

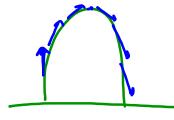
A <u>Vector Field</u> on a domain in space or in the plane is a function that assigns a vector to each point in the space.

input: pt (x,y,z) output: vector

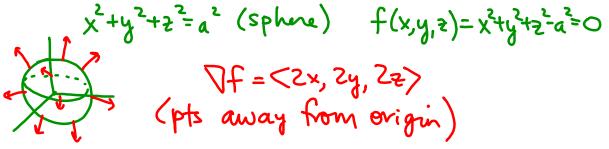
EX 1 a) Attach a projectile's velocity vector to each point of its trajectory.

Domain: trajectory

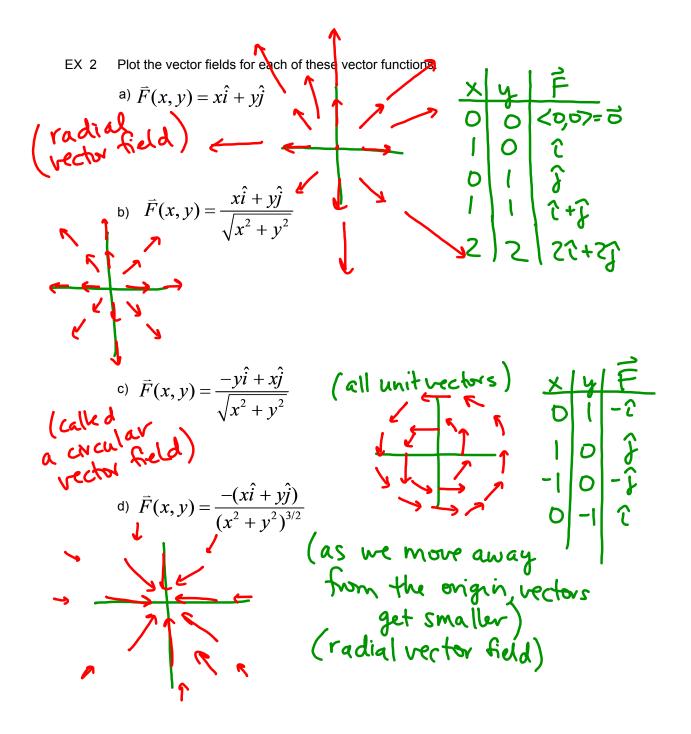
Range: velocity field



b) Attach the gradient vector of a function to each point in the function's domain.



c) Attach a velocity vector to each point of a 3-D fluid flow.



$$\begin{array}{c} \begin{array}{c} \mbox{Scalar field} \\ f; \ensuremath{\mathbb{R}}^{3} \rightarrow \ensuremath{\mathbb{R}} \\ (x,y,z) \rightarrow f(x,y,z) \\ \mbox{cnput:} 3 \mbox{-} d \\ \mbox{number} \end{array} \qquad \begin{array}{c} \mbox{Vector field} \\ \hline F: \ensuremath{\mathbb{R}}^{3} \rightarrow \ensuremath{\mathbb{R}} \\ (x,y,z) \rightarrow \langle M, N, P \rangle \\ \mbox{input:} (x,y,z$$

Think of ∇ as a vector-valued operator.

Then
$$\nabla = \frac{\partial}{\partial x}\hat{i} + \frac{\partial}{\partial y}\hat{j} + \frac{\partial}{\partial z}\hat{k}$$

$$Vf(x,y,z) = \underbrace{\partial \xi}_{x}\hat{c} + \underbrace{\partial \xi}_{y}\hat{j} + \underbrace{\partial \xi}_{z}\hat{k}$$

$$F = M\hat{c} + N\hat{j} + P\hat{c},$$

$$= \left(\frac{\partial}{\partial x}\hat{i} + \frac{\partial}{\partial y}\hat{j} + \frac{\partial}{\partial z}\hat{k}\right) \cdot (M\hat{i} + N\hat{j} + P\hat{k})$$

$$M = M(x,y,z)$$

$$N = N(x,y,z)$$

$$N = N(x,y,z)$$

$$P = P(x,y,z)$$

$$Curl \vec{F} = \nabla \times \vec{F} = \begin{vmatrix}\hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P\end{vmatrix}$$

<u>Note</u>: If \vec{F} is a velocity field for a fluid, then $div \vec{F}$ measures the tendency to diverge away from/toward a point.

$$\begin{array}{c} O \\ div \ \vec{F} > 0 \ away \\ O \\ div \ \vec{F} < 0 \ toward \\ curl \ \vec{F} < 0 \ toward \\ curl \ \vec{F} - the \ direction \ about \ which \ the \ fluid \ rotates \ most \ rapidly. \\ \|curl \ \vec{F}\| = \text{speed of this rotation} \\ for \ vector \ field \ to \\ rotate \ about \ a \ gren \\ Pt \end{array}$$

EX 3 Let
$$\overline{F}(x, y, z) = e^x \cos y\hat{i} + e^x \sin y\hat{j} + z\hat{k}$$

find
 $\nabla \cdot \overline{F}$
 $\nabla \cdot \overline{F} = dN \overline{F} = \left(\frac{\partial}{\partial x}\hat{i} + \frac{\partial}{\partial y}\hat{j} + \frac{\partial}{\partial z}\hat{k}\right) \cdot \left(e^x \cos y\hat{i} + e^x \sin y\hat{j} + z\hat{k}\right)$
 $= \frac{\partial}{\partial x}(e^x \cos y) + \frac{\partial}{\partial y}(e^x \sin y) + \frac{\partial}{\partial z}(z)$
 $= e^x \cos y + e^x \cos y + 1$
 $\nabla x\overline{F} = \left(\begin{array}{c} 1 & F \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ e^x \cos y & e^x \sin y \end{array}\right)$
 $= \hat{i} \left(\frac{\partial x}{\partial y} - \frac{\partial}{\partial z}(e^x \sin y)\right) - \hat{j} \left(\frac{\partial x}{\partial x} - \frac{\partial}{\partial z}(e^x \cos y)\right)$
 $+ \hat{k} \left(\frac{\partial}{\partial x}(e^x \sin y) - \frac{\partial}{\partial y}(e^x \cos y)\right)$
 $= \hat{i} \left(D\right) - \hat{j} \left(D\right) + \hat{k} \left(e^x \sin y + e^x \sin y\right)$
 $\nabla x\overline{F} = Ze^x \sin y \hat{k}$

EX 4 Show that
a)
$$\nabla \cdot (\nabla \times \overline{F}) = 0$$
 for any $\overline{F}(x,y,z)$ $\overline{F}(x,y,z) = m(x,y,z) T^{1}$
 $+N(x,y,z) T^{2}$
b) $\nabla \times (\nabla f) = 0$ for any $f(x,y,z)$ $+ P(x,y,z) T^{2}$
(a) $\nabla \cdot (\nabla \times \overline{F}) = dw (uv T \overline{F}) = 0$
 $\nabla \times \overline{F} = \hat{T} \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z}\right) - \hat{T} \left(\frac{\partial P}{\partial x} - \frac{\partial m}{\partial z}\right) + \hat{T} \left(\frac{\partial N}{\partial x} - \frac{\partial m}{\partial y}\right)$
 $\nabla \cdot (\nabla \times \overline{F}) = \frac{\partial}{\partial x} \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z}\right) + \frac{\partial}{\partial z} \left(\frac{\partial P}{\partial x} - \frac{\partial m}{\partial z}\right)$
 $= \frac{\partial^{2} P}{\partial x \partial y} - \frac{\partial^{2} N}{\partial z \partial z} + \frac{\partial^{2} N}{\partial y \partial z} + \frac{\partial m}{\partial z \partial y}$
 $= \frac{\partial^{2} P}{\partial x \partial y} - \frac{\partial^{2} N}{\partial x \partial z} - \frac{\partial^{2} P}{\partial y \partial x} + \frac{\partial m}{\partial z \partial y}$
 $= 0$ (as long as \overline{F} is "nice")
 $i \cdot e = \frac{\partial^{2} m}{\partial x \partial y} = \frac{\partial^{2} m}{\partial y \partial x}$
(b) given fn $f(x,y,z)$
 $\nabla \times (\nabla f) = cur L (\nabla f) = \overline{O} (claim)$
 $\nabla f = f_{x} \hat{T} + f_{y} \hat{J} + f_{z} \hat{F}$
 $\nabla \times (\nabla f) = \begin{vmatrix} \hat{T} & \hat{J} & \hat{F} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{vmatrix}$
 $= \hat{D} \left(f_{zx} - f_{xz}\right)$
 $+ \hat{F} (f_{yx} - f_{xy}) = \overline{D}$

A vector field is called <u>conservative</u> if

$$\overline{F}(x, y, z) = \nabla f(x, y, z)$$
 for some $f : \mathbb{R}$

then f is called the <u>potential function</u>.

(also known as
gradrent vector

$$\mathbb{R}^3 \rightarrow \mathbb{R}$$
 field)
 f is a function
that maps from
 (X,Y,Z) to a #

EX 5 Let
$$\vec{F}(x, y, z) = \frac{-c\vec{r}}{\|\vec{r}\|^3}$$

$$f(x, y, z) = \frac{c}{\sqrt{x^2 + y^2 + z^2}} = c (x^2 + y^2 + z^2)^{-1/2}$$

show that

$$\overline{F} = \nabla f$$

$$\nabla f = f_{x} \hat{\tau} + f_{y} \hat{j} + f_{z} \hat{k} = \frac{1}{2} c (x^{2} + y^{2} + z^{2})^{3} (2x \hat{\tau} + 2y \hat{j} + z \hat{k})$$

$$= \frac{-c}{\sqrt{(x^{2} + y^{2} + z^{2})^{3}}} (x \hat{\tau} + y \hat{j} + z \hat{k})$$

$$rote: \overline{F} = \langle x, y, z \rangle = x \hat{\tau} + y \hat{j} + z \hat{k}$$

$$||\overline{F}|| = \sqrt{x^{2} + y^{2} + z^{2}}$$

$$\nabla f = \frac{-c(\overline{F})}{||\overline{F}||^{3}} = \overline{F} /$$