

2b) Use these linearity properties to show that

Theorem 0 the solution space to the homogeneous second order linear DE

$$L(y) = y'' + p(x)y' + q(x)y = 0$$

is closed under addition and scalar multiplication, i.e. it is a subspace. Notice that this is the "same" proof one uses to show that the solution space to a homogeneous matrix equation $A\mathbf{x} = \mathbf{0}$ is a subspace.

Let $L(y_1) = 0, L(y_2) = 0$.
(i.e. Let y_1, y_2 be solns to the homogeneous DE.)

then $L(y_1 + y_2) = L(y_1) + L(y_2) = 0 + 0 = 0$
so $y_1 + y_2$ is a homog. soln.

also $L(cy_1) = cL(y_1) = c \cdot 0 = 0$
so cy_1 is a homog. soln.

Exercise 3) As an example, find the solution space to the following homogeneous differential equation for $y(x)$

$$y'' + 2y' = 0$$

on the x -interval $-\infty < x < \infty$. Notice that the solution space is the span of two functions. Hint: This is really a first order DE for $v = y'$.

$$v' + 2v = 0$$

$$e^{2x}(v' + 2v) = e^{2x} \cdot 0 = 0$$

$$\frac{d}{dx}(e^{2x}v) = 0$$

$$e^{2x}v = C$$

$$v = Ce^{-2x}$$

$$y'(x) = Ce^{-2x}$$

$$\Rightarrow y(x) = -\frac{C}{2}e^{-2x} + D$$

$$y(x) = c_1 e^{-2x} + c_2 \cdot 1$$

soln space is $\text{span}\{e^{-2x}, 1\}$

two ways that one sees subspace:
implicit way \rightarrow (1) soln space to $L(y) = 0$, where L is linear in y 's

explicit way \rightarrow (2) $\text{span}\{y_1, y_2, \dots, y_n\} = \{c_1 y_1 + c_2 y_2 + \dots + c_n y_n\}$
 $c_1, c_2, \dots, c_n \in \mathbb{R}$

in 2270
"homogeneous soln space"
i.e. $\{\vec{x} \in \mathbb{R}^n \text{ s.t. } A\vec{x} = \vec{0}\}$
is a subspace:
Let \vec{z}, \vec{w} be homogeneous solns, i.e. $A\vec{z} = \vec{0}$
 $A\vec{w} = \vec{0}$
then $A(\vec{z} + \vec{w}) = A\vec{z} + A\vec{w} = \vec{0} + \vec{0} = \vec{0}$
 $A(c\vec{z}) = cA\vec{z} = c\vec{0} = \vec{0}$

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soln space of \vec{x} 's
s.t. $A\vec{x} = \vec{0}$
"nullspace"
(2) $\text{span}\{\vec{v}_1, \dots, \vec{v}_n\}$

Exercise 4) Use the linearity properties to show

Theorem 1 All solutions to the nonhomogeneous second order linear DE

$$L(y) = y'' + p(x)y' + q(x)y = f(x)$$

are of the form $y = y_p + y_H$ where y_p is any single particular solution and y_H is some solution to the homogeneous DE. (y_H is called y_c , for complementary solution, in the text). Thus, if you can find a single particular solution to the nonhomogeneous DE, and all solutions to the homogeneous DE, you've actually found all solutions to the nonhomogeneous DE.

① if y_p is a particular soln
i.e. $L(y_p) = f$
let $L(y_H) = 0$.

then $L(y_p + y_H) = L(y_p) + L(y_H)$
 $= f + 0$
 $= f$
so $y_p + y_H$ solves the homog DE

② if y_Q is
any (other) soln
to $L(y) = f$
write

$y_Q = y_p + (y_Q - y_p)$
 $\Rightarrow L(y_Q) = L(\text{---})$
 $f = L(y_p) + L(y_Q - y_p)$
 ~~$f = f + L(y_Q - y_p)$~~
 $0 = L(y_Q - y_p)$ so $y_Q = y_p + y_H$, with $y_H = y_Q - y_p$

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$A\vec{x} = \vec{b}$
if $A\vec{x}_p = \vec{b}$
then every soln to
 $A\vec{x} = \vec{b}$ is of the
form $\vec{x} = \vec{x}_p + \vec{x}_H$
where \vec{x}_H is in the
nullspace of A

Theorem 2 (Existence-Uniqueness Theorem): Let $p(x), q(x), f(x)$ be specified continuous functions on the interval I , and let $x_0 \in I$. Then there is a unique solution $y(x)$ to the initial value problem

$$\begin{aligned} y'' + p(x)y' + q(x)y &= f(x) \\ y(x_0) &= b_0 \\ y'(x_0) &= b_1 \end{aligned}$$

and $y(x)$ exists and is twice continuously differentiable on the entire interval I .

Chptr 4

for now, we'll just believe this \rightarrow

why this true (later)
2nd order DE is actually
equivalent to a 1st order system:

if y solves *

$$\text{then } \begin{bmatrix} y \\ y' \end{bmatrix}' = \begin{bmatrix} y' \\ y'' \end{bmatrix}$$

$$\begin{bmatrix} y \\ y' \end{bmatrix}' = \begin{bmatrix} y' \\ f - py' - qy \end{bmatrix}$$

of form $(x_1 = y, x_2 = y')$

$$\text{ivp } \begin{cases} \begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \begin{bmatrix} x_2 \\ f - px_2 - qx_1 \end{bmatrix} \\ \begin{bmatrix} x_1(x_0) \\ x_2(x_0) \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \end{bmatrix} \end{cases}$$

$y_p + y_h$ — existence, uniqueness

Exercise 5) Verify Theorems 1 and 2 for the interval $I = (-\infty, \infty)$ and the IVP

$y(x)$

$$y'' + 2y' = 3$$

$$y(0) = b_0$$

$$y'(0) = b_1$$

Let $v = y'$

$$v' + 2v = 3$$

$$e^{2x}(v' + 2v) = 3e^{2x}$$

$$\frac{d}{dx} e^{2x} v = 3e^{2x}$$

$$e^{2x} v = \frac{3}{2} e^{2x} + C$$

$$v = \frac{3}{2} + C e^{-2x}$$

$$y' = \frac{3}{2} + C e^{-2x}$$

$$y = \frac{3}{2} x + \frac{C}{-2} e^{-2x} + D$$

$$y(x) = \underbrace{\frac{3}{2} x}_{y_p} + \underbrace{c_1 e^{-2x} + c_2}_{y_h}$$

$$y_p \quad (y_p'' + 2y_p' = 0 + 2 \cdot \frac{3}{2} = 3 \checkmark)$$

note, $\frac{3}{2}x + 2e^{-2x} + 7$

is another particular soln, so I could also have written

$$y(x) = \frac{3}{2}x + 2e^{-2x} + 7 + d_1 e^{-2x} + d_2$$

Thm 2 $y(x) = \frac{3}{2}x + c_1 e^{-2x} + c_2$
 $\Rightarrow y'(x) = \frac{3}{2} - 2c_1 e^{-2x}$

for IVP: $y(0) = b_0 = 0 + c_1 + c_2$
 $y'(0) = b_1 = \frac{3}{2} - 2c_1$

for each initial value vector

$$\begin{bmatrix} b_0 \\ b_1 \end{bmatrix} \text{ there is a unique } \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}.$$

general soln to $y'' + 2y' = 0$ (Friday)

Unlike in the previous example, and unlike what was true for the first order linear differential equation

$$y' + p(x)y = q(x)$$

there is not a clever integrating factor formula that will always work to find the general solution of the second order linear differential equation

$$y'' + p(x)y' + q(x)y = f(x).$$

Rather, we will usually resort to vector space theory and algorithms based on clever guessing to solve these differential equations. It will help to know

Theorem 3: The solution space to the second order homogeneous linear differential equation

$$y'' + p(x)y' + q(x)y = 0$$

is 2-dimensional.

This Theorem is illustrated in Exercise 2 that we completed earlier. Theorem 3 and the techniques we'll actually be using going forward are illustrated by

Exercise 6) Consider the homogeneous linear DE for $y(x)$

$$y'' - 2y' - 3y = 0$$

6a) Find two exponential functions $y_1(x) = e^{r_1 x}$, $y_2(x) = e^{r_2 x}$ that solve this DE. Deduce that arbitrary linear combinations of y_1, y_2 also solve the DE.

6b) Show that every IVP

$$y'' - 2y' - 3y = 0$$

$$y(0) = b_0$$

$$y'(0) = b_1$$

$$\begin{aligned} y(x) &= c_1 e^{3x} + c_2 e^{-x} \quad \text{want} \\ \Rightarrow y(0) &= c_1 + c_2 = b_0 \\ y'(0) &= 3c_1 - c_2 = b_1 \end{aligned}$$

$$\begin{bmatrix} 1 & 1 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \end{bmatrix}$$

can be solved with a unique linear combination $y(x) = c_1 y_1(x) + c_2 y_2(x)$.

6c) Use your work from part b to explain why the solution space is two-dimensional.

6d) Now consider the nonhomogeneous DE

$$y'' - 2y' - 3y = 9$$

Notice that $y_p(x) = -3$ is a particular solution. Use this information and superposition (linearity) to find the solution to the initial value problem

$$y'' - 2y' - 3y = 9$$

$$y(0) = 6$$

$$y'(0) = -2.$$

$$\Rightarrow \begin{cases} y = y_p + y_H \\ y = -3 + c_1 e^{3x} + c_2 e^{-x} \end{cases}$$

$$\begin{aligned} 6a) \quad y'' - 2y' - 3y &= 0. \quad * \\ \text{try } y &= e^{rx} \quad (\text{find "r"}). \\ y' &= r e^{rx} \\ y'' &= r^2 e^{rx} \end{aligned}$$

$$\begin{aligned} \text{so } y'' - 2y' - 3y &= r^2 e^{rx} - 2r e^{rx} - 3e^{rx} \\ &= e^{rx} [r^2 - 2r - 3] \end{aligned}$$

$$= 0 \quad (\text{zero fun})$$

$$\text{iff } r \text{ is a root of } p(r) = r^2 - 2r - 3 = (r-3)(r+1)$$

$$r = 3, -1.$$

$$\begin{cases} y_1 = e^{3x} \\ y_2 = e^{-x} \end{cases} \quad \text{solve } * \\ \text{you could check.} \end{cases}$$

$$\Rightarrow y_H(x) = c_1 e^{3x} + c_2 e^{-x} \quad \text{solve } *$$

$$\begin{aligned} y' - ky &= 0 \\ y' &= ky \\ y &= ce^{kx} \end{aligned}$$

c) Why soln is 2-dim'l.

claim: $y_1(x) = e^{3x}$, $y_2(x) = e^{-x}$ is a basis for soln space

- span
- linearly independent.

We showed in (b) that every IVP $\begin{cases} y'' - 2y' - 3y = 0 & \text{DE} \\ y(0) = b_0 \\ y'(0) = b_1 \end{cases}$

has a soln $y(x) = c_1 y_1 + c_2 y_2$.

Let $z(x)$ be any soln to DE.

call $z(0) = b_0$, $z'(0) = b_1$. pick $y(x) = c_1 y_1 + c_2 y_2$ so that $\begin{cases} y(0) = b_0 \\ y'(0) = b_1 \end{cases}$ } c_1, c_2 uniquely determined by b_0, b_1

uniqueness theorem

\Rightarrow our $y(x) = z(x)$.

\Rightarrow soln space = $\text{Span}\{y_1, y_2\}$.

if $c_1 y_1 + c_2 y_2 \equiv 0$

then $y(x)$ is a homog. soln.

$\begin{cases} y(0) = 0 \\ y'(0) = 0 \end{cases} \Rightarrow c_1 = c_2 = 0$.

$$d) \begin{cases} y'' - 2y' - 3y = 9 \\ y(0) = 6 \\ y'(0) = -2 \end{cases}$$

$$\begin{aligned} y(x) &= -3 + c_1 e^{3x} + c_2 e^{-x} \\ y'(x) &= 3c_1 e^{3x} - c_2 e^{-x} \end{aligned}$$

$$\text{1. C's: } \begin{aligned} y(0) = 6 &= -3 + c_1 + c_2 \\ y'(0) = -2 &= 3c_1 - c_2 \end{aligned}$$

$$\begin{bmatrix} 9 \\ -2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$-\frac{1}{4} \begin{bmatrix} -1 & -1 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 9 \\ -2 \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$-\frac{1}{4} \begin{bmatrix} -7 \\ -29 \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$