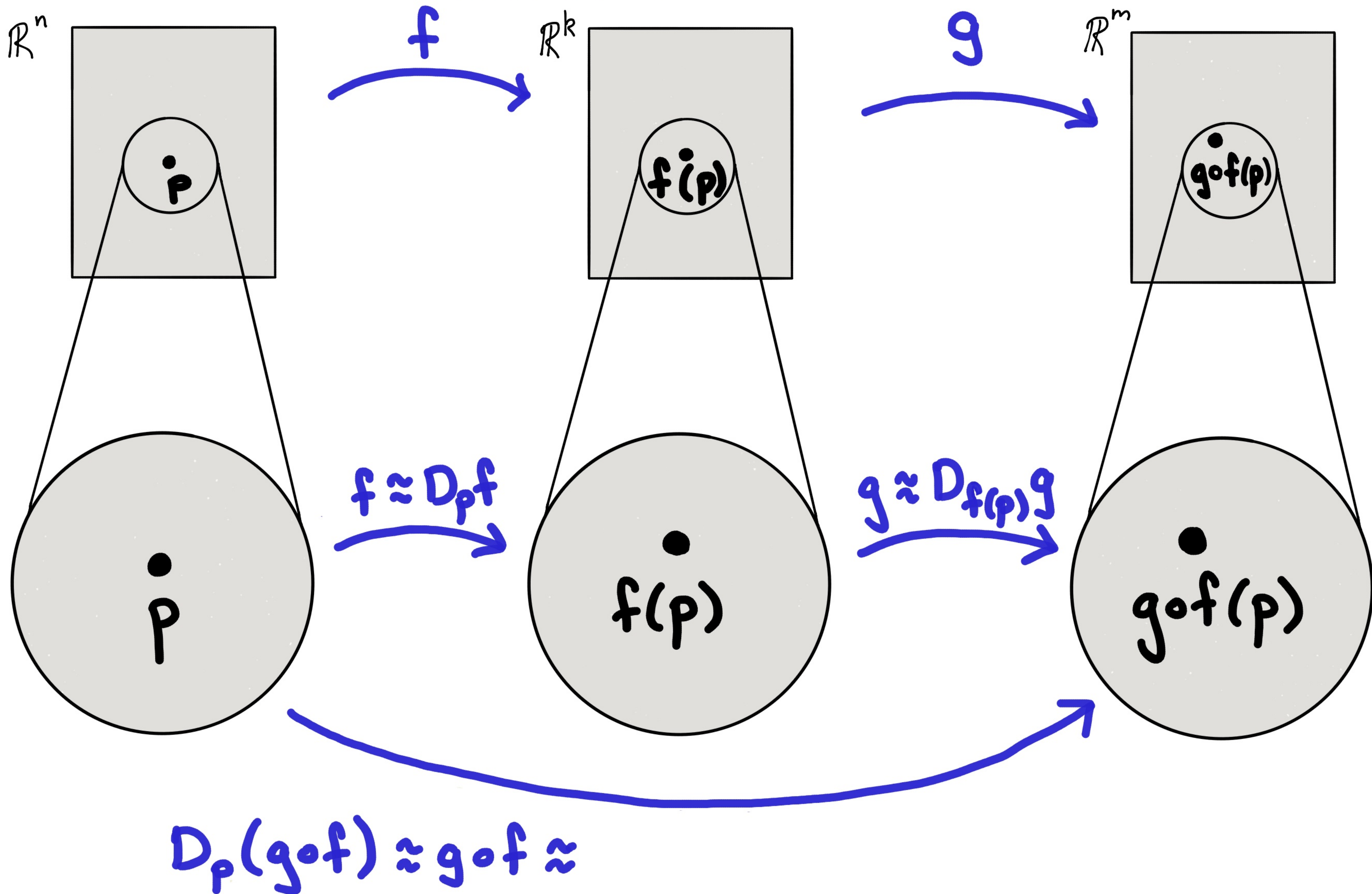
Chain Rule



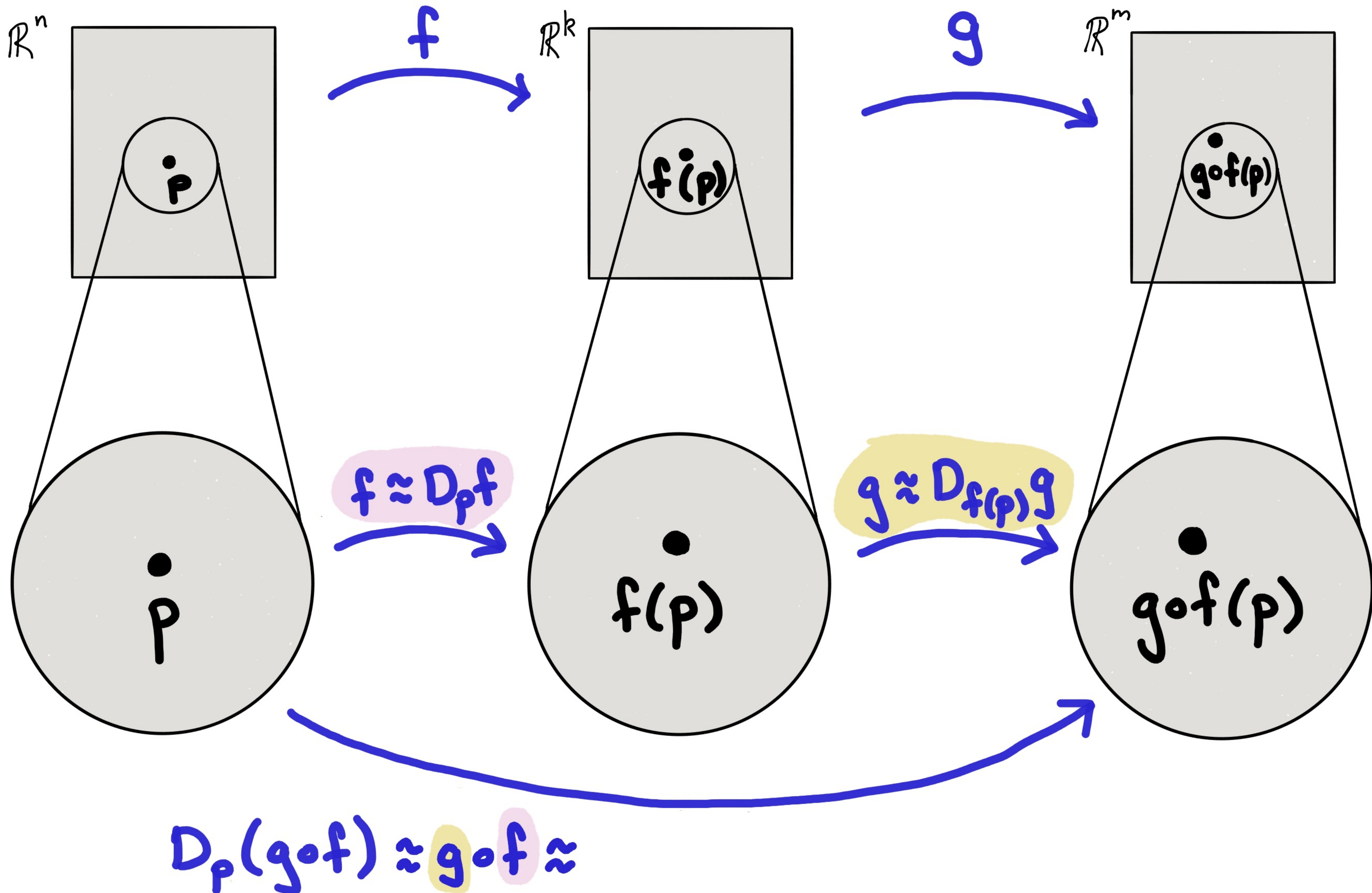
Chain Rule



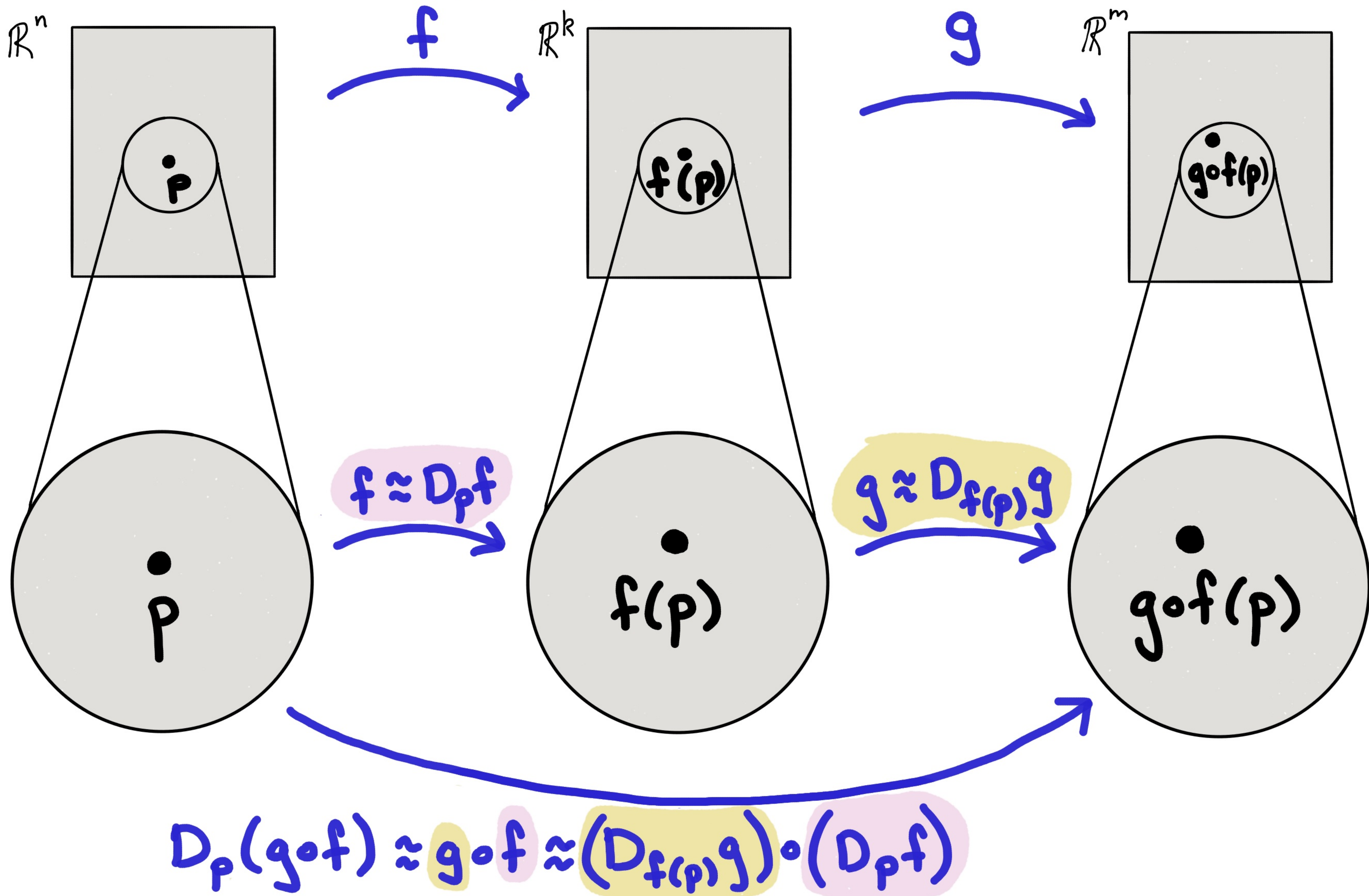
Chain Rule



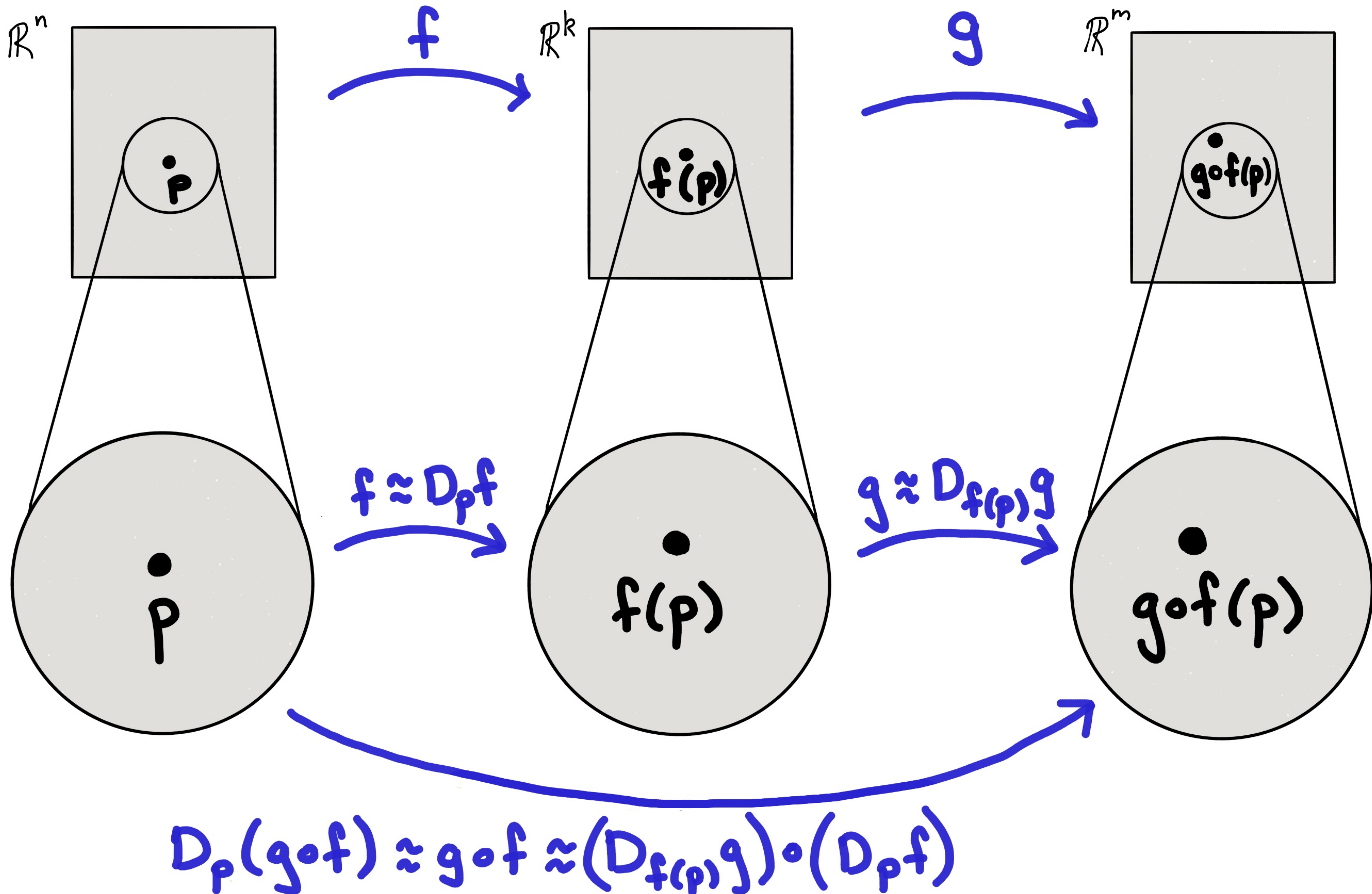
Chain Rule



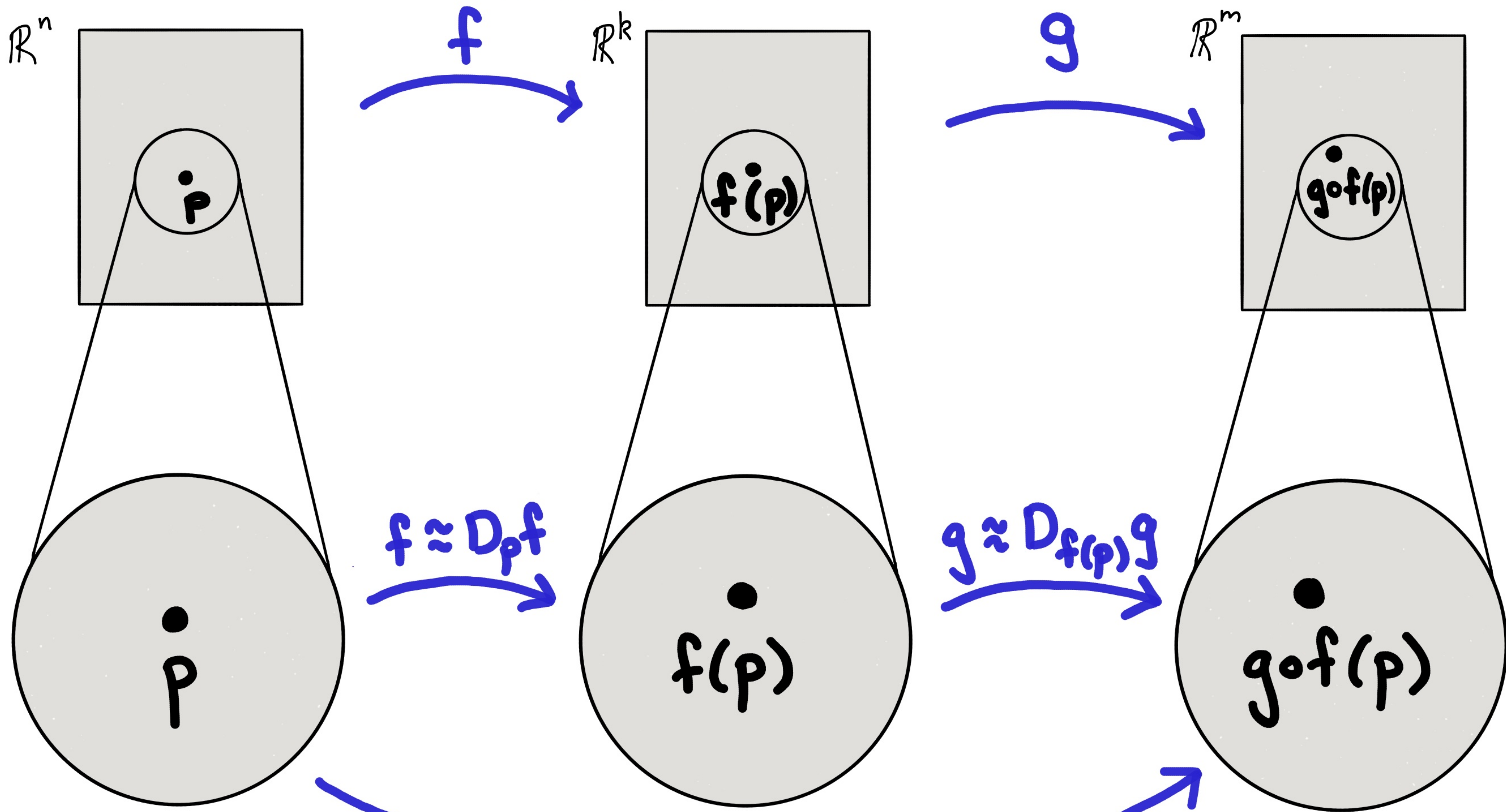
Chain Rule



Chain Rule

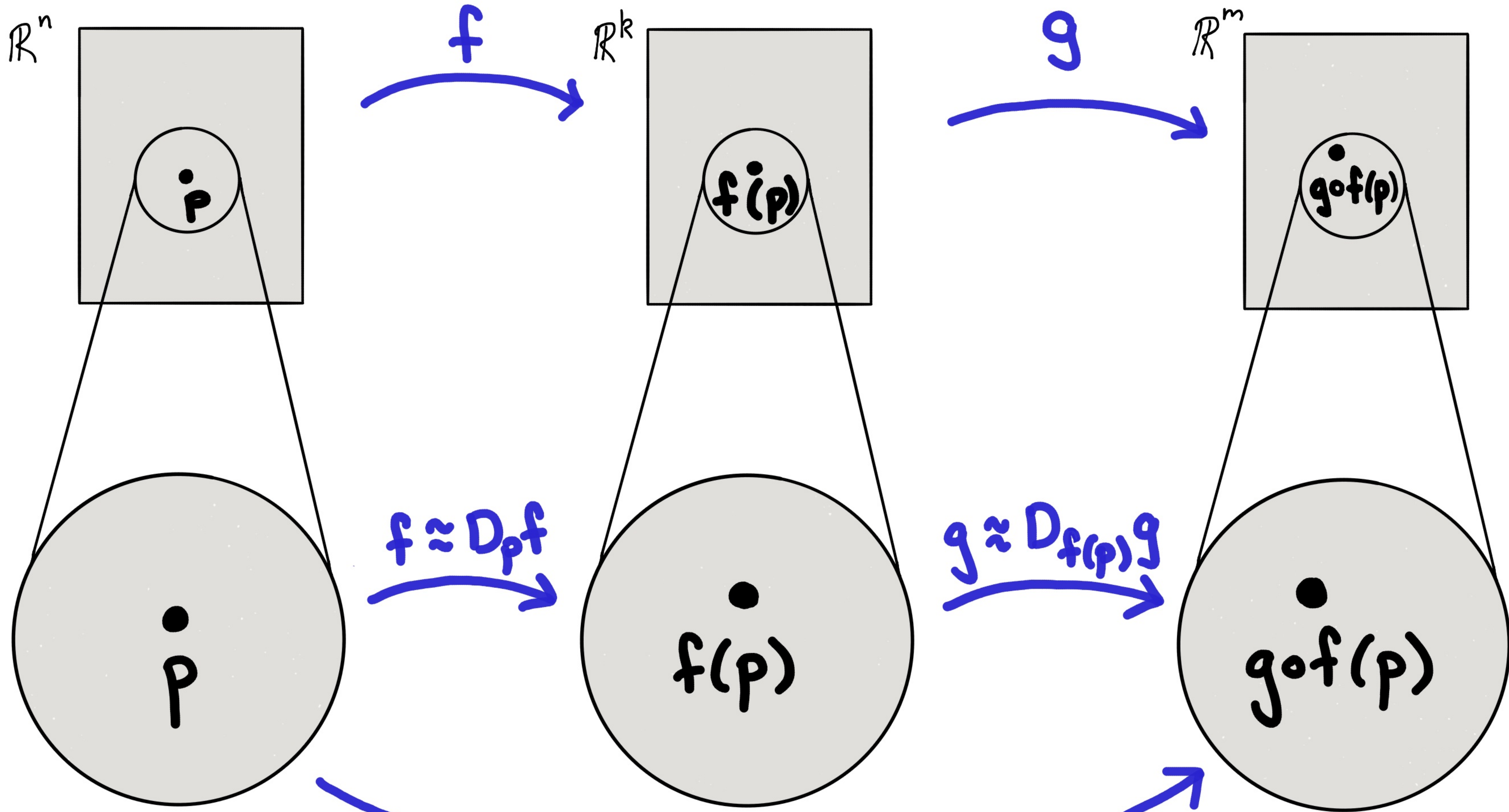


Chain Rule



$$D_p(g \circ f) \approx g \circ f \approx (D_{f(p)} g) \circ (D_p f) = (D_{f(p)} g)(D_p f)$$

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Chain Rule

If $f: \mathbb{R}^n \rightarrow \mathbb{R}^k$, $g: \mathbb{R}^k \rightarrow \mathbb{R}^m$, and $p \in \mathbb{R}^n$,
then

$$D_p(g \circ f) = (D_{f(p)}g)(D_p f)$$

Example:

$$(g \circ f)'(p) = g'(f(p))f'(p)$$

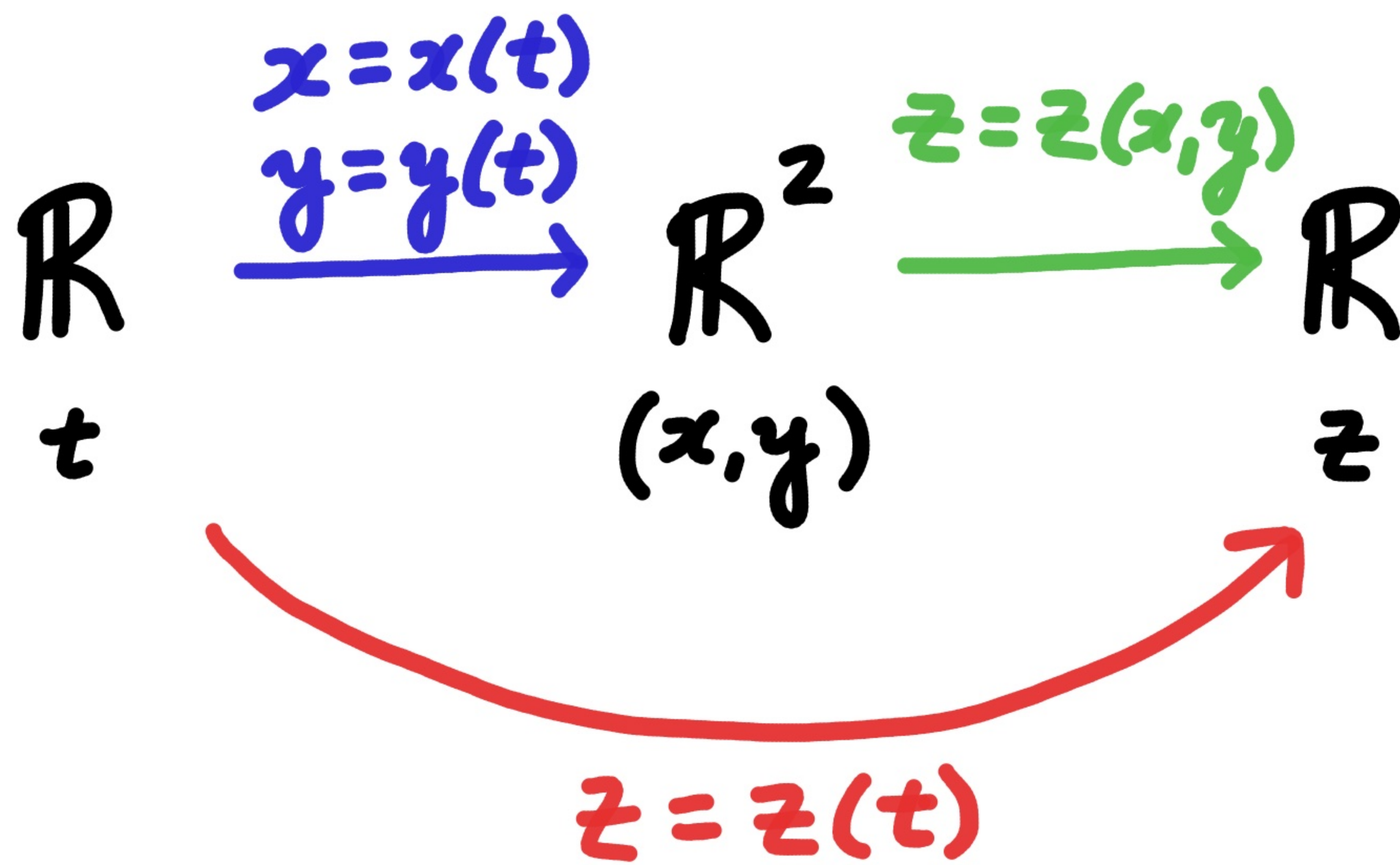
⑤ The chain
rule in practice

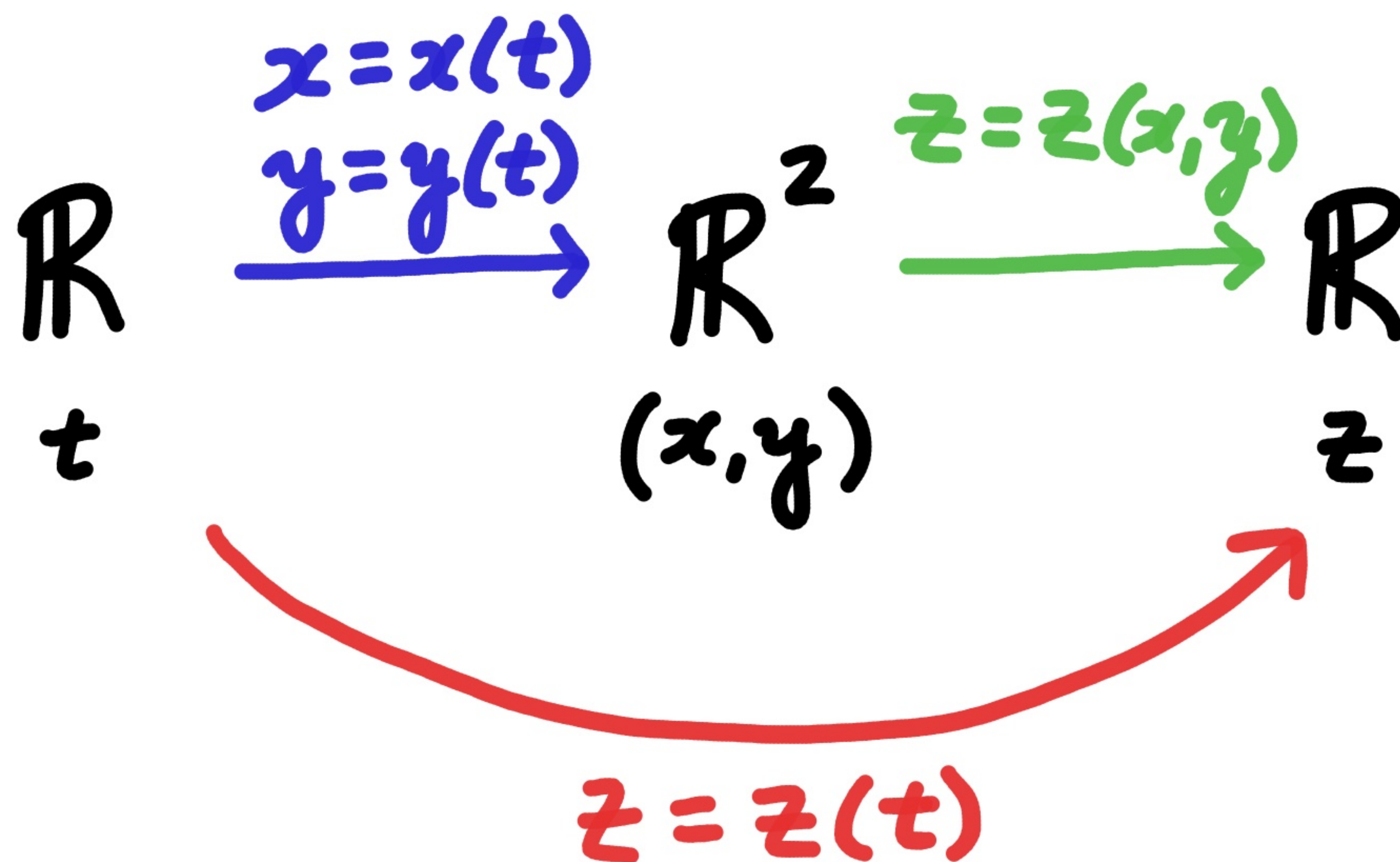
$\mathbb{R}$
 t

$\mathbb{R}^2$
 (x, y)

$\mathbb{R}$
 z

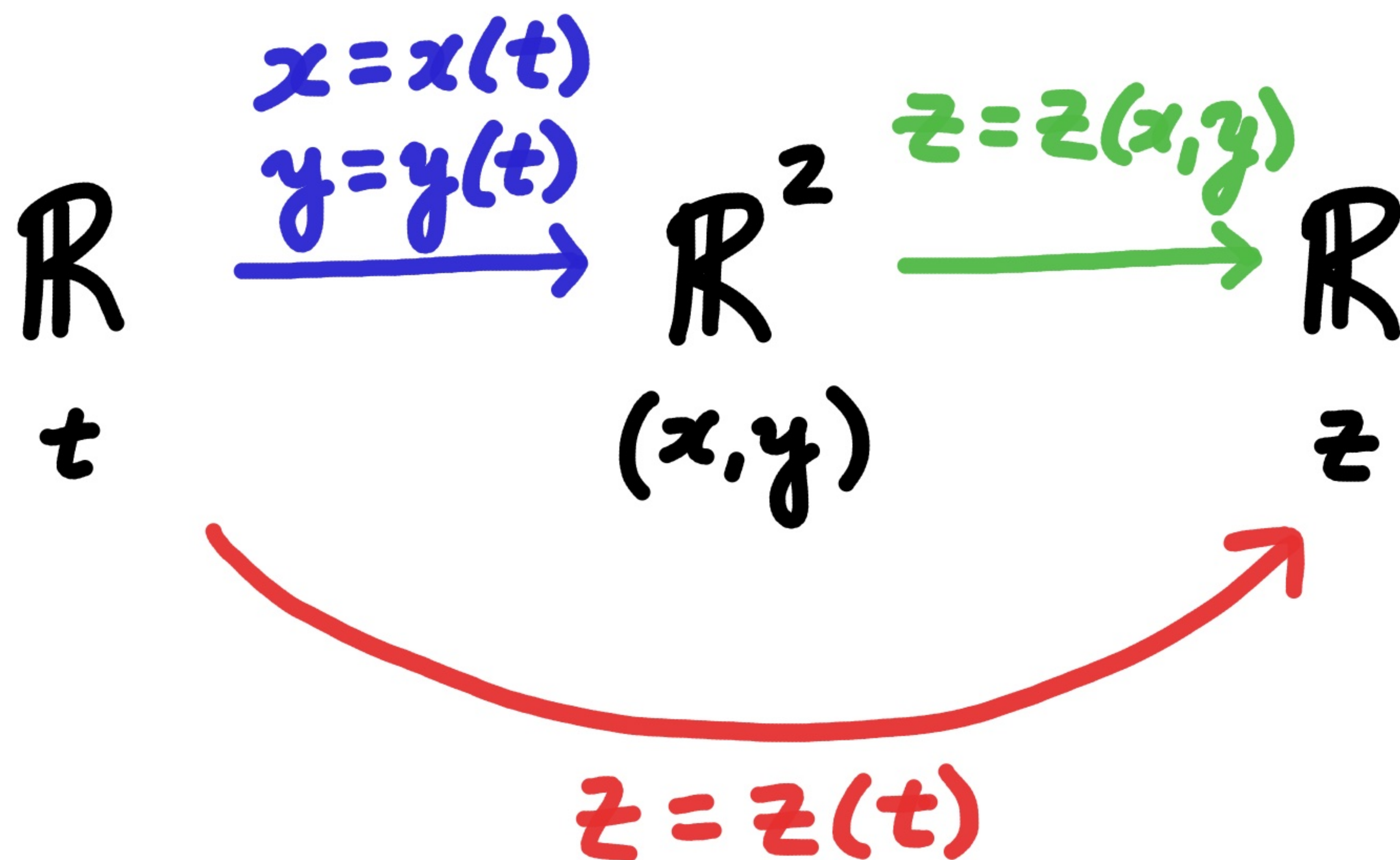
$$\begin{array}{ccccc} \mathbb{R} & \xrightarrow[\text{blue}]{\substack{x=x(t) \\ y=y(t)}} & \mathbb{R}^2 & \xrightarrow[\text{green}]{z=z(x,y)} & \mathbb{R} \\ t & & (x,y) & & z \end{array}$$





Chain rule:

$$\frac{dz}{dt} = \left(\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y} \right) \begin{pmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{pmatrix}$$



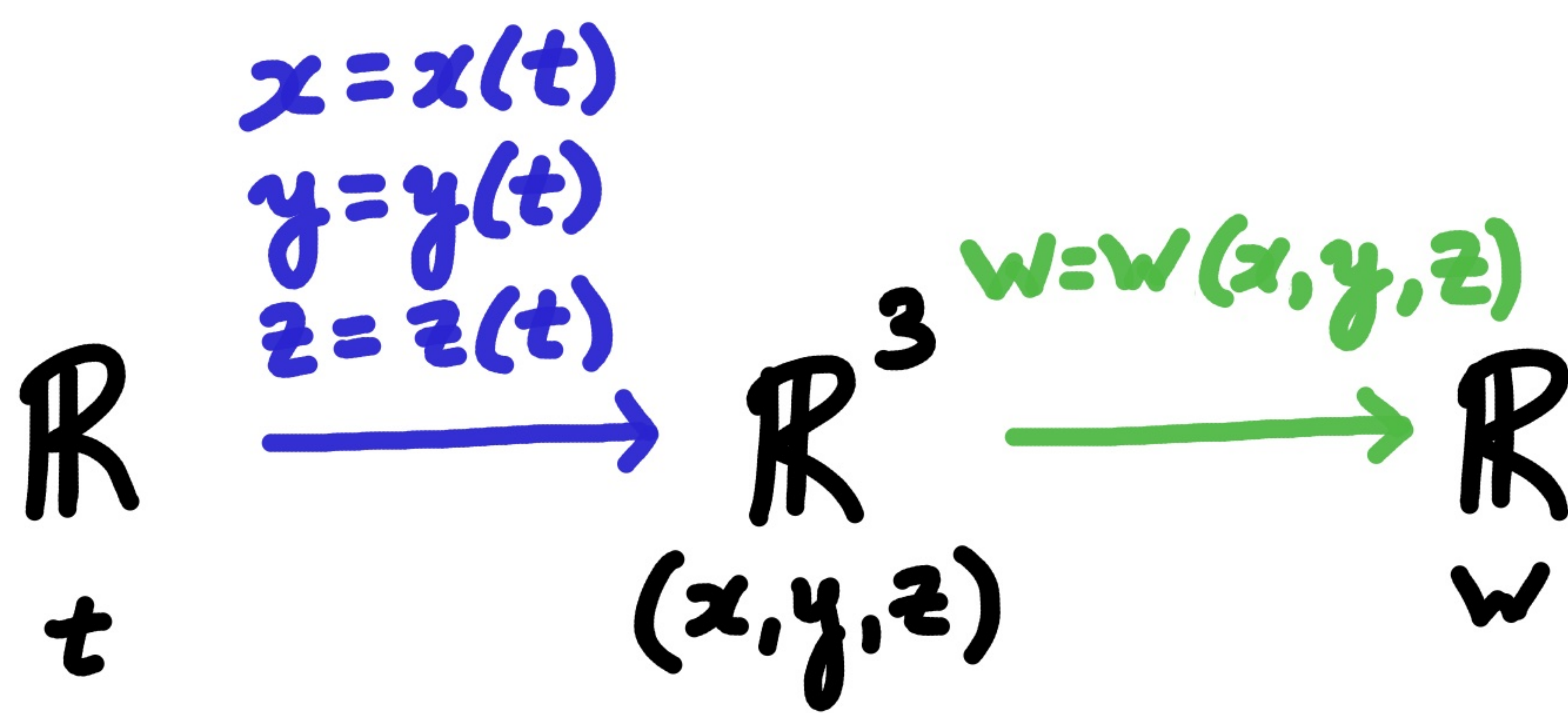
Chain rule:

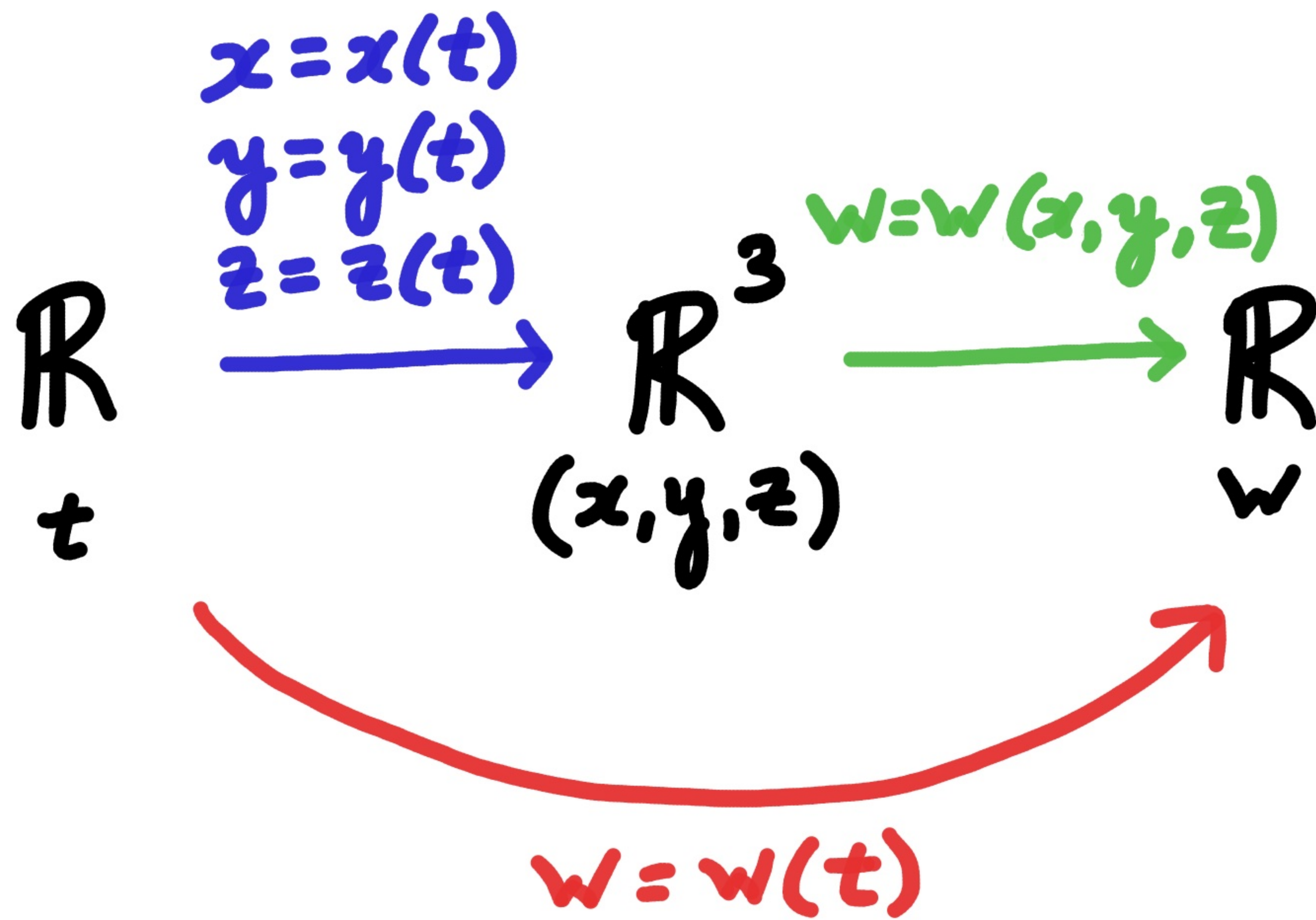
$$\frac{dz}{dt} = \left(\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y} \right) \begin{pmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{pmatrix} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$$

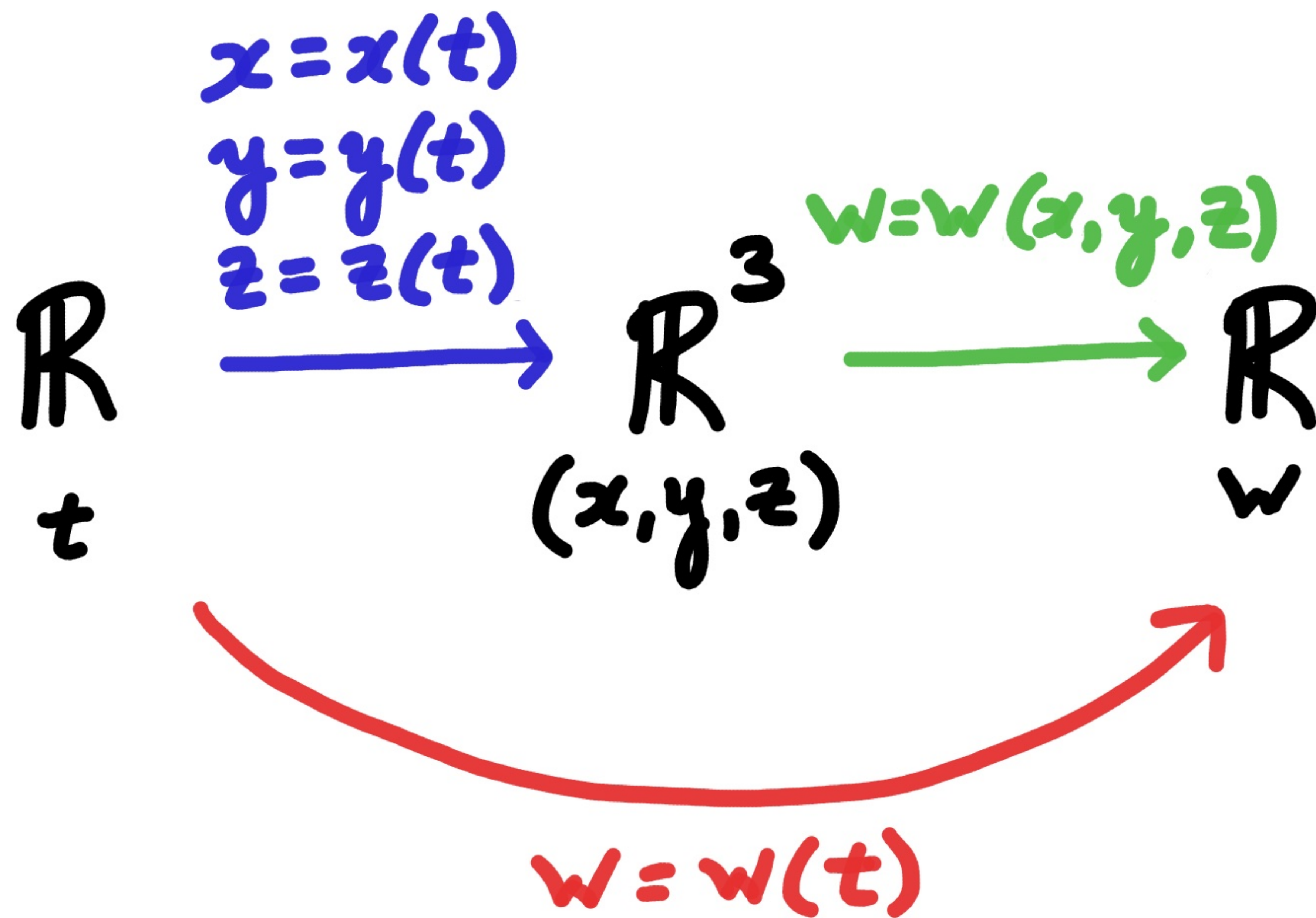
$\mathbb{R}$
 t

$\mathbb{R}^3$
 (x, y, z)

$\mathbb{R}$
 w

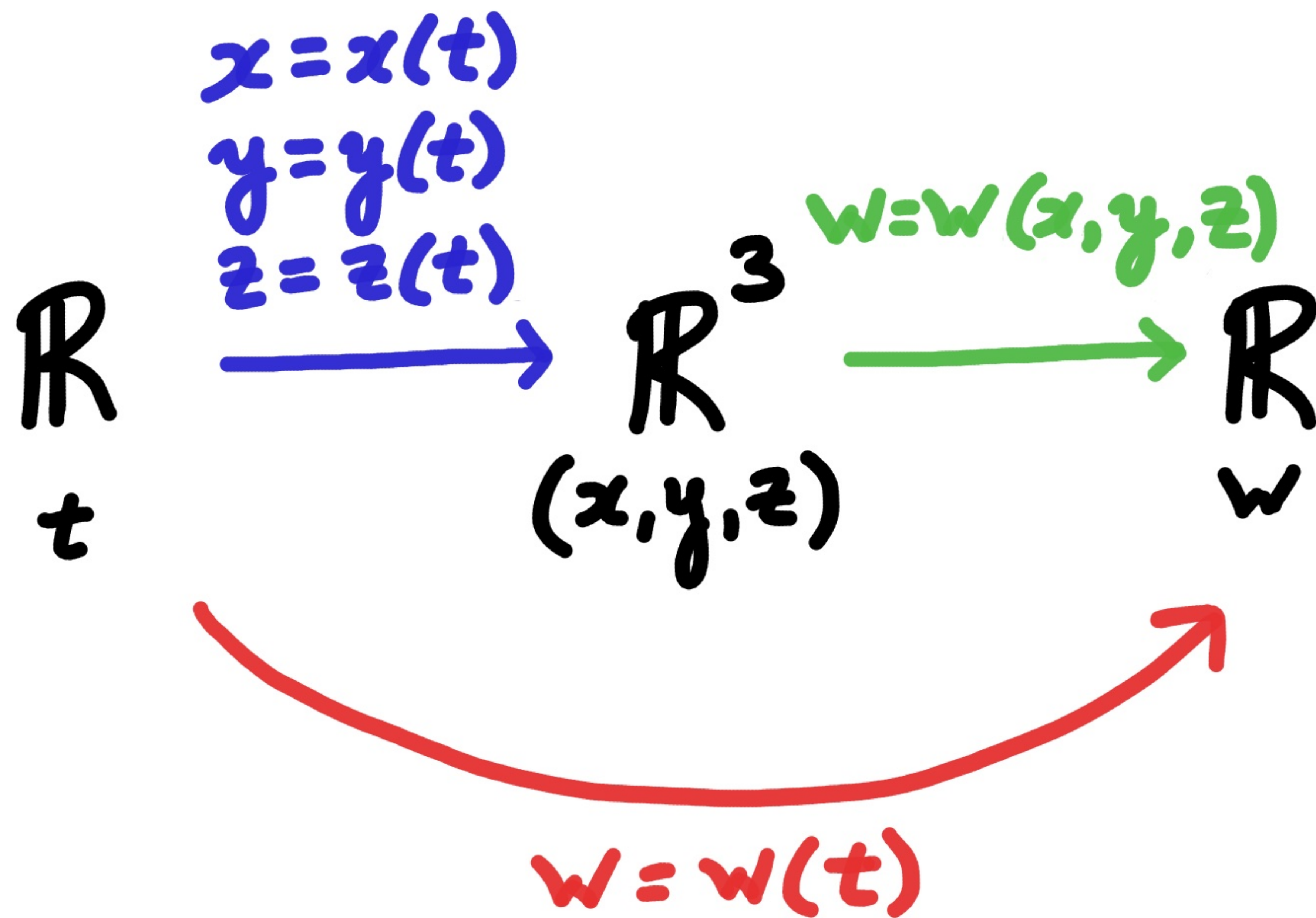






Chain rule:

$$\frac{dw}{dt} = \left(\frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}, \frac{\partial w}{\partial z} \right) \begin{pmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \\ \frac{dz}{dt} \end{pmatrix}$$



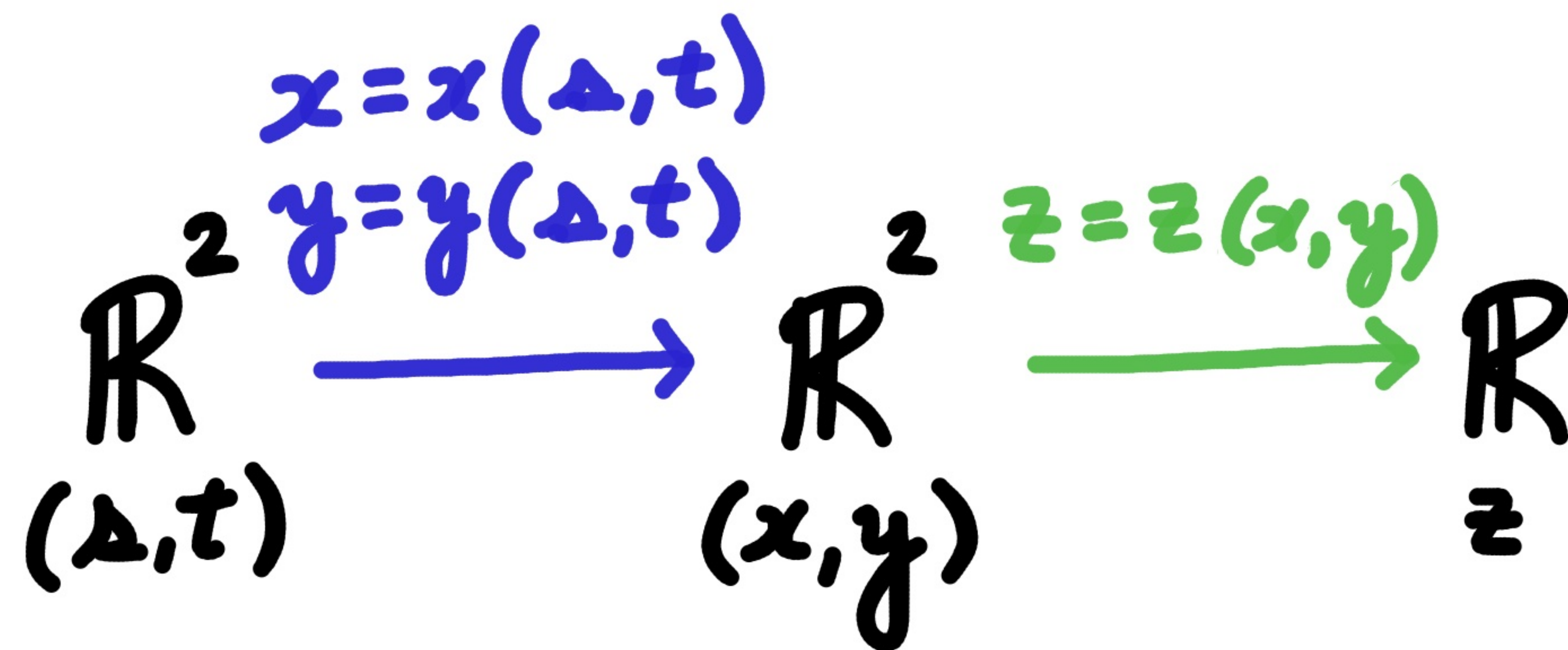
Chain rule:

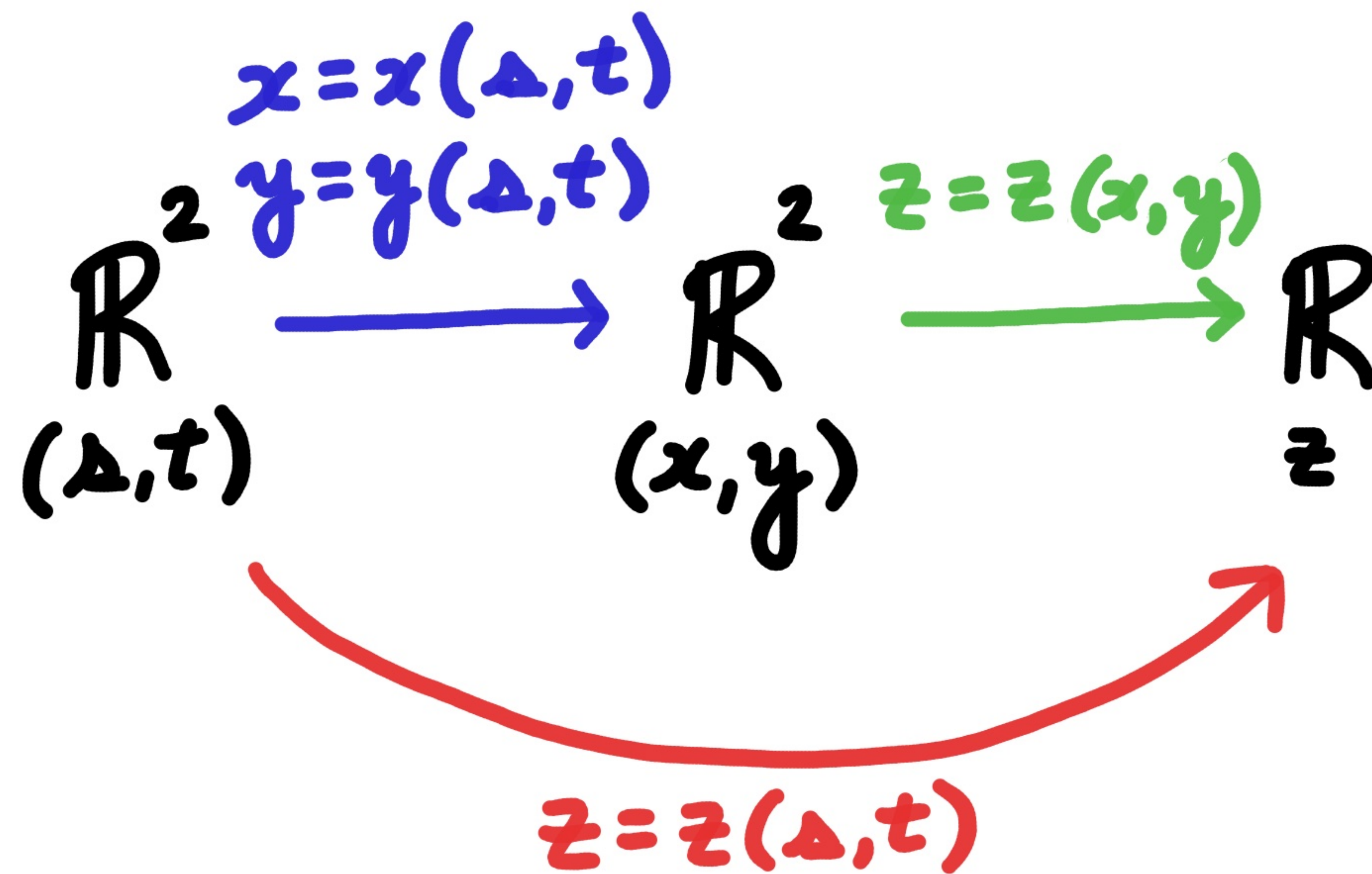
$$\frac{dw}{dt} = \left(\frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}, \frac{\partial w}{\partial z} \right) \begin{pmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \\ \frac{dz}{dt} \end{pmatrix} = \frac{\partial w}{\partial x} \frac{dx}{dt} + \frac{\partial w}{\partial y} \frac{dy}{dt} + \frac{\partial w}{\partial z} \frac{dz}{dt}$$

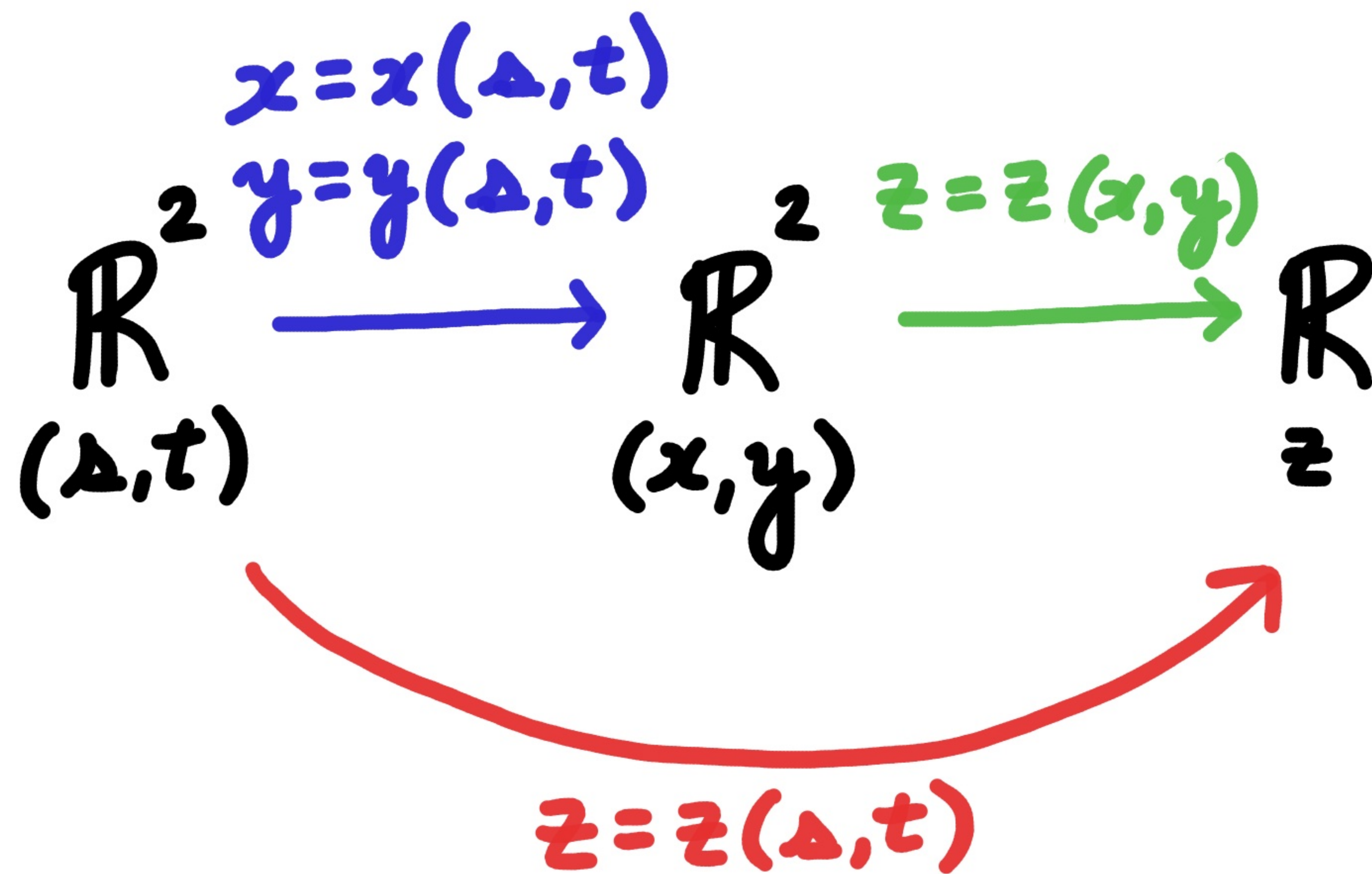
$$\mathbb{R}^2_{(\Delta, t)}$$

$$\mathbb{R}^2_{(x, y)}$$

$$\mathbb{R}_z$$

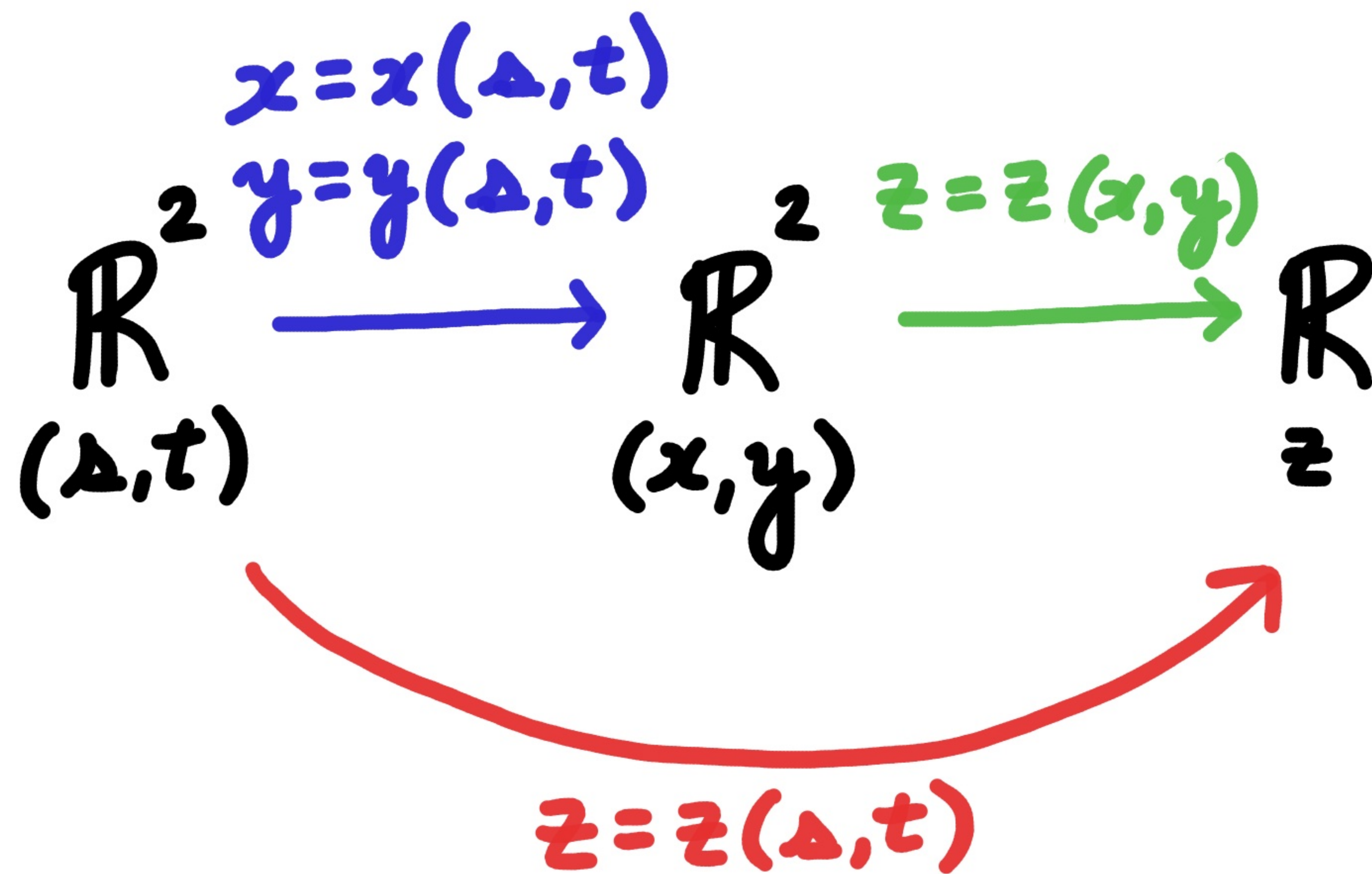






Chain rule:

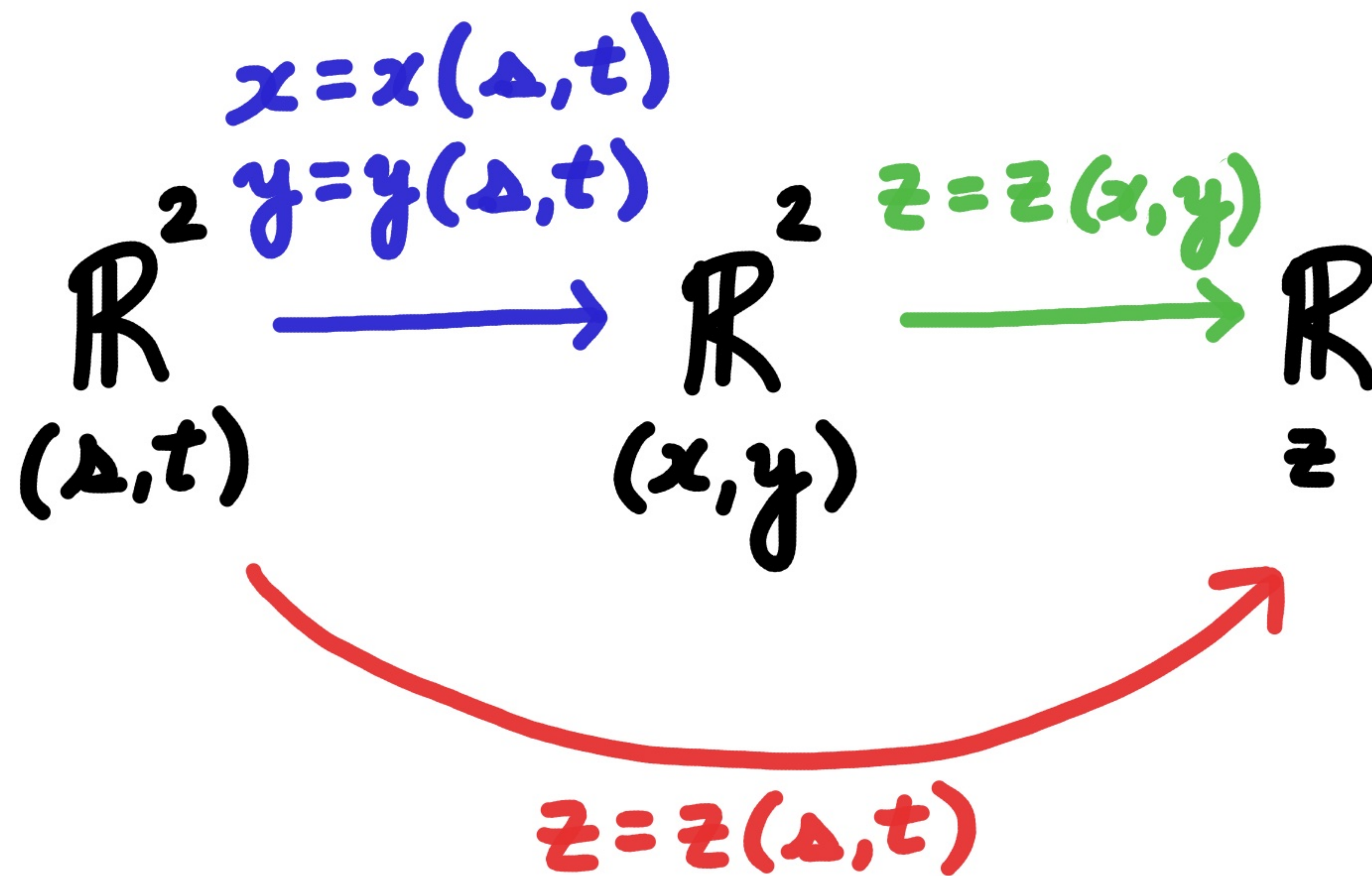
$$\left(\frac{\partial z}{\partial \Delta}, \frac{\partial z}{\partial t} \right) = \left(\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y} \right) \begin{pmatrix} \frac{\partial x}{\partial \Delta} & \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial \Delta} & \frac{\partial y}{\partial t} \end{pmatrix}$$



Chain rule:

$$\left(\frac{\partial z}{\partial \Delta}, \frac{\partial z}{\partial t} \right) = \left(\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y} \right) \begin{pmatrix} \frac{\partial x}{\partial \Delta} & \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial \Delta} & \frac{\partial y}{\partial t} \end{pmatrix}$$

$$= \left(\frac{\partial z}{\partial x} \frac{\partial x}{\partial \Delta} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial \Delta}, \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t} \right)$$



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$$= \left(\frac{\partial z}{\partial x} \frac{\partial x}{\partial \Delta} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial \Delta}, \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t} \right)$$

Problem:

Suppose $z = xy$, $x = 2t + 1$, and $y = t^2$.

Find $\frac{dz}{dt}$ as a function of t using the chain rule.

Solution:

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Solution:

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial z}{\partial y} \cdot \frac{dy}{dt}$$

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Solution:

$$\begin{aligned}\frac{dz}{dt} &= \frac{\partial z}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial z}{\partial y} \cdot \frac{dy}{dt} \\ &= y \cdot 2 + x \cdot 2t\end{aligned}$$

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$$= t^2 \cdot 2 + (2t + 1) \cdot 2t$$

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$$= t^2 \cdot 2 + (2t + 1) \cdot 2t$$

$$= 6t^2 + 2t$$

Problem:

Suppose $z = xy$, $x = t + \Delta$, and $y = \Delta t^2$.

Find $\frac{\partial z}{\partial t}$ as a function of Δ and t using the chain rule.

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$$= \Delta t^2 + (t + \Delta) \cdot 2\Delta t$$

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$$= y \cdot 1 + x \cdot 2\Delta t$$

$$= \Delta t^2 + (t + \Delta) \cdot 2\Delta t$$

$$= 3\Delta t^2 + 2\Delta^2 t$$