# **Ellipses and Hyperbolas**

In this chapter we'll see three more examples of conics.

### Ellipses

If you begin with the unit circle,  $C^1$ , and you scale x-coordinates by some nonzero number a, and you scale y-coordinates by some nonzero number b, the resulting shape in the plane is called an *ellipse*.



Let's begin again with the unit circle  $C^1$ , the circle of radius 1 centered at (0,0). We learned earlier that  $C^1$  is the set of solutions of the equation

 $x^2 + y^2 = 1$ 

The matrix  $\begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}$  scales the *x*-coordinates in the plane by *a*, and it scales the *y*-coordinates by *b*. What's drawn below on the right is  $\begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} (C^1)$ , which is the shape resulting from scaling  $C^1$  horizontally by *a* and vertically by *b*. It's an example of an ellipse.



Using POTS, the equation for this distorted circle, the ellipse  $\begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} (C^1)$ , is obtained by precomposing the equation for  $C^1$ , the equation  $x^2 + y^2 = 1$ , by the matrix

$$\begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}^{-1} = \begin{pmatrix} \frac{1}{a} & 0 \\ 0 & \frac{1}{b} \end{pmatrix}$$





Because  $\begin{pmatrix} \frac{1}{a} & 0\\ 0 & \frac{1}{b} \end{pmatrix}$  replaces x with  $\frac{x}{a}$  and y with  $\frac{y}{b}$ , the equation for the ellipse  $\begin{pmatrix} a & 0\\ 0 & b \end{pmatrix} (C^1)$  is  $(x)^2 = (y)^2$ 

$$\left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 = 1$$

which is equivalent to the equation

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

The equation for an ellipse described above is important. It's repeated at the top of the next page.

Suppose  $a, b \in \mathbb{R} - \{0\}$ . The equation for the ellipse obtained by scaling the unit circle

by a in the x-coordinate and by b in the y-coordinate is



#### Example.

• The equation for the ellipse shown below is  $\frac{x^2}{25} + \frac{y^2}{4} = 1$ . In this example, we are using the formula from the top of the page with a = 5 and b = 2.



### Circles are ellipses

A circle is a perfectly round ellipse.

If we scale the unit circle by the same number r > 0 in both coordinates, then we'll stretch the unit circle evenly in all directions.



The result will be another circle, one whose equation is

$$\frac{x^2}{r^2} + \frac{y^2}{r^2} = 1$$

We can multiply both sides of this equation by  $r^2$  to obtain the equivalent equation

$$x^2 + y^2 = r^2$$

which we had seen earlier as the equation for  $C^r$ , the circle of radius r centered at (0, 0).

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### Hyperbolas from scaling

We've seen one example of a hyperbola, namely the set of solutions of the equation xy = 1. We'll call this hyperbola  $H^1$ , the *unit hyperbola*.



Suppose c > 0. We can horizontally stretch the unit hyperbola  $H^1$  using the diagonal matrix  $\begin{pmatrix} c & 0 \\ 0 & 1 \end{pmatrix}$ . This is the matrix that scales the *x*-coordinate by *c* and does not alter the *y*-coordinate. The resulting shape in the plane,  $\begin{pmatrix} c & 0 \\ 0 & 1 \end{pmatrix} (H^1)$ , is also called a hyperbola.



The equation for the hyperbola  $\begin{pmatrix} c & 0 \\ 0 & 1 \end{pmatrix} (H^1)$  is obtained by precomposing the equation for  $H^1$ , the equation xy = 1, with  $\begin{pmatrix} c & 0 \\ 0 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} \frac{1}{c} & 0 \\ 0 & 1 \end{pmatrix}$ . This is the matrix that replaces x with  $\frac{x}{c}$  and does not alter y. Thus, the equation for the hyperbola  $\begin{pmatrix} c & 0 \\ 0 & 1 \end{pmatrix} (H^1)$  is

$$\left(\frac{x}{c}\right)y = 1$$

which is equivalent to

$$xy = c$$

From now on, we'll call this hyperbola  $H^c$ .

To summarize:

Let c > 0. Then  $H^c$  is the hyperbola that is the set of solutions of the equation xy = c.



#### Example.

• The equation for the hyperbola  $H^2$ , obtained by scaling the unit hyperbola by 2 in the x-coordinate is xy = 2.



## Hyperbolas from flipping

We can flip the hyperbola  $H^c$  over the y-axis using the matrix  $\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$ , the matrix that replaces x with -x and does not alter y.



The shape resulting from flipping the hyperbola  $H^c$  over the y-axis is also called a hyperbola. Its equation is obtained by precomposing the equation for  $H^c$ , the equation xy = c, with the inverse of  $\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$ , which is  $\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$  itself, the matrix that replaces x with -x.

$$xy = C \qquad \begin{array}{c} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \\ x \mapsto -x \qquad (-x)y = C \\ y \mapsto y \qquad \text{or} \\ xy = -C \end{array}$$

So the equation for  $H^c$  after being flipped over the y-axis is

$$(-x)y = c$$

which is equivalent to

xy = -c

To summarize:

Let 
$$c > 0$$
. The equation for  $H^c$  flipped  
over the y-axis is  $xy = -c$ .



Example.

• The equation for  $H^3$  after being flipped over the y-axis is xy = -3.



## Ellipses and hyperbolas are conics

The equations that we've seen for ellipses and hyperbolas in this chapter are quadratic equations in two variables:  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ , xy = c, and xy = -c. Thus, the solutions of these equations, the ellipses and hyperbolas above, are examples of conics.

# Exercises

4.)

5.)

6.)

For #1-6, match the numbered pictures with the lettered equations.













A.) xy = 4B.)  $x^2 + 4y^2 = 1$ C.)  $x^2 + y^2 = 9$ D.) xy = -4E.)  $\frac{x^2}{9} + \frac{y^2}{16} = 1$ F.)  $\frac{x^2}{25} + y^2 = 1$  For #7-10, write an equation for each of the given shapes in the plane. Your answers should have the form  $(y - q) = a(x - p), (x - p)^2 + (y - q)^2 = r^2$ , (x - p)(y - q) = c, or  $\frac{(x-p)^2}{a^2} + \frac{(y-q)^2}{b^2} = 1$ . (As with the *x*- and *y*-axes, the dotted lines are not part of the shapes. They're just drawn to provide a point of reference.)



For #11-14, multiply the matrices.

11.) 
$$\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 3 \\ 2 & -3 \end{pmatrix}$$
  
13.)  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 5 & 7 \\ 8 & 9 \end{pmatrix}$   
12.)  $\begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{3} \end{pmatrix}$   
14.)  $\begin{pmatrix} 3 & -2 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 0 & 1 \end{pmatrix}$