(1.3-1.4 quiz is at the end of class)

Section 1.5, linear differential equations:

A first order linear DE for y(x) is one that can be (re)written as

$$y' + P(x)y = Q(x)$$

Exercise 1: Classify the differential equations below as linear, separable, both, or neither. Justify your answers.

a)
$$y'(x) = -2y + 4x^2$$

b)
$$y'(x) = x - y^2 + 1$$

c)
$$y'(x) = x^2 - x^2y + 1$$

d)
$$y'(x) = \frac{6x - 3xy}{x^2 + 1}$$

e)
$$y'(x) = x^2 + y^2$$

f)
$$y'(x) = x^2 e^{x^3}$$

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X	no	ho	
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	V	/	y' + (3)
	ho	NO	1
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$y' + x^2 y = x^2 + 1$ $y' + \frac{3x}{x^2 + 1} y' = \frac{6x}{x^2 + 1}$
$y' = \frac{3 \times (2 - \gamma)}{x^2 + 1}$
y + 0 y = x ² ex ³
dy = x2ex. 1
(61-2)

Recall that the method for solving separable differential equations via differentials was actually using the differentiation chain rule "backwards" to antidifferentiate and find the solution functions. The algorithm for solving linear DEs is a method to use the differentiation product rule backwards:

$$y' + P(x)y = Q(x)$$

Let $\int P(x)dx$ be any antiderivative of P. Multiply both sides of the DE by its exponential to yield an "integrating factor" I.F. equivalent DE:

This makes the left side a derivative (check via product rule): $(y' + P(x)y) = e^{\int P(x)dx}Q(x)$

$$\int \frac{d}{dx} \left(e^{\int P(x)dx} y \right) = e^{\int P(x)dx} Q(x) .$$

So you can antidifferentiate both sides with respect to x:

$$e^{\int P(x)dx} y = \int e^{\int P(x)dx} Q(x)dx + C.$$

Dividing by the positive function $e^{\int P(x)dx}$ yields a formula for y(x).

• Remark: If we abbreviate the function $e^{\int_{-\infty}^{\infty} f(x)dx}$ by renaming it G(x), then the formula for the solution y(x) to the first order DE above is

$$y(x) = \frac{1}{G(x)} \int e^{\int P(x)dx} Q(x)dx + \frac{C}{G(x)}.$$

If x_0 is a point in any interval I for which the functions P(x), Q(x) are continuous, then G(x) is positive and differentiable, and the formula for y(x) yields a differentiable solution to the DE. By adjusting C to solve the IVP $y(x_0) = y_0$, we get a solution to the DE IVP on the entire interval. And, rewriting the DE as

$$y' = -P(x)y + Q(x)$$

we see that the existence-uniqueness theorem implies this is actually the only solution to the IVP on the interval (since f(x, y) and $\frac{\partial}{\partial y} f(x, y) = P(x)$ are both continuous). These facts would not necessarily be true for separable DE's...and we've seen how separable DE solutions may not exist or be unique on arbitrarily large intervals.

Exercise 2: Solve the differential equation

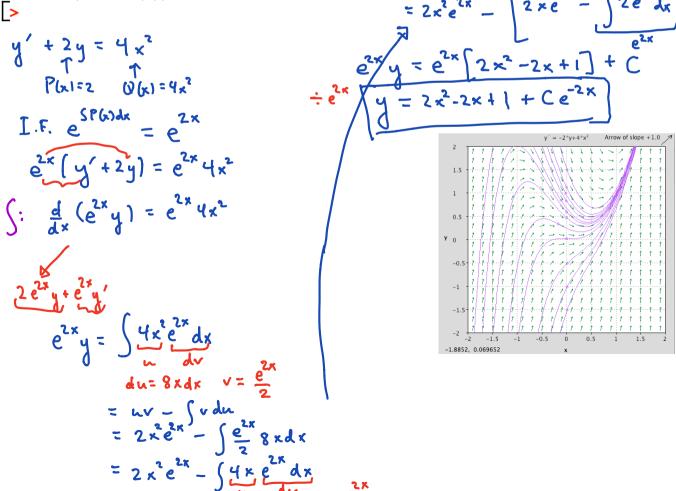
$$y'(x) = -2y + 4x^2$$
,

and compare your solutions to the dfield plot below.

> with(DEtools): # load differential equations library

> $deqtn2 := y'(x) = -2 \cdot y(x) + 4 \cdot x^2$: #notice you must use \cdot for multiplication in Maple, # and write y(x) rather than y.

dsolve(deqtn2, y(x)); # Maple check



Exercise 3: Find all solutions to the linear (and separable) DE

$$y'(x) = \frac{6x - 3xy}{x^2 + 1} = (\frac{3x}{x^2 + 1})(2 - y)$$

Hint: as you can verify below, the general solution is $y(x) = 2 + C(x^2 + 1)^{-\frac{3}{2}}$.

> with (DEtools): dsolve(

Separable:
$$\int \frac{dy}{y-2} = \int -\frac{3x}{x^2+1} dx \quad (y \neq 2, y \mid x \mid \leq 2 \text{ is sold.})$$

$$|x-2| = -\frac{3}{2} \ln |x^2 + i| + C_1$$

$$|x-2| = e^{C_1} \left[(x^2 + 1)^{-3/2} \right]$$

$$|x-2| = C \left[(x^2 + 1)^{-3/2} \right]$$

$$|x-2| = C \left[(x^2 + 1)^{-3/2} \right]$$

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linear:
$$y' + \frac{3x}{x^2 + 1}y = \frac{6x}{x^2 + 1}$$

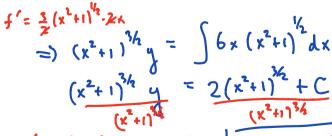
I.F.:
$$\int \frac{3x}{x^{2}+1} dx = \frac{3}{2} \ln(x^{2}+1)$$

$$\int \frac{3}{x^{2}+1} dx = \frac{3}{2} \ln(x^{2}+1) = (x^{2}+1)^{3}/2$$

$$(x^{2}+1)^{3}/2 \left[y' + \frac{3x}{x^{2}+1} y \right] = (x^{2}+1)^{3}/2$$

$$\int \frac{3}{x^{2}+1} dx = \frac{3}{2} \ln(x^{2}+1) = (x^{2}+1)^{3}/2$$

$$\frac{d}{dx}\left[\underbrace{(x^2+1)}_{5}^{4}y\right] = 6x(x^2+1)^{1/2}$$



$$(x^{2}+1)^{3/4} y = 2(x^{2}+1)^{3/4} + C$$

$$(x^{2}+1)^{3/4} \Rightarrow (F: | y = 2 + C(x^{2}+1)^{3/4})$$

$$\frac{d_{-3}}{dx^2} \ln (x^2 + 1) = -\frac{3}{2} \frac{1}{x^2 + 1} \cdot 2x$$

An extremely important class of modeling problems that lead to linear DE's involve input-output models. These have diverse applications ranging from bioengineering to environmental science. For example, The "tank" below could actually be a human body, a lake, or a pollution basin, in different applications.

For the present considerations, consider a tank holding liquid, with volume V(t) (e.g. units l). Liquid flows in at a rate r_i (e.g. units $\frac{l}{s}$), and with solute concentration c_i (e.g. units $\frac{gm}{l}$). Liquid flows out at a rate r_o , and with concentration c_0 . We are attempting to model the volume V(t) of liquid and the amount of solute x(t) (e.g. units gm) in the tank at time t, given $V(0) = V_0$, $x(0) = x_0$. We assume the solution in the tank is well-mixed, so that we can treat the concentration as uniform throughout the tank, i.e.

contentration as uniform throughout the tank, i.e.
$$c_o = \frac{x(t)}{V(t)} \frac{gm}{l}.$$
in tank is the same i.e. average concentration
$$\frac{x(t)}{V(t)} = \frac{x(t)}{V(t)} = \frac{x(t)}{V(t)}$$

See the diagram below.

Exercise 4: Under these assumptions use your modeling ability and Calculus to derive the following

Exercise 4: Under these assumptions use your modeling ability and Calculus to derive the following differential equations for
$$V(t)$$
 and $x(t)$:

a) The DE for $V(t)$, which we can just integrate:

$$V'(\tau)_{t} = \int_{0}^{t} r_{i}(\tau) - r_{0}(\tau) d\tau$$

b) The linear DE for $x(t)$.

$$x'(t) = r_{i} c_{i} - r_{o} c_{o} = r_{i} c_{i} - r_{o} \frac{x}{V}$$

$$V'(t) = r_{i} c_{i} - r_{o} c_{o} = r_{i} c_{i} - r_{o} \frac{x}{V}$$

$$V'(t) = r_{i} c_{i} - r_{o} c_{o} = r_{i} c_{i} - r_{o} \frac{x}{V}$$

$$\Delta V \approx r_i \Delta t - r_i \Delta t$$

ord thuy

 $\Delta V \approx r_i - r_i$
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$$x'(t) = r_{i} c_{i} - r_{o} c_{o} = r_{i} c_{i} - r_{o} \frac{x}{V}.$$

$$x'(t) + \frac{r_{o}}{V} x(t) = r_{i} c_{i}$$

$$x'(t) + \frac{r_{o}}{V} x(t) = r_{o} c_{i}$$

$$x'(t) + \frac$$

Often (but not always) the tank volume remains constant, i.e. $r_i = r_o$. If the incoming concentration c_i is also constant, then the IVP for solute amount is

$$x' + a x = b$$
$$x(0) = x_0$$

where a, b are constants.

Exercise 5: The constant coefficient initial value problem above will recur throughout the course in various contexts, so let's solve it now. Hint: We will check our answer with Maple first, and see that the solution is

$$x(t) = \frac{b}{a} + \left(x_o - \frac{b}{a}\right)e^{-at}.$$

Exercise 6 (taken from section 1.5 of text) Solve the following pollution problem IVP, to answer the follow-up question: Lake Huron has a relatively constant concentration for a certain pollutant. Since Lake Huron is the primary water source for Lake Erie, this is also the usual pollutant concentration in Lake Erie Due to an industrial accident, however, Lake Erie has suddenly obtained a concentration five times as large. Lake Erie has a volume of 480 km³, and water flows into and out of Lake Erie at a rate of 350 km³ per year. Essentially all of the in-flow is from Lake Huron (see below). We expect that as time goes by, the water from Lake Huron will flush out Lake Erie. Assuming that the pollutant concentration is roughly the same everywhere in Lake Erie, about how long will it be until this concentration is only twice the original background concentration from Lake Huron?



http://www.enchantedlearning.com/usa/statesbw/greatlakesbw.GIF

<u>a)</u> Set up the initial value problem. Maybe use symbols c for the background concentration (in Huron),

$$V = 480 \text{ km}^3$$

$$r = 350 \ \frac{km^3}{y}$$

b) Solve the IVP, and then answer the question.