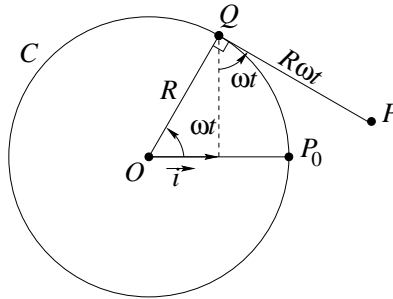


## Correction of the problem of First Midterm

### Problem II. Unwinding a fixed bobbin.

Consider a fixed bobbin (it cannot turn nor move) around which a thread is wound. The bobbin has the shape of a circle  $C$  of radius  $R$ . We take the center of the bobbin  $O$  to be the origin of the coordinate system (we assume that everything happens in a plane containing the circle  $C$ ). Let  $P$  be the end of the thread. The goal of the problem is to study the movement of  $P$  as you unwind the thread, keeping it tight.

We assume that the point  $P$  is initially at  $P_0(R, 0)$ . Since the thread is tight, it is tangent to  $C$  at some point  $Q$ . We assume that at time  $t$ , the angle between  $\vec{i}$  and  $\overrightarrow{OQ}$  is  $\omega t$ . The length  $|PQ|$  of the unwound thread is  $R\omega t$ .



- 1 Show that  $x = R(\cos \omega t + \omega t \sin \omega t)$  and  $y = R(\sin \omega t - \omega t \cos \omega t)$  are the coordinates of  $P$ .**

$\overrightarrow{OP} = \cos \omega t \vec{i} + \sin \omega t \vec{j}$ . Moreover, since  $\overrightarrow{OP} \perp \overrightarrow{PQ}$ , the angle between the vertical direction and  $\overrightarrow{PQ}$  is  $\omega t$ , so that  $\overrightarrow{PQ} = R\omega t(\sin \omega t \vec{i} - \cos \omega t \vec{j})$ . Therefore,

$$\overrightarrow{OQ} = \overrightarrow{OP} + \overrightarrow{PQ} = R(\cos \omega t + \omega t \sin \omega t)\vec{i} + R(\sin \omega t - \omega t \cos \omega t)\vec{j}.$$

This means that the coordinates of  $P$  are  $x = R(\cos \omega t + \omega t \sin \omega t)$  and  $y = R(\sin \omega t - \omega t \cos \omega t)$ .

- 2 Show that the velocity  $\vec{v}$  is  $R\omega^2 t(\cos(\omega t)\vec{i} + \sin(\omega t)\vec{j})$  and compute the unit tangent vector  $\vec{T}$ .**

$$\begin{aligned} \vec{r}(t) = \overrightarrow{OP} &= R(\cos \omega t + \omega t \sin \omega t)\vec{i} + R(\sin \omega t - \omega t \cos \omega t)\vec{j} \\ \vec{v} = \vec{r}'(t) &= R(-\omega \sin \omega t + (\omega \sin \omega t + \omega^2 t \cos \omega t))\vec{i} + R(\omega \cos \omega t - (\omega \cos \omega t - \omega^2 t \sin \omega t))\vec{j} \\ &= R\omega^2 t(\cos \omega t \vec{i} + \sin \omega t \vec{j}) \end{aligned}$$

$$\vec{T} = \frac{\vec{v}}{|\vec{v}|} = \frac{1}{R\omega^2 t} R\omega^2 t(\cos \omega t \vec{i} + \sin \omega t \vec{j}) = \cos \omega t \vec{i} + \sin \omega t \vec{j}$$

- 3 What is the angle  $\phi$  between  $\vec{i}$  and  $\vec{T}$ ? Deduce the curvature  $\kappa$  of the curve.**

The angle  $\phi$  between  $\vec{i}$  and  $\vec{T}$  is  $\omega t$  since  $\cos \phi = \frac{\vec{i} \cdot \vec{T}}{|\vec{i}| |\vec{T}|} = \frac{\cos \omega t}{1 \times 1} = \cos \omega t$ .

The easiest way to compute the curvature is by using its formula in terms of  $\phi$ :

$$\begin{aligned} \kappa &= \frac{d\phi}{ds} = \frac{d\phi/dt}{ds/dt} = \frac{d\phi/dt}{v} \\ &= \frac{\omega}{R\omega^2 t} = \frac{1}{R\omega t} \end{aligned}$$

You could also use the formula of the curvature in terms of  $\vec{T}$ :

$$\begin{aligned}\kappa &= \frac{|\vec{T}'|}{v} = \frac{1}{R\omega^2 t} \left| \frac{d}{dt} (\cos \omega t \vec{i} + \sin \omega t \vec{j}) \right| \\ &= \frac{1}{R\omega^2 t} |(-\omega \sin \omega t \vec{i} + \omega \cos \omega t \vec{j})| = \frac{1}{R\omega t}\end{aligned}$$

You could also compute the curvature from the formula

$$\kappa = \frac{|x'y'' - x''y'|}{\sqrt{x'^2 + y'^2}^3}$$

To compute  $x''$  and  $y''$ , we just have to derive the coordinates of the velocity:

$$\begin{aligned}x' &= R\omega^2 t \cos \omega t & x'' &= R\omega^2 (\cos \omega t - \omega t \sin \omega t) \\ y' &= R\omega^2 t \sin \omega t & y'' &= R\omega^2 (\sin \omega t + \omega t \cos \omega t)\end{aligned}$$

$$\begin{aligned}x'y'' - x''y' &= R^2 \omega^4 t (\cos \omega t \sin \omega t + \omega t \cos^2 \omega t - \cos \omega t \sin \omega t + \omega t \sin^2 \omega t) \\ &= R^2 \omega^5 t^2 \\ \sqrt{x'^2 + y'^2} &= v = R\omega^2 t \\ \kappa &= \frac{R^2 \omega^5 t^2}{(R\omega^2 t)^3} = \frac{1}{R\omega t}\end{aligned}$$

#### 4 What are the tangential and radial accelerations ?

$$\begin{aligned}a_T &= \frac{dv}{dt} = \frac{d|\vec{v}|}{dt} = \frac{d}{dt} R\omega^2 t = R\omega^2 \\ a_N &= \kappa v^2 = \frac{1}{R\omega t} (R\omega^2 t)^2 = R\omega^3 t\end{aligned}$$

#### 5 Compute the length of the curve between $t = 0$ and $t = 2\pi/\omega$ .

$$\begin{aligned}L &= \int_0^{2\pi/\omega} |\vec{v}| dt = \int_0^{2\pi/\omega} \sqrt{x'^2 + y'^2} dt \\ &= \int_0^{2\pi/\omega} R\omega^2 t dt = R\omega^2 \left[ \frac{t^2}{2} \right]_0^{2\pi/\omega} = R\omega^2 \frac{4\pi^2}{2\omega^2} = 4\pi^2 R\end{aligned}$$

#### 6 Show that the line through $P$ perpendicular to the tangent line at $P$ is tangent to the circle $C$ . (*Hint: Show that this line is the line $(PQ)$* )

Since the line  $(QP)$  contains  $P$ , we just have to prove that  $\overrightarrow{QP}$  is normal to the curve, that is  $\overrightarrow{QP} \perp \vec{T}$  (or we could have taken  $\vec{v}$  instead of  $\vec{T}$  since they have same direction). So we just have to check that  $\overrightarrow{QP} \cdot \vec{T} = 0$ .

$$\overrightarrow{QP} \cdot \vec{T} = R\omega t (\sin \omega t \vec{i} - \cos \omega t \vec{j}) \cdot (\cos \omega t \vec{i} + \sin \omega t \vec{j}) = 0$$

- 7 Sketch a graph of the curve for  $0 \leq t \leq 2\pi/\omega$  by plotting the point  $P$  for  $\omega t = 0, \pi/2, \pi, 3\pi/2, 2\pi$  together with the tangent lines at these points. *Hint: you may use the previous question to draw the tangent line.*

