Nar	ne
I.D.	number

## Math 2280-1 FINAL EXAM Dec 17, 2008

This exam is closed-book and closed-note. You may use a scientific calculator, but not one which is capable of graphing or of solving differential or linear algebra equations. Laplace Transform Tables are included with this exam. In order to receive full or partial credit on any problem, you must show all of your work and justify your conclusions. This exam counts for 30% of your course grade. It has been written so that there are 200 points possible, however, and the point values for each problem are indicated in the right-hand margin. Good Luck!

problem	score	possible
man'		35
2		40
3		20
4	december of the second	20
5	<del>*************************************</del>	25
6	***************************************	20
7		40

1a) A motorboat containing the pilot has total mass of 360 kilograms, and its motor is able to provide 120 Newtons of thrust. However, when the boat is in motion, drag from the water produces a force of 6 newtons for each meter/sec of boat velocity. Use Newton's law to explain why (while the motor is on) the boat velocity satisfies the differential equation

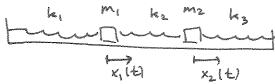
$$\frac{dv}{dt} = \frac{1}{3} - \frac{v}{60}$$

(5 points)

1b) What is the equilibrium solution for the velocity v(t)? Is this solution stable or unstable? Explain with a phase diagram.

1c) Solve the initial value problem for the boat's velocity, assuming the boat starts at resintegrating-factor method we learned in Chapter 1, for first order linear differential equation	. Use the
, , , , , , , , , , , , , , , , , , ,	(10 points)
1d) Resolve the same IVP, this time using the algorithm for separable differential equation	ns.
	(10 points)
4 > 70.1	
1e) If the boat starts at rest, how long does it take to reach 75% of its terminal velocity?	(5 points)
	(o pours)

2) Consider a two mass, 3 spring system consisting of two masses with mass  $m_1$  and  $m_2$ , and springs with Hooke's constants  $k_1$ ,  $k_2$ ,  $k_3$ , as sketched below. You can think of the masses as sliding along a frictionless table, or as hanging vertically. Let  $x_1(t)$  and  $x_2(t)$  measure displacement from equilbrium, as indicated. Assume there are no external forces.



2a) Derive the system of differential equations which governs the motion of the masses.

(5 points).

2b) What is the dimension of the solution space to this system of DEs? Explain brieflly.

(5 points)

2c) Consider the case in which the left mass is 2 kg and the right mass is 1 kg, and the left and right springs don't exist, and the middle spring has Hooke's constant 6 N/m. Show that the system in (2a) reduces to

$$\begin{bmatrix} \frac{\mathrm{d}^2}{\mathrm{d}t^2} x_1(t) \\ \frac{\mathrm{d}^2}{\mathrm{d}t^2} x_2(t) \end{bmatrix} = \begin{bmatrix} -3 & 3 \\ 6 & -6 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

2d) Find the general solution to the mass-spring system in (2c). For your convenience, the system is rewritten below.

$$\begin{bmatrix} \frac{\mathrm{d}^2}{\mathrm{d}t^2} x_1(t) \\ \frac{\mathrm{d}^2}{\mathrm{d}t^2} x_2(t) \end{bmatrix} = \begin{bmatrix} -3 & 3 \\ 6 & -6 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

(10 points)

2e) Describe the two fundmental motions (modes) for the system above, which superpose to give the general solution.

2f) Now suppose there is an external sinusoidal force, so that the second order system becomes inhomogeneous,

$$\frac{\mathrm{d}^2}{\mathrm{d}t^2} x(t) = A x + \cos(\omega t) b.$$

Using matrix algebra (like we did in class, and you did in your Maple project), derive a formula for a particular solution

$$x_p(t) = \cos(\omega t) c$$

 $x_p(t) = \cos(\omega t) c$  to this system. What happens to this solution if  $\omega$  is close to one of the natural frequencies?

3a) Find  $e^{At}$  for the matrix from problem 2,

$$A = \begin{bmatrix} -3 & 3 \\ 6 & -6 \end{bmatrix}.$$

(10 points)

3b) Find  $e^{Bt}$  for the matrix

$$B = \left[ \begin{array}{cc} 3 & -4 \\ 4 & 3 \end{array} \right]$$

- 4) Use Laplace transform to solve the initial value problem for the undamped oscillator, where the system begins at rest. There are two cases,
- 4a) Driving angular frequency  $\omega$  is not the natural frequency  $\omega_0$ :

$$\frac{d^2}{dt^2}x(t) + \omega_0^2 x(t) = F_0 \cos(\omega t)$$
$$x(0) = 0$$
$$D(x)(0) = 0$$

(10 points)

4b)  $\omega = \omega_0$ :

$$\frac{d^2}{dt^2}x(t) + \omega_0^2 x(t) = F_0 \cos(\omega_0 t)$$

$$x(0) = 0$$

$$D(x)(0) = 0$$

5a) Use your work from problem (4) to solve the initial value problem

$$\frac{d^2}{dt^2}x(t) + x(t) = 4\cos(3t) + 7\cos(t)$$
$$x(0) = 5$$

$$D(x)(0) = 2$$

(10 points)

5b) In problem 6 you will verify that the 2  $\pi$ -periodic "tent" function has Fourier series

$$tent(t) = \frac{1}{2} \pi - \frac{4 \left( \sum_{n=odd} \frac{\cos(n t)}{n^2} \right)}{\pi}.$$

Use this fact to find a particular solution to

$$\frac{\mathrm{d}^2}{\mathrm{d}t^2}x(t)+x(t)=2\,tent(t).$$

(10 points)

5c) Does the solution to forced oscillation problem in (5b) exhibit resonance? Explain.

6a) Let tent(t) be the 2  $\pi$  periodic extension of absolute value function from the interval  $[-\pi, \pi]$  to the entire real line. Prove that tent(t) has Fourier Series given by

$$tent(t) = \frac{1}{2} \pi - \frac{4 \left( \sum_{n=odd} \frac{\cos(n t)}{n^2} \right)}{\pi}.$$
(12 points)

6b) We were allowed to use the = sign for the Fourier series in (6a) because the tent function is continuous and piecewise differentible, so the Fourier series converges to the function at each point. Use this fact to prove the magic formulas (use the first to prove the second):

$$\sum_{n=odd} \frac{1}{n^2} = \frac{1}{8} \pi^2$$

$$\sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{1}{6} \pi^2$$

(8 points)

7) Consider the system of differential equations below which models two populations x(t) and y(t):

$$\begin{bmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{bmatrix} = \begin{bmatrix} 9x - x^2 - 2xy \\ 12y - y^2 - 2xy \end{bmatrix}$$

7a) If this was a model of two interacting populations, what kind would it be? Explain.

(2 points)

7b) Find all four equilbrium solutions to this system of differential equations. (Hint: One of them is [5, 2].)

(8 points)

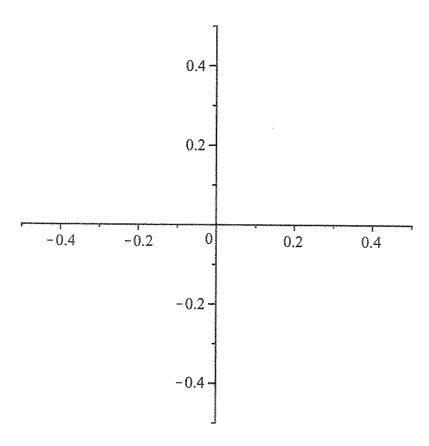
7c) Find the linearization of the population model near the equilibrium solution [5,2]. Use eigenvalues for the linearization to classify the type of singularity in the nonlinear problem. For your convenience, the system is repeated below:

(10 points)

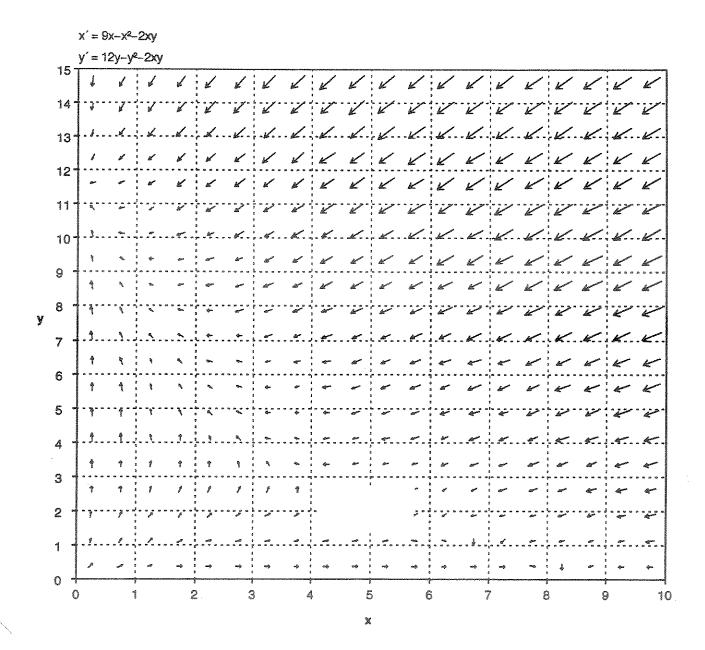
$$\begin{bmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{bmatrix} = \begin{bmatrix} 9x - x^2 - 2xy \\ 12y - y^2 - 2xy \end{bmatrix}$$

- 7d) Finding and using the eigenvectors from the linearization above, write the general solution
- $\begin{bmatrix} u(t) \\ v(t) \end{bmatrix}$  of the linearized problem at [5,2].

7e) Sketch the phase portrait for the linearized problem, using your work in (7d). Hint: the eigendirections should appear in your sketch.



7f) Use your work from (7e) to fill the portion of the phase portrait below which has been excised. Then describe what happens to solutions to the initial value problem for this system of DE's, depending on initial populations. You may wish to sketch representative solution curves, and indicate regions of the first quadrant in order to help you answer this part.



## **Table of Laplace Transforms**

This table summarizes the general properties of Laplace transforms and the Laplace transforms of particular functions derived in Chapter 10.

Function	Transform	Function	Transform
f(t)	F(s)	e <sup>at</sup>	$\frac{1}{s-a}$
af(t) + bg(t)	aF(s) + bG(s)	$t^n e^{at}$	$\frac{n!}{(s-a)^{n+1}}$
f'(t)	sF(s) - f(0)	$\cos kt$	$\frac{s}{s^2 + k^2}$
f''(t)	$s^2F(s) - sf(0) - f'(0)$	sin <i>kt</i>	$\frac{k}{s^2 + k^2}$
$f^{(n)}(t)$	$s^n F(s) - s^{n-1} f(0) - \dots - f^{(n-1)}(0)$	cosh kt	$\frac{s}{s^2 - k^2}$
$\int_0^t f(\tau)d\tau$	$\frac{F(s)}{s}$	sinh kt	$\frac{k}{s^2 - k^2}$
$e^{at}f(t)$	F(s-a)	e <sup>at</sup> cos kt	$\frac{s-a}{(s-a)^2+k^2}$
u(t-a)f(t-a)	$e^{-as}F(s)$	e <sup>at</sup> sin kt	$\frac{k}{(s-a)^2+k^2}$
$\int_0^t f(\tau)g(t-\tau)d\tau$	F(s)G(s)	$\frac{1}{2k^3}(\sin kt - kt\cos kt)$	$\frac{1}{(s^2+k^2)^2}$
tf(t)	-F'(s)	$\frac{t}{2k}\sin kt$	$\frac{s}{(s^2+k^2)^2}$
$t^n f(t)$	$(-1)^n F^{(n)}(s)$	$\frac{1}{2k}(\sin kt + kt\cos kt)$	$\frac{s^2}{(s^2+k^2)^2}$
$\frac{f(t)}{t}$	$\int_{s}^{\infty} F(\sigma)  d\sigma$	u(t-a)	$\frac{e^{-as}}{s}$
f(t), period $p$	$\frac{1}{1-e^{-ps}}\int_0^p e^{-st}f(t)dt$	$\delta(t-a)$	$e^{-as}$
l	$\frac{1}{s}$	$(-1)^{[t/a]}$ (square wave)	$\frac{1}{s} \tanh \frac{as}{2}$
t	$\frac{1}{s^2}$	$\begin{bmatrix} \frac{t}{a} \end{bmatrix}$ (staircase)	$\frac{e^{-as}}{s(1-e^{-as})}$
$t^n$	$\frac{n!}{s^{n+1}}$		
$\frac{1}{\sqrt{\pi t}}$	$\frac{1}{\sqrt{s}}$		
$t^a$	$\frac{\Gamma(a+1)}{s^{a+1}}$		