

Math 2270-3
Tuesday Sept. 22

* remind me to explain why $\text{rref}(A)$ is unique - using big Maple example

(1)

§ 3.3 bases and dimension, for subspaces.

We'll be using definitions and ideas from the past several lectures...
What do the following words mean?

Subspace $W \subset \mathbb{R}^n$

linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$

span of $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$

for $T(\vec{x}) = A\vec{x}$; $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ linear

ker T

Image T

$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ linearly dependent

$\{\vec{v}_1, \dots, \vec{v}_k\}$ linearly independent

$\{\vec{v}_1, \dots, \vec{v}_k\}$ a basis for the subspace W .

dimension of W

• Yesterday we showed that if a collection of vectors spans a subspace W , we can successively remove ones which are in the span of those that remain, until we finally call the original set into a basis for W . We did this procedure to the columns of A to obtain a basis for $\text{Image}(T)$ consisting of some of the original columns.

• A complementary procedure, which we used when we found all subspaces of \mathbb{R}^3 , is to start with an independent collection of vectors

$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ in W . If this set does not yet span W , find

$\vec{w} \in W$; $\vec{w} \notin \text{span}\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$.

Then $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k, \vec{w}\}$ is also independent. (In this way you can build up to a basis!)

proof: Let $c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_k\vec{v}_k + d\vec{w} = \vec{0}$

Case I: $d \neq 0$. Then $\vec{w} = -\frac{c_1}{d}\vec{v}_1 - \frac{c_2}{d}\vec{v}_2 - \dots - \frac{c_k}{d}\vec{v}_k$
so this case did not happen!

Case II: $d = 0$. Then $c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_k\vec{v}_k = \vec{0}$

Since $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ lin. ind.,

each $c_1 = c_2 = \dots = c_k = 0$

since also $d = 0$, deduce

$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k, \vec{w}\}$ lin independent ■

(2)

Today we will prove & learn important facts about bases for \mathbb{R}^n and for subspaces. Almost every one of these facts uses rref.

① Every basis of \mathbb{R}^n must have exactly n vectors, because

- more than n vectors must be dependent

e.g. could
 $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \end{bmatrix} \right\}$
 be independent?

- fewer than n vectors cannot span \mathbb{R}^n

e.g. could
 $\left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 27 \\ 36 \\ 2 \end{bmatrix} \right\}$
 span \mathbb{R}^3 ?

② $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a basis for \mathbb{R}^n iff $\text{rref} \left[\vec{v}_1 \mid \vec{v}_2 \mid \dots \mid \vec{v}_n \right] = I$.

③ Now let W be any subspace of \mathbb{R}^n .

- We can find a basis $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ for W by successively adding vectors until we have an independent spanning set, just like we did in our discussion of \mathbb{R}^3 subspaces... the process must stop for $k \leq n$, since $>n$ vectors in \mathbb{R}^n are dependent

Then we deduce

as vectors in W

① If $\{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_\ell\} \subset W$ with $\ell > k$, then this set must be dependent.
 (proving this fact only uses that $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ span W)

Hint: You can write

$$n \times \underbrace{\begin{bmatrix} | & | & \dots & | \\ \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_k \\ | & | & \dots & | \end{bmatrix}}_k \begin{bmatrix} | & | & \dots & | \\ A & & & \\ | & | & \dots & | \end{bmatrix}_{k \times \ell} = \begin{bmatrix} | & | & \dots & | \\ \vec{w}_1 & \vec{w}_2 & \dots & \vec{w}_\ell \\ | & | & \dots & | \end{bmatrix}_{n \times \ell}$$

where the j th col of A expresses \vec{w}_j as a linear combo of $\{\vec{v}_1, \dots, \vec{v}_k\}$.

② If $\{\vec{w}_1, \dots, \vec{w}_\ell\} \subset W$ with $\ell < k$, then this set cannot span W
 (Use part (a), reverse roles & use logic!)

Notice, (a), (b) prove that every basis of W has k vectors, so the concept of dimension for a subspace is well-defined (doesn't depend on which basis you use.)

(c) If $\dim(W) = k$ (as it does here), then
 if $\{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_k\}$ span W , they are automatically independent
 \Rightarrow basis!

proof: If dependent, remove vectors to get a basis with $< k$ vectors.
 impossible!

(d) If $\dim(W) = k$ and if $\{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_k\} \subset W$ are linearly ind., then they
 automatically span W , \Rightarrow basis!

proof: If $\{\vec{w}_1, \dots, \vec{w}_k\}$ doesn't span, successively add
 vectors to get a basis with $> k$ vectors.
 impossible!

examples : • Are $\left\{ \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -3 \\ 2 \end{bmatrix} \right\}$ a basis for the plane $x + 2y - 3z = 0$?

• Find a basis for \mathbb{R}^3 including $\left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} \right\}$

④ (rank + nullity Theorem)

$$\text{If } f(\vec{x}) = A\vec{x}$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\underbrace{\dim(\ker f)}_{\text{"nullity"}} + \underbrace{\dim(\text{image}(f))}_{\text{"rank"}} = \dim(\text{domain}) = n$$

↕
 before, we said $\text{rank}(A) = \#$ of non-zero rows in $\text{rref}(A)$.
 why is this the same as $\dim(\text{image}(f))$?

Examples • the Maple example from yesterday $T(\vec{x}) = \begin{bmatrix} A_{3 \times 6} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} \end{bmatrix}$

• $T: \mathbb{R}^6 \rightarrow \mathbb{R}^3$ $T(\vec{x}) = A_{\text{non}}$; A^{-1} exists:

• $T: \mathbb{R}^6 \rightarrow \mathbb{R}^3$ $T(\vec{x}) = \vec{0} \quad \forall \vec{x}$.