

Math 4200
Fri 18 Nov.

HW for Wed 11/25:
8.2 1c, 2, 9

+ Exercise: Use Laplace transform to show "linear factors"

partial fractions algorithm ^{always works,}
even with repeated roots!

Multi-variable FTC ~ a key tool in understanding PDE's.

1st recall 1-variable version

$$\int_a^b f(x) dx = F(b) - F(a), \text{ where } F'(x) = f(x)$$

$$\text{or } \int_a^b F'(x) dx = F(b) - F(a)$$

A good way to think of this:

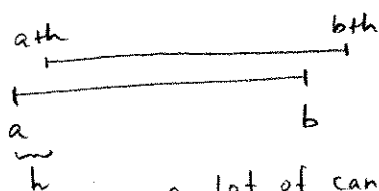
$$F'(x) \approx \frac{F(x+h) - F(x)}{h}$$

$$\begin{aligned} \text{so } \int_a^b F'(x) dx &\stackrel{(1)}{\approx} \int_a^b \frac{F(x+h) - F(x)}{h} dx \\ &= \frac{1}{h} \int_a^b F(x+h) dx - \frac{1}{h} \int_a^b F(x) dx \end{aligned}$$

$$\begin{aligned} z &= x+h \\ dz &= dx \end{aligned}$$

(translation of variables)

$$= \frac{1}{h} \int_{a+h}^{b+h} F(z) dz - \frac{1}{h} \int_a^b F(x) dx$$



$$= \frac{1}{h} \int_b^{b+h} F(x) dx - \frac{1}{h} \int_a^{a+h} F(x) dx$$

$$\stackrel{(2)}{\approx} F(b) - F(a)$$

In fact, as $h \rightarrow 0$ you can deduce

$$\int_a^b F'(x) = F(b) - F(a)$$

[For first $\approx$ you need e.g. $F'(x)$ continuous on $[a, b]$
For second $\approx$ you need e.g. $F(x)$ continuous at a & b]

This is prep for § 2.5

- understanding significance of Poisson integral formula for harmonic funcs

Then Fourier transform discussion of heat eqn, partly in § 4.3, mostly extra.
Contour integrals appear in both topics. Then, chapter 5.

Details:

①

$\approx$ By MVT

$$\frac{F(x+h) - F(x)}{h} = F'(c_x), \quad |x - c_x| < h$$

$$\begin{aligned} \text{so } \left| \int_a^b F'(x) - \left(\frac{F(x+h) - F(x)}{h} \right) dx \right| \\ \leq \int_a^b |F'(x) - F'(c_x)| dx, \end{aligned}$$

$$|x - c_x| < h$$

If F' unif cont on $[a, b]$

then $\forall \varepsilon > 0 \exists \delta > 0$ s.t.

$$|x - c_x| < \delta$$

$$\Rightarrow |F'(x) - F'(c_x)| < \varepsilon$$

in which case,

$$\leq \int_a^b \varepsilon dx = \varepsilon(b-a) \blacksquare$$

②

$$\approx \left| \frac{1}{h} \int_b^{b+h} F(x) dx - F(b) \right|$$

$$= \left| \frac{1}{h} \int_b^{b+h} F(x) - F(b) dx \right|$$

F cont at $b \Rightarrow \forall \varepsilon > 0 \exists \delta > 0$

$$\text{s.t. } |F(x) - F(b)| < \varepsilon$$

when $|x - b| < \delta$

in which case

$$\leq \frac{1}{h} \int_b^{b+h} \varepsilon dx = \varepsilon \blacksquare$$

The same idea is behind $\mathbb{R}^m$ version
(although proof usually follows a technically simpler route)

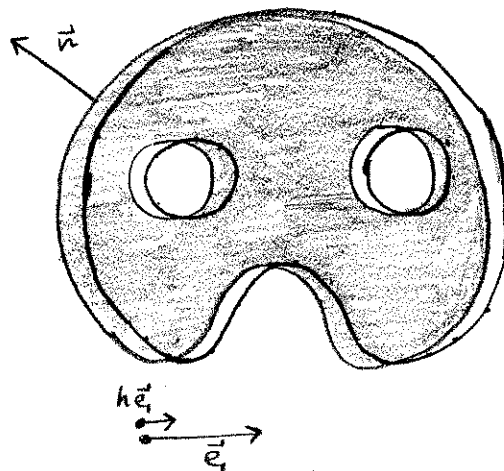
(2)

Illustrate when $n=2$

Domain D (shaded), $\partial D = \text{bdry curve}$

$$D_h := \{ \vec{z} = \vec{x} + h\vec{e}_1 \mid \vec{x} \in D \}$$

is translation by amt h in $\vec{e}_1$ direction



$\vec{n}$ = unit exterior normal

$$F: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\vec{x} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\iint_D \frac{\partial F}{\partial x} dA \stackrel{\textcircled{1}}{\approx} \iint_D \frac{F(\vec{x} + h\vec{e}_1) - F(\vec{x})}{h} dA$$

$$= \frac{1}{h} \iint_D F(\vec{x} + h\vec{e}_1) dA - \frac{1}{h} \iint_D F(\vec{x}) dA$$

$$\vec{z} = \vec{x} + h\vec{e}_1$$

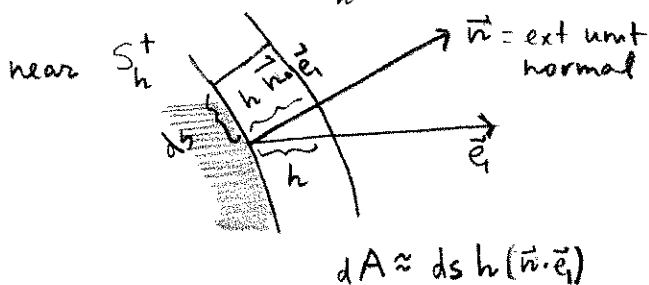
$$dA_z = dA_x$$

(translation of domains)

$$= \frac{1}{h} \iint_{D_h} F(\vec{z}) dA_z - \frac{1}{h} \iint_D F(\vec{x}) dA_x$$

lots of cancellation in the middle

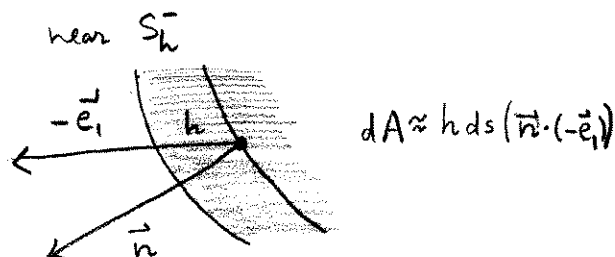
$$* = \frac{1}{h} \iint_{S_h^+} F(x) dA - \frac{1}{h} \iint_{S_h^-} F(x) dA$$



$$dA \approx ds h (\vec{n} \cdot \vec{e}_1)$$

$$S_h^+ = D_h \setminus D = \text{unshaded strip}(s)$$

$$S_h^- = D \setminus D_h = \text{shaded strip}(s)$$



$$dA \approx h ds (\vec{n} \cdot (-\vec{e}_1))$$

$$\text{so } * \stackrel{\textcircled{2}}{\approx} \int_{\partial D} F \vec{e}_1 \cdot \vec{n} ds$$

(h's cancel, also signs in 2nd term)

In the limit

$$\boxed{\iint_D \frac{\partial F}{\partial x} dA = \int_{\partial D} F \vec{e}_1 \cdot \vec{n} ds}$$

$\textcircled{1}$ and $\textcircled{2}$ are messy to prove, so rigorous proof is exposited slightly differently in general (page 4), but with this idea hiding behind it.

$\mathbb{R}^1$ $\int_a^b F'(x) dx = F(b) - F(a)$	$\mathbb{R}^m$ $\int_{D_m} \frac{\partial F}{\partial x_i} dVol_m = \int_{\partial D_m} F(\vec{e}_i \cdot \vec{n}) dVol_{m-1}$ unit ext. normal
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SAME!

Special forms: Divergence Theorem

$\mathbb{R}^2$: $\text{div} \begin{bmatrix} P \\ Q \end{bmatrix} := P_x + Q_y$

$$\begin{aligned} \iint_D P_x dA &= \int_{\partial D} P \vec{e}_1 \cdot \vec{n} ds \\ + \iint_D Q_y dA &= \int_{\partial D} Q \vec{e}_2 \cdot \vec{n} ds \\ \hline \iint_D \text{div} \begin{bmatrix} P \\ Q \end{bmatrix} dA &= \int_{\partial D} \begin{bmatrix} P \\ Q \end{bmatrix} \cdot \vec{n} ds \end{aligned}$$

$\vec{F}(\vec{x})$ a vector field

in $\mathbb{R}^m$

$$\int_{D_m} \text{div} \vec{F} dVol_m = \int_{\partial D_m} \vec{F} \cdot \vec{n} dVol_{m-1}$$

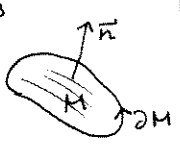
Green's & Stoke's Thm

Green: $\iint_D Q_x - P_y dA = \oint_{\partial D} P dx + Q dy$

(We used this to give initial proofs of Cauchy's Theorem and the Cauchy integral formula)

Stokes:

$M^2 \subset \mathbb{R}^3$
a surface in $\mathbb{R}^3$



$$\iint_M (\vec{\nabla} \times \vec{F}) \cdot \vec{n} dA = \oint_{\partial M} \vec{F} \cdot d\vec{x} = \oint_{\partial M} P dx + Q dy + R dz$$

(Stoke's generalizes Green's from flat surfaces to general ones)
(Stokes follows from Green's as well.)

equivalent to $m=2$ div thm:

$$\iint_D Q_x - P_y dA = \iint_D \text{div} (Q, -P) dA \stackrel{n=2 \text{ div}}{\downarrow} = \int_{\partial D} (Q, -P) \cdot \vec{n} ds$$

$$\begin{aligned} \int_a^b (Q(\vec{\gamma}(t)), -P(\vec{\gamma}(t))) \cdot (y'(t), -x'(t)) dt \\ = \int_{\partial D} P dx + Q dy! \end{aligned}$$

-π/2 rotation

$$\vec{\gamma}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

$$\vec{\gamma}'(t) = \begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} \quad ds = \|\vec{\gamma}'(t)\| dt$$

unit tangent $T = \frac{1}{\|\vec{\gamma}'(t)\|} \begin{bmatrix} x' \\ y' \end{bmatrix}$

$$\vec{n} = \text{rot}_{-\pi/2} T = \frac{1}{\|\vec{\gamma}'(t)\|} \begin{bmatrix} y' \\ -x' \end{bmatrix}$$

$$\vec{n} ds = \begin{bmatrix} y' \\ -x' \end{bmatrix} dt$$

Sample PDE derivation (See Strauss notes for more - most derivations depend on some use of FTC.) (Also see page 349 text) (5)

Heat (diffusion) equation

$u(\vec{x}, t)$ can represent temperature at position $\vec{x}$, time t . Here $\vec{x} \in \Omega$, $t \in \mathbb{R}^+$
(or it can represent concentration of some solute)

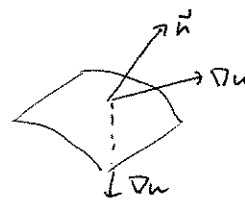
Model: • Assume temp (or solute) diffuses from warmer to cooler (concentrated to less concentrated), moving in direction of greatest decrease, i.e. $-\nabla u$ (spatial gradient $= \nabla u$).

• no energy (or solute) sources or sinks inside the domain

The precise way to encode this model, using units for $u = \text{temp} = \text{energy density}$ (up to a constant) is, for any "test" subdomain $\Theta \subset \Omega$

$$E(t) := \iiint_{\Theta} c \rho u(\vec{x}, t) dV_{\vec{x}} \quad \text{total energy inside } \Theta$$

$\uparrow$ density (mass/vol)
 $\uparrow$ specific heat
 (energy required to heat 1 mass unit by 1 temp unit)



Model

$$\frac{dE}{dt} = \iint_{\partial\Theta} \kappa \nabla u \cdot \vec{n} dA_{\vec{x}}$$

$\uparrow$ thermal conductivity

total energy in Θ only changes by energy flowing through $\partial\Theta$ in direction of $-\nabla u$.

Assuming u is differentiable enough, pass $\frac{d}{dt}$ through integral on left, apply div. thm on right

$$\Rightarrow \iiint_{\Theta} c \rho u_t(\vec{x}, t) dV_{\vec{x}} = \iiint_{\Theta} \kappa \underbrace{\text{div}(\nabla u)}_{=\Delta u} dV_{\vec{x}}$$

$$\iiint_{\Theta} (c \rho u_t - \kappa \Delta u) dV_{\vec{x}} = 0$$

This can be true for all test domains iff the integrand is identically zero (assuming it's continuous)
e.g. let $\Theta = B(\vec{x}_0, r) = \{\vec{x} \mid \|\vec{x} - \vec{x}_0\| < r\}$

$$\therefore \begin{cases} u_t = \frac{\kappa}{c\rho} \Delta u & \text{Heat Eqn} \\ 0 = \Delta u & \text{Laplace} \end{cases}$$

if sol'n is stationary in time

$$\frac{1}{\text{Vol}(B(\vec{x}_0, r))} \iiint_{B(\vec{x}_0, r)} f(\vec{x}) dV \rightarrow f(\vec{x}_0) \quad \text{as } r \rightarrow 0 \quad \text{if } f \text{ is cont at } \vec{x}_0$$

Natural boundary value problems:

① $u(\vec{x}) = f(\vec{x})$ on $\partial\Omega$ (Dirichlet)
- temp on $\partial\Omega$ is fixed.

② $\nabla u \cdot \vec{n} = 0$ on $\partial\Omega$ (Neumann)

- no flux on $\partial\Omega$, i.e. insulated body for heat, impermeable body for solute.