

Math 2280 - Lecture 29

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A few lectures ago we learned that the Laplace transform is linear, which can enormously simplify the calculation of Laplace transforms for sums and scalar multiples of functions. The next natural question is what relations, if any, are there for Laplace transforms of products? It might be “nice” if

$$\mathcal{L}(f(t) \cdot g(t)) = \mathcal{L}(f(t)) \cdot \mathcal{L}(g(t))^1$$

But we can see right away that this would be ridiculous:

$$\frac{1}{s} = \mathcal{L}(1) = \mathcal{L}(1 \cdot 1) = \mathcal{L}(1) \cdot \mathcal{L}(1) = \frac{1}{s^2}.$$

That ain’t right. So, we must state that, in general

$$\mathcal{L}(f(t) \cdot g(t)) \neq \mathcal{L}(f(t)) \cdot \mathcal{L}(g(t)).$$

So, that doesn’t work, and the question remains. Namely, what, if any, relation is there between products and Laplace transforms? It turns out there is an operation called the *convolution* of two functions, and this operation will give us the best answer to our question.

¹This is NOT true. Not true, not true, not true. Don’t memorize this because it’s NOT TRUE.

In addition to convolutions, today we'll also discuss derivatives and integrals of Laplace transforms, and how they relate to inverse Laplace transforms.

Today's lecture corresponds with section 7.4 of the textbook, and the assigned problems are:

Section 7.4 - 1, 5, 10, 19, 31

Convolutions and Products of Transforms

To answer our question about products and Laplace transforms we first need to define an operator called *convolution*. The convolution of two functions $f(t)$ and $g(t)$ is denoted by $f(t) * g(t)$, and is defined by:

$$f(t) * g(t) = \int_0^t f(\tau)g(t - \tau)d\tau.$$

We note that it's a straightforward if tedious task to verify that the operator is commutative and associative.

Example - Calculate the convolution:

$$t^2 * \cos t.$$

More room for the example problem.

Now, why are these convolutions important? Well, as you might expect, they relate to products of Laplace transforms in a big way. This relation is given by the next theorem.

Theorem - Suppose that $f(t)$ and $g(t)$ are piecewise continuous for $t \geq 0$ and that $|f(t)|$ and $|g(t)|$ are bounded by Me^{ct} as $t \rightarrow \infty$. Then the Laplace transform of $f * g$ exists for $s > c$, and

$$\mathcal{L}(f(t) * g(t)) = \mathcal{L}(f(t)) \cdot \mathcal{L}(g(t)).$$

Example - Calculate the inverse Laplace transform of:

$$F(s) = \frac{1}{s(s^2 + 1)}.$$

Derivatives and Integrals of Laplace Transforms

Finally, just as there are relations for the Laplace transform of a derivative, there are relations for the derivative of a Laplace transform. These are:

$$\mathcal{L}(t \cdot f(t)) = -F'(s),$$

and in greater generality

$$\mathcal{L}(t^n \cdot f(t)) = (-1)^n F^{(n)}(s).$$

Also, conversely

$$\mathcal{L}\left(\frac{f(t)}{t}\right) = \int_s^\infty F(\sigma) d\sigma.$$

Deriving these relations is fairly straightforward, and is done at the end of section 7.4 from the textbook.

Example - Calculate the Laplace transform:

$$\mathcal{L}(t \sin(3t)).$$

Example - Calculate the Laplace transform:

$$\mathcal{L}\left(\frac{e^{3t} - 1}{t}\right).$$

Notes on Homework Problems

Problems 7.4.1 and 7.4.5 are exercises in calculating convolutions.

Problem 7.4.10 requires that you recognize the given Laplace transform as the product of two Laplace transforms you know. You need to then take the convolution of the two inverses of the Laplace transforms you know.

Problem 7.4.19 is a straightforward application of the theorem regarding the integral of a Laplace transform.

Problem 7.4.31 is by far the hardest problem in this section. You'll need to use the rules about Laplace transforms of derivatives, and derivatives of Laplace transforms, to find a differential equation involving the Laplace transform of $x!$ This will be a differential equation you know how to solve. Solve it, and then calculate the inverse Laplace transform. Difficult, but our first real example of how we can use Laplace transforms to solve differential equations we don't already know how to solve using other methods.