

small change in syllabus

Math 2270-1

Notes of 10/04/2019

4.3, 4.5, Vector Spaces, Bases, and Dimension

- Note: we focus on finite dimensional vector spaces.
- Let's use the space of quadratic polynomials as a running example.

$$V = \{p : p(x) = ax^2 + bx + c\}$$

- Recall the definition:

A **vector space**⁻¹⁻ is a nonempty set V of objects, called vectors, on which are defined two operations, called **addition** and **multiplication by scalars (real numbers)**, subject to the ten axioms (or rules) listed below. The axioms must hold for all vectors \mathbf{u} , \mathbf{v} , and \mathbf{w} in V , and for all scalars c and d .

1. The sum of \mathbf{u} and \mathbf{v} , denoted by $\mathbf{u} + \mathbf{v}$, is in V .
2. $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$.
3. $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$.
4. There is a zero vector $\mathbf{0}$ in V such that

$$\mathbf{u} + \mathbf{0} = \mathbf{u}.$$

5. For each \mathbf{u} in V , there is a vector $-\mathbf{u}$ in V such that $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$.
6. The scalar multiple of \mathbf{u} by c , denoted by $c\mathbf{u}$, is in V .
7. $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$.
8. $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$.
9. $c(d\mathbf{u}) = (cd)\mathbf{u}$.
10. $1\mathbf{u} = \mathbf{u}$.

⁻¹⁻ Also called a **linear space**

- A **linear combination** of a set *of vectors*

$$S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$$

of vectors is a vector of the form

$$\mathbf{v} = \sum_{i=1}^n \alpha_i \mathbf{v}_i$$

where the α_i are constants.

- A vector space is closed under linear combinations.

- A finite set

$$S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$$

of vectors is **linearly independent** if

$$\sum_{i=1}^n \alpha_i \mathbf{v}_i = \mathbf{0} \implies \alpha_1 = \alpha_2 = \dots = \alpha_n = 0.$$

- The **span** of a set S of vectors is the set of all linear combinations of vectors in S .



Usually S is finite. If S is infinite we assume that the linear combination has only finitely many non-zero terms.

$$\{1, x, x^2\} \quad \text{l.i.}$$

$$\{1, x, x+1\} \quad \text{l.d.}$$

$\text{span}(S)$ vector space

- A **spanning set** of a vector space V is a set S such that V equals the span of S .

$\{1, x, x^2\}$ linearly independent
basis

$\{1, x, x^2, x^2+x+1, x^2-1\}$

V is a spanning set of
(or for) V

- A **basis** of a vector space V is a linearly independent spanning set for V .

- Major Fact: All Bases of a given vector space V have the same number of elements (vectors). That number is the **dimension** of V .
- This is a consequence of Theorem 9 on page 227 of the textbook:
- If a vector space V has a basis

$$\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$$

then any set in V containing more than n vectors is linearly dependent.

- The textbook has a proof using coordinate vectors, but those are not needed.

Proof: Suppose

$$\mathcal{B} = \{\mathbf{b}_1, \quad \mathbf{b}_2, \quad \dots, \quad \mathbf{b}_n\}$$

is a basis of V and

$$\mathcal{S} = \{\mathbf{v}_1, \quad \mathbf{v}_2, \quad \dots, \quad \mathbf{v}_m\}$$

is a larger set of

$$m > n$$

vectors.

Since \mathcal{B} is a basis we can write every vector \mathbf{v}_i as a linear combination of the basis vectors \mathbf{b}_j :

$$\mathbf{v}_i = \sum_{j=1}^n c_{ij} \mathbf{b}_j, \quad i = 1, \dots, m. \quad (1)$$

Now consider a linear combination of the \mathbf{v}_i . We want to show that there are non-trivial such linear combinations that equal zero.

$$\sum_{i=1}^m \alpha_i \mathbf{v}_i = \mathbf{0} \quad \text{and} \quad \alpha_i \neq 0$$

for some i .

Using (1) we get

$$\begin{aligned} \mathbf{0} &= \sum_{i=1}^m \alpha_i \mathbf{v}_i \\ &= \sum_{i=1}^m \alpha_i \sum_{j=1}^n c_{ij} \mathbf{b}_j \\ &= \sum_{j=1}^n \underbrace{\left(\sum_{i=1}^m \alpha_i c_{ij} \right)}_{=0} \mathbf{b}_j. \end{aligned}$$

Hence $\sum_{i=1}^m \alpha_i \mathbf{v}_i$ is zero so long as

$$\sum_{i=1}^m \alpha_i c_{ij} = 0 \tag{2}$$

and we are done if we can show that there are coefficients α_i , some of which are non-zero, such (2) is satisfied.

Now let

$$C = [c_{ij}]_{\substack{i=1,\dots,m \\ j=1,\dots,n}} \quad \text{and} \quad \mathbf{a} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_m \end{bmatrix}$$

In matrix form the equations (2) can be written as

$$C^T \mathbf{a} = \mathbf{0}. \quad (3)$$

C is an $m \times n$ matrix with $m > n$. Thus C^T has more columns than rows and the homogeneous system (3) does have a non-trivial solution. The set \mathcal{S} is linearly dependent.

$$Ax = 0$$

$$V = \text{span}\{1, x, x^2\} \quad B_1$$

$$B_2 = \{2, 2x, 2x^2\}$$

$$B_3 = \{1, 2x, 3x^2\}$$

$$\{1, 1+x, 1+x+x^2\}$$

$$ax^2 + bx + c = \alpha + \beta(1+x) + \gamma(1+x+x^2)$$

$$c = \alpha$$

$$b = \alpha + \beta$$

$$a = \alpha + \beta + \gamma$$

Examples

- Find bases (and dimensions) for the following vector spaces.
- The set of all quadratic polynomials.



- The set of all upper triangular 2×2 matrices.

$$\mathcal{B}_1 = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\} \quad \dim = 3$$

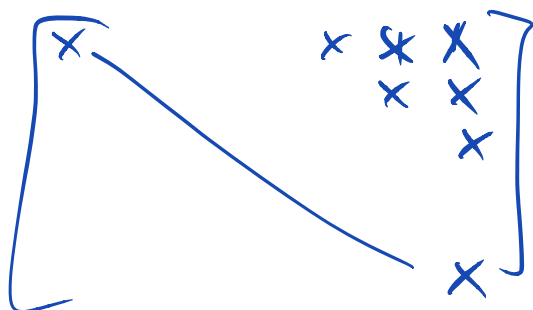
$$\begin{bmatrix} a & b \\ 0 & c \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\mathcal{B}_2 = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & \alpha \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & \beta \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & \gamma \end{bmatrix} \right\}$$

$$\begin{bmatrix} a & b \\ 0 & c \end{bmatrix} = \begin{bmatrix} \alpha + \beta + \gamma & \beta + \gamma \\ 0 & \gamma \end{bmatrix} \quad \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

The set V of all upper triangular $n \times n$ matrices.

$$\dim V = 1 + 2 + \dots + n = \frac{n(n+1)}{2}$$



- The set of all solutions of the differential equation

$$y'' = k^2 y$$

$$\mathcal{B} = \{ e^{kx}, e^{-kx} \}$$

$$0 = 0 \cdot e^{kx} + 0 \cdot e^{-kx}$$

- The set of all sequences that satisfy the Fibonacci⁻²⁻ equation

$$y_{n+2} = y_n + y_{n+1}, \quad n = 0, 1, 2, \dots$$

form a linear space. Find a basis.

⁻²⁻ Fibonacci, approx. 1170-1250, came up with this equation (where $y_0 = y_1 = 1$) to model the growth of a rabbit population.