

Math 4530

Monday 2/14

Example

Compute and interpret the shape operator at $P = (0,0,0)$, for the Monge patch

$$\vec{X}(x,y) = x\vec{e}_1 + y\vec{e}_2 + (x^2 + y^2 + 3xy)\vec{e}_3$$

This is a special case of graphing a surface locally above its tangent plane at $P \in M^2$, which can be done for any point

$$\vec{X}_x = \begin{bmatrix} 1 \\ 0 \\ 2x+3y \end{bmatrix} \quad \leftarrow \text{using coords wrt } \{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\vec{X}_y = \begin{bmatrix} 0 \\ 1 \\ 2y+3x \end{bmatrix}$$

$$\vec{U} = \begin{bmatrix} -2x-3y \\ -2y-3x \\ 1 \end{bmatrix} \frac{1}{\sqrt{1+Q(x,y)}}$$

$Q(x,y)$ quadratic in x,y .

at $P = (0,0,0)$, $\vec{X}_x = \vec{e}_1$, $\vec{X}_y = \vec{e}_2$

$$S(\vec{X}_x) = -\nabla_{\vec{X}_x} \vec{U} = -\vec{U}_x$$

$$\text{at } P = \begin{bmatrix} +2 \\ +3 \\ 0 \end{bmatrix} = 2\vec{e}_1 + 3\vec{e}_2$$

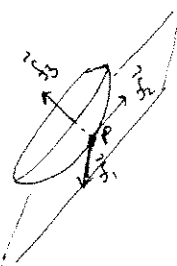
$$S(\vec{X}_y) = -\vec{U}_y = \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix} = 3\vec{e}_1 + 2\vec{e}_2$$

so at P ,

$$[S]_{\{\vec{e}_1, \vec{e}_2\}} = \begin{bmatrix} 2 & 3 \\ 3 & 2 \end{bmatrix}$$

$\uparrow \quad \quad \uparrow$
 $[S(\vec{e}_1)]_{\{\vec{e}_1, \vec{e}_2\}} \quad [S(\vec{e}_2)]_{\{\vec{e}_1, \vec{e}_2\}}$

Notice this is the Hessian matrix of 2nd partials of $x^2 + y^2 + 3xy$, evaluated at $(0,0)$



$$Z(x,y) = P + x\vec{f}_1 + y\vec{f}_2 + g(x,y)\vec{f}_3, \quad \nabla g(0,0) = \vec{0}$$

$$T_P M = \text{span}\{\vec{f}_1, \vec{f}_2\}$$

$$\vec{f}_3 = \vec{f}_1 \times \vec{f}_2 = \vec{U}(P)$$

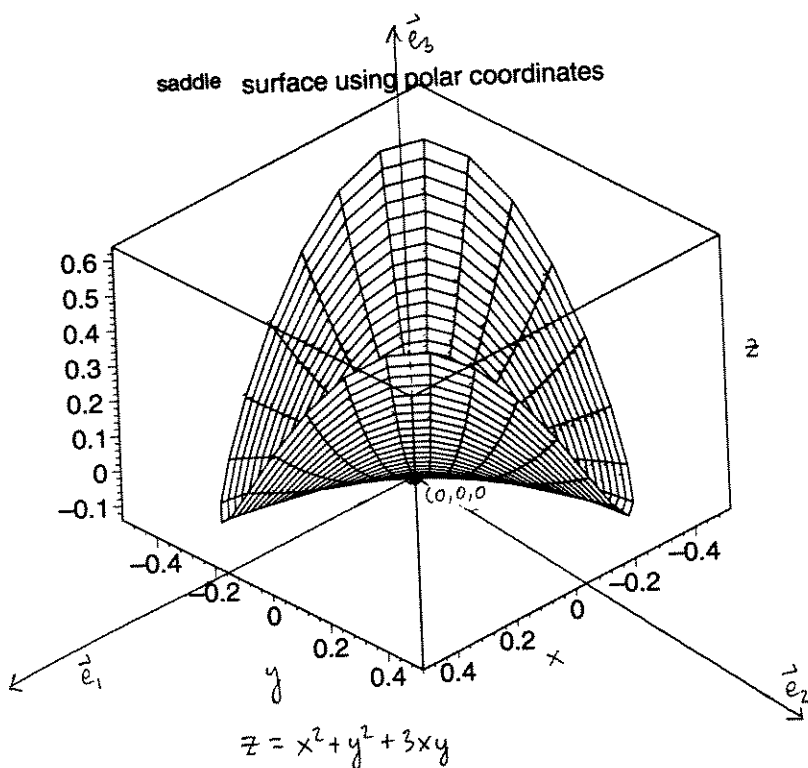
$(\{\vec{f}_1, \vec{f}_2, \vec{f}_3\})$ orthonormal

$$\vec{Z}_x = \begin{bmatrix} 1 \\ 0 \\ g_x \end{bmatrix}$$

$$\vec{Z}_y = \begin{bmatrix} 0 \\ 1 \\ g_y \end{bmatrix}$$

$$\vec{U} = \begin{bmatrix} -g_x \\ -g_y \\ 1 \end{bmatrix} \frac{1}{\sqrt{1+g_x^2+g_y^2}}$$

(expressed in coords for the $\{\vec{f}_1, \vec{f}_2, \vec{f}_3\}$ basis)



unit eigenvectors of S
are called the principal directions

eigenvalues k_1, k_2 are
principal curvatures

Find them!

$$S\vec{v} = \lambda \vec{v}$$

$$\Leftrightarrow [S\vec{v}]_{\{\vec{e}_1, \vec{e}_2\}} = \lambda [\vec{v}]_{\{\vec{e}_1, \vec{e}_2\}}$$

$$\begin{bmatrix} 2 & 3 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \lambda \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$0 = \begin{vmatrix} 2-\lambda & 3 \\ 3 & 2-\lambda \end{vmatrix} = (\lambda-2)^2 - 9 \\ = (\lambda-2-3)(\lambda-2+3) \\ = (\lambda-5)(\lambda+1)$$

$$k_1 \\ \lambda = 5$$

$$\begin{array}{cc|c} -3 & 3 & 0 \\ 3 & -3 & 0 \\ \hline -1 & 1 & 0 \\ 0 & 0 & 0 \end{array}$$

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$k_2 \\ \lambda = -1$$

$$\begin{array}{cc|c} 3 & 3 & 0 \\ 3 & 3 & 0 \\ \hline 1 & 1 & 0 \\ 0 & 0 & 0 \end{array}$$

$$\vec{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

New basis for $T_P M$:

$$\mathcal{B} = \left\{ \frac{1}{\sqrt{2}}(\vec{e}_1 + \vec{e}_2), \frac{1}{\sqrt{2}}(-\vec{e}_1 + \vec{e}_2) \right\} \\ = \{ \vec{w}_1, \vec{w}_2 \}$$

$$S(\vec{w}_1) = 5\vec{w}_1$$

$$S(\vec{w}_2) = -\vec{w}_2$$

Can you see this in the
page 1 picture?

In fact, if we change coordinates to the $\{\vec{w}_1, \vec{w}_2\}$ basis

$$x\vec{e}_1 + y\vec{e}_2 = r\vec{w}_1 + s\vec{w}_2$$

$$\Rightarrow x = (r\vec{w}_1 + s\vec{w}_2) \cdot \vec{e}_1 = \frac{1}{\sqrt{2}}(r-s)$$

$$y = (r\vec{w}_1 + s\vec{w}_2) \cdot \vec{e}_2 = \frac{1}{\sqrt{2}}(r+s)$$

$$x^2 + y^2 + 3xy = \frac{1}{2}(r-s)^2 + \frac{1}{2}(r+s)^2 + \frac{3}{2}(r-s)(r+s)$$

$$= \frac{5}{2}r^2 - \frac{1}{2}s^2$$

So better param is

$$\tilde{X}(r, s) = r\vec{w}_1 + s\vec{w}_2 + \left(\frac{5}{2}r^2 - \frac{1}{2}s^2\right)\vec{e}_3$$

(We knew this result based on shape computations on left,
and general Hessian result on right)

(2)

general graph above tangent plane
continued

$$Z_x(0,0) = \vec{f}_1$$

$$Z_y(0,0) = \vec{f}_2$$

$$\text{so } S(\vec{f}_1) = -\nabla_{\vec{f}_1} \vec{U} = -\vec{U}_x \quad \text{at } P$$

$$= \begin{bmatrix} +g_{xx}(\vec{0}) \\ +g_{yx}(\vec{0}) \\ 0 \end{bmatrix} = g_{xx}\vec{f}_1 + g_{yx}\vec{f}_2$$

$$S(\vec{f}_2) = -\vec{U}_y \quad \text{at } P, = \begin{bmatrix} g_{xy} \\ g_{yy} \end{bmatrix}$$

at P ,

$$[S] = \begin{bmatrix} g_{xx}(\vec{0}) & g_{xy}(\vec{0}) \\ g_{yx}(\vec{0}) & g_{yy}(\vec{0}) \end{bmatrix}$$

matrix wrt $\{\vec{f}_1, \vec{f}_2\}$ basis

Remark: This is another proof
that the shape operator is
self adjoint, since its matrix
with respect to the orthonormal
basis $\{\vec{f}_1, \vec{f}_2\}$ is symmetric.

Thus, as at left example, spectral
theorem guarantees an ortho-normal
eigenbasis for the shape operator

Hessian discussion cont'd.

Recall for a fn of 2 variables, the Hessian matrix is used to measure 2nd directional derivatives at a point

If point is $(0,0)$, fn is $g(x,y)$, direction is $\langle a,b \rangle$, then

$$\left. \frac{d^2}{dt^2} g(ta, tb) \right|_{t=0} = \left(g_x(\cdot)a + g_y(\cdot)b \right)' \Big|_{t=0} = g_{xx}a^2 + g_{xy}ab + g_{yx}ab + g_{yy}b^2$$

$$= [a \ b] \begin{bmatrix} g_{xx} & g_{xy} \\ g_{yx} & g_{yy} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

If we use the rotated basis $\{\vec{w}_1, \vec{w}_2\}$

in page 1 $\rightarrow$ 2 example, this becomes (in the r -s variables)

$$\left. \frac{d^2}{dt^2} g(t \cos \theta \vec{w}_1 + t \sin \theta \vec{w}_2) \right|_{t=0} = [\cos \theta, \sin \theta] \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$$

$$= 5 \cos^2 \theta - \sin^2 \theta$$

so these pure 2nd directional derivatives are between -1 and 5, as the page 1 picture illustrated.

Gauss and Mean Curvature

If $S: V \rightarrow V$ is linear,

then $\det(S)$, $\text{trace}(S) \leftarrow$ (sum of diagonal elements)

are well defined, i.e. you can use the matrix of S with respect to any basis to compute them

$$(\text{since } \det(ASA^{-1}) = (\det A)(\det S) \frac{1}{\det A} = \det S)$$

$$\text{and since } \text{trace}(AB) = \sum_i [AB]_{ii} = \sum_{i,j} a_{ij} b_{ji} \quad \text{so } \text{trace}(ASA^{-1})$$

$$\text{trace}(BA) = \sum_i [BA]_{ii} = \sum_{i,j} b_{ij} a_{ji} \quad = \text{trace}(SA^{-1}A) = \text{trace } S.$$

$K :=$ Gauss curvature

$$= \det(S)$$

$S =$ Shape operator

} has an interesting interpretation in terms of area ratios for the normal map $\mathcal{U}: M^2 \rightarrow S^2$, called the Gauss map.

$H :=$ Mean curvature

$$= \frac{1}{2} \text{trace}(S)$$

} measures average concavity of surface at $P \sim$ see Hessian discussion above

For the shape operator,

$$K = k_1 k_2, \quad H = \frac{1}{2}(k_1 + k_2)$$

And k_1, k_2 are roots of $|\lambda I - A| = 0$

$$\lambda^2 - 2H\lambda + K = 0.$$