

Name \_\_\_\_\_

Math 217      Winter, 2007

**Midterm 1**

Problem	Possible Points	Actual Points
1	10	
2	10	
3	10	
TRUE/FALSE	20	
<hr/>		
Total	50	

In all the problems (with the exception of the TRUE/FALSE), indicate how you arrived at your answer. The answer alone will get at best partial credit.

**Problem 1** (10 points)

a) Let  $\mathbf{v}_1 = \begin{bmatrix} 3 \\ 9 \\ 3 \end{bmatrix}$ ,  $\mathbf{v}_2 = \begin{bmatrix} 0 \\ -12 \\ 6 \end{bmatrix}$ , and  $\mathbf{v}_3 = \begin{bmatrix} 4 \\ 18 \\ 1 \end{bmatrix}$ . If  $A = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \mathbf{v}_3]$ ,

find the solution set to  $A\mathbf{x} = \begin{bmatrix} 6 \\ 6 \\ 12 \end{bmatrix}$ , and describe it geometrically.

b) Are the columns of  $A$  linearly independent or dependent?

**Problem 2** (10 points) Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be the linear transformation given

by multiplication by the matrix  $A = \begin{bmatrix} 1 & -2 \\ 2 & 1 \\ 1 & 3 \end{bmatrix}$ .

a) Is  $T$  one-to-one? If so, explain why. If not, give an example of two distinct vectors  $\mathbf{x}_1$  and  $\mathbf{x}_2$  such that  $T(\mathbf{x}_1) = T(\mathbf{x}_2)$ .

b) Is  $T$  onto? If so, explain why. If not, give an example of a vector  $\mathbf{b}$  in  $\mathbb{R}^3$  such that the equation  $T(\mathbf{x}) = \mathbf{b}$  has no solution.

**Problem 3** (10 points)

a) Give an example of an invertible  $2 \times 2$  matrix (other than the identity matrix).

b) Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the linear transformation given by rotation counter-clockwise by ninety degrees. Write down the standard matrix for  $T$  and the inverse of  $T$ .

c) Let  $S : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  given by the matrix  $A = \begin{bmatrix} 3 & 0 \\ 1 & 1 \\ -1 & 2 \end{bmatrix}$ . Let  $U : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be the composition of  $S$  and  $T$ , i.e.,  $U(\mathbf{x}) = S(T(\mathbf{x}))$ . Write down the standard matrix for  $U$ .

**TRUE/FALSE** (20 points)

Below are ten assertions. For each, circle either T or F to indicate whether you believe the assertion is always TRUE or sometimes FALSE. There is no need to justify your response.

- T   F   Let  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  be a set of  $k$  linearly independent vectors in  $\mathbb{R}^5$ . Then  $k < 6$ .
- T   F   The span of two vectors is a plane.
- T   F   If  $A$  is an  $n \times n$  matrix such that  $A = A^T$ , then  $A$  is invertible.
- T   F   Let  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  be three linearly independent vectors in  $\mathbb{R}^n$ . Then  $\text{Span}\{\mathbf{u}, \mathbf{v}\} \neq \text{Span}\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ .
- T   F   Let  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  be three linearly dependent vectors in  $\mathbb{R}^n$ . Then  $\text{Span}\{\mathbf{u}, \mathbf{v}\} = \text{Span}\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ .
- T   F   Suppose  $A$  and  $B$  are invertible matrices of the same size. Then the inverse of  $(AB)^T$  is  $(A^T)^{-1}(B^T)^{-1}$ .
- T   F   A homogeneous system is always consistent.
- T   F   Suppose  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$  are linearly dependent vectors. Then we can write  $\mathbf{v}_1 = c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k$  for some real scalars  $c_2, \dots, c_k$ .
- T   F   The  $n \times n$  identity matrix,  $I_n$ , is row equivalent to every invertible  $n \times n$  matrix.
- T   F   Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^m$  be a linear transformation, and let  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  be three vectors in the range of  $T$ . Then  $\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{w}$  are linearly dependent.