

Math 2270 - Assignment 4

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Section 2.5 - 1, 7, 25, 27, 29

Section 2.6 - 3, 5, 7, 13, 16

Section 2.7 - 1, 12, 19, 22, 40

2.5 - Inverse Matrices

2.5.1 Find the inverses (directly or from the 2 by 2 formula) of A, B, C :

$$A = \begin{pmatrix} 0 & 3 \\ 4 & 0 \end{pmatrix} \quad B = \begin{pmatrix} 2 & 0 \\ 4 & 2 \end{pmatrix} \quad C = \begin{pmatrix} 3 & 4 \\ 5 & 7 \end{pmatrix}$$

$$A^{-1} = \frac{1}{-12} \begin{pmatrix} 0 & -3 \\ -4 & 0 \end{pmatrix} = \begin{pmatrix} 0 & \frac{3}{12} \\ \frac{4}{12} & 0 \end{pmatrix}$$

$$B^{-1} = \frac{1}{4} \begin{pmatrix} 2 & 0 \\ -4 & 2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & 0 \\ -1 & \frac{1}{2} \end{pmatrix}$$

$$C^{-1} = \begin{pmatrix} 7 & -4 \\ -5 & 3 \end{pmatrix}$$

2.5.7 (Important) If A has row 1 + row 2 = row 3, show that A is not invertible:

- (a) Explain why $Ax = (1, 0, 0)$ cannot have a solution.
- (b) Which right sides (b_1, b_2, b_3) might allow a solution to $Ax = \mathbf{b}$?
- (c) What happens to row 3 in elimination?

$$a) \quad A \vec{x} = \begin{pmatrix} (\text{row 1 of } A) \cdot \vec{x} \\ (\text{row 2 of } A) \cdot \vec{x} \\ (\text{row 3 of } A) \cdot \vec{x} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

If (row 3 of A) = (row 1 of A) + (row 2 of A)
then $\Rightarrow (\text{row 3 of } A) \cdot \vec{x} = (\text{row 1 of } A) \cdot \vec{x} + (\text{row 2 of } A) \cdot \vec{x}$
 $= (\text{row 1 of } A) \cdot \vec{x}$ as $(\text{row 2 of } A) \cdot \vec{x} = 0$.

So, we'd have to have

$$(\text{row 1 of } A) \cdot \vec{x} = 1 \quad \underline{\text{and}}$$

$$(\text{row 1 of } A) \cdot \vec{x} = 0$$

which is impossible.

b) If $b_3 = b_1 + b_2$ then there ~~is~~ could be a solution

c) It becomes a row of 0s.

2.5.25 Find A^{-1} and B^{-1} (if they exist) by elimination of $[A \ I]$ and $[B \ I]$:

$$A = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$B = \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 1 & 1 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 & 1 & 1 & 1 & 0 & 0 \\ 0 & \frac{3}{2} & \frac{1}{2} & -\frac{1}{2} & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 2 & 1 & 1 & 1 & 0 & 0 \\ 0 & \frac{3}{2} & 0 & -\frac{1}{2} & 1 & -\frac{1}{2} \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 & 1 & 0 & 1 & 0 & -1 \\ 0 & \frac{3}{2} & 0 & -\frac{1}{2} & 1 & -\frac{1}{2} \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 2 & 0 & 0 & \frac{4}{3} & -\frac{2}{3} & -\frac{2}{3} \\ 0 & \frac{3}{2} & 0 & -\frac{1}{2} & 1 & -\frac{1}{2} \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow A^{-1} = \begin{pmatrix} \frac{2}{3} & -\frac{1}{3} & -\frac{1}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{1}{3} \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 2 & -1 & -1 & 1 & 0 & 0 \\ -1 & 2 & -1 & 0 & 1 & 0 \\ -1 & -1 & 2 & 0 & 0 & 1 \end{pmatrix} \Rightarrow$$

$$\begin{pmatrix} 2 & -1 & -1 & 1 & 0 & 0 \\ 0 & \frac{3}{2} & -\frac{3}{2} & \frac{1}{2} & 1 & 0 \\ 0 & -\frac{3}{2} & \frac{3}{2} & \frac{1}{2} & 0 & 1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 2 & -1 & -1 & 1 & 0 & 0 \\ 0 & \frac{3}{2} & -\frac{3}{2} & \frac{1}{2} & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 \end{pmatrix}$$

Fail.

B is not invertible.

2.5.27 Invert these matrices A by the Gauss-Jordan method starting with $[A \ I]$:

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 2 & 1 & 3 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 3 & -2 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & -2 & 1 & -3 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

$$A^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & -3 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 2 & 2 & 0 & 1 & 0 \\ 1 & 2 & 3 & 0 & 0 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & -1 & 1 & 0 \\ 0 & 1 & 2 & -1 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 0 & -1 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 1 & 0 & 1 & 1 & -1 \\ 0 & 1 & 0 & -1 & 2 & -1 \\ 0 & 0 & 1 & 0 & -1 & 1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 1 & 0 & 0 & 2 & -1 & 0 \\ 0 & 1 & 0 & -1 & 2 & -1 \\ 0 & 0 & 1 & 0 & -1 & 1 \end{pmatrix}$$

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$$A^{-1} = \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix}$$

2.5.29 True or false (with a counterexample if false and a reason if true):

- (a) A 4 by 4 matrix with a row of zeros is not invertible.
- (b) Every matrix with 1's down the main diagonal is invertible.
- (c) If A is invertible then A^{-1} and A^2 are invertible.

a) True. Elimination must fail with a row of 0's

b) False. $\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ is not invertible.

c) True. The inverse of A^{-1} is A .
The inverse of A^2 is
 $(A^{-1})(A^{-1}) = A^{-2}$.

2.6 - Elimination = Factorization: $A = LU$

2.6.3 Forward elimination changes $Ax = \mathbf{b}$ to a triangular $Ux = \mathbf{c}$:

$$\begin{aligned} x + y + z &= 5 \\ x + 2y + 3z &= 7 \\ x + 3y + 6z &= 11 \end{aligned}$$

$$\begin{aligned} x + y + z &= 5 \\ y + 2z &= 2 \\ \textcircled{\times} 2y + 5z &= 6 \\ x + y + z &= 5 \\ y + 2z &= 2 \\ z &= 2 \end{aligned}$$

The equation $z = 2$ in $Ux = \mathbf{c}$ comes from the original $x + 3y + 6z = 11$ in $Ax = \mathbf{b}$ by subtracting $l_{31} = \underline{\quad 1 \quad}$ times equation 1 and $l_{32} = \underline{\quad 2 \quad}$ times the *final* equation 2. Reverse that to recover $\begin{bmatrix} 1 & 3 & 6 & 11 \end{bmatrix}$ in the last row of A and \mathbf{b} from the final $\begin{bmatrix} 1 & 1 & 1 & 5 \end{bmatrix}$ and $\begin{bmatrix} 0 & 1 & 2 & 2 \end{bmatrix}$ and $\begin{bmatrix} 0 & 0 & 1 & 2 \end{bmatrix}$ in U and \mathbf{c} :

$$\text{Row 3 of } \begin{bmatrix} A & \mathbf{b} \end{bmatrix} = (l_{31} \text{ Row 1} + l_{32} \text{ Row 2} + 1 \text{ Row 3}) \text{ of } \begin{bmatrix} U & \mathbf{c} \end{bmatrix}.$$

In matrix notation this is multiplication by L . So $A = LU$ and $\mathbf{b} = L\mathbf{c}$.

2.6.5 What matrix E puts A into triangular form $EA = U$? Multiply by $E^{-1} = L$ to factor A into LU :

$$A = \begin{pmatrix} 2 & 1 & 0 \\ 0 & 4 & 2 \\ 6 & 3 & 5 \end{pmatrix}$$

$$E = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{pmatrix} \left/ \begin{matrix} 2 & 1 & 0 \\ 0 & 4 & 2 \\ 6 & 3 & 5 \end{matrix} \right.$$
$$= \begin{pmatrix} 2 & 1 & 0 \\ 0 & 4 & 2 \\ 0 & 0 & 5 \end{pmatrix} = U$$

$$E^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix} = L$$

$$A = \boxed{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix} \left/ \begin{matrix} 2 & 1 & 0 \\ 0 & 4 & 2 \\ 0 & 0 & 5 \end{matrix} \right.}$$

2.6.7 What three elimination matrices E_{21}, E_{31}, E_{32} put A into its upper triangular form $E_{32}E_{31}E_{21}A = U$? Multiply by E_{32}^{-1}, E_{31}^{-1} and E_{21}^{-1} to factor A into L times U :

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 2 & 2 \\ 3 & 4 & 5 \end{pmatrix}$$

$$L = E_{21}^{-1}E_{31}^{-1}E_{32}^{-1}$$

$$E_{21} = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 2 & 2 & 2 \\ 3 & 4 & 5 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 3 & 4 & 5 \end{pmatrix}$$

$$E_{31} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 3 & 4 & 5 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 4 & 2 \end{pmatrix}$$

$$E_{32} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 4 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$E_{21}^{-1}E_{31}^{-1}E_{32}^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 2 & 1 \end{pmatrix} = L$$

$$\boxed{\begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}} = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 2 & 2 \\ 3 & 4 & 5 \end{pmatrix}$$

2.6.13 (Recommended) Compute L and U for the symmetric matrix A :

$$A = \begin{pmatrix} a & a & a & a \\ a & b & b & b \\ a & b & c & c \\ a & b & c & d \end{pmatrix}$$

Find four conditions on a, b, c, d to get $A = LU$ with four pivots.

$$\begin{pmatrix} a & a & a & a \\ 0 & b-a & b-a & b-a \\ 0 & b-a & c-a & c-a \\ 0 & b-a & c-a & d-a \end{pmatrix} \Rightarrow \begin{pmatrix} a & a & a & a \\ 0 & b-a & b-a & b-a \\ 0 & 0 & c-b & c-b \\ 0 & 0 & c-b & d-b \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} a & a & a & a \\ 0 & b-a & b-a & b-a \\ 0 & 0 & c-b & c-b \\ 0 & 0 & 0 & d-c \end{pmatrix} = U$$

$$L = \begin{pmatrix} 1 & 0 & 0 & 0 \\ +1 & +1 & 0 & 0 \\ +1 & +1 & +1 & 0 \\ +1 & +1 & +1 & +1 \end{pmatrix} \begin{pmatrix} a & a & a & a \\ a & b & b & b \\ a & b & c & c \\ a & b & c & d \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} a & a & a & a \\ 0 & b-a & b-a & b-a \\ 0 & 0 & c-b & c-b \\ 0 & 0 & 0 & d-c \end{pmatrix}$$

Must have $a \neq 0, b \neq a, c \neq b, d \neq c$

2.6.16 Solve $Lc = \mathbf{b}$ to find c . Then solve $Ux = c$ to find x . What was A ?

$$L = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} \quad \text{and} \quad U = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{and}$$

$$\mathbf{b} = \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}.$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix} \quad \begin{matrix} c_1 = 4 \\ c_2 = 1 \\ c_3 = 1 \end{matrix}$$

$$\vec{c} = \begin{pmatrix} 4 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 4 \\ 1 \\ 1 \end{pmatrix} \quad \begin{matrix} x_3 = 1 \\ x_2 = 0 \\ x_1 = 3 \end{matrix}$$

$$\vec{x} = \begin{pmatrix} 1 \\ 0 \\ 3 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} / \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix}$$

2.7 - Transposes and Permutations

2.7.1 Find A^T and A^{-1} and $(A^{-1})^T$ and $(A^T)^{-1}$ for

$$A = \begin{pmatrix} 1 & 0 \\ 9 & 3 \end{pmatrix} \quad \text{and also} \quad A = \begin{pmatrix} 1 & c \\ c & 0 \end{pmatrix}.$$

$$A = \begin{pmatrix} 1 & 0 \\ 9 & 3 \end{pmatrix} \quad A^T = \begin{pmatrix} 1 & 9 \\ 0 & 3 \end{pmatrix}$$

$$A^{-1} = \frac{1}{3} \begin{pmatrix} 3 & 0 \\ -9 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ -3 & \frac{1}{3} \end{pmatrix}$$

$$(A^{-1})^T = \begin{pmatrix} 1 & -3 \\ 0 & \frac{1}{3} \end{pmatrix} \quad (A^T)^{-1} = \begin{pmatrix} 1 & -3 \\ 0 & \frac{1}{3} \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & c \\ c & 0 \end{pmatrix} \quad A^T = \begin{pmatrix} 1 & c \\ c & 0 \end{pmatrix}$$

$$A^{-1} = \frac{1}{0-c^2} \begin{pmatrix} 0 & -c \\ -c & 1 \end{pmatrix} = \begin{pmatrix} 0 & \frac{1}{c} \\ \frac{1}{c} & -\frac{1}{c^2} \end{pmatrix}$$

$$(A^{-1})^T = \begin{pmatrix} 0 & \frac{1}{c} \\ \frac{1}{c} & -\frac{1}{c^2} \end{pmatrix} \quad (A^T)^{-1} = \begin{pmatrix} 0 & \frac{1}{c} \\ \frac{1}{c} & -\frac{1}{c^2} \end{pmatrix}$$

2.7.12 Explain why the dot product of \mathbf{x} and \mathbf{y} equals the dot product of $P\mathbf{x}$ and $P\mathbf{y}$. Then from $(P\mathbf{x})^T(P\mathbf{y}) = \mathbf{x}^T\mathbf{y}$ deduce that $P^T P = I$ for any permutation. With $\mathbf{x} = (1, 2, 3)$ and $\mathbf{y} = (1, 4, 2)$ choose P to show that $P\mathbf{x} \cdot \mathbf{y}$ is not always $\mathbf{x} \cdot P\mathbf{y}$.

$$\vec{x} \cdot \vec{y} = x_1 y_1 + x_2 y_2 + \dots + x_n y_n$$

Permuting the order doesn't change the sum.

$$(P\vec{x})^T (P\vec{y}) = \vec{x}^T P^T P \vec{y} = \vec{x}^T \vec{y}$$

$$\text{So, } P^T P = I.$$

$$\vec{x} \cdot \vec{y} = 1 + 8 + 6 = 15$$

$$P = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$P\vec{x} = (3, 2, 1) \quad P\vec{y} = (2, 4, 1)$$

$$P\vec{x} \cdot \vec{y} = 3 + 8 + 2 = 13$$

$$\vec{x} \cdot P\vec{y} = (1, 2, 3) \cdot (2, 4, 1) = 13$$

$$P = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$P\vec{x} = (2, 3, 1) \quad P\vec{y} = (4, 2, 1)$$

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$$P\vec{x} \cdot \vec{y} = 2 + 12 + 2 = 16$$

$$\vec{x} \cdot P\vec{y} = 4 + 4 + 3 = \del{16} \del{13} 11$$

2.7.19 Suppose R is rectangular (m by n) and A is symmetric (m by m).

(a) Transpose $R^T A R$ to show its symmetry. What shape is this matrix?

(b) Show why $R^T R$ has no negative numbers on its diagonal.

$$\begin{aligned} \text{a) } (R^T A R)^T &= R^T A^T (R^T)^T = R^T A^T R \\ &= R^T A R \quad \text{as } A \text{ is symmetric.} \\ (n \times m) \times (m \times m) \times (m \times n) &\text{ gives an } \boxed{n \times n} \text{ matrix} \end{aligned}$$

b) $R^T R = A$. The diagonal term a_{ii} is

$$\begin{aligned} a_{ii} &= (\text{Row } i \text{ of } R^T) \cdot (\text{column } i \text{ of } R) \\ &= (\text{column } i \text{ of } R) \cdot (\text{column } i \text{ of } R) \\ &\geq 0. \end{aligned}$$

as $\vec{v} \cdot \vec{v} \geq 0$ for any vector \vec{v} .

2.7.22 Find the $PA = LU$ factorization (and check them) for

$$A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 2 & 3 & 4 \end{pmatrix} \quad \text{and} \quad A = \begin{pmatrix} 1 & 2 & 0 \\ 2 & 4 & 1 \\ 1 & 1 & 1 \end{pmatrix}.$$

$$\left(\begin{array}{ccc|ccc} 0 & 1 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 & 3 & 4 \end{array} \right) = \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & & & \\ 0 & 1 & 1 & & & \\ 2 & 3 & 4 & & & \end{array} \right)$$

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ -2 & 0 & 1 & 2 & 3 & 4 \end{array} \right) = \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & & & \\ 0 & 1 & 1 & & & \\ 0 & 3 & 2 & & & \end{array} \right)$$

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 0 & -3 & 1 & 0 & 3 & 2 \end{array} \right) = \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & & & \\ 0 & 1 & 1 & & & \\ 0 & 0 & -1 & & & \end{array} \right)$$

$$E^{-1} = \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 2 & 0 & 1 & 0 & 3 & 1 \end{array} \right) = \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & & & \\ 0 & 1 & 0 & & & \\ 2 & 3 & 1 & & & \end{array} \right) = L$$

$$\left(\begin{array}{ccc|ccc} 0 & 1 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 & 3 & 4 \end{array} \right) = \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 2 & 3 & 1 & 0 & 0 & -1 \end{array} \right)$$

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & 2 & 4 & 1 \\ 0 & 1 & 0 & 1 & 1 & 1 \end{array} \right) = \left(\begin{array}{ccc|ccc} 1 & 2 & 0 & & & \\ 1 & 1 & 1 & & & \\ 2 & 4 & 1 & & & \end{array} \right)$$

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 2 & 0 \\ -1 & 1 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 2 & 4 & 1 \end{array} \right) = \left(\begin{array}{ccc|ccc} 1 & 2 & 0 & & & \\ 0 & -1 & 1 & & & \\ 2 & 4 & 1 & & & \end{array} \right)$$

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 2 & 0 \\ 0 & 1 & 0 & 0 & -1 & 1 \\ -2 & 0 & 1 & 2 & 4 & 1 \end{array} \right) = \left(\begin{array}{ccc|ccc} 1 & 2 & 0 & & & \\ 0 & -1 & 1 & & & \\ 0 & 0 & 1 & & & \end{array} \right)$$

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$$\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & 2 & 4 & 1 \\ 0 & 1 & 0 & 1 & 1 & 1 \end{array} \right) = \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 2 & 0 \\ 1 & 1 & 0 & 0 & -1 & 1 \\ 2 & 0 & 1 & 0 & 0 & 1 \end{array} \right)$$

2.7.40 Suppose Q^T equals Q^{-1} (transpose equals inverse, so $Q^T Q = I$):

(a) Show that the columns q_1, \dots, q_n are unit vectors: $\|q_i\|^2 = 1$.

(b) Show that every two columns of Q are perpendicular: $q_1^T q_2 = 0$.

(c) Find a 2 by 2 example with first entry $q_{11} = \cos \theta$.

a) The entry $(Q^T Q)_{ij} = (\text{row } i \text{ of } Q^T) \cdot (\text{column } j \text{ of } Q)$
 $= (\text{column } i \text{ of } Q) \cdot (\text{column } j \text{ of } Q)$
 $= \vec{q}_i \cdot \vec{q}_j = \delta_{ij}.$

For $i=j$ we get $\vec{q}_i \cdot \vec{q}_i = 1$

So, $\|\vec{q}_i\| = 1.$

b) $\vec{q}_i \cdot \vec{q}_j = (Q^T Q)_{ij} = 0$ if $i \neq j.$

c)
$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

