

$y''(x) + 4y'(x) - 5y(x) = 2\cos(3x)$

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Input:

$$y''(x) + 4y'(x) - 5y(x) = 2\cos(3x)$$

Open code

ODE classification:

second-order linear ordinary differential equation

Alternate forms:

More

$$y''(x) = -4y'(x) + 5y(x) + 2\cos(3x)$$

$$5y(x) + 2\cos(3x) = y''(x) + 4y'(x)$$

$$y''(x) + 4y'(x) - 5y(x) = e^{-3ix} + e^{3ix}$$

Differential equation solution:

Approximate form ☒ Step-by-step solution

$$y(x) = c_1 e^{-5x} + c_2 e^x + \frac{6}{85} \sin(3x) - \frac{7}{85} \cos(3x)$$

All of the previous exercises rely on:

Method of undetermined coefficients (base case): Let $L : V \rightarrow V$ be a linear transformation, with V a finite dimensional vector space, and let $f \in V$. Then $\exists! y_p \in V$ with $L(y_p) = f$ if and only if the only $y \in V$ for which $L(y) = 0$ is $y = 0$.

why: You definitely learned this fact in Math 2270, for the special case of matrix transformations $L : \mathbb{R}^n \rightarrow \mathbb{R}^n$ given by $L(\mathbf{x}) = A_{n \times n} \mathbf{x}$. (Each non-homogeneous matrix equation $A \mathbf{x} = \mathbf{b}$ has a unique solution \mathbf{x} if and only if A reduces to the identity matrix I , if and only if the only solution to the homogeneous equation $A \mathbf{x} = \mathbf{0}$ is $\mathbf{x} = \mathbf{0}$.) The theorem above is a generalization of this fact to general linear transformations $L : V \rightarrow V$. In fact, if we pick a basis $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ for V , this base case of undetermined coefficients follows from the fact that the (square) matrix A for L with respect to this basis is invertible if and only if $\text{Nul } A = \{\mathbf{0}\}$.

↓ "β" basis

$$L y_p = f \quad \text{has unique soltn in } V?$$

$$\Leftrightarrow [L(y_p)]_\beta = [f]_\beta \quad (\text{iff coords agree})$$

$$A [y_p]_\beta = [f]_\beta \quad \text{has unique soltn.}$$

Wed Feb 20:

3.5: Finding y_p for non-homogeneous linear differential equations, continued,

$$L(y) = f$$

(so that you can use the general solution $y = y_p + y_H$ to solve initial value problems).

Announcements:

- Pick up your exams
- Quiz today on yesterday's & today's material

Warm-up Exercise: Pick the appropriate form for undetermined coefficients $y_p(x)$ "guess"

a) $y'' + 6y' + 9y = 4e^{-2x}$

$$y_p = de^{-2x}$$

$$V = \text{span}\{e^{-2x}\} \quad 1\text{-dim'l space}$$

$$L: V \rightarrow V$$

$$\begin{aligned} L(de^{-2x}) &= d L(e^{-2x}) \\ &= d e^{-2x} [4 - 12 + 9] \\ &= d e^{-2x} \cdot 1 \end{aligned}$$

b) $y'' + 6y' + 9y = 18 \cos 3x$

$$y_p = d_1 \cos 3x + d_2 \sin 3x$$

$$V = \text{span}\{\cos 3x, \sin 3x\} \quad \begin{array}{l} \text{want} \\ 2\text{-dim'l} \end{array} = 4e^{-2x} \quad \text{pick } d=4$$

c) $y'' + 6y' + 9y = 2e^{-3x}$

naive guess $y_p = de^{-3x}$

$$L(y_p) = d L(e^{-3x}) = d e^{-3x} (9 - 18 + 9) = 0$$

oh oh.

Note: y_H :

$$y'' + 6y' + 9y = 0$$

$$p(r) = r^2 + 6r + 9 = (r+3)^2 = 0 \quad r = -3$$

$$y_H(x) = c_1 e^{-3x} + c_2 x e^{-3x}$$

return to this in class ... $y_p(x) = dx^2 e^{-3x}$

$$L = D^2 + 6D + 9I$$

$$= (D+3I) \circ (D+3I)$$

$$y_p = x^2 e^{-3x}$$

$$L(dx^2 e^{-3x}) = d L(x^2 e^{-3x}) = d (D+3I) \circ (D+3I) x^2 e^{-3x}$$

$$\text{let } d=1$$

$$= 2d e^{-3x} \text{ want } 2e^{-3x} \quad \underbrace{2x e^{-3x}}_{2e^{-3x}}$$

On Tuesday we discussed the base case of undetermined coefficients:

Method of undetermined coefficients (base case): If you wish to find a particular solution y_p , i.e.

$L(y_p) = f$ and if the non-homogeneous term f is in a finite dimensional subspace V with the properties that

- (i) $L : V \rightarrow V$, i.e. L transforms functions in V into functions which are also in V ; and
- (ii) The only function $g \in V$ for which $L(g) = 0$ is $g = 0$.

Then there is always a unique $y_p \in V$ with $L(y_p) = f$.

Exercise 1) Use the method of undetermined coefficients to guess the form for a particular solution $y_p(x)$ for a constant coefficient differential equation

$$L(y) := y^{(n)} + a_{n-1}y^{(n-1)} + \dots + a_1 y' + a_0 y = f$$

(assuming the only such solution in your specified subspace that would solve the homogeneous DE is the zero solution):

1a) $L(y) = x^3 + 6x - 5$

$$y_p = d_1 x^3 + d_2 x^2 + d_3 x + d_4$$

$$V = \text{span}\{x^3, x^2, x, 1\}$$

$$L : V \rightarrow V$$

1b) $L(y) = 4e^{2x} \sin(3x)$

$$y_p = d_1 e^{2x} \sin 3x + d_2 e^{2x} \cos 3x$$

$$V = \text{span}\{e^{2x} \sin 3x, e^{2x} \cos 3x\}$$

1c) $L(y) = x \cos(2x)$

$$y_p = d_1 x \cos 2x + d_2 x \sin 2x + d_3 \cos 2x + d_4 \sin 2x$$

$$V = \text{span}\{x \cos 2x, x \sin 2x, \cos 2x, \sin 2x\}$$

$$L : V \rightarrow V$$

$$(D - rI) f(x) e^{rx} = f'(x) e^{rx}$$

$$= f'(x) e^{rx} + \cancel{f(x) e^{rx}} - \cancel{r f(x) e^{rx}}$$

BUT LOOK OUT

Exercise 2a) Find a particular solution to

$$L(y) = y'' + 4y' - 5y = 4e^x.$$

Hint: since $y_H = c_1 e^x + c_2 e^{-5x}$, a guess of $y_P = a e^x$ will not work (and $\text{span}\{e^x\}$ does not satisfy the "base case" conditions for undetermined coefficients). Instead try

$$y_P = d x e^x$$

and factor $L = D^2 + 4D - 5I = [D + 5I] \circ [D - I]$.

naive:

$$\begin{aligned} & -5(y_P = d x e^x) \\ & + 4(y_P' = d e^x + d x e^x) \\ & + 1(y_P'' = 2d e^x + d x e^x) \end{aligned}$$

$$L(y_P) = x e^x (-5d + 4d + d) + e^x (4d + 2d)$$

$$= 6d e^x \overset{\text{want}}{=} 4e^x$$

$$d = 2/3$$

$$y_P = \frac{2}{3} x e^x$$

$$y_H: y'' + 4y' - 5y = 0$$

$$p(r) = r^2 + 4r - 5$$

$$= (r+5)(r-1)$$

Case 1 does not apply

Smart way

$$(D + 5I) \circ (D - I) \overset{f(x)}{d x e^x}$$

$$(D + 5I) d e^x$$

$$= d e^x + 5d e^x$$

$$= 6d e^x$$

Same!

2b) check work with technology

$y''(x) + 4y'(x) - 5y(x) = 4e^x$

Web Apps Examples Random

Input:

$$y''(x) + 4y'(x) - 5y(x) = 4e^x$$

Open code

Enlarge | Data | Customize | Plaintext | Interactive

DE classification:

second-order linear ordinary differential equation

Alternate forms:

$$y''(x) = -4y'(x) + 5y(x) + 4e^x$$

$$5y(x) + 4e^x = y''(x) + 4y'(x)$$

Differential equation solution:

$$y(x) = c_1 e^{-5x} + c_2 e^x + \frac{2e^x x}{3}$$

Approximate form Step-by-step solution

Linear algebra to the rescue...just extend our previous discussion:

Theorem: Let

$$L : V \rightarrow W$$

be a linear transformation between vector spaces, where $\dim V = \dim W = n$. Then for each $f \in W$ there exists unique $y \in V$ solving

$$L(y) = f$$

if and only if the only solution $y \in V$ to $L(y) = 0$ is the trivial solution $y = 0$.

Proof: Let $\beta = \{y_1, y_2, \dots, y_n\}$ be a basis for V . Let $C = \{f_1, f_2, \dots, f_n\}$ be a basis for W . Let A be the matrix for L with respect to these two bases. Specifically, A is the matrix which converts β coordinates of input vectors into C coordinates of the outputs of L :

$$[L(y)]_C = A [y]_\beta$$

Then the equation $L(y) = f$ has a unique solution if and only if $[L(y)]_C = [f]_C$ does, i.e. if and only if the matrix equation

$$A [y]_\beta = [f]_C$$

has a unique solution. And this holds if and only if A reduces to the identity, i.e. if and only if $\text{Nul } A = \{0\}$, if and only if the only solution $y \in V$ to $L(y) = 0$ is the trivial solution $y = 0$.

QED

Method of undetermined coefficients ("Rule 2" page 190 text): Finding y_p for non-homogeneous linear differential equations

$$L(y) = f$$

If L has a factor $(D - r)^s$ and e^{rx} is also associated with (a portion of) the right hand side $f(x)$ then the corresponding guesses you would have made in the "base case" need to be multiplied by x^s , as in Exercise 2. (There's also a current homework problem related to this case.) You may also need to use superposition, as in our Tuesday exercises, if different portions of $f(x)$ are associated with different exponential functions.

Extended case of undetermined coefficients

$f(x)$	y_p	$s > 0$ when $p(r)$ has these roots:
$P_m(x) = b_0 + b_1x + \dots + b_mx^m$	$x^s(c_0 + c_1x + c_2x^2 + \dots + c_mx^m)$	$r = 0$
$b_1 \cos(\omega x) + b_2 \sin(\omega x)$	$x^s(c_1 \cos(\omega x) + c_2 \sin(\omega x))$	$r = \pm i\omega$
$e^{ax}(b_1 \cos(\omega x) + b_2 \sin(\omega x))$	$x^s e^{ax}(c_1 \cos(\omega x) + c_2 \sin(\omega x))$	$r = a \pm i\omega$
$b_0 e^{ax}$	$x^s c_0 e^{ax}$	$r = a$
$(b_0 + b_1x + \dots + b_mx^m)e^{ax}$	$x^s(c_0 + c_1x + c_2x^2 + \dots + c_mx^m)e^{ax}$	$r = a$