

A <u>Vector Field</u> on a domain in space or in the plane is a function that assigns a vector to each point in the space.

EX 1 a) Attach a projectile's velocity vector to each point of its trajectory.

Domain: trajectory Range: velocity field

b) Attach the gradient vector of a function to each point in the function's domain.

c) Attach a velocity vector to each point of a 3-D fluid flow.

EX 2 Plot the vector fields for each of these vector functions.

a)
$$\vec{F}(x, y) = x\hat{i} + y\hat{j}$$

b)
$$\vec{F}(x, y) = \frac{x\hat{i} + y\hat{j}}{\sqrt{x^2 + y^2}}$$

c)
$$\vec{F}(x,y) = \frac{-y\hat{i} + x\hat{j}}{\sqrt{x^2 + y^2}}$$

d)
$$\vec{F}(x,y) = \frac{-(x\hat{i}+y\hat{j})}{(x^2+y^2)^{3/2}}$$

Scalar fieldVector field
$$f: \mathbb{R}^3 \rightarrow \mathbb{R}$$
 $\vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ $(x, y, z) \rightarrow f(x, y, z)$ $(x, y, z) \rightarrow \langle M, N, P \rangle$ where $M = M(x, y, z)$ $N = N(x, y, z)$ $N = N(x, y, z)$ $P = P(x, y, z)$ $P = P(x, y, z)$ Gradient of scalar fieldDivergence of vector field $\nabla f(x, y, z) = \frac{\partial f}{\partial x}\hat{i} + \frac{\partial f}{\partial y}\hat{j} + \frac{\partial f}{\partial z}\hat{k}$ $\nabla \cdot \vec{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$ (scalar)

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix}$$
$$= \hat{i} \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) - \hat{j} \left(\frac{\partial P}{\partial x} - \frac{\partial M}{\partial z} \right) + \hat{k} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right)$$

Think of ∇ as a vector-valued operator.

Then
$$\nabla = \frac{\partial}{\partial x}\hat{i} + \frac{\partial}{\partial y}\hat{j} + \frac{\partial}{\partial z}\hat{k}$$

 $div \vec{F} = \nabla \cdot \vec{F}$
 $= \left(\frac{\partial}{\partial x}\hat{i} + \frac{\partial}{\partial y}\hat{j} + \frac{\partial}{\partial z}\hat{k}\right) \cdot \left(M\hat{i} + N\hat{j} + P\hat{k}\right)$
 $= \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$
 $curl \vec{F} = \nabla \times \vec{F} = \begin{vmatrix}\hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P\end{vmatrix}$

<u>Note</u>: If \vec{F} is a velocity field for a fluid, then $div \vec{F}$ measures the tendency to diverge away from/toward a point.

 $div \vec{F} > 0$ away

 $\operatorname{div} \vec{F} < 0$ toward

 $curl \vec{F}$ - the direction about which the fluid rotates most rapidly.

 $||curl \vec{F}||$ = speed of this rotation

EX 3 Let
$$\vec{F}(x, y, z) = e^x \cos y\hat{i} + e^x \sin y\hat{j} + z\hat{k}$$

find
 $\nabla \cdot \vec{F}$
 $\nabla \times \vec{F}$

EX 4 Show that

a)
$$\nabla \cdot (\nabla \times \vec{F}) = 0$$
 for any $\vec{F}(x,y,z)$

b)
$$\nabla \times (\nabla f) = \vec{0}$$
 for any $f(x,y,z)$

A vector field is called <u>conservative</u> if

$$\overline{F}(x, y, z) = \nabla f(x, y, z)$$
 for some $f : \mathbb{R}^3 \to \mathbb{R}$

then f is called the <u>potential function</u>.

EX 5 Let
$$\vec{F}(x, y, z) = \frac{-c\vec{r}}{\|\vec{r}\|^3}$$

 $f(x, y, z) = \frac{c}{\sqrt{x^2 + y^2 + z^2}}$

show that

$$\vec{F} = \nabla f$$