

Math 4530
Friday April 20
Christoffel symbols and Gauss' Theorem Egregium

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> restart;
  #always a good idea
> with(linalg):
  #as much as possible we will use matrix algebra
Warning, the protected names norm and trace have been redefined and unprotected

> #dot product
dp:=proc(X,Y)
  X[1]*Y[1]+X[2]*Y[2]+X[3]*Y[3];
end:

> nrm:=proc(X)
  sqrt(dp(X,X));
end:

> #cross product:
xp:=proc(X,Y)
  local a,b,c;
  a:=X[2]*Y[3]-X[3]*Y[2];
  b:=X[3]*Y[1]-X[1]*Y[3];
  c:=X[1]*Y[2]-X[2]*Y[1];
  [a,b,c];
end:

> #Derivative matrix for mapping X:
DXq:=proc(X)
  local Xu,Xv;
  Xu:=matrix(3,1,[diff(X[1],u),diff(X[2],u),diff(X[3],u)]);
  Xv:=matrix(3,1,[diff(X[1],v),diff(X[2],v),diff(X[3],v)]);
  simplify(augment(Xu,Xv));
end:

> #Matrix of first fundamental form:
gij:=proc(X)
  local Y;
  Y:=evalm(DXq(X));
  simplify(evalm(transpose(Y)*Y));
end:

> #unit normal:
N:=proc(X)
  local Y,Z,s;
  Y:=DXq(X);
  Z:=xp(col(Y,1),col(Y,2));
  s:=nrm(Z);
  simplify(evalm((1/s)*Z));
end:

> #matrix of second fundamental form:
hij:=proc(X)
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local Y,Xu,Xv,Xuu,Xuv,Xvv,U,h11,h12,h22;
Y:=DXq(X);
U:=N(X);
Xu:=col(Y,1);
Xv:=col(Y,2);
Xuu:=[diff(Xu[1],u),diff(Xu[2],u),diff(Xu[3],u)];
Xuv:=[diff(Xu[1],v),diff(Xu[2],v),diff(Xu[3],v)];
Xvv:=[diff(Xv[1],v),diff(Xv[2],v),diff(Xv[3],v)];
h11:=dp(Xuu,U);
h12:=dp(Xuv,U);
h22:=dp(Xvv,U);
simplify(matrix(2,2,[h11,h12,h12,h22]));
end:

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> #matrix A of the (opposite) of the differential
#of the normal map

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aij:=proc(X)
local Y,H,G;
H:=hij(X);
G:=gij(X);
simplify(evalm(inverse(G)*H));
end:

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> #Gauss curvature from second fundamental form

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GK2:=proc(X)
local A;
A:=aij(X);
det(A);
end:

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> #Mean curvature

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MK:=proc(X)
local A;
A:=aij(X);
(1/2)*trace(A);
end:

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> #Christoffel symbols

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Gamma:=proc(X)
local Gammas,G,Ginv,DG,i,j,k,l;
G:=X;
Ginv:=evalm(inverse(G));
DG:=array(1..2,1..2,1..2);
DG[1,1,1]:=diff(G[1,1],u);
DG[1,1,2]:=diff(G[1,1],v);
DG[1,2,1]:=diff(G[1,2],u);
DG[2,1,1]:=DG[1,2,1];
DG[1,2,2]:=diff(G[1,2],v);
DG[2,1,2]:=DG[1,2,2];
DG[2,2,1]:=diff(G[2,2],u);
DG[2,2,2]:=diff(G[2,2],v);
Gammas:=array(1..2,1..2,1..2);

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    for i from 1 to 2 do
      for j from 1 to 2 do
        for l from 1 to 2 do
          Gammas[i,j,l]:=sum((1/2)*Ginv[k,l]*
            (DG[i,k,j]+DG[k,j,i]-DG[i,j,k]),k=1..2);
        od:
      od:
    od:
  simplify(Gammas);
end:

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> #derivatives of Christoffel symbols
DGamma:=proc(X)
  local G,Gammas,DGammass,i,j,k,m;
  G:=X;
  Gammas:=Gamma(G);
  DGammass:=array(1..2,1..2,1..2,1..2);
  for i from 1 to 2 do
    for j from 1 to 2 do
      for m from 1 to 2 do
        DGammass[i,j,m,1]:=diff(Gammas[i,j,m],u);
        DGammass[i,j,m,2]:=diff(Gammas[i,j,m],v);
      od:
    od:
  od:
  simplify(DGammass);
end:

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> #Gauss curvature from first fundamental form
GK1:=proc(X)
  local G,Gammas,DGammass,Ginv,K,i,r;
  G:=X;
  Ginv:=inverse(G);
  Gammas:=Gamma(G);
  DGammass:=DGamma(G);

  K:=sum(Ginv[1,i]*(DGammass[i,1,2,2] - DGammass[i,2,2,1]
    + sum(
      Gammas[i,1,r]*Gammas[r,2,2] -
      Gammas[i,2,r]*Gammas[r,1,2],
      r=1..2)),
    i=1..2);

  simplify(K);
end:

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[ > test:=(u,v)->[u,v,k1*u^2+k2*v^2];
    #good idea to check our derivation on a graph:
    test := (u, v) → [u, v, k1 u^2 + k2 v^2]
[ > GK1(gij(test(u,v)));
    #from the first fundamental form
    4  $\frac{k1 k2}{(1 + 4 k2^2 v^2 + 4 k1^2 u^2)^2}$ 
[ > GK2(test(u,v));
    #from the differential of the normal map
    4  $\frac{k1 k2}{(1 + 4 k2^2 v^2 + 4 k1^2 u^2)^2}$ 
[ > stinv:=(u,v)->[2*u/(u^2+v^2+1),2*v/(u^2+v^2+1),(u^2+v^2-1)/(u^2+v^2+1)];
    #inverse of stereographic projection onto the sphere
    stinv := (u, v) →  $\left[ 2 \frac{u}{u^2 + v^2 + 1}, 2 \frac{v}{u^2 + v^2 + 1}, \frac{u^2 + v^2 - 1}{u^2 + v^2 + 1} \right]$ 
[ > GK1(gij(stinv(u,v)));
    GK2(stinv(u,v));
    #notice the second expression also equals 1; it would've been
    #neater if I'd assumed v,u real.
    1
     $\frac{1}{\sqrt{(u^2 + v^2)^2 u^8 + 4(u^2 + v^2)^2 u^6 v^2 + 6(u^2 + v^2)^2 u^4 v^4 + 4(u^2 + v^2)^2 u^2 v^6 + (u^2 + v^2)^2 v^8 + 2|u^2 + v^2|^6 u^2 + 2|u^2 + v^2|^6 v^2 + |u^2 + v^2|^8}}{(u^2 + v^2)^2}$ 
[ > helcat:=(u,v)->[cos(t)*sinh(v)*sin(u)+sin(t)*cosh(v)*cos(u),
    -cos(t)*sinh(v)*cos(u)+sin(t)*cosh(v)*sin(u),u*cos(t)+v*sin(t)];
    #in your homework you showed these are all isometric as the
    parameter
    #t varies, so Gauss curvature should be t-independent
    helcat := (u, v) → [cos(t) sinh(v) sin(u) + sin(t) cosh(v) cos(u),
    -cos(t) sinh(v) cos(u) + sin(t) cosh(v) sin(u), u cos(t) + v sin(t)]
[ > GK1(gij(helcat(u,v)));
    -  $\frac{1}{\cosh(v)^4}$ 
[ > GK2(helcat(u,v));
    -  $\frac{\text{csgn}(\cosh(v)^2)^2 (\sin(t)^2 + \cos(t)^2)}{\cosh(v)^4}$ 
[ > hypgij:=(u,v)->matrix(2,2,[1/v^2,0,0,1/v^2]);
    #the hyperbolic plane is the upper half plane, with conformal
    metric

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#in which g11=g22=1/v^2. This "surface" is not realizable as a
surface
#in R^3, yet it has a "curvature":
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$$\text{hypgij} := (u, v) \rightarrow \text{matrix}\left(2, 2, \left[\frac{1}{v^2}, 0, 0, \frac{1}{v^2}\right]\right)$$

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[ > GK1(hypgij(u,v));
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