# Math 2270 - Practice Exam 4

University of Utah

#### Fall 2012

Key Name: \_\_

This is a 50 minute exam. Please show all your work, as a worked problem is required for full points, and partial credit may be rewarded for some work in the right direction.

## 1. Cofactor Matrices (15 points)

Calculate the cofactor matrix of *A*:

$$A = \left(\begin{array}{cc} 4 & 3\\ 2 & 8 \end{array}\right)$$

$$C = \begin{pmatrix} 8 & -2 \\ -3 & 4 \end{pmatrix}$$

# 2. *Eigenvalues* (20 points)

Find the eigenvalues and the corresponding eigenvectors of

$$\begin{vmatrix} 2-\lambda & -|2 \\ 1 & -S-\lambda \end{vmatrix} = (2-\lambda)(-S-\lambda) - (-|1\rangle)(1) \\ = \lambda^{2} + 3\lambda + 2 = (\lambda+2)(\lambda+1) \\ So, \quad eigenvalues \quad \lambda = -1, -2 \\ \lambda = -1 \begin{pmatrix} 3 & -12 \\ 1 & -4 \end{pmatrix} \begin{pmatrix} \chi_{1} \\ \chi_{2} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \vec{X} = \begin{pmatrix} 4 \\ 1 \end{pmatrix} \\ \lambda = -2 \begin{pmatrix} 4 & -12 \\ 1 & -3 \end{pmatrix} \begin{pmatrix} \chi_{1} \\ \chi_{2} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \vec{X} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \\ \vec{X} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \\ \vec{X} = \begin{pmatrix} 4 \\ 1 \end{pmatrix} \\ \vec{X} = \begin{pmatrix} 4 \\ 1 \end{pmatrix} \\ \vec{X} = \begin{pmatrix} 4 \\ 1 \end{pmatrix} \\ \vec{X} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \\ \vec{X} = \begin{pmatrix} 4 \\ 1 \end{pmatrix} \\ \vec{X} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \\ \vec$$

#### 3. *Diagonalization* (20 points)

Diagonalize the matrix

$$A = \begin{pmatrix} 1 & 3 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$

$$\begin{vmatrix} 1 - \lambda & 3 & 0 \\ 3 & 1 - \lambda & 0 \\ 0 & 0 - 2 - \lambda \end{vmatrix} = (-2 - \lambda) [(1 - \lambda)^{2} - 9]$$

$$= (-2 - \lambda) [\chi^{2} - 2\lambda - 8]$$

$$= -(\lambda + 2)(\lambda - 4)(\lambda + 2)$$

$$\lambda^{2} = 4, -2, -2$$

$$\lambda = 4 \begin{pmatrix} -3 & 3 & 0 \\ 3 & -3 & 0 \\ 0 & 0 - 6 \end{pmatrix} \begin{pmatrix} \chi_{1} \\ \chi_{2} \\ \chi_{3} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \chi^{2} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\lambda = -2 \begin{pmatrix} 3 & 3 & 0 \\ 3 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \chi_{1} \\ \chi_{2} \\ \chi_{3} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \chi^{2} = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} or \begin{pmatrix} 0 \\ 6 \\ 1 \end{pmatrix}$$
or the normalize 
$$\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{pmatrix}, \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

 $A = \begin{pmatrix} 1 & 3 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -2 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -2 \\ 0 &$ 

#### 4. Positive Definite Matrices (10 points)

Prove that if A is positive definite, and B is positive definite, then A + B is positive definite. (Hint - A matrix is positive definite if  $\mathbf{x}^T A \mathbf{x} > 0$  for all  $\mathbf{x} \neq 0$ .)

Suppose A and B are positive  
definite. Then  
$$\vec{x}^{\dagger}(A+B)\vec{x} = \vec{x}^{\dagger}A\vec{x} + \vec{x}^{\dagger}B\vec{x} > 0$$
  
for all  $\vec{x}$  as  $\vec{x}^{\dagger}A\vec{x}, \vec{x}^{\dagger}B\vec{x} > 0$   
for all  $\vec{x}$ .

#### 5. Jordan Form

If a matrix has eigenvalues  $\lambda = 2, 2, 1, 0$  what are all the possible Jordan forms of the matrix?

 $\begin{bmatrix}
 0 & 0 \\
 0 & 2 & 0 \\
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## 6. *Singular Value Decomposition* (20 points)

Calculate the singular value decomposition of the matrix

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$A^{T} A = \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\begin{vmatrix} 1 & -\lambda & 1 \\ 1 & 1 & -\lambda \end{vmatrix} = (1 - \lambda)^{T} - 1 = \lambda^{T} - 2\lambda = \lambda(\lambda - 2)$$

$$\lambda = 2, 0$$

$$\begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} X_{1} \\ X_{2} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \overrightarrow{X} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \overrightarrow{V_{1}} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$

$$A \overrightarrow{V}_{1} = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} \sqrt{2} \\ 0 \end{pmatrix} = \sqrt{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \overrightarrow{U_{1}} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$U_{1} = \sqrt{2}$$

$$A = V \mathcal{E} V^{T} = \begin{bmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} (\sqrt{2}) \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 0 \end{pmatrix} \xrightarrow{V_{1}}$$

#### 7. Linear Transformations (15 points)

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(a) Is the transformation  $T : \mathbb{R}^2 \to \mathbb{R}^1$  defined by

$$T(v_1, v_2) = 2v_1 + v_2$$

a linear transformation? Explain why or provide a counterexample.

$$T(u_{1}+v_{1}, u_{2}+v_{2}) = l(u_{1}+v_{1}) + u_{2}+v_{2}$$

$$= (lu_{1}+u_{2}) + (lv_{1}+v_{2}) = T(u_{1},u_{2}) + T(v_{1},v_{2})$$

$$T((v_{1}, (v_{2})) = l(v_{1}+(v_{2})) = ((lv_{1}+v_{2}))$$

$$= lT(v_{1}, v_{2}), \quad So_{1} \text{ [linear]}$$
(b) Is the transformation  $T: \mathbb{R}^{2} \to \mathbb{R}^{3}$  defined by

$$T(v_1, v_2) \rightarrow (2v_1, 3v_1 + 2v_2, v_1v_2)$$

a linear transformation? Explain why or provide a counterexample.

$$\begin{split} \vec{u} &= \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \vec{v} &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ \vec{v} &= \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \\ T (\vec{u} + \vec{v}) &= t(1,1) = (2,5,1) \\ \vec{v} \\ T (u) + t(v) &= (2,3,0) + (0,2,0) = (2,5,0) \\ So, \quad hot \quad linear \end{pmatrix}. \end{split}$$