

# Math 2280 - Exam 3

University of Utah

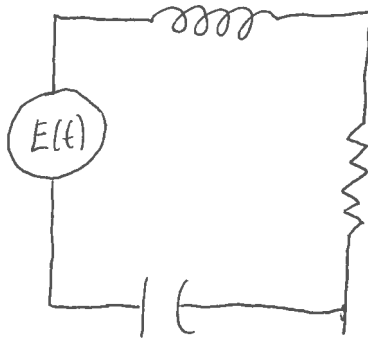
Spring 2013

Name: Solutions

This is a 50 minute exam. Please show all your work, as a worked problem is required for full points, and partial credit may be rewarded for some work in the right direction.

1. (15 points) *An RLC Circuit*

For the RLC circuit pictured below:



Calculate  $I(t)$  for the values:

$$L = 10H \quad R = 20\Omega \quad C = 0.02F$$

$$E(t) = 50 \sin 3t \text{ V}$$

More room, if necessary, for Problem 1.

$$10 Q'' + 20 Q' + \frac{1}{.02} Q = 50 \sin(3t)$$

$$Q'' + 2 Q' + 5 Q = 5 \sin(3t)$$

$$\frac{-2 \pm \sqrt{2^2 - 4(1)(5)}}{2} = -1 \pm 2i$$

$$\Rightarrow Q_h(t) = c_1 e^{-t} \cos(2t) + c_2 e^{-t} \sin(2t)$$

$$Q_p(t) = A \sin(3t) + B \cos(3t)$$

$$Q_p'(t) = 3A \cos(3t) - 3B \sin(3t)$$

$$Q_p''(t) = -9A \sin(3t) - 9B \cos(3t)$$

$$(-4A - 6B) \sin(3t) + (-4B + 6A) \cos(3t) = 5 \sin(3t)$$

$$\begin{aligned} -4A - 6B &= 5 & \Rightarrow & \quad -12A - 18B = 15 & \Rightarrow & \quad -26B = 15 \\ 6A - 4B &= 0 & \Rightarrow & \quad 12A - 8B = 0 & & \end{aligned}$$

$$B = -\frac{15}{26} \quad \frac{3}{2}A = B \Rightarrow A = \frac{2}{3}B = \frac{2}{3} \left(-\frac{15}{26}\right) = -\frac{15}{39}$$

$$\Rightarrow Q_p = -\frac{15}{39} \sin(3t) - \frac{15}{26} \cos(3t) + c_1 e^{-t} \cos(2t) + c_2 e^{-t} \sin(2t)$$

$$\Rightarrow \boxed{I(t) = -\frac{15}{13} \cos(3t) + \frac{45}{26} \sin(3t) + \tilde{c}_1 e^{-t} \cos(2t) + \tilde{c}_2 e^{-t} \sin(2t)}$$

2. (15 points) *An Endpoint Problem*

The eigenvalues for this problem are all nonnegative. First, determine whether  $\lambda = 0$  is an eigenvalue; then find the positive eigenvalues and associated eigenfunctions.

$$y'' + \lambda y = 0;$$

$$y'(-\pi) = 0 \quad y'(\pi) = 0.$$

$$\lambda = 0$$

$$y(x) = Ax + B$$

$$y'(x) = A$$

$$y'(-\pi) = y'(\pi) = 0 \Rightarrow A = 0$$

So,  $y(x) = B$  and

$\lambda = 0$  is an eigenvalue with eigenfunction

$$y(x) = 1.$$

$$\lambda > 0$$

$$y(x) = A \cos(\sqrt{\lambda} x) + B \sin(\sqrt{\lambda} x)$$

~~$y'(x)$~~

$$y'(x) = -\sqrt{\lambda} A \sin(\sqrt{\lambda} x) + \sqrt{\lambda} B \cos(\sqrt{\lambda} x)$$

~~$y'(x)$~~

$$y'(-\pi) = \sqrt{\lambda} A \sin(\sqrt{\lambda} \pi) + \sqrt{\lambda} B \cos(\sqrt{\lambda} \pi) = 0$$

$$y'(\pi) = -\sqrt{\lambda} A \sin(\sqrt{\lambda} \pi) + \sqrt{\lambda} B \cos(\sqrt{\lambda} \pi) = 0$$

$$\Rightarrow 2\sqrt{\lambda} B \cos(\sqrt{\lambda} \pi) = 0$$

True if  $B = 0$  or if

$\cos(\sqrt{\lambda} \pi) = 0$ . Now,  $\cos(t) = 0$  for  $t = \frac{\pi}{2}, \frac{3\pi}{2}, \frac{5\pi}{2}, \dots$

$$\Rightarrow \sqrt{\lambda} = \frac{2n+1}{2} \quad n \in \mathbb{Z}$$

$$\lambda_n = \left( \frac{2n+1}{2} \right)^2$$

Note:  $A = 0$  in this case.

More room, if necessary, for Problem 2.

If  $B = 0$  then

$$\sqrt{\lambda} A \sin(\sqrt{\lambda} \pi) = 0$$

$$-\sqrt{\lambda} A \sin(\sqrt{\lambda} \pi) = 0$$

$$\Rightarrow A = 0 \text{ or}$$

$$\sin(\sqrt{\lambda} \pi) = 0$$

true if  $\sqrt{\lambda} = 0, 1, 2, \dots$

$$\text{So, } \sqrt{\lambda} = n \text{ and } \lambda = n^2.$$

So, the eigenvalues are:

$$\lambda = \left(\frac{n}{2}\right)^2 \quad n \in \mathbb{Z}, n > 0$$

with eigenfunctions

~~$$\cos(\sqrt{\lambda} x)$$~~

~~$$\cos\left(\frac{(2n+1)}{2} x\right)$$~~

$$\cos\left(\frac{n}{2} x\right) \text{ for } n \text{ odd}$$

$$\sin\left(\frac{n}{2} x\right) \text{ for } n \text{ even.}$$

3. (10 points) *Converting to First-Order Systems*

Transform the given differential equation into an equivalent system of first-order differential equations:

$$x^{(4)} + 6x'' - 3x' + x = \cos 3t$$

$$x = x_1$$

$$x_1' = x_2$$

$$x_2' = x_3$$

$$x_3' = x_4$$

$$x_4' = -6x_3 + 3x_2 - x_1 + \cos(3t)$$

So, the system is:

$$x_1' = x_2$$

$$x_2' = x_3$$

$$x_3' = x_4$$

$$x_4' = -6x_3 + 3x_2 - x_1 + \cos(3t)$$

4. (25 points) *Systems of First-Order ODEs*

Find the general solution to the system of ODEs:

$$x' = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} x + \begin{pmatrix} 5 \\ -2t \end{pmatrix}.$$

Homogeneous solution:

$$\begin{vmatrix} 2-\lambda & 3 \\ 2 & 1-\lambda \end{vmatrix} = (2-\lambda)(1-\lambda) - 6 \\ = \lambda^2 - 3\lambda - 4 = (\lambda - 4)(\lambda + 1)$$

So, eigenvalues are  $\lambda = 4, -1$

eigenvectors

$$\lambda = 4 \quad \begin{pmatrix} -2 & 3 \\ 2 & -3 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 3 \\ 2 \end{pmatrix} \text{ works}$$

$$\lambda = -1 \quad \begin{pmatrix} 3 & 3 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 1 \\ -1 \end{pmatrix} \text{ works.}$$

So,

$$x_h = c_1 \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^{4t} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t}$$

More room, if necessary, for Problem 4.

Method of undetermined coefficients:

$$\begin{aligned} \vec{x}_p &= \vec{a}t + \vec{b} \\ x_p' &= \vec{a} \end{aligned} \Rightarrow \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} a_1 t + b_1 \\ a_2 t + b_2 \end{pmatrix} + \begin{pmatrix} 5 \\ -2t \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} (2a_1 + 3a_2)t + (2b_1 + 3b_2) + 5 \\ (2a_1 + a_2)t + (2b_1 + b_2) - 2t \end{pmatrix}$$

$$\begin{aligned} 2a_1 + 3a_2 &= 0 \\ 2b_1 + 3b_2 + 5 &= a_1 \\ 2a_1 + a_2 - 2 &= 0 \\ 2b_1 + b_2 &= a_2 \end{aligned}$$

$$\begin{aligned} 2(2b_1 + 3b_2 + 5) + 3(2b_1 + b_2) &= 0 \\ 2(2b_1 + 3b_2 + 5) + (2b_1 + b_2) - 2 &= 0 \end{aligned}$$

$$\begin{aligned} 10b_1 + 9b_2 &= -10 & 60b_1 + 54b_2 &= -60 \\ 6b_1 + 7b_2 &= -8 & \Rightarrow -60b_1 - 70b_2 &= 80 \end{aligned}$$

$$-16b_2 = 20$$

$$b_2 = -\frac{5}{4}$$

$$6b_1 = -8 + \frac{35}{4}$$

$$6b_1 = \frac{-67}{4} \quad \frac{3}{4}$$

$$b_1 = \frac{-67}{24} \quad b_1 = \frac{1}{8}$$

$$\begin{aligned} a_1 &= 2\left(\frac{1}{8}\right) + 3\left(-\frac{5}{4}\right) + 5 \\ &= \frac{1}{4} - \frac{15}{4} + \frac{20}{4} = \frac{3}{2} \end{aligned}$$

$$a_2 = 2\left(\frac{1}{8}\right) - \frac{5}{4} = \frac{1}{4} - \frac{5}{4} = -1$$

$$\vec{x}_p = \begin{pmatrix} \frac{3}{2} \\ -1 \end{pmatrix} t + \begin{pmatrix} \frac{1}{8} \\ -\frac{5}{4} \end{pmatrix}$$

$$\vec{x} = \begin{pmatrix} \frac{3}{2} \\ -1 \end{pmatrix} t + \begin{pmatrix} \frac{1}{8} \\ -\frac{5}{4} \end{pmatrix} + c_1 \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^{4t} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t}$$

$$a_1 = 2\left(\frac{-67}{24}\right)$$



5. (20 points) *Multiple Eigenvalues*<sup>1</sup>

Find the general solution to the system of ODEs:

$$x' = \begin{pmatrix} 7 & 1 \\ -4 & 3 \end{pmatrix} x.$$

$$\begin{vmatrix} 7-\lambda & 1 \\ -4 & 3-\lambda \end{vmatrix} = \lambda^2 - 10\lambda + 25 = (\lambda - 5)^2$$

$\lambda = 5, 5$  repeated eigenvalue

$$\begin{pmatrix} 2 & 1 \\ -4 & -2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 1 \\ -2 \end{pmatrix} \text{ works. Only one!}$$

$$\begin{pmatrix} 2 & 1 \\ -4 & -2 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ -4 & -2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} !$$

So, try  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$$\begin{pmatrix} 2 & 1 \\ -4 & -2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -4 \end{pmatrix}$$

So, solution is:

$$\vec{x} = c_1 \begin{pmatrix} 2 \\ -4 \end{pmatrix} e^{5t} + c_2 \left[ \begin{pmatrix} 2 \\ -4 \end{pmatrix} t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right] e^{5t}$$

<sup>1</sup>This is a hint.

More room, if necessary, for Problem 5.

6. (15 points) *Matrix Exponentials*

Calculate the matrix exponential  $e^A$  for the matrix:

$$\begin{pmatrix} 2 & 0 & 0 \\ 3 & 1 & 0 \\ 4 & 3 & 1 \end{pmatrix}.$$

$$\begin{pmatrix} 2 & 0 & 0 \\ 3 & 1 & 0 \\ 4 & 3 & 1 \end{pmatrix} = \underbrace{\begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}}_B + \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 3 & 0 & 0 \\ 4 & 3 & 0 \end{pmatrix}}_C$$

$$C^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 9 & 0 & 0 \end{pmatrix} \quad C^3 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$BC = CB$  as  $B$  is diagonal

$$e^B = \begin{pmatrix} e^2 & 0 & 0 \\ 0 & e & 0 \\ 0 & 0 & e \end{pmatrix} \quad e^C = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 0 & 0 \\ 3 & 0 & 0 \\ 4 & 3 & 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 9 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow e^A = e^B e^C = \begin{pmatrix} e^2 & 0 & 0 \\ 0 & e & 0 \\ 0 & 0 & e \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ \frac{17}{2} & 3 & 1 \end{pmatrix} = \boxed{\begin{pmatrix} e^2 & 0 & 0 \\ 3e & e & 0 \\ \frac{17}{2}e & 3e & e \end{pmatrix}}$$