

Math 1210-23

- No class or office hours on Monday!
- Study Session today, after class, right here!
- hw 6 # 11

Notes of 2/16/24

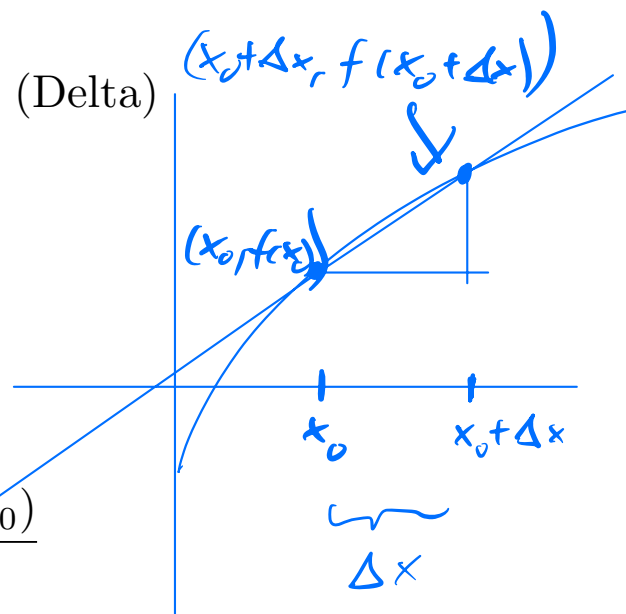
2.9 Differentials and Approximation

- An application of derivatives
- Recall that the Greek capital letter Δ (Delta) is often used to denote differences:

$$\Delta f = f(x_0 + \Delta x) - f(x_0)$$

- Recall our definition:

$$f'(x_0) = \lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}$$



- rise over run, slope of secant approaches slope of tangent, average velocity approaches instantaneous velocity.
- We can turn things around, not take the limit, and think of the slope of the tangent (i.e., the derivative) as an **approximation** of the slope of the secant

$$f'(x_0) \approx \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}$$

for some specific $\Delta x \neq 0$.

- This can be rewritten as

$$\Delta f = f(x_0 + \Delta x) - f(x_0) \approx f'(x_0)\Delta x.$$

- This can be considered the key property of the derivative:



The change in the function value equals approximately the change in the independent variable multiplied with the derivative.

- The approximation is the better the smaller the change in the independent variable.



Put differently: To approximate the change in the output multiply the change in the input with the derivative!



This makes the chain rule more plausible. When you compose two functions then each multiplies a change in input by its derivative, and so the composition multiplies with the product of the derivatives. Thus the derivative of the composition equals the product of the derivatives.

- Example: Suppose you need a good approximation of $\sqrt{4.6}$ and your calculator is broken.
- We can easily compute $\sqrt{4} = 2$.
- Let

$$f(x) = \sqrt{x} \quad \implies \quad f'(x) = \frac{1}{2\sqrt{x}}.$$

- Then

$$\begin{aligned} f(4.6) - f(4.0) &= \sqrt{4.6} - \sqrt{4.0} \\ &\approx f'(4) \times (4.6 - 4.0) \\ &= \frac{4.6 - 4.0}{2\sqrt{4.0}} = \frac{0.6}{4} \\ &= 0.15 \end{aligned}$$

and hence

$$\sqrt{4.6} = \sqrt{4} + (\sqrt{4.6} - \sqrt{4}) \approx 2 + 0.15 = 2.15.$$

- The difference between the true function value and its approximation is called the **error**.
- In this case $\sqrt{4.6} = 2.1448\dots$ and the error is

$$\sqrt{4.6} - 2.15 = -0.0052\dots$$

- This works the better the smaller the difference in inputs. In this case this means the number whose square root we want to approximate is closer to 4.
- Consider this Table:

Δx	$x_0 + \Delta x$	$f(x_0 + \Delta x)$	$f(x_0) + f'(x_0)\Delta x$	
Δx	$4 + \Delta x$	$\sqrt{4 + \Delta x}$	$2 + \frac{\Delta x}{\sqrt{4}}$	error
0.6	4.6	2.144761059	2.150000000	-0.005238
0.3	4.3	2.073644135	2.075000000	-0.001356
0.15	4.15	2.037154879	2.037500000	-0.000345
0.075	4.075	2.018662924	2.018750000	-0.000087



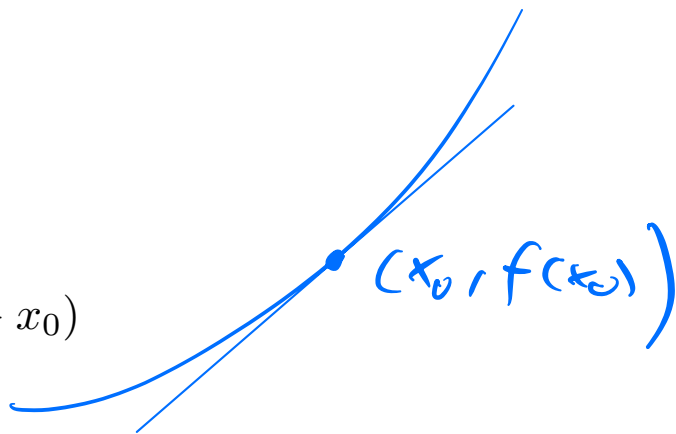
Note that as we go from one line to the next the value of Δx is halved. On the other hand, the **error** is reduced by a factor about 4.

- This means the error goes to zero faster than linearly.
- In a profound way this behavior can be used to define the derivative, but that subject is beyond our scope.

Linear Approximation

- We saw that in general

$$f(x) \approx f(x_0) + f'(x_0)(x - x_0)$$



- The right hand side of this approximation is a linear function of x . (Its graph of course is the tangent line at $(x_0, f(x_0))$). It is called the **linear approximation** of f at (or about) x_0 .
- Some examples for linear approximations:

$$f(x) = \sqrt{x} \approx 2 + \frac{x-4}{2\sqrt{4}} = 2 + \frac{x-4}{4} \quad (x_0 = 4)$$

$$f(x) = \sin x \approx \sin(0) + (x - 0) \cos 0 = x \quad (x_0 = 0)$$

$$f(x) = x^2 \approx 1^2 + 2 \times 1 \times (x - 1) = 1 + 2(x - 1) \quad (x_0 = 1)$$

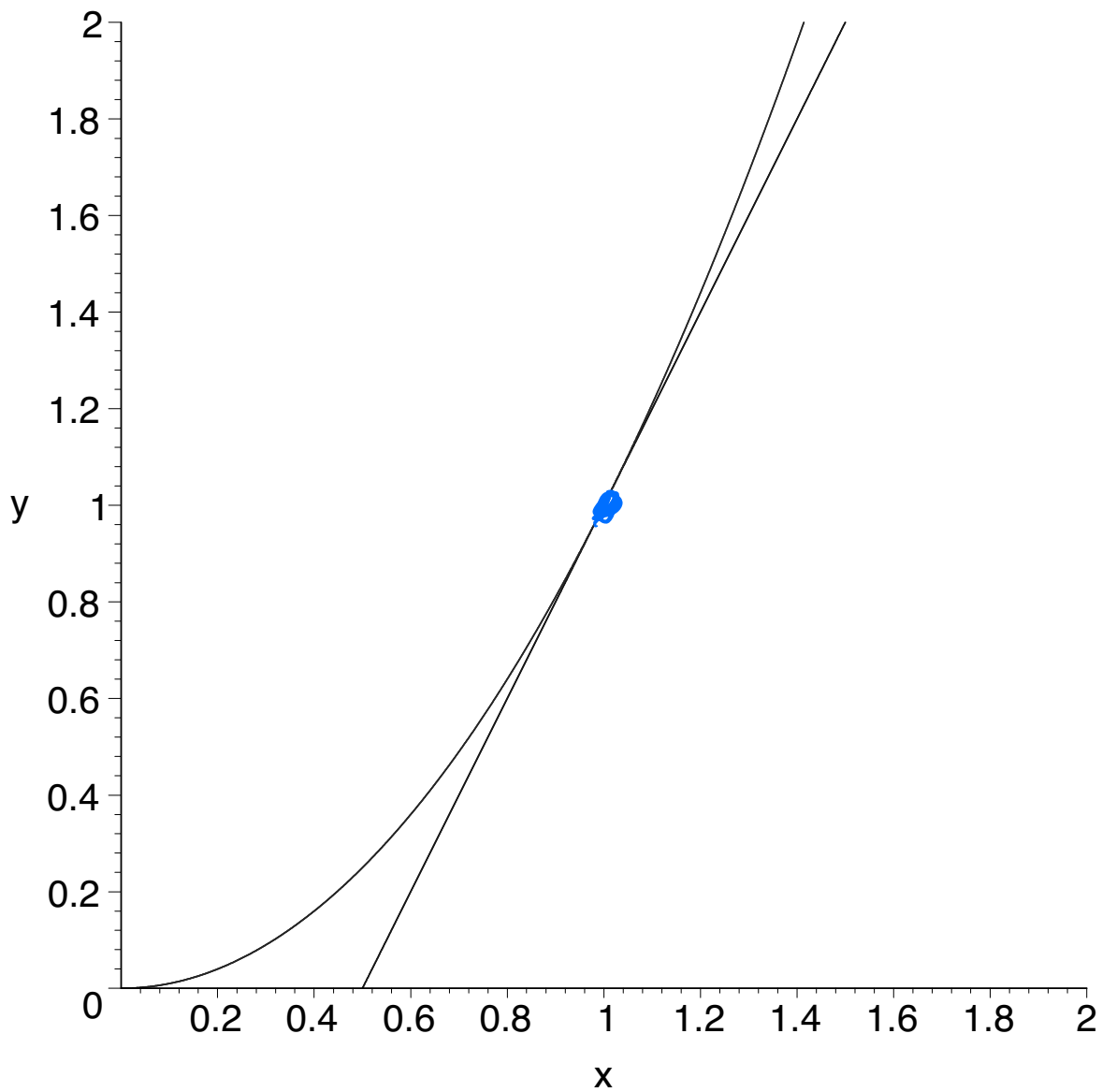


Figure 1. Linear Approximation of $f(x) = x^2$.

- Another Example: You manufacture cubes. Their nominal length s (and width and height) are 12 inches. How will an error of Δs effect the volume (and weight and material cost) of the cube?

$$f(s) = s^3 = V$$

$$f'(s) = 3 \cdot s^2$$

$$\Delta V \approx 3 \cdot 12^2 (s-12) = 3 \cdot 144 \Delta s$$

- Here is a similar Table as in the first example:

Δs	$s_0 + \Delta s$	$f(s_0 + \Delta s)$	$f(s_0) + f'(s_0)\Delta s$	
Δs	$12 + \Delta s$	$(12 + \Delta s)^3$	$12^3 + 3 \times 144 \times \Delta s$	error
1	13	2197	2160	37
0.1	12.1	1771.561	1771.2	0.361000
0.01	12.01	1732.323601	1732.32	0.003601
0.001	12.001	1728.432036	1728.432	0.000036

- In this case we reduce the change by a factor 10 each time, and the error is reduced by a factor $100 = 10^2$.

Notation

- The notation and terminology is confusing. Don't lose track of the key idea: change in output equals approximately the change in input multiplied with the derivative.
- We consider the equation $y = f(x)$. x is the independent variable, y the dependent variable.
- Δx is an arbitrary increment in the independent variable.
- $dx = \Delta x$ is called the **differential** of the independent variable x .
- $\Delta y = \Delta f = f(x + \Delta x) - f(x)$ is the actual change in the dependent variable (or the function, or the output).
- dy is the **differential** of the dependent variable y , defined by

$$dy = f'(x)dx \quad (1)$$

In this context you can think of both dy and dx as ordinary variables. The equation (1) is extremely suggestive. It can be rewritten as

$$f'(x) = \frac{dy}{dx} \quad (2)$$

- Previously we thought of (2) as a short hand notation for derivatives. Now we are thinking of the differential dx and dy as variables.

$$y = f(x)$$

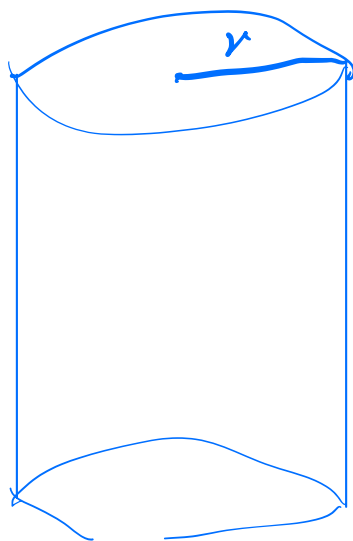
- However, with this new notation we have the key fact

$$\Delta y \approx dy = f'(x)dx$$

$$f'(x) = \frac{dy}{dx}$$

- Again, this captures the key idea: change in output equals approximately the change in input multiplied with the derivative.

- Another Example. Let's consider a cylinder. How does a relative error in radius ($\frac{\Delta r}{r}$) or height ($\frac{\Delta h}{h}$), affect the relative error in the volume ($\frac{\Delta V}{V}$)?
- The relative error might be measured in percent.



$$V = \pi r^2 h$$

$$D_r V = 2\pi r h$$

$$D_h V = \pi r^2$$

(r)

$$\Delta V \approx 2\pi r h \cdot \Delta r \quad \div V$$

$$\frac{\Delta V}{V} \approx \frac{2\pi r h \cdot \Delta r}{\pi r^2 h} = \frac{2 \Delta r}{r} = 2 \cdot \frac{\Delta r}{r}$$

$$\Delta V \approx \pi r^2 \Delta h$$

$$\frac{\Delta V}{V} \approx \frac{\pi r^2 \Delta h}{\pi r^2 h} = \frac{\Delta h}{h}$$

cube

$$V = s^3$$

$$V' = 3s^2$$

$$\Delta V \approx 3s^2 \Delta s$$

$$\frac{\Delta V}{V} \approx \frac{3s^2}{s^3} \Delta s = 3 \frac{\Delta s}{s}$$

- Casually speaking, when making cylinders, it's more important (twice as important!) to get the radius right, than to get the height right.

Aside: More Confusion $\frac{d}{dx} f(u(x)) = f'(u(x))u'(x)$
 $= \frac{df}{du} \frac{du}{dx}$

- Using the Leibniz notation

$$f'(x) = \frac{dy}{dx}$$

and at the same time thinking of the differentials as variables can lead to confusing notation.

- For example, recall the product rule:

$$\frac{d}{dx}(uv) = uv' + vu' \quad (3)$$

$$\frac{d(uv)}{dx} = u \frac{dv}{dx} + v \frac{du}{dx}$$

- “Multiplying with dx ” turns this into

$$d(uv) = u dv + v du \quad (4)$$

- The textbook does use this notation in some places. See the Table on page 143 (and the box in the margin next to that Table). I think of that notation as extremely confusing, and avoid it when possible. You can go from (4) to (3) by “dividing by dx ”.