

Friday April 1
Math 4530

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Geodesics & geodesic curvature & physics

Let $\alpha: I \rightarrow M$, α pbal.

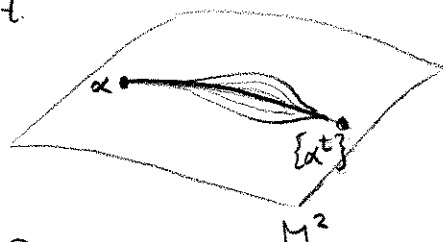
When is α critical wrt total length? (this is when α is called a geodesic)

i.e. if $\alpha^t(s)$ $- \varepsilon < t < \varepsilon$
1-par. family of curves to M s.t.

$$(1) \alpha^0 = \alpha$$

$$(2) \alpha^t(0) = \alpha(0)$$

$$\alpha^t(L) = \alpha(L)$$

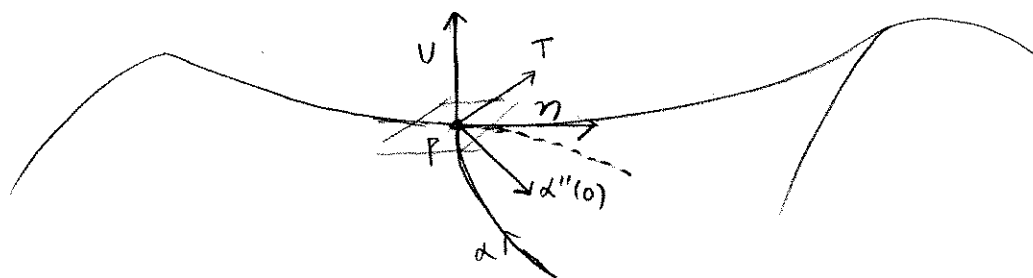


For what α is

$$\left. \frac{d}{dt} (\text{length}(\alpha^t)) \right|_{t=0} = 0 \quad \forall \text{ such families?}$$

This is an intrinsic question, i.e. only depends on 1st fundamental form,
but answer is easier to visualize in the extrinsic surface setting.

Answer to question:



$\alpha: I \rightarrow M$
 α pbal
 $\alpha(0) = p$
 $\alpha'(0) = T$
 $\eta := T \times U$
 $\uparrow$
conormal

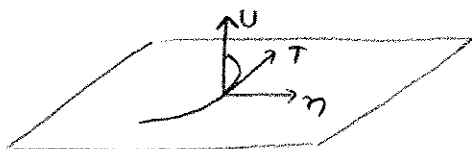
$$\alpha'' = (\alpha'' \cdot \eta) \eta + (\alpha'' \cdot T) T + (\alpha'' \cdot U) U$$

$$:= -k_g \eta + k_n U$$

normal curvature $k_n := \alpha'' \cdot U$
geodesic curvature $k_g := -\alpha'' \cdot \eta$

α is a geodesic iff $k_g \equiv 0$,
i.e. $\alpha''(s) \parallel U(\alpha(s))$

you can "see" this



$$T' = (k_g)(-n)$$

and $T = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$

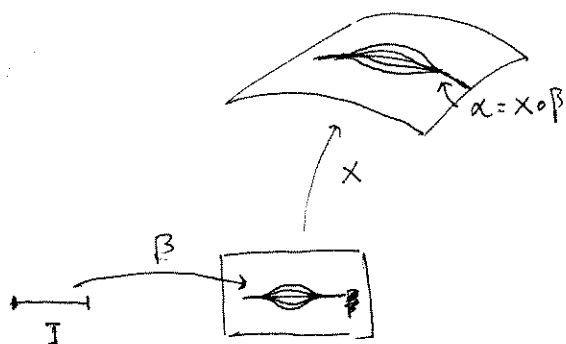
$$T' = \frac{d\theta}{ds} \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}$$

$k_g = \frac{d\theta}{ds} = \text{planar curvature.}$

$k_g = 0 \Leftrightarrow \alpha \text{ is a line.}$

so, k_g is a generalization of planar curvature to surfaces, and geodesics generalize straight lines.

Extrinsic derivation of geodesic condition



$$\alpha^t(s) = X(\beta(s) + t\tilde{w}(s))$$

$$\alpha^0(s) = \alpha(s) \text{ pbal}$$

expand in t : $\tilde{w}(s) = \langle u(s), v(s) \rangle$

$$\alpha^t(s) = X(\beta(s)) + t \left[X_u \begin{bmatrix} u(s) \\ v(s) \end{bmatrix} \right] + O(t^2)$$

$$= \alpha(s) + tZ(s) + O(t^2)$$

where $Z(s)$ is a vector field along α , $Z(s) \in T_{\alpha(s)}M$

$$\left| \frac{d}{ds} \alpha^t(s) \right| = \sqrt{\alpha^{t(s)'} \cdot \alpha^{t(s)'}}$$

$$= \left\{ (\alpha' + tZ' + O(t^2)) \cdot (\alpha' + tZ' + O(t^2)) \right\}^{1/2}$$

$$= (1 + 2t\alpha' \cdot Z' + O(t^2))^{1/2}$$

$$= 1 + t\alpha' \cdot Z' + O(t^2) \quad (\text{Taylor } \sqrt{1+x} = 1 + \frac{1}{2}x + O(x^2))$$

$$\Rightarrow L(\alpha^t) = \int_0^L 1 + t\alpha' \cdot Z' + O(t^2) ds$$

$$= L + t \int_0^L \alpha'(s) \cdot Z'(s) ds + O(t^2)$$

$$\Rightarrow \left. \frac{d}{dt} L(\alpha^t) \right|_{t=0} = \int_0^L \alpha'(s) \cdot Z'(s) ds$$

$$= \alpha' \cdot Z \Big|_0^L - \int_0^L \alpha''(s) \cdot Z(s) ds$$

this term is zero when $Z(0) = Z(L) = 0$

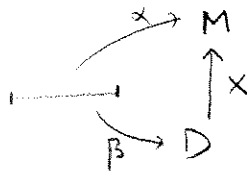
thus, for fixed endpoint deformations ($\tilde{w}(0) = Z(0) = \tilde{w}(L) = Z(L) = 0$),

$$\left. \frac{d}{dt} L(\alpha^t) \right|_{t=0} = - \int_0^L \alpha'' \cdot Z ds$$

$$\text{If } k_g = 0, \alpha'' \perp T_p M \Rightarrow \alpha'' \cdot Z \equiv 0 \Rightarrow \left. \frac{d}{dt} L(\alpha^t) \right|_{t=0} = 0$$

$$\text{If } \left. \frac{d}{dt} L(\alpha^t) \right|_{t=0} = 0 \quad \forall Z \text{ tangential, then } \alpha'' \perp T_p M \quad \forall s \text{ i.e. } k_g = 0$$

Intrinsic eqns for geodesic



$$\alpha = X \circ \beta$$

$$\alpha' = X_{,i} \dot{\beta}^i$$

$$\begin{aligned} \alpha'' &= X_{,ij} \dot{\beta}^i \dot{\beta}^j + X_{,i} \ddot{\beta}^i \\ &= (T_{ij}^k X_{,k} + h_{ij} U) \dot{\beta}^i \dot{\beta}^j + X_{,k} \ddot{\beta}^k \end{aligned}$$

$\alpha'' // U$ iff

$$\ddot{\beta}^k + T_{ij}^k \dot{\beta}^i \dot{\beta}^j = 0 \quad k=1,2$$

see "Geodesic eqns" display, p. 230 of text

the Christoffel symbols make the β curve on the "map", "bend".

For your reading pleasure:

completely intrinsic derivation of geodesic eqns: (i.e., only using $[g_{ij}]$)

$$\alpha^t = X(\beta + t\dot{\beta}(s))$$

$$L(\alpha^t) = \int_0^L \sqrt{g_{ij}(\dot{\beta}^i + t\dot{v}^i)(\dot{\beta}^j + t\dot{v}^j)} ds$$

$\uparrow$
 α^t
 $\beta(s) + t\dot{\beta}(s)$



← abbreviate $\frac{d}{ds}(\cdot)$ with $(\dot{\cdot})$

$$= \int_0^L \sqrt{(g_{ij} + t g_{ij,k} v^k + O(t^2)) (\dot{\beta}^i + t \dot{v}^i) (\dot{\beta}^j + t \dot{v}^j)} ds$$

$\uparrow$ $\uparrow$
 α^t affine approx

$$= \int_0^L \sqrt{\underbrace{g_{ij} \dot{\beta}^i \dot{\beta}^j}_{=1 \text{ (a pbal)}} + t (g_{ij,k} v^k \dot{\beta}^i \dot{\beta}^j + g_{ij} \dot{v}^i \dot{\beta}^j + g_{ij} \dot{v}^j \dot{\beta}^i) + O(t^2)} ds$$

$$= \int_0^L 1 + \frac{1}{2} t \left(\frac{\dot{\beta}^i \dot{\beta}^i}{\beta^i} \right) + O(t^2) ds$$

$$\left. \frac{d}{dt} L(\alpha^t) \right|_{t=0} = \int_0^L \frac{1}{2} (g_{ij,k} v^k \dot{\beta}^i \dot{\beta}^j + g_{ij} \dot{v}^i \dot{\beta}^j + g_{ij} \dot{v}^j \dot{\beta}^i) ds$$

$$= \int_0^L \frac{1}{2} \left[(g_{ij,k} v^k \dot{\beta}^i \dot{\beta}^j - v^i (g_{ij} \dot{\beta}^j) - v^j (g_{ij} \dot{\beta}^i)) \right] ds \quad (\text{integ. by parts})$$

$\underbrace{g_{ij,k} \dot{\beta}^k \dot{\beta}^j}_{+ g_{ij} \dot{\beta}^j} \quad \underbrace{g_{ij,k} \dot{\beta}^k \dot{\beta}^i}_{+ g_{ij} \dot{\beta}^i}$

$$= \int_0^L -v^k \left[g_{kj} \dot{\beta}^j + \frac{1}{2} (-g_{ij,k} \dot{\beta}^i \dot{\beta}^j + g_{kj,r} \dot{\beta}^r \dot{\beta}^j + g_{ik,r} \dot{\beta}^r \dot{\beta}^i) \right] ds$$

iff α is stationary $\forall \tilde{v}$,

$$g_{kj} \ddot{\beta}^j + \frac{1}{2} (-g_{rj,k} + g_{kj,r} + g_{jk,r}) \dot{\beta}^r \dot{\beta}^j = 0 \quad k=1,2$$

$g^{lk}(\sigma_0)$:

$$\boxed{\ddot{\beta}^l + \Gamma_{rj}^l \dot{\beta}^r \dot{\beta}^j = 0} \quad l=1,2$$

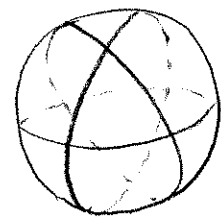
yipes!
[one should find a better way to do intrinsic Calculus
~ "covariant derivative"
(next lecture!)]

Examples

sphere: great circles satisfy $\alpha'' \parallel \tilde{v}$

every geodesic is a great circle:

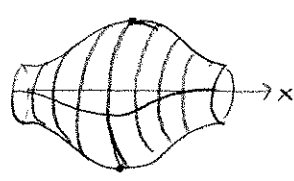
$$\begin{aligned} \alpha \text{ pbal} \quad \alpha'' \parallel \tilde{v} \parallel \alpha &\Rightarrow (\alpha \times \alpha')' = 0 \\ &\Rightarrow \alpha \times \alpha' = \tilde{c} \quad (\& \tilde{c} \neq 0) \\ &\Rightarrow (\alpha \cdot \tilde{c})' = 0 \\ &\Rightarrow \alpha \text{ lies on plane thru origin!} \quad \blacksquare \end{aligned}$$



hyperbolic space: ? (good question)

cylinder } wrap up paper
cone }

surfaces of revolution



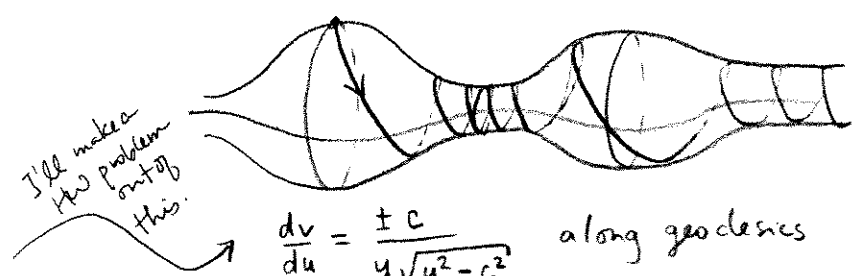
u-coord curves
all meridians are geodesics
max & min parallels.
else? (not all parallels!)

$$X(u, v) = \begin{bmatrix} x(u) \\ y(u) \cos v \\ y(u) \sin v \end{bmatrix} \quad \begin{bmatrix} x \\ y \end{bmatrix} \text{ pbal}$$

$$[g_{ij}] = \begin{bmatrix} 1 & 0 \\ 0 & y^2(u) \end{bmatrix} \rightsquigarrow T_{ij}^k$$

special case of page 230

$$\begin{cases} u'' - (y y_u) (v')^2 = 0 \\ v'' + \left(\frac{y_u}{y}\right) u' v' = 0 \\ (u')^2 + y^2 (v')^2 = 1 \end{cases}$$



I'll make a few problems out of this.

$$\frac{dv}{du} = \frac{\pm c}{y \sqrt{y^2 - c^2}} \quad \text{along geodesics}$$

page 162 Clairant relation.
larger y $\Rightarrow$ smaller $\frac{dv}{du}$

(9)

Physics : A particle constrained to lie on a surface (but with no other external forces), satisfies

$$\alpha''(t) = f(t)U(t) \quad \text{Newton!}$$

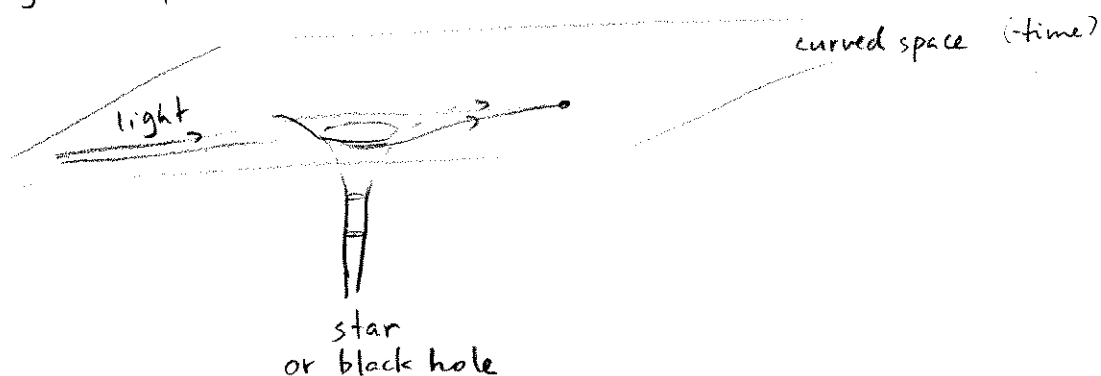
this is geodesic eqn!

notice if $\|\alpha'(0)\| = 1$

then $\frac{d}{dt}(\alpha' \cdot \alpha') = 2\alpha' \cdot \alpha'' = 0$, so α pbal.

$\uparrow$
 $T_p(M)$ $\parallel$
 U

then,
light is a particle. ($E = mc^2$)



how many geodesics are there?

physics intuition: you should be able to start at any point and go in any direction

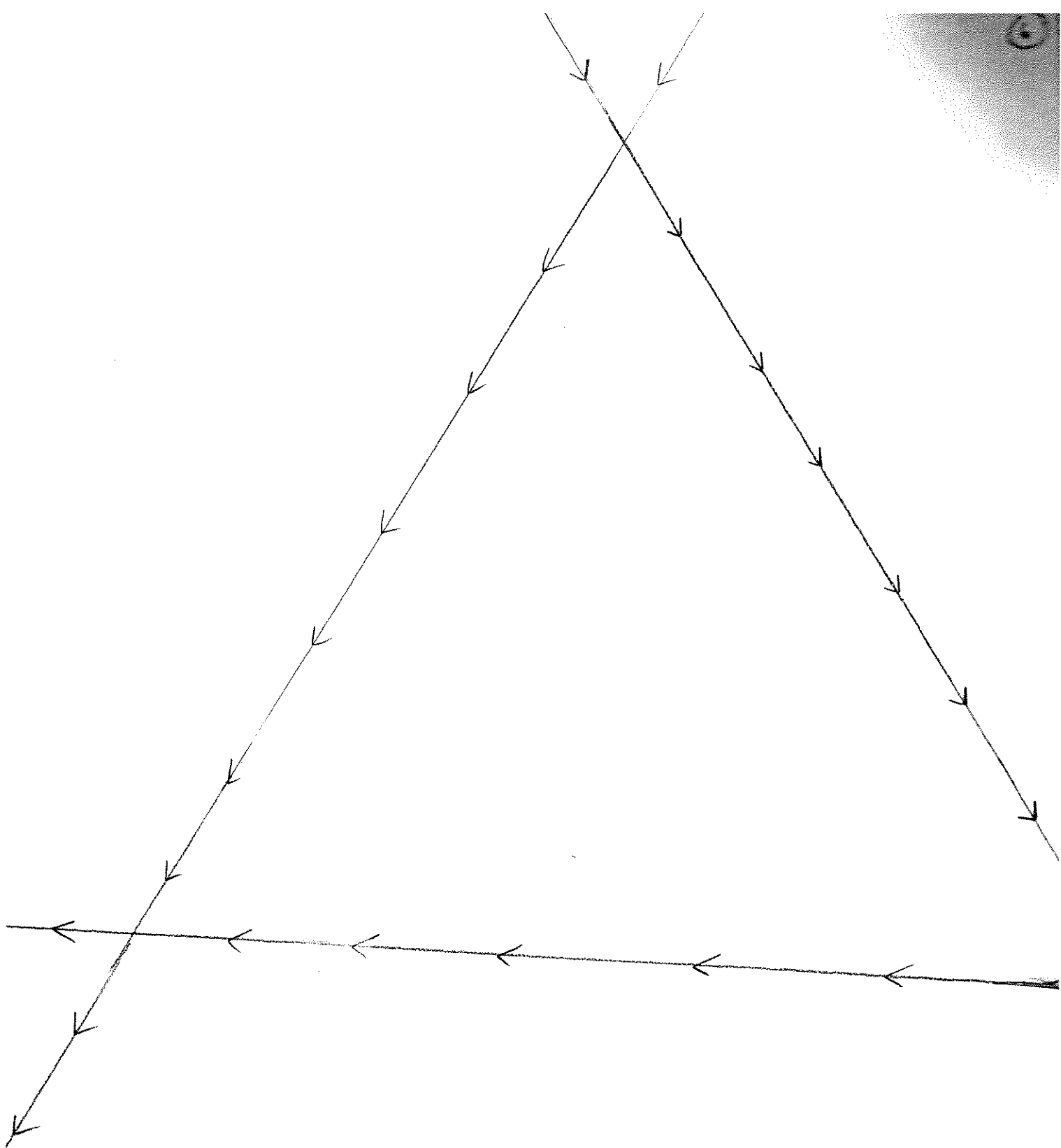
math proof:

Consider the 1st order system IVP

$$\begin{cases} \ddot{\beta}^k = v^k & k=1,2 \\ \dot{v}^k + \Gamma_{ij}^k v^i v^j = 0 & k=1,2 \\ \beta(0) = \vec{q} \\ \dot{\beta}(0) = \vec{v}_0 \quad \text{s.t.} \quad v_0^i v_0^j g_{ij}(q) = 1 \end{cases}$$

$\exists!$ soltn, and in fact $\alpha := X_0 \beta$ is pbal, hence satisfies geodesic eqn to IVP

check $\frac{d}{dt}(g_{ij} \dot{\beta}^i \dot{\beta}^j) \equiv 0$ from the system.



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