Tues Mar 27

• 5.5 Complex eigenvalues and eigenvectors

Announcements:
$$95.5 \text{ HW}$$
: $1, 7, 11, 13$
• qu'e tonorvow: find eigenvals & eigenvects fn a 2×2 matrix
• Wad, Fn: : a taske (they will be complex)
of applications
• Monday starts Cloptrs 6,7 "or thogonality" & Spectral theorem
big, important unit.
Warm-up Exercise: Find the eigenvalues of
 $A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$ $\lambda = 1 \pm i$
 $\begin{bmatrix} 1-\lambda & -1 \\ 1 & 1-\lambda \end{bmatrix} = (1-\lambda)^2 + 1 = (\lambda - 1)^2 + 1 = 0$
 $(\lambda - 1)^2 = -1$
 $\lambda - 1 = \pm i$
 $\overline{\lambda} = 1 \pm i$

We'll focus on 2×2 matrices, for simplicity. In this case it will turn out that a matrix with real entries and complex eigenvalues is always similar to a rotation-dilation matrix.

Definition A matrix of the form
$$A = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$
 is called a *rotation-dilation* matrix, because for
 $r = \sqrt{a^2 + b^2}$ we can rewrite A as
$$A = r \begin{bmatrix} \frac{a}{r} & -\frac{b}{r} \\ \frac{b}{r} & \frac{a}{r} \end{bmatrix} = r \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}.$$

$$\frac{b}{r} = \frac{b}{\sqrt{a^2 + b^2}}$$

So the transformation $T(\underline{x}) = A \underline{x}$ rotates vectors by an angle θ and then scales them by a factor of r. (So A^2 rotates by an angle 2 θ and scales by r^2 ; A^3 rotates by an angle 3 θ and scales by r^3 , etc.



Exercise 1 Draw the transformation picture for



Exercise 2) What are the eigenvalues of a rotation-dilation matrix $A = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$?

$$\begin{bmatrix} A - \lambda I \end{bmatrix} = \begin{vmatrix} a - \lambda & -b \\ b & a - \lambda \end{vmatrix} = (\lambda - a)^{2} + b^{2} = 0$$
$$(\lambda - a)^{2} = -b^{2}$$
$$\lambda - a = \pm ib$$
$$\lambda = a \pm ib$$

It is possible for a matrix *A* with real entries to be diagonalizable if one allows complex scalars and vectors, even if it's not diagonalizable with real eigenvalues and eigenvectors. You saw an example of that on a food for thought problem, if you weren't afraid. We'll use a matrix today that we'll use later as well, in section 5.6, to study an interesting discrete dynamical system. This matrix is not a rotation-dilation matrix, but it is *similar* to one, and that fact will help us understand the discrete dynamical system.

Exercise 3) Let

$$B = \left[\begin{array}{cc} .9 & -.4 \\ .1 & .9 \end{array} \right]$$

Find the (complex) eigenvalues and eigenvectors for *B*.

$$\begin{vmatrix} .9 - \lambda & -.9 \\ .1 & .9 - \lambda \end{vmatrix} = (\lambda - .9)^{2} + .09 = 0 \quad \text{in general:} \\ \text{expand & size} \\ (\lambda - .9)^{2} = -.09 \quad \text{guad.formule} \\ \lambda - .9 = \pm .2i \\ \lambda - .9 = \pm .2i \\ \lambda = .9 \pm .2i \\ \lambda = .9 \pm .2i \\ \lambda = .9 \pm .2i \\ \text{isompley} \\ \text{Nul} (B - \lambda I) \quad 1 \quad -.2i \quad 0 \\ 10R_{2} - 9R_{1} \quad 1 \quad -.2i \quad 0 \\ 10R_{2} - 9R_{1} \quad 1 \quad -.2i \quad 0 \\ 10R_{1} - 2i \quad 0 \\ 2iR_{1} + R_{2} - 8R_{2} \quad 0 \quad 0 \\ 2iR_{1} + R_{2} - 8R_{2} \quad 0 \quad 0 \\ 1 \quad -.2i \quad 0 \\ 2i(-2i) - 4 = 4 - 4 - 0 \\ \overline{V} = \begin{bmatrix} 2ii \\ 1 \end{bmatrix} \quad E_{\lambda = .9 + .2i} = \sup_{all \text{ isompley}} \left\{ \begin{bmatrix} 2ii \\ 1 \end{bmatrix} \right\} \quad (= \operatorname{Span} \left\{ \begin{bmatrix} -2 \\ i \end{bmatrix} \right\} \\ \text{expand & size} \\ \text{expand &$$

$$E_{\lambda=.9-.2i} \xrightarrow{.2i -.9|0}_{i -.2i 0}$$

$$= \frac{1}{1} \frac{2i 0}{i - 2i 0}$$

$$= \frac{1}{1} \frac{1}{1}$$

$$= \frac{1}{1} \qquad E_{\lambda=.9-.2i} = span \left\{ \begin{bmatrix} -2i \\ 1 \end{bmatrix} \right\}$$

$$= \frac{1}{1} \frac{1}{1} \qquad E_{\lambda=.9-.2i} = span \left\{ \begin{bmatrix} -2i \\ 1 \end{bmatrix} \right\}$$

General facts we saw illustrated in the example, about complex eigenvalues and eigenvectors: Let A be a matrix with real entries, and let A_{hrm}

 $A \underline{v} = \lambda \underline{v}$

with $\lambda = a + b i$, $\underline{v} = \underline{u} + i \underline{w}$ complex, $(a, b \in \mathbb{R}, \underline{u}, \underline{w} \in \mathbb{R}^n)$. Then we write

Re
$$\lambda = a$$
, Im $\lambda = b$

Re
$$\underline{v} = \underline{u}$$
, Im $\underline{v} = \underline{w}$.

So, the equation $A \underline{v} = \lambda \underline{v}$ expands as

So, the equation
$$A \underline{v} - \lambda \underline{v}$$
 expands as

$$A (\underline{u} + i \underline{w}) = (a + bi)(\underline{u} + i \underline{w}).$$
It will always be true then that the conjugate $\underline{\lambda} = a - bi$ is also an eigenvalue, and the conjugate vector
 $\underline{v} = \underline{u} - i \underline{w}$ will be a corresponding eigenvector, because it will satisfy

$$A (\underline{u} - i \underline{w}) = (a - bi)(\underline{u} - i \underline{w})$$
Exercise 4 Verify that if the first eigenvector equation holds, then

$$A (\underline{u} = a \underline{u} - b \underline{w} + a \underline{w}$$

Then check that these equalities automatically make the second conjugate eigenvector equation true as well.

$$\vec{\nabla} = \vec{n} + i\vec{w}$$

erigenvector
 $\lambda = a + ib$
 $\vec{n} = b\vec{n} + a\vec{w}$

Example 2 <u>Theorem</u> Let A be a real 2×2 matrix with complex eigenvalues. Then A is similar to a rotation-dilation matrix.

proof: Let a complex eigenvalue and eigenvector be given by $\lambda = a + b i, \underline{v} = \underline{u} + i \underline{w}$ complex, ($a, b \in \mathbb{R}, \underline{u}, \underline{w} \in \mathbb{R}^n$) Choose

$$P = [\operatorname{Re} \underline{v} \quad \operatorname{Im} \underline{v}] = [\underline{u} \quad \underline{w}]$$

(One can check that $\{\underline{u}, \underline{w}\}$ is automatically independent.) Then, using the equations of Exercise 4, we mimic what we did for diagonalizable matrices...

•
$$A [\underline{u} \ \underline{w}] = [a \underline{u} - b \underline{w}, b \underline{u} + a \underline{w}]$$

 $= [\underline{u} \ \underline{w}] \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$.
 $A P = P \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$.
 $A P = P \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$.
 $P^{-1} A P = \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$.

(The matrix on the right is a rotation-dilation matrix ... nobody ever said what the sign of b was. :-))

It's a mess, but we can carry out the procedure of the theorem, for the matrix B in exercise 3,

$$B = \begin{bmatrix} .9 & -.4 \\ .1 & .9 \end{bmatrix}$$

$$\text{using } \lambda = .9 - .2 \ i, \ \mathbf{v} = \begin{bmatrix} -2 \ i \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + i \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix}, \text{ one gets}$$

$$P = \begin{bmatrix} \operatorname{Re} \, \mathbf{v} \quad \operatorname{Im} \, \mathbf{v} \end{bmatrix} = \begin{bmatrix} 0 & -2 \\ 1 & 0 \end{bmatrix}, P^{-1} = \frac{1}{2} \begin{bmatrix} 0 & 2 \\ -1 & 0 \end{bmatrix}$$

$$P^{-1}B P = \frac{1}{2} \begin{bmatrix} 0 & 2 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} .9 & -.4 \\ .1 & .9 \end{bmatrix} \begin{bmatrix} 0 & -2 \\ 1 & 0 \end{bmatrix}$$

$$P^{-1}B P = \begin{bmatrix} .9 & -.2 \\ .2 & .9 \end{bmatrix} = \sqrt{.85} \begin{bmatrix} \frac{.9 \\ \sqrt{.85} \\ \frac{.2 }{\sqrt{.85}} \\ \frac{.9 }{\sqrt{.85}} \end{bmatrix}$$

$$P^{-1}B P = r \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}.$$
for $r = \sqrt{.85} \approx .92$, $\theta = \arctan\left(\frac{2}{.9}\right) \approx .22$ radians.