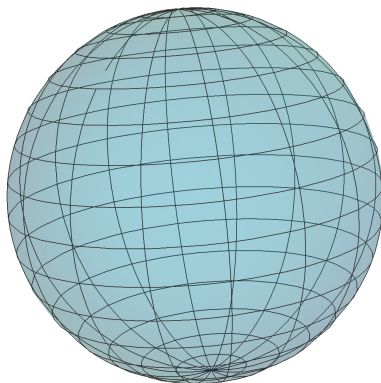


- (1) (2 pts) *Geodesic curvature of parallels in S^2* : As usual S^2 is the unit sphere in \mathbb{R}^3 . It can be parametrized by spherical coordinates ϕ, θ , where $0 \leq \phi \leq \pi$ is co-latitude and $0 \leq \theta \leq 2\pi$ is longitude:

$$(1) \quad (x, y, z) = (\sin \phi \cos \theta, \sin \phi \sin \theta, \cos \phi)$$

The parallels are the curves $\phi = c$, $0 \leq c \leq \pi$ a constant. The curves $\phi = 0, \pi$ degenerate



to the north and south pole respectively, and $\phi = \pi/2$ is the equator. Compute the geodesic curvature $|\frac{D\gamma'}{Ds}| = |\gamma''^T|$ of the parallel $\gamma = \gamma_\phi$ for each value of ϕ

Suggestion:

- (a) For fixed ϕ , (??) gives a curve with parameter θ , which is not arc-length unless $\phi = \pi/2$, the equator. Re-parametrize this curve by arc-length s , get a curve $\gamma(s)$ (depending on ϕ)
 - (b) Figure out the tangential component γ''^T and find its magnitude (answer: $\cot \phi$)
- (2) (4 pts) *Gaussian curvature of the sphere of radius R* : Let $S^2(R)$ denote the sphere in \mathbb{R}^3 of radius R and let $\mathbf{x}(\phi, \theta)$ be the parametrization of $S^2(R)$ obtained by multiplying (??) by R . Thus $\mathbf{x} : [0, \pi] \times [0, 2\pi] \rightarrow S^2(R)$ is surjective but maps $0 \times [0, 2\pi]$ to the north pole, etc.
- (a) Not to forget topology, prove that \mathbf{x} is an identification.
 - (b) Write the expression for $ds^2 = d\mathbf{x} \cdot d\mathbf{x}$ for this parametrization.
 - (c) Let r be distance from the north pole. Express ϕ as a function of r and change the expression for ds^2 to one that is a function of r and θ . It should be of the form

$dr^2 + g(r)^2 d\theta^2$ for a suitable function $g(r)$. Observe that the circumference of a circle centered at the north pole of radius r is $\int_0^{2\pi} g(r) d\theta = 2\pi g(r)$.

- (d) Show that the Taylor expansion of g at $r = 0$ begins

$$g(r) = r - \frac{r^3}{6R^2} + \dots$$

The quantity $1/R^2$ is called the “Gaussian curvature” of $S^2(R)$. It measures the deviation of the circumference of circles of radius r from the value $2\pi r$ in Euclidean geometry.

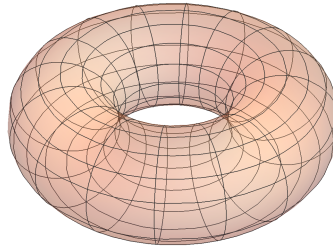
- (3) (4 pts) *Gaussian curvature of a cylinder*: Let C be the cylinder $\{x^2 + y^2 = 1\} \subset \mathbb{R}^3$. “Parametrize” C by the map $\mathbf{x} : \mathbb{R}^2 \rightarrow C$ defined by

$$\mathbf{x}(u, v) = (\cos u, \sin u, v).$$

- (a) Even though \mathbf{x} is not injective, show that \mathbf{x} is locally injective, is an open map, and is an identification. So it can be used to compute $ds^2 = d\mathbf{x} \cdot d\mathbf{x}$.
 (b) Find $ds^2 = d\mathbf{x} \cdot d\mathbf{x}$. Any surprises?
 (c) Find the circumference of the geodesic circles of radius r , for small enough r , so that these curves will not intersect themselves. What’s the Gaussian curvature?
 (d) Find all geodesics in C joining $(1, 0, 0)$ to $(1, 0, 2\pi)$. Show that there are infinitely many distinct ones. Draw a picture.
- (4) *Extra credit problems on the torus*

Let T be the torus $\mathbb{R}^2 / (2\pi\mathbb{Z})^2 = \mathbb{R}^2 / \sim$, where $(x, y) \sim (x', y')$ if and only if $x - x'$ and $y - y' \in 2\pi\mathbb{Z}$. Can measure lengths of curves in two ways:

- $ds_1^2 = dx^2 + dy^2$ on \mathbb{R}^2 , is invariant under translations, is well defined on T .
- $ds_2^2 = d\mathbf{x} \cdot d\mathbf{x}$ where $\mathbf{x}(\phi, \theta) = ((2 + \cos \phi) \cos \theta, (2 + \cos \phi) \sin \theta, \sin \phi)$. Then $\mathbf{x} : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ and $\mathbf{x}(\phi + 2\pi m, \theta + 2\pi n) = \mathbf{x}(\phi, \theta)$ for all $m, n \in \mathbb{Z}$, therefore \mathbf{x} gives a map $\mathbf{x} : T \rightarrow \mathbb{R}^3$ with image the familiar torus of revolution in \mathbb{R}^3 .



- (a) For (T, ds_1^2) find the Gaussian curvature and all the geodesics from $[(0, 0)]$ to $[(\frac{1}{2}, \frac{1}{2})]$.
 (b) For (T, ds_2^2) show that all circles $\theta = \text{const}$ are geodesics, and decide which of the circles $\phi = \text{const}$ are geodesics.
 (c) Prove that there is no isometry between (T, ds_1^2) and (T, ds_2^2) .