

Math 5440
Wed 11/17

HW will be due Wed
next week. Do you want
a Tues or Mond. problem session?

(1)

Chapter 7 of Strauss text: Green's functions and divergence theorem
major for Laplace's equation

Note: Strauss is working in $\mathbb{R}^3$. We will include $\mathbb{R}^2$ and $\mathbb{R}^n$ $n \geq 3$, at the same time.

• Recall these FTC's for bounded, piecewise smooth domains $\Omega \subset \mathbb{R}^n$

$$(i) \int_{\Omega} \frac{\partial u}{\partial x_i} dV_n = \int_{\partial\Omega} u \hat{e}_i \cdot \hat{n} dV_{n-1}$$

$$(ii) \int_{\Omega} \nabla \cdot \vec{F} dV_n = \int_{\partial\Omega} \vec{F} \cdot \hat{n} dV_{n-1}$$

$$(iii) \int_{\Omega} u \Delta v + \nabla u \cdot \nabla v dV_n = \int_{\partial\Omega} u \nabla v \cdot \hat{n} dV_{n-1}$$

$$(iv) \int_{\Omega} u \Delta v - v \Delta u dV_n = \int_{\partial\Omega} u \nabla v \cdot \hat{n} - v \nabla u \cdot \hat{n} dV_{n-1}$$

Strauss notation

$\nabla \cdot \hat{n} = \frac{\partial v}{\partial n}$ (direc. deriv in $\hat{n}$ dir.)

← with $u=v$ we used this to
show uniqueness for D.P. for
 Δ equation; uniqueness up
to additive const for N.P.

• Now consider the following rotationally symmetric fundamental soltns for Laplace operator

$$K(x) = \frac{1}{2} |x| \quad n=1$$

$$K(\vec{x}) = -\frac{1}{2\pi} \ln |\vec{x}| \quad n=2$$

$$K(\vec{x}) = -\frac{1}{4\pi} \frac{1}{|\vec{x}|} \quad n=3$$

$$K(\vec{x}) = -\frac{1}{c_n} |\vec{x}|^{2-n} \quad n \geq 3 \quad \text{s.t.} \quad \frac{c_n}{n-2} = \text{surface area (volume) of unit sphere } \{\vec{x} \mid |\vec{x}|=1\} \text{ in } \mathbb{R}^n$$

These functions have the property that

$$(i) \Delta K = 0 \quad \text{for } \vec{x} \neq \vec{0} \quad \leftarrow \text{we've checked for } n=1,2,3.$$

$$(ii) \forall \varepsilon > 0, \int_{S_{\varepsilon}^{n-1}(\vec{0})} \nabla K \cdot \hat{n} dV_{n-1} = 1 \quad \left(" = " \int_{B_{\frac{1}{2}}^n(\vec{0})} \Delta K dV_n \right) \quad \leftarrow \text{check this!!}$$

$S_{\varepsilon}^{n-1}(\vec{0})$
↑
radius

$$\text{i.e. } \Delta K = \delta(\vec{x}).$$

↑
 $S^{n-1}(\vec{0})$
↑
center

• Why would it make sense to look for a rotationally symmetric
fundamental soltns?

harmonic
↓

• Notice $K(\vec{x}-\vec{x}_0)$ and $K(\vec{x}-\vec{x}_0) + u(\vec{x})$ will have analogous properties

the magic begins...

Def. Denote the average value of a function over balls or spheres as follows:

$$\int_{S_R^{n-1}(x_0)} u(x) dV_{n-1} = \frac{1}{|S_1^{n-1}| R^{n-1}} \int_{S_R^{n-1}(x_0)} u(x) dV_{n-1}$$

$$\int_{B_R^n(x_0)} u(x) dV_n = \frac{1}{|B_1^n| R^n} \int_{B_R^n(x_0)} u(x) dV_n$$

Theorem 1 (mean value property) Let $u \in C^2(\Omega)$ be harmonic, $\Delta u = 0$.
Let $\overline{B_R(x_0)} \subset \Omega$.

Then

$$u(x_0) = \int_{S_R^{n-1}(x_0)} u(x) dV_{n-1} = \int_{B_R^n(x_0)} u(x) dV_n.$$



Proof: Let $0 < \epsilon < R$.

Let $v(x) = K(x - x_0) - K(R)$.

$$\begin{aligned} 0 &= \int_{B_R(x_0) \setminus B_\epsilon(x_0)} u \Delta v - v \Delta u = \int_{S_R(x_0)} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} - \int_{S_\epsilon(x_0)} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \\ &= I_1 - I_2. \end{aligned}$$

on any sphere $S_r(x_0)$, $\frac{\partial v}{\partial n} = \frac{\partial v}{\partial r} = d_n r^{1-n}$ with $d_n = \frac{1}{|S_1^{n-1}|}$

Thus

$$I_1 = \frac{1}{|S_1^{n-1}| R^{n-1}} \int_{S_R(x_0)} u(x) dx = \int_{S_R(x_0)} u(x) dx.$$

$$-I_2 = - \int_{S_\epsilon(x_0)} u dx + \int_{S_\epsilon(x_0)} v \frac{\partial u}{\partial n}$$

(or $|\ln \epsilon|$ $n=2$)

As $\epsilon \rightarrow 0$, deduce

$$0 = \int_{S_R(x_0)} u(x) dx - u(x_0)$$

$-u(x_0)$ as $\epsilon \rightarrow 0$.

$\downarrow$ as $\epsilon \rightarrow 0$
0



(integral average for balls in $\mathbb{H}^n$)

Theorem 2 Let $u \in C^2(\Omega) \cap C^1(\bar{\Omega})$ satisfy $\Delta u = 0$. Let $x_0 \in \partial\Omega$.
Then for $v(x) = K(x-x_0)$,

$$u(x_0) = \int_{\partial\Omega} u(x) \frac{\partial v}{\partial n} - v(x) \frac{\partial u}{\partial n} dV_{n-1}$$

proof: this is the same proof as in Theorem 1, but applied to $\Omega \setminus B_\varepsilon(x_0)$,
as $\varepsilon \rightarrow 0$.

(not so useful if you want
to solve Dirichlet problem, because
you'd also need Neumann data (& vice versa))

Def (using Strauss' notation). The Green's function $G(x, x_0)$, $G: \bar{\Omega} \times \bar{\Omega} \rightarrow \mathbb{R}$,
for the Dirichlet problem and the operator $-\Delta$ satisfies

(i) $G(x, x_0) \in C^2(\Omega \setminus \{x_0\}) \cap C^1(\bar{\Omega} \setminus \{x_0\})$, $\Delta_x G(x, x_0) = 0$

(ii) $G(x, x_0) = 0 \quad \forall x \in \partial\Omega$

(iii) $G(x, x_0) - K(x-x_0) \in C^2(\Omega)$ and is harmonic.

Theorem Green's functions are unique, symmetric, and they exist
↑ ↑
not hard hard.

Theorem 3 Let $G(x, x_0)$ be the Green's function above. Let u solve

$$\begin{aligned} \Delta u &= 0 \text{ in } \Omega \\ u &= f \text{ on } \partial\Omega \end{aligned}$$

Then for $x_0 \in \partial\Omega$,

$$u(x_0) = \int_{\partial\Omega} u(x) \frac{\partial G(x, x_0)}{\partial n} dV_{n-1}$$

Generalizes Poisson integral
formula to any domain

$$\left(u(x) = \int_{\partial\Omega} u(s) \nabla_s (G(s, x)) \cdot \hat{n} dV_{n-1} \right)$$

Proof : $G(x, x_0) = K(x-x_0) + w(x)$, $w(x)$ harmonic.

Use method of Theorem 2