Name.
I.D. number.

## Math 2280-001 <br> Practice Second Midterm

April 1, 2015

This exam is closed-book and closed-note. You may use a scientific calculator, but not one which is capable of graphing or of solving differential or linear algebra equations. In order to receive full or partial credit on any problem, you must show all of your work and justify your conclusions. There are 100 points possible, and the point values for each problem are indicated in the right-hand margin. Good Luck!

1

2

3

4

5
total

1) Consider a general input-output model with two compartments as indicated below. The compartments contain volumes $V_{1}, V_{2}$ and solute amounts $x_{1}(t), x_{2}(t)$ respectively. The flow rates (volume per time) are indicated by $r_{i}, i=1 . .6$. The two input concentrations (solute amount per volume) are $c_{1}, c_{5}$.


1a) Suppose $r_{2}=r_{3}=100, r_{1}=r_{4}=r_{5}=200, r_{6}=300 \frac{m^{3}}{h o u r}$. Explain why the volumes $V_{1}(t), V_{2}(t)$ remain constant.

1b) Using the flow rates above, incoming concentrations $c_{1}=0.05, c_{5}=0 \frac{\mathrm{~kg}}{\mathrm{~m}^{3}}$, volumes $V_{1}=V_{2}=100 \mathrm{~m}^{3}$, show that the amounts of solute $x_{1}(t)$ in tank 1 and $x_{2}(t)$ in tank 2 satisfy

$$
\left[\begin{array}{l}
x_{1}{ }^{\prime}(t) \\
x_{2}{ }^{\prime}(t)
\end{array}\right]=\left[\begin{array}{rr}
-3 & 1 \\
2 & -4
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right]+\left[\begin{array}{c}
10 \\
0
\end{array}\right] .
$$

1c) Find the solution to the homogeneous system of differential equations

$$
\left[\begin{array}{l}
x_{1}{ }^{\prime}(t) \\
x_{2}{ }^{\prime}(t)
\end{array}\right]=\left[\begin{array}{rr}
-3 & 1 \\
2 & -4
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right] .
$$

1d) Find the general solution to the inhomogeneous system of differential equations in 7 b ,

$$
\left[\begin{array}{l}
x_{1}{ }^{\prime}(t) \\
x_{2}{ }^{\prime}(t)
\end{array}\right]=\left[\begin{array}{rr}
-3 & 1 \\
2 & -4
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right]+\left[\begin{array}{c}
10 \\
0
\end{array}\right] .
$$

Hint: you will need to find a particular solution as part of your work.
2) We used the principle of conservation of energy and the method of linearization to derive the second order linear differential equation which describes undamped unforced pendulum motion. This differential equation is

$$
L \cdot \theta^{\prime \prime}(t)+g \cdot \theta(t)=0
$$

where $\theta(t)$ is the angle from vertical, $L$ is the length of the (massless) rod or string, $m$ is the mass at the end of the string, and $g=9.8 \frac{\mathrm{~m}}{\mathrm{~s}^{2}}$ is the acceleration of gravity on earth.
2a) Derive the linear model above, using the fact that kinetic plus potential energy is constant for any solution to this conservative system. This will yield a non-linear differential equation which you can linearize to the one above, under the assumption that $\theta(t)$ is near zero.

2b) If you wished to create a pendulum for which the natural period was 2 seconds/cycle, what length $L$ would you choose? (A symbolic answer suffices - the correct decimal value for $L$ is close to 1 meter.) Note that you can answer this question from the differential equation given at the start of this problem.
3) A focus in this course is a careful analysis of the mathematics and physical phenomena exhibited in forced and unforced mechanical (or electrical) oscillation problems. Using the mass-spring model, we've studied the differential equation for functions $x(t)$ solving

$$
m x^{\prime \prime}+c x^{\prime}+k x=F_{0} \cos (\omega t)
$$

with $m, k, \omega>0 ; c, F_{0} \geq 0$.

Explain what values (or ranges of values) for $c, k, F_{0}$, $\omega$ lead to the phenomena listed below. (If you use " $\omega_{0}$ " in this discussion make sure to explain what it is as well.) What form will the key parts of the solutions $x(t)$ have in those cases, in order that the physical phenomena be present? (We're not expecting the precise formulas for these parts of the solutions, just what their forms will be.)

3a) pure resonance

3b) beating

3c) practical resonance.
4) Consider the following configuration of 2 masses held together with two springs (a 2 car train), with positive displacements from equilibrium for each mass measured to the right, as usual.


4a) Use Newton's Law and Hooke's usual linearization to derive the system of 2 second order differential equations governing the masses' motion.

4b) What is the dimension of the solution space to this problem? Explain.

4c) Assume that all $m_{1}=m_{2}=m$. Show that in this case the system in (3a) reduces to

$$
\left[\begin{array}{l}
x_{1}{ }^{\prime \prime}(t) \\
x_{2}{ }^{\prime \prime}(t)
\end{array}\right]=\frac{k}{m}\left[\begin{array}{cc}
-1 & 1 \\
1 & -1
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right]
$$

4d) Find the general solution to the differential equation in 3 c , repeated here for your convenience. Then describe the general motion as a superposition of two "fundamental modes". Hint: One of the modes is not oscillatory, since this "train" is not tethered to any wall.

$$
\left[\begin{array}{c}
x_{1}{ }^{\prime \prime}(t) \\
x_{2}{ }^{\prime \prime}(t)
\end{array}\right]=\frac{k}{m}\left[\begin{array}{cc}
-1 & 1 \\
1 & -1
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right]
$$

5) Draw the phase portrait for the first order system, and classify it as one of the following: saddle, nodal source, nodal sink, center, spiral sink, spiral source.

$$
\left[\begin{array}{l}
x_{1}{ }^{\prime}(t) \\
x_{2}{ }^{\prime}(t)
\end{array}\right]=\left[\begin{array}{rr}
-4 & 3 \\
0 & 6
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right]
$$

Hint: Use the eigendata and the form of the general solution.

