

Name..... SOLUTIONS
I.D. number.....

Math 2280-1

Exam 1

February 15, 2006

This exam is closed-book and closed-note. You may use a scientific calculator, but not one which is capable of graphing or of solving differential or linear algebra equations. **In order to receive full or partial credit on any problem, you must show all of your work and justify your conclusions.** There are 100 points possible. The point values for each problem are indicated in the right-hand margin. **Good Luck!**

1) Consider a mass-spring system with damping, in which the mass is 3 kg.
1a) What values of damping coefficient and spring constant (including correct units!) would lead to the following differential equation for the displacement $x(t)$ from equilibrium?

$$3(x''(t) + 4x'(t) + 3x(t)) = 0$$
$$3x'' + cx' + kx = 0$$

(4 points)

$$\Rightarrow c = 12 \text{ N s/m (or kg/s)}$$
$$k = 9 \text{ N/m}$$

[deduce units because mx'' has units $\text{kgm/s}^2 = \text{N}$,
as do all 3 terms]

1b) Find the general solution to the differential equation in 1a. What kind of damping is exhibited by this spring system?

(10 points)

$$x'' + 4x' + 3x = 0$$
$$x = e^{rt} \rightarrow p(r) = r^2 + 4r + 3$$
$$= (r+3)(r+1)$$
$$r = -1, -3$$
$$x_H(t) = c_1 e^{-3t} + c_2 e^{-t}$$

over-damped

1c) Solve the initial value problem for the spring system in 1a, with $x(0)=0$, $Dx(0)=2$.

(8 points)

$$x(t) = c_1 e^{-3t} + c_2 e^{-t}$$

$$x(0) = 0$$

$$x'(0) = 2$$

$$x(0) = c_1 + c_2 = 0$$

$$x'(0) = -3c_1 - c_2 = 2$$

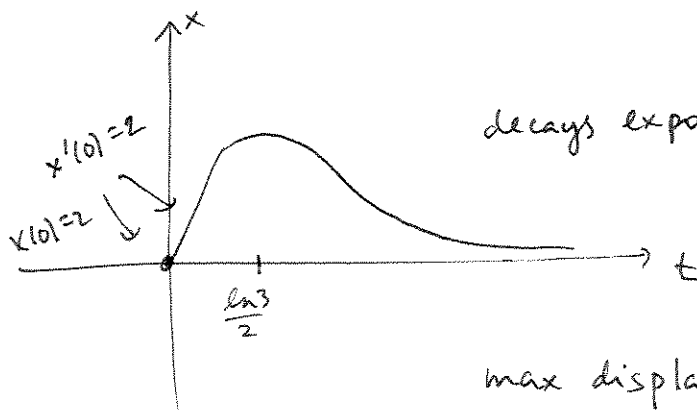
add eqns $\Rightarrow -2c_1 = 2$
 $c_1 = -1$
 $c_2 = 1$

$x(t) = -e^{-3t} + e^{-t}$

1d) Sketch a qualitative graph of your solution $x(t)$ to part (c) as a function of t . Solve for the time when the mass is displaced a maximum amount from equilibrium.

(8 points)

$$x(t) = e^{-t} [1 - e^{-2t}] \quad \text{only root at } t=0$$



max displacement when $x'(t) = 0$

$$x'(t) = 3e^{-3t} - e^{-t}$$

$$= e^{-t} [1 - 3e^{-2t}]$$

$$3e^{-2t} = 1$$

$$e^{-2t} = \frac{1}{3}$$

$$-2t = -\ln(3)$$

$t = \frac{\ln 3}{2}$

2) Consider the differential equation

$$\frac{dP}{dt} = P^2 - 4P - 5.$$

which could be a model for a certain population.

2a) Find the equilibrium solutions.

(6 points)

$$\frac{dP}{dt} = (P-5)(P+1)$$

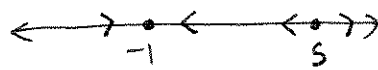
equil sol'ns $P = 5$
 $P = -1$

2b) Sketch the phase diagram for this differential equation. Use this phase diagram to deduce the stability of your (2a) equilibrium solutions

(6 points)



Phase portrait:



so $P = -1$ is stable and $P = 5$ is unstable.

2c) Describe a population model which could lead to differential equation of this type. Be as precise as you can, so that you can account for all three terms on the right-hand side of the differential equation.

(4 points)

$$\frac{dP}{dt} = P^2 - 4P = P(P-4) \text{ is doomsday-extinction}$$

so this could be doomsday-extinction with harvesting (at rate 5 pop units/time unit)

2e) Solve the initial value problem for this differential equation, with $P(0)=3$. Explain what happens to your solution as time increases, and explain why this is consistent with your phase diagram in (2b). (14 points)

$$\frac{dP}{(P-5)(P+1)} = dt$$

$$\frac{1}{6} \left(\frac{1}{P-5} - \frac{1}{P+1} \right) dP = dt$$

$$\frac{1}{P-5} - \frac{1}{P+1} dP = 6 dt$$

$$\ln \left| \frac{P-5}{P+1} \right| = 6t + C$$

$$\frac{P-5}{P+1} = C e^{6t}$$

$$P(0)=3 \Rightarrow C = \frac{3-5}{3+1} = -\frac{1}{2}$$

$$(P-5) = -\frac{1}{2} e^{6t} (P+1)$$

$$P \left[1 + \frac{1}{2} e^{6t} \right] = 5 - \frac{1}{2} e^{6t}$$

$$P = \frac{5 - \frac{1}{2} e^{6t}}{1 + \frac{1}{2} e^{6t}} = \frac{10 - e^{6t}}{2 + e^{6t}} \quad \frac{e^{-6t}}{e^{-6t}} = \frac{-1 + 10e^{-6t}}{1 + 2e^{-6t}}$$

$$P(t) \rightarrow -1 \text{ as } t \rightarrow \infty$$

(so for a real population there was doomsday at finite time)

as predicted by phase portrait

3a) Using the Chapter 1 algorithm for solving first order linear differential equations, find the solution to the initial value problem

$$x'(t) + \frac{3}{50+3t} x(t) = 3$$

$$x(0) = 0.$$

$$e^{\int \frac{3}{50+3t} dt} \left(x' + \frac{3}{50+3t} x \right) = 3 e^{\int \frac{3}{50+3t} dt}$$

(10 points)

$$e^{\ln(50+3t)}$$

$$(50+3t) \left(x' + \frac{3}{50+3t} x \right) = 3(50+3t)$$

$$[(50+3t)x]' = 3(50+3t)$$

$$(50+3t)x = 150t + \frac{9}{2}t^2 + C$$

$$x(0) = 0 \Rightarrow C = 0.$$

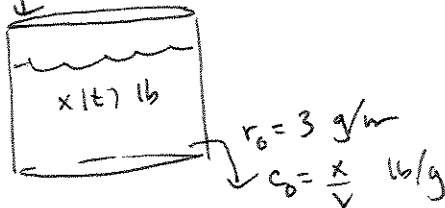
$$x(t) = \frac{150t + \frac{9}{2}t^2}{50+3t}$$

3b) Consider a mixing tank with one input pipe and one output pipe. Assume the tank initially contains 50 gallons of salt-free water. Assume that water flows into the tank at a rate of 6 gallons per minute, and that the input concentration is 1/2 pound of salt per gallon of water. Assume that well-mixed water flows out of the tank at a rate of 3 gallons per minute. Let $x(t)$ be the amount of salt in the tank at time t . Using the input-output tank model we've studied, show that $x(t)$ satisfies the initial value problem which you have just solved in part 3a and, at least until the tank overflows.

(5 points)

$$r_i = 6 \text{ gal/min}$$

$$c_i = \frac{1}{2} \text{ lb/g}$$



water volume

$$\frac{dV}{dt} = r_i - r_o$$

$$= 6 - 3 = 3$$

$$\begin{cases} \frac{dV}{dt} = 3 \\ V(0) = 50 \end{cases} \Rightarrow V(t) = 50 + 3t$$

$$\frac{dx}{dt} = r_i c_i - r_o c_o$$

$$\frac{dx}{dt} = 3 - \frac{3x}{V(t)} = 3 - \frac{3x(t)}{50+3t}$$

i.e.

$$\frac{dx}{dt} + \left(\frac{3}{50+3t} \right) x(t) = 3$$

4a) What is the dimension of the solution space to the differential equation
 $y''''(x) + 4y'(x) = 0$

(3 points)

if L is n^{th} order linear DE, $\dim \ker L = n$
 so in our case $\boxed{\dim = 3}$

4b) Find a basis for the solution space in 4a.

(10 points)

$$y = e^{rt}$$

$$L(y) = e^{rt} p(r) = e^{rt} (r^3 + 4r)$$

$$r^3 + 4r = r(r^2 + 4)$$

$$\{1, \cos 2t, \sin 2t\}$$

roots $r=0 \rightarrow y_1(t) = 1$
 $r = \pm 2i \rightarrow y_2(t) = \cos 2t, y_3(t) = \sin 2t$

4c) Prove the functions you found in you part 4b basis are linearly independent. (You may perhaps like to use the Wronskian or related ideas.)

(7 points)

$$W = \det \begin{vmatrix} 1 & \cos 2t & \sin 2t \\ 0 & -2\sin 2t & 2\cos 2t \\ 0 & -4\cos 2t & -4\sin 2t \end{vmatrix} = \begin{vmatrix} M_{11} \end{vmatrix} = 8 \sin^2 2t + 8 \cos^2 2t$$

$$= 8 \neq 0$$

so $\{y_1, y_2, y_3\}$ are linearly independent

[the actual variable was "x" not "t", so define $t := x$ in the above]

5) State and derive the formulas which show how C and α are related to A and B , in the identity

$$A \cos(\omega t) + B \sin(\omega t) = C \cos(\omega t - \alpha)$$

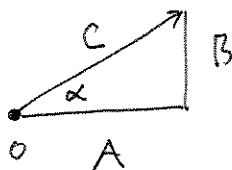
$$= C [\cos \omega t \cos \alpha + \sin \omega t \sin \alpha] \quad (5 \text{ points})$$

since $\cos \omega t, \sin \omega t$ are lin. ind. fns,
identity can hold iff

$$* \begin{cases} A = C \cos \alpha \\ B = C \sin \alpha \end{cases}$$

$$\text{iff } A^2 + B^2 = C^2 \quad (= C^2 (\cos^2 \alpha + \sin^2 \alpha))$$

and α is the
angle in the \mathbb{R}^2 triangle



since $*$ holds iff

$$C = \sqrt{A^2 + B^2}$$

$$A/C = \cos \alpha$$

$$B/C = \sin \alpha$$

(the hypotenuse vector C
can point into any
quadrant, depending
on the signs of A and B).

$n=29$

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Exam 1 scores

