postpone today. Cover Tuesday.

The transpose operation. One reason for considering this particular operation will be more clear by the beginning of next week, but since the text introduces it in section 2.1, we will as well.

<u>Definition</u>: Let $B_{m \times n} = [b_{ij}]$. Then the <u>transpose</u> of B, denoted by B^T is an $n \times m$ matrix defined by

$$entry_{ij}(B^T)$$

$$= entry_{ji}(B) = b_{ji}$$

The effect of this definition is to turn the columns of B into the rows of B^T : $entry_i(col_j(B)) = b_{ij}.$ $entry_i(row_j(B^T) = entry_j(B^T) = b_{ij}.$ $entry_i(row_j(B^T) = entry_j(B^T) = b_{ij}.$ And to turn the rows of B into the columns of B^T : $entry_i(row_i(B)) = b_{ij}.$ $entry_i(row_i(B)) = b_{ij}.$ $entry_i(row_i(B)) = b_{ij}.$ $entry_i(row_i(B)) = b_{ij}.$

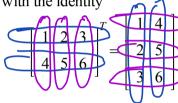
$$entry_{i}(col_{j}(B)) = b_{ij}.$$

$$entry_{i}(row_{j}(B^{T}) = entry_{ji}(B^{T}) = b_{ij}.$$

$$entry_{j}(row_{i}(B)) = b_{ij}$$

$$entry_{j}(col_{i}(B^{T})) = entry_{ij}(B^{T}) = b_{ij}$$

Exercise 1) explore these properties with the identity



$$\begin{bmatrix} 1, 2, 3 \end{bmatrix}^{\mathsf{T}} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

[1,2,3] = [] in some lexts, makes sense

Algebra of transpose:

$$\underline{\mathbf{a}} \quad \left(A^T\right)^T = A \qquad \mathbf{V}$$

$$(A+B)^T = A^T + B^T \qquad \checkmark$$

for every scalar
$$r (rA)^T = rA^T$$



entry:
$$(AB)^T = entry: AB$$

$$= row; (A) \cdot \omega l_i(B)$$

$$= \omega l_i(A^T) \cdot row_i(B^T)$$

$$= row; (B^T) \cdot \omega l_i(A^T)$$

$$= entry: (B^T A^T)$$
if A existe

d (The only surprising property, so we should check it.)
$$(AB)^T = B^TA^T$$

then so does

one consequence: if
$$AA^{-1}=I$$
, $A^{-1}A=I$ $(A^{-1})^{-1}$. X take transpose: $(A^{-1})^TA^T=I$, $A^T(A^{-1})^T=I$ if $=(A^{-1})^T$

$$A^{-1}A = I$$

 $A^{T}(A^{-1})^{T} = I$

Wed Sept 19

• 2.2-2.3 Matrix inverses: the product of elementary matrices approach to matrix inverses

Announcements: Wed woles, after fill in the (AB) = BTAT
quiz...

Warm-up Exercise: Compute

(Can you express the result as a linear combination of the rows in the 3×4 matrix?

Exercise 1) Show that if A, B, C are invertible matrices, then

a)
$$(AB)^{-1} = B^{-1}A^{-1}$$

b) $(ABC)^{-1} = C^{-1}B^{-1}A^{-1}$
(all the skps)
a). $(AB)(B^{-1}A^{-1})$
 $= A(BB^{-1})A^{-1}$
 $= (A I)A^{-1}$
 $= AA^{-1} = I$
b) $(AB(C)(C^{-1}B^{-1}A^{-1}) \stackrel{?}{=} I$
 $= A(B \not = B^{-1})A^{-1}$
 $= A(B \not = B^{-1})A^{-1}$
 $= A(B \not = B^{-1})A^{-1}$
 $= A(B \not = B^{-1})A^{-1}$

<u>Theorem</u> The product of $n \times n$ invertible matrices is invertible, and the inverse of the product is the product of their inverses in reverse order.

Our algorithm for finding the inverse of a matrix can be reformulated in terms of a product of so-called "elementary" matrices. This product idea will pay off elsewhere. To get started, let's notice an analog of the fact that a matrix times a vector is a linear combination of the matrix columns. That was in fact how we defined matrix times vector in week 2.

<u>Definition</u> (from 1.4) If A is an $m \times n$ matrix, with columns $\underline{a}_1, \underline{a}_2, \dots \underline{a}_n$ (in \mathbb{R}^m) and if $\underline{x} \in \mathbb{R}^n$, then $A \underline{x}$ is defined to be the linear combination of the columns, with weights given by the corresponding entries of \underline{x} . In other words,

$$A \underline{\mathbf{x}} = \begin{bmatrix} \underline{\mathbf{a}}_1 & \underline{\mathbf{a}}_2 & \dots & \underline{\mathbf{a}}_n \end{bmatrix} \underline{\mathbf{x}} := x_1 \underline{\mathbf{a}}_1 + x_2 \underline{\mathbf{a}}_2 + \dots x_n \underline{\mathbf{a}}_n.$$

Theorem If we multiply a row vector times an $n \times m$ matrix B we get a linear combination of the rows of B: proof: We want to check whether

$$\underline{\boldsymbol{x}}^T B = \left[\begin{array}{cccc} \boldsymbol{x}_1 & \boldsymbol{x}_2 & \dots & \boldsymbol{x}_n \end{array} \right] \left[\begin{array}{c} \underline{\boldsymbol{b}}_1 \\ \underline{\boldsymbol{b}}_1 \\ \vdots \\ \underline{\boldsymbol{b}}_n \end{array} \right] = \boldsymbol{x}_1 \ \underline{\boldsymbol{b}}_1 \ + \ \boldsymbol{x}_2 \ \underline{\boldsymbol{b}}_2 \ + \ \dots \ \boldsymbol{x}_n \ \underline{\boldsymbol{b}}_n \ .$$

where the rows of B are given by the row vectors $\underline{\boldsymbol{b}}_1, \underline{\boldsymbol{b}}_2, \dots \underline{\boldsymbol{b}}_n$. This proposed identity is true if and only if its transpose is a true identity. But the transpose of the left side is

$$(\underline{\boldsymbol{x}}^T B)^T = B^T (\underline{\boldsymbol{x}}^T)^T = B^T \underline{\boldsymbol{x}}$$

$$= [\underline{\boldsymbol{b}}_1^T \ \underline{\boldsymbol{b}}_2^T \ \dots \underline{\boldsymbol{b}}_n^T] \underline{\boldsymbol{x}}$$

$$x \cdot \underline{\boldsymbol{b}}^T + x \cdot \underline{\boldsymbol{b}}^T + x \cdot \underline{\boldsymbol{b}}^T$$

which is the transpose of the right side of the proposed identity. So the identity is true.

Q.E.D.

Exercise 2a Use the Theorem on the previous page and work row by row on so-called "elementary matrix" E_1 on the right of the product below, to show that E_1 A is the result of replacing $row_3(A)$ with $row_3(A) - 2 row_1(A)$, and leaving the other rows unchanged:

<u>2b</u>) The inverse of E_1 must undo the original elementary row operation, so must replace any $row_3(A)$ with $row_3(A) + 2 row_1(A)$. So it must be true that

$$E_1^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Check!

<u>2c</u>) What 3×3 matrix E_2 can we multiply times A, in order to multiply $row_2(A)$ by 5 and leave the other rows unchanged. What is E_2^{-1} ?

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \qquad E_{2}^{-1} : replace "S"$$
with $\frac{1}{5}$

2d) What 3×3 matrix E_3 can we multiply time A, in order to swap $row_1(A)$ with $row_3(A)$? What is E_3^{-1} ?

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \qquad \begin{bmatrix} E_3^{-1} = E_3 \\ E_3^{-1} = E_3 \end{bmatrix}$$

<u>Definition</u> An *elementary matrix* E is one that is obtained by doing a single elementary row operation on the identity matrix.

<u>Theorem</u> Let $E_{m \times m}$ be an elementary matrix. Let $A_{m \times n}$. Then the product EA is the result of doing the same elementary row operation to A that was used to construct E from the identity matrix.

Algorithm for finding A^{-1} re-interpreted: Suppose a sequence of elementary row operations reduces the $n \times n$ square matrix A to the identity I_n . Let the corresponding elementary matrices, in order, be given by

 $E_1, E_2, \dots E_p.$

Then we have

$$\begin{split} E_p \left(E_{p-1} & \dots & E_2 \left(E_1(A) \right) \dots \right) = I_n \\ \left(E_p & E_{p-1} & \dots & E_2 & E_1 \right) A &= I_n \\ & & \\$$

So,

$$A^{-1} = E_p E_{p-1} \dots E_2 E_1.$$

Notice that

$$E_n E_{n-1} \dots E_2 E_1 = E_n E_{n-1} \dots E_2 E_1 I_n$$

so we have obtained A^{-1} by starting with the identity matrix, and doing the same elementary row operations to it that we did to A, in order to reduce A to the identity. I find this explanation of our original algorithm to be somewhat convoluted, but as I said, the matrix product decomposition idea is going to pay dividends elsewhere.

Also, notice that we have ended up "factoring" A into a product of elementary matrices:

$$A = \left(A^{-1}\right)^{-1} = \left(E_p \, E_{p\,-\,1} \, \, E_2 \, E_1\right)^{-1} = E_1^{-1} \, E_2^{-1} \, \, E_{p\,-\,1}^{-1} \, E_p^{-1} \ .$$