

①

Math 4530

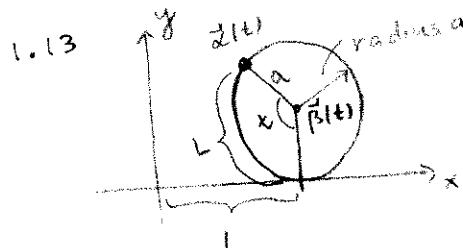
HW set I, Due 1/21

Iabcde : Applications of Pythag thm

Chapter 1:

1.13, 1.14, ~~1.21~~, 1.22, 1.25

2.2, 2.7, 2.8, 3.5



$$L = at = x\text{-coord of center}$$

Let $\vec{P}(t) = \text{coords of disc center}$,

$$\text{so } \vec{P}(t) = \begin{bmatrix} at \\ a \end{bmatrix}$$



$$\vec{z}(t) - \vec{P}(t) = \begin{bmatrix} -a \sin t \\ -a \cos t \end{bmatrix}$$

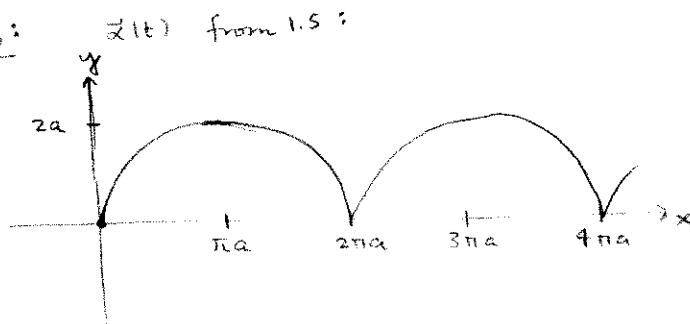
$$1.14 \quad \vec{y}(t) = \begin{bmatrix} A \\ B \end{bmatrix} + a \begin{bmatrix} t - \sin t \\ \cos t - 1 \end{bmatrix}$$

this
translates
by $\begin{bmatrix} A \\ B \end{bmatrix}$

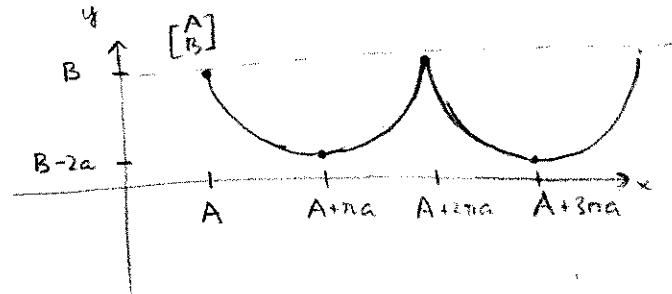
$\underbrace{\hspace{2cm}}$ $\underbrace{\hspace{2cm}}$
this is reflection of $\vec{z}(t)$ across x -axis [same x -coord
opposite y -coord]

$$\text{so } \vec{y}(t) = \begin{bmatrix} at \\ a \end{bmatrix} + \begin{bmatrix} -a \sin t \\ -a \cos t \end{bmatrix} = a \begin{bmatrix} t - \sin t \\ 1 - \cos t \end{bmatrix}$$

graphs:



$\vec{y}(t)$ from 1.6



1.14 cont'd.

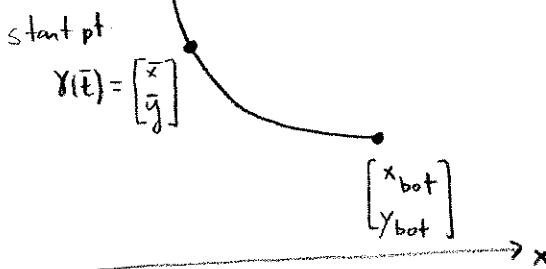
(2)

this a difficult model.

KE PE

$$\text{Physics: } \frac{1}{2}mv^2 + mgy = \text{const} = mg\bar{y}$$

since particle starts at rest.



$$\text{Thus } \frac{1}{2}v^2 + g(y - \bar{y}) = 0$$

Since "t" has already been reserved as the parameter in the cycloid, let us temporarily use "s" for time,
 $0 \leq s \leq T$

as the particle moves x is an increasing fun of s ,

$$\text{in fact speed } v = \sqrt{(dx/ds)^2 + (dy/ds)^2} \quad \frac{dy}{ds} = \frac{dy}{dx} \frac{dx}{ds}$$

$$\sqrt{2g(\bar{y} - y)} = v = \sqrt{1 + (y')^2} \frac{dx}{ds} \quad y' = \frac{dy}{dx}$$

physics box

so also s is an increasing fun of x (1 var inv fun thm)

$$T = \int_0^T ds = \int_x^{x_{bot}} \frac{ds}{dx} dx = \int_x^{x_{bot}} \sqrt{\frac{1 + (y')^2}{2g(\bar{y} - y)}} dx \quad \left(\frac{ds}{dx} = \frac{1}{(dx/ds)} = \frac{\sqrt{1 + (y')^2}}{\sqrt{2g(\bar{y} - y)}} \right)$$

now do another change of variables,
from the cycloid parameterization

$$x(t) = A + a(t - \sin t), \quad y(t) = B + a(\cos t - 1)$$

$$dx = a(1 - \cos t)dt \quad \frac{dy}{dx} = \frac{dy/dt}{dx/dt} = \frac{-a \sin t}{a(1 - \cos t)} = \frac{\sin t}{1 - \cos t}$$

$$\text{so } T = \int_{\frac{1}{\sqrt{2g}}}^{\pi} \sqrt{1 + \left(\frac{\sin t}{1 - \cos t}\right)^2} a(1 - \cos t) dt$$

$$\bar{y} - y = B + a(\cos t - 1) - [B - a(\cos t - 1)] \\ = a(\cos t - \cos t)$$

$$1 - 2\cos t + \cos^2 t + \sin^2 t = 2 - 2\cos t$$

$$T = \sqrt{\frac{a}{2g}} \int_{\frac{1}{\sqrt{2}}}^{\pi} \sqrt{\frac{(1 - \cos t)^2 + \sin^2 t}{\cos t - \cos t}} dt$$

Whew!

$$T = \sqrt{\frac{a}{g}} \int_{\frac{1}{\sqrt{2}}}^{\pi} \sqrt{\frac{1 - \cos t}{\cos t - \cos t}} dt$$

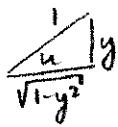
(3)

$$u = \arcsin y$$

$$\sin u = y$$

$$(\cos u) \frac{du}{dy} = 1$$

$$\frac{du}{dy} = \frac{1}{\sqrt{1-y^2}}$$



$$\begin{aligned} \frac{d}{dt} \arcsin \left[\frac{\sqrt{2} \cos t/2}{\sqrt{1+\cos^2 t}} \right] \\ = \frac{1}{\sqrt{1-\frac{2\cos^2 t/2}{1+\cos^2 t}}} \frac{\sqrt{2}}{\sqrt{1+\cos t}} \left(-\frac{1}{2} \sin t/2 \right) \\ = -\frac{1}{\sqrt{2}} \frac{\sin t/2}{\sqrt{1+\cos t - 2\cos^2 t/2}} \end{aligned}$$

so, as claimed,

$$\begin{aligned} T &= \sqrt{\frac{a}{g}} (-2) \arcsin \left[\frac{\sqrt{2} \cos t/2}{\sqrt{1+\cos^2 t}} \right] \Big|_0^\pi \\ &= -2\sqrt{\frac{a}{g}} \left[\arcsin 0 - \arcsin \left[\frac{\sqrt{2} \cos t/2}{\sqrt{1+\cos^2 t}} \right] \right] \\ &= -2\sqrt{\frac{a}{g}} \left[\arcsin \left(\frac{\sqrt{2} \cos t/2}{\sqrt{1+\cos^2 t}} \right) \right] \Big|_0^\pi \\ &= 2\sqrt{\frac{a}{g}} \pi/4 = \frac{\pi}{2} \sqrt{\frac{a}{g}} \end{aligned}$$

$$\begin{aligned} \cos t &= 1 - 2\sin^2 t/2 ; \quad \sin t/2 = \sqrt{\frac{1-\cos t}{2}} \\ &= 2\cos^2 t/2 - 1 \\ &= -\frac{1}{\sqrt{2}} \frac{\sqrt{1-\cos t}}{\sqrt{\cos t - \cos t}} = -\frac{1}{2} \sqrt{\frac{1-\cos t}{\cos t - \cos t}} \quad \checkmark \end{aligned}$$

$$T = \frac{\pi}{2} \sqrt{\frac{a}{g}}$$

not assigned

$$\begin{aligned} 1.76 \cos 3t &= \cos t (\cos 2t) - \sin t \sin 2t \\ &= \cos t (\cos^2 t - \sin^2 t) - 2\sin^2 t \cos t \\ &= \cos t (\cos^2 t - 3\sin^2 t) \\ &= \cos t (4\cos^2 t - 3) \\ \cos 3t &= -3\cos t + 4\cos^3 t \end{aligned}$$

$$\text{so } a \left[\frac{3}{4} \cos t + \frac{1}{4} \cos^3 t \right]$$

$$= a \cos^3 t \quad \checkmark$$

$$\begin{aligned} \sin 3t &= \sin 2t \cos t + \cos 2t \sin t \\ &= 2\sin t \cos^2 t + (\cos^2 t - \sin^2 t) \\ &= \sin t (3\cos^2 t - \sin^2 t) \\ &= \sin t (3 - 4\sin^2 t) \end{aligned}$$

$$\begin{aligned} \text{so } a \left[\frac{3}{4} \sin t - \frac{1}{4} \sin 3t \right] \\ = a \sin^3 t \quad \checkmark \end{aligned}$$

$$\text{if } \alpha(t) = \begin{bmatrix} a \cos^3 t \\ a \sin^3 t \end{bmatrix}$$

$$\text{then } x^{\frac{2}{3}} + y^{\frac{2}{3}} = a^{\frac{2}{3}} \left[\cos^2 t + \sin^2 t \right] = a^{\frac{2}{3}}$$

little circle center
 $\frac{3}{4}a \begin{bmatrix} \cos t \\ \sin t \end{bmatrix} + \frac{a}{4} \begin{bmatrix} \cos(3t) \\ \sin(3t) \end{bmatrix}$

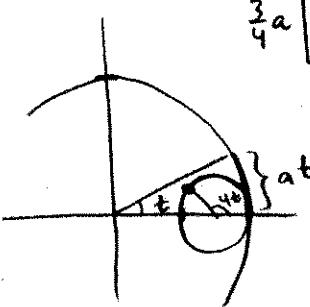
displacement from origin

conversely if $x^{\frac{2}{3}} + y^{\frac{2}{3}} = a^{\frac{2}{3}}$

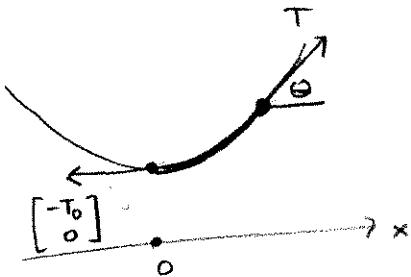
$$\text{then } \begin{bmatrix} x^{\frac{2}{3}} \\ y^{\frac{2}{3}} \end{bmatrix} \text{ is on circle of rad } a^{\frac{1}{3}}$$

$$\text{so may write } \begin{aligned} x^{\frac{2}{3}} &= a^{\frac{1}{3}} \cos t \\ y^{\frac{2}{3}} &= a^{\frac{1}{3}} \sin t \end{aligned} \quad \blacksquare$$

$$\text{so } \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} a \cos^3 t \\ a \sin^3 t \end{bmatrix}$$



1.22



horizontal force balancing: $T \cdot \vec{e}_1 = T_0$
 $\text{so } \vec{T} = \begin{bmatrix} T_0 \\ T_0 y' \end{bmatrix} \text{ since } \vec{T} \parallel \begin{bmatrix} 1 \\ y' \end{bmatrix}$

on the other hand, the right end (at "x") is holding up the whole cable piece from the center:

$$\int_0^x W\sqrt{1+(y'(s))^2} ds = T_0 y'$$

$$\frac{d}{dx}: W\sqrt{1+y'(x)^2} = T_0 y'' \quad \blacksquare$$

(let $z = \frac{dy}{dx}$ then

$$\frac{dz}{dx} = \frac{W}{T_0} \sqrt{1+z^2}$$

$$\frac{dz}{\sqrt{1+z^2}} = \frac{W}{T_0} dx$$

$$z = \sinh u$$

$$dz = \cosh u du$$

$$\sqrt{1+z^2} = \cosh u$$

$$u = \int du = \frac{W}{T_0} x + C$$

$$z = \sinh u = \sinh\left(\frac{W}{T_0} x + C\right)$$

$$z(0) = 0 \text{ so}$$

$$z = \sinh\left(\frac{W}{T_0} x\right)$$

$$\text{so } y = \int z dx = \frac{T_0}{W} \cosh\left(\frac{W}{T_0} x\right) + D$$

$$(1.25) \vec{\alpha}(t) = \begin{bmatrix} \frac{W}{T_0} \cos t \\ \sin t \\ \frac{1}{T_0} \cos t \end{bmatrix} \quad 0 \leq t \leq 2\pi$$

$$\vec{\alpha}'(t) = \begin{bmatrix} -\frac{W}{T_0} \sin t \\ \cos t \\ -\frac{1}{T_0} \sin t \end{bmatrix} \quad \|\alpha'(t)\|^2 = 1$$

$$\text{so } L(\alpha) = 2\pi$$

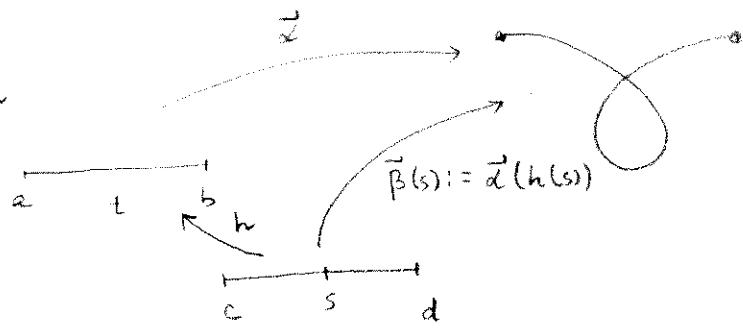
$$\vec{\alpha}'' = -\vec{\alpha}$$

$\vec{\alpha}$ is a circle of radius 1, centered at the origin ($\|\alpha(t)\|^2 = 1$), and lying on the plane $x-z=0$

(so it is the intersection of this plane thru the origin with the unit sphere.)

(5)

2.2



$$L = \int_a^b \| \vec{\alpha}'(t) \| dt \quad \text{if } t = h(s) \\ dt = h'(s) ds \\ \text{then } L = \int_{h^{-1}(a)}^{h^{-1}(b)} \| \vec{\alpha}'(h(s)) \| h'(s) ds$$

Case 1: $h'(s) > 0$, then

$$L = \int_c^d \| \vec{\alpha}'(h(s)) \| h'(s) ds$$

$$\text{But } \vec{\beta}'(s) = \vec{\alpha}'(h(s)) h'(s) \\ \| \vec{\beta}' \| = \| \vec{\alpha}' \| \| h' \|$$

$$= \int_c^d \| \vec{\beta}'(s) \| ds$$

Case 2: $h'(s) < 0$, then

$$L = \int_d^c \| \vec{\alpha}'(h(s)) \| h'(s) ds = \int_d^c - \| \vec{\beta}'(s) \| ds \quad (\text{since } h' < 0) \\ = \int_c^d \| \vec{\beta}'(s) \| ds \quad (\text{reverse limits})$$

1.2.2 Arc length invariance under reparameterization:

$$\alpha: [a, b] \rightarrow \mathbb{R}^3, \quad \beta(r): [c, d] \rightarrow \mathbb{R}^3,$$

$$h: [c, d] \rightarrow [a, b], \quad h(c) = a, \quad h(d) = b, \quad h'(r) \geq 0.$$

Show $L(\alpha) = L(\beta)$:

Pf

$$\int_c^d \|\beta'(r)\| dr = \int_a^b \|\alpha'(h(r)) \cdot \frac{dh}{dr}(r)\| dr$$

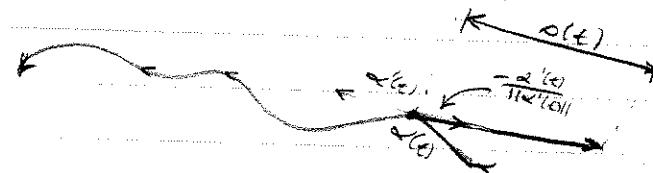
$$= \int_c^d \|\alpha'(h(r))\| \cdot h'(r) dr$$

$$= \int_{h(c)}^{h(d)} \|\alpha'(u)\| du = \int_a^b \|\alpha'(u)\| du$$

this is always
nonnegative

1.2.7 Involute curve:

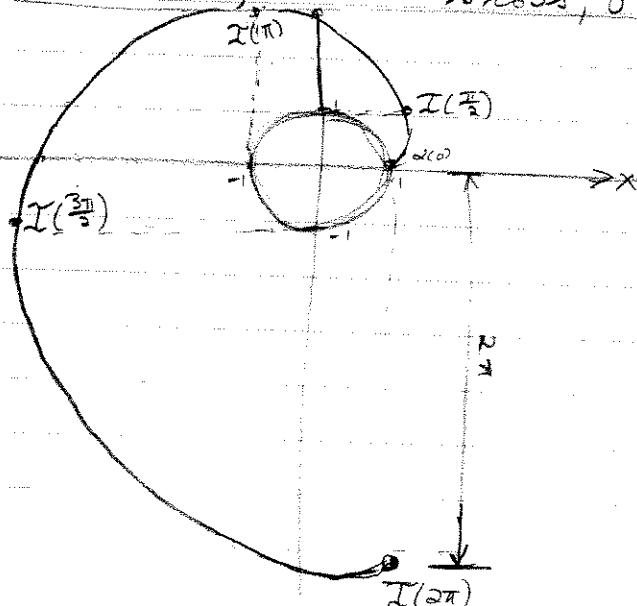
- (a) Let $\alpha: [a, b] \rightarrow \mathbb{R}^3$. For each $t \in [a, b]$, start at $\alpha(t)$, then move $s(t)$ units in the opposite direction of $\alpha'(t)$;
i.e. $I(t) = \alpha(t) - s(t) \frac{\alpha'(t)}{\|\alpha'(t)\|}$.



- (b) Involute of unit circle. $\alpha(t) = (\cos t, \sin t, 0)$.
 $\|\alpha'(t)\| = 1 \Rightarrow I(s) = \alpha(s) - s\alpha'(s)$

$$\Rightarrow I(s) = (\cos s + s \sin s, \sin s - s \cos s, 0)$$

* Involute of the unit circle \rightarrow



Thanks Ben!

⑦

1.2.8 Involute of a helix is a plane curve

P4

$$I(t) = \alpha(t) - s(t) \frac{\alpha'(t)}{\|\alpha'(t)\|}$$

$$\alpha(t) = \begin{bmatrix} a \cos t \\ a \sin t \\ bt \end{bmatrix} \Rightarrow \alpha'(t) = \begin{bmatrix} -a \sin t \\ a \cos t \\ b \end{bmatrix}$$

$$\Rightarrow \|\alpha'(t)\| = \sqrt{a^2 + b^2} = c$$

$$s(t) = \int_0^t c dt = ct \Rightarrow I(t) = \alpha(t) - \frac{ct}{c} \alpha'(t)$$

$$\Rightarrow I(t) = \begin{bmatrix} a(\cos t + t \sin t) \\ a(\sin t - t \cos t) \\ 0 \end{bmatrix}$$

$I(t)$ never leaves the xy -plane.

1.3.5 $\|\nabla \times \vec{w}\|^2 = \|\nabla\|^2 \|\vec{w}\|^2 - (\nabla \cdot \vec{w})^2$

$$\text{LHS} = \|\nabla \times \vec{w}\|^2 = (\nabla \times \vec{w}) \cdot (\nabla \times \vec{w}) =$$

$$= (v_2 w_3 - v_3 w_2)^2 + (v_3 w_1 - v_1 w_3)^2 + (v_1 w_2 - v_2 w_1)^2 =$$

$$= v_2^2 w_3^2 + v_3^2 w_2^2 - 2v_2 v_3 w_2 w_3 +$$

$$+ v_1^2 w_3^2 + v_3^2 w_1^2 - 2v_1 v_3 w_1 w_3 +$$

$$+ v_1^2 w_2^2 + v_2^2 w_1^2 - 2v_1 v_2 w_1 w_2 =$$

$$= v_1^2 (w_2^2 + w_3^2) + v_2^2 (w_1^2 + w_3^2) + v_3^2 (w_1^2 + w_2^2) - 2v_1 v_2 w_1 w_2 - 2v_1 v_3 w_1 w_3 - 2v_2 v_3 w_2 w_3$$

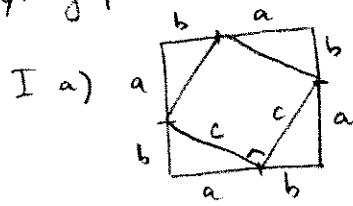
$$= v_1^2 (w_1^2 + w_2^2 + w_3^2) + v_2^2 (w_1^2 + w_2^2 + w_3^2) + v_3^2 (w_1^2 + w_2^2)$$

$$- v_1^2 w_1^2 - v_2^2 w_2^2 - v_3^2 w_3^2 - 2v_1 v_2 w_1 w_2 - 2v_1 v_3 w_1 w_3 - 2v_2 v_3 w_2 w_3$$

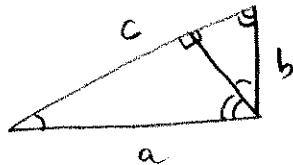
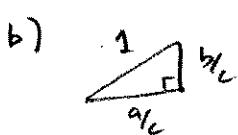
$$= (v_1^2 + v_2^2 + v_3^2)(w_1^2 + w_2^2 + w_3^2) - (v_1 w_1 + v_2 w_2 + v_3 w_3)^2$$

$$= (\nabla \cdot \vec{w})(\vec{w} \cdot \vec{w}) - (\nabla \cdot \vec{w})^2 = \|\nabla\|^2 \|\vec{w}\|^2 - (\nabla \cdot \vec{w})^2 = \text{RHS. } \checkmark$$

Pythag prob.

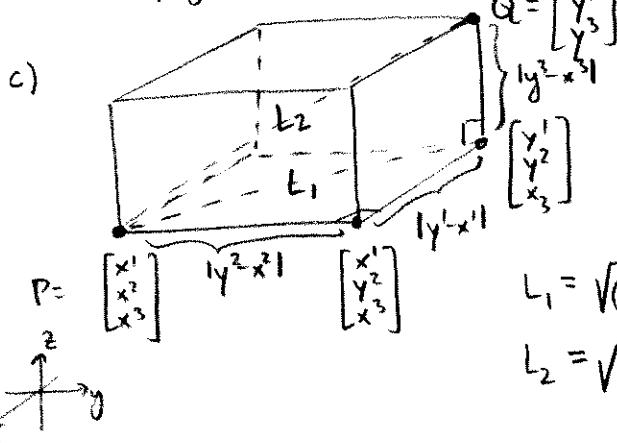


$$\begin{aligned} \text{Area} &= (a+b)^2 = a^2 + 2ab + b^2 \quad (\text{square } (a+b) \text{ by } (a+b)) \\ &= c^2 + 2ab \quad (c \times c \text{ square} + 4 \Delta's \text{ with base } a \text{ & ht } b) \\ \text{thus } a^2 + b^2 &= c^2! \end{aligned}$$



ref Δ
area A_0

dilate ref Δ by factor of c ,
to get big Δ
 $A = c^2 A_0$



but this Δ is union of two similar Δ 's, one scaled by factor of a , other by b , from ref Δ , so also

$$A = a^2 A_0 + b^2 A_0$$

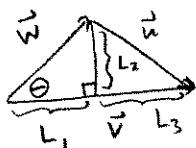
Hence $a^2 + b^2 = c^2$!

$$L_1 = \sqrt{(y^2 - x^2)^2 + (y^1 - x^1)^2}$$

$$L_2 = \sqrt{L_1^2 + (y^3 - x^3)^2} = \sqrt{(y^1 - x^1)^2 + (y^2 - x^2)^2 + (y^3 - x^3)^2}$$

d) Law of cosines

Case I $\theta < \pi/2$. By name choice, assume $\|\vec{w}\| \leq \|\vec{v}\|$ so have diagram



$$L_1 = \|\vec{w}\| \cos \theta$$

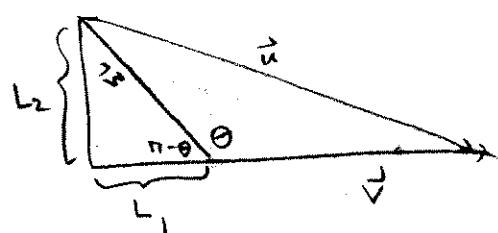
$$L_3 = \|\vec{v}\| - L_1$$

$$L_2 = \|\vec{w}\| \sin \theta$$

$$\begin{aligned} \|\vec{u}\|^2 &= L_2^2 + L_3^2 \\ &= \|\vec{w}\|^2 \sin^2 \theta + (\|\vec{v}\| - \|\vec{w}\| \cos \theta)^2 \\ &= \|\vec{w}\|^2 (\sin^2 \theta + \cos^2 \theta) + \|\vec{v}\|^2 - 2 \|\vec{v}\| \|\vec{w}\| \cos \theta \\ &= \|\vec{w}\|^2 + \|\vec{v}\|^2 - 2 \|\vec{v}\| \|\vec{w}\| \cos \theta \quad \checkmark \end{aligned}$$

($\theta = \pi/2$ is Pythag thm)

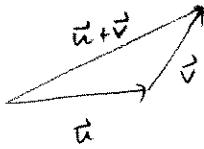
Case II $\theta > \pi/2$, $\|\vec{w}\| > \|\vec{v}\|$



$$\begin{aligned} \|\vec{u}\|^2 &= (\|\vec{v}\| + L_1)^2 + L_2^2 \\ &= (\|\vec{v}\| + \|\vec{w}\| \cos(\pi - \theta))^2 + \|\vec{w}\| \sin(\pi - \theta)^2 \\ &= \|\vec{v}\|^2 + \|\vec{w}\|^2 + 2 \|\vec{v}\| \|\vec{w}\| \underbrace{\cos(\pi - \theta)}_{-\cos \theta} \end{aligned}$$

(7)

Ie)



$$\begin{aligned}\|\vec{u} + \vec{v}\|^2 &= (\vec{u} + \vec{v}) \cdot (\vec{u} + \vec{v}) \\ &= \vec{u} \cdot \vec{u} + 2\vec{u} \cdot \vec{v} + \vec{v} \cdot \vec{v} \\ &= \|\vec{u}\|^2 + 2\vec{u} \cdot \vec{v} + \|\vec{v}\|^2\end{aligned}$$

$$\begin{aligned}&\leq \|\vec{u}\|^2 + 2\|\vec{u}\|\|\vec{v}\| + \|\vec{v}\|^2 \quad \text{equality iff} \\ &= (\|\vec{u}\| + \|\vec{v}\|)^2 \quad \begin{matrix} \cos\theta = 1 \\ \theta = 0 \end{matrix}\end{aligned}$$

so $\|\vec{u} + \vec{v}\| \leq \|\vec{u}\| + \|\vec{v}\|$

equality iff \vec{u}, \vec{v} are positive scalar multiples.

END!