

Math 2270-3

Tuesday Dec. 8

§ 8.1 - 8.2 cont'd. (Tomorrow § 8.3; Friday course review)

- do Example 3 on Monday notes, which is the implicit equation of a quartic surface

Example 4 Identify and graph the solution set to

$$5x^2 + 5y^2 + 6z^2 - 2xy - 4xz - 4yz = 8$$

$$(*) \quad [x, y, z] \begin{bmatrix} 5 & -1 & -2 \\ -1 & 5 & -2 \\ -2 & -2 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 8$$

$$\uparrow \\ G = C + 4I$$

$$\uparrow \text{ matrix from example 3: } \begin{bmatrix} 1 & -1 & -2 \\ -1 & 1 & -2 \\ -2 & -2 & 2 \end{bmatrix}$$

so same eigenvects, old evals + 4!

$$\lambda = 2 \quad \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad \lambda = 6 \quad \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \quad \lambda = 8 \quad \begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix}$$

$$\text{same } S: \begin{bmatrix} \sqrt{3} & -\sqrt{2} & -\sqrt{6} \\ \sqrt{3} & \sqrt{2} & -\sqrt{6} \\ \sqrt{3} & 0 & 2\sqrt{6} \end{bmatrix}; \quad \begin{bmatrix} x \\ y \\ z \end{bmatrix} = S \begin{bmatrix} x' \\ y' \\ z' \end{bmatrix}$$

$$(***) \quad [x' \ y' \ z'] \begin{bmatrix} 2 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 8 \end{bmatrix} \begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} = 8$$

finish up! graph!

Spectral Theorem Let $A_{n \times n}$ be a real, symmetric matrix.

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Then \exists an orthonormal \mathbb{R}^n basis made of

eigenvectors of A , $B = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n\}$ $A\vec{u}_j = \lambda_j \vec{u}_j$

Thus for $S = [\vec{u}_1 | \vec{u}_2 | \dots | \vec{u}_n]$,

$$S^T A S = \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots & 0 \\ 0 & & & \lambda_n \end{bmatrix} \text{ is diagonal.}$$

proof

① On Monday we showed that if $\lambda_1 \neq \lambda_2$ are real eigenvalues of A , with eigenvectors $\vec{v}_1, \vec{v}_2 \neq \vec{0}$

$$A\vec{v}_1 = \lambda_1 \vec{v}_1$$

$$A\vec{v}_2 = \lambda_2 \vec{v}_2$$

Then $\vec{v}_1 \perp \vec{v}_2$

$$\begin{aligned} \text{proof } v_2^T A \vec{v}_1 &= v_2^T (\lambda_1 \vec{v}_1) = \lambda_1 \vec{v}_2^T \vec{v}_1 \\ (v_2^T A^T) \vec{v}_1 &= (A \vec{v}_2)^T \vec{v}_1 \\ &= \lambda_2 \vec{v}_2^T \vec{v}_1 \\ &= \lambda_2 \vec{v}_2^T \vec{v}_1 \xrightarrow{\text{so}} \vec{v}_2^T \vec{v}_1 = 0 \end{aligned}$$

We also showed that for $A_{2 \times 2}$ symmetric,

either A is already diagonal

(a multiple of I , in fact), or A has 2 distinct

real eigenvalues $\Rightarrow A$ diagonalizable. By ① the

eigenvectors are \perp , so normalize to get orthonormal eigenbasis.

② All eigenvalues of A are real:

(let $\lambda = a+bi$ be any root of $f_A(\lambda)$, and let $\vec{u}+i\vec{v}$ be a corresponding non-zero eigenvector.

$$A(\vec{u}+i\vec{v}) = (a+ib)(\vec{u}+i\vec{v})$$

$$A(\vec{u}-i\vec{v}) = (a-ib)(\vec{u}-i\vec{v}).$$

take conjugates: $\underbrace{A(\vec{u}-i\vec{v})}_{\text{Now consider}} = (\vec{u}-i\vec{v})^T (a-ib)(\vec{u}+i\vec{v}) = (a-ib)[(\vec{u}-i\vec{v})^T(\vec{u}+i\vec{v})]$

$$\begin{aligned} (\vec{u}-i\vec{v})^T A(\vec{u}+i\vec{v}) &= (\vec{u}-i\vec{v})^T (a+ib)(\vec{u}+i\vec{v}) = (a+ib)[(\vec{u}-i\vec{v})^T(\vec{u}+i\vec{v})] \\ &= (a+ib)[(\vec{u}-i\vec{v}) \cdot (\vec{u}+i\vec{v})] \\ &= (a+ib)(\|\vec{u}\|^2 + \|\vec{v}\|^2) \end{aligned}$$

$$\underbrace{((\vec{u}-i\vec{v})^T A^T)(\vec{u}+i\vec{v})}_{\text{[A}(\vec{u}-i\vec{v})]^T(\vec{u}+i\vec{v})}$$

$$\begin{aligned} [A(\vec{u}-i\vec{v})]^T(\vec{u}+i\vec{v}) &= (a-ib)(\vec{u}-i\vec{v})^T(\vec{u}+i\vec{v}) \\ &= (a-ib)(\|\vec{u}\|^2 + \|\vec{v}\|^2) \end{aligned}$$

↑

$b=0!$

thus $f_A(\lambda)$ factors completely over \mathbb{R} .

■

- If it has n distinct roots, then $\text{alg mult} = \text{geom mult} = 1$, all eigenvectors \perp different evals are \perp by ①, and normalize to get orthonormal eigenbasis
- Otherwise it's a little harder: (In practice, if λ_i has $\text{alg mult} > 1$ just Gram-Schmidt its eigenbasis)

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③ General proof, by induction:

Spectral Theorem true for $n=1$ (1×1 matrices are diagonal)
 $n=2$ (we checked yesterday).

Inductive step:

- Assume all $(n-1) \times (n-1)$ symmetric matrices are diagonalizable with an orthogonal matrix (with eigenbasis columns).

- Now let $A_{n \times n}$ symmetric

Let λ_1 be any root of $f_A(\lambda)$. λ_1 is real by ②.

Let \vec{u}_1 be a unit eigenvector

$$A\vec{u}_1 = \lambda_1 \vec{u}_1, \quad \|\vec{u}_1\| = 1.$$

Complete to an orthonormal basis $\vec{v}_2, \vec{v}_3, \dots, \vec{v}_n$ probably not eigenvectors!

$$B_o = \{\vec{u}_1, \vec{v}_2, \vec{v}_3, \dots, \vec{v}_n\} \text{ of } \mathbb{R}^n$$

$$S_o = \begin{bmatrix} \vec{u}_1 & \vec{v}_2 & \dots & \vec{v}_n \end{bmatrix} \quad S_o^T S_o = I$$

$S_o^T A S_o$ is symmetric (take its transpose!)

$$\text{1st column is } \begin{bmatrix} \lambda_1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$\text{so } S_o^T A S_o = \begin{bmatrix} \lambda_1 & & \\ 0 & & \\ 0 & & B \end{bmatrix}$$

$B_{(n-1) \times (n-1)}$ is symmetric, so by induction hypothesis $\exists S_1$ orthog,
 with $S_1^T B S_1 = \begin{bmatrix} \lambda_2 & 0 \\ 0 & 2_n \end{bmatrix}$ (λ_i 's need not be distinct!)

$$\text{Thus } \underbrace{\begin{bmatrix} 1 & & \\ 0 & S_1^T & \\ 0 & & 1 \end{bmatrix}}_{S_o^T} \underbrace{\begin{bmatrix} \lambda_1 & & \\ 0 & & \\ 0 & & B \end{bmatrix}}_{A} \underbrace{\begin{bmatrix} 1 & & \\ 0 & S_1 & \\ 0 & & 1 \end{bmatrix}}_{S_o} = \begin{bmatrix} \lambda_1 & 0 & \\ 0 & \lambda_2 & \\ 0 & 0 & 2_n \end{bmatrix}$$

$$\text{so } S^T A S = D$$

$$S = S_o \begin{bmatrix} 1 & & \\ 0 & S_1 & \\ 0 & & 1 \end{bmatrix} \text{ orthog (product of orthog)}$$



2nd derivative test for multivariable functions

Recall Taylor (McLaurin) for sufficiently differentiable function $g(t)$ of scalar variable t :

$$\bullet \quad g(t) = g(0) + g'(0)t + \frac{1}{2!}g''(0)t^2 + \text{error}$$

Now let $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $f(\vec{x})$

We wish to approximate

$f(\vec{x}_0 + \vec{h})$ for \vec{h} near zero.

$$\text{write } \vec{h} = t\vec{u} \quad (t = \|\vec{h}\|, \vec{u} = \frac{\vec{h}}{\|\vec{h}\|}).$$

define

$$g(t) := f(\vec{x}_0 + t\vec{u})$$

to plug into Taylor •, need $g'(t), g''(t)$ @ $t=0$.

Chain rule!

$$g'(t) = \frac{d}{dt} f(\vec{x}_0 + t\vec{u}) = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(\vec{x}_0 + t\vec{u}) \underbrace{\frac{d}{dt}(\vec{x}_{0,i} + tu_i)}_{u_i}$$

$$= \sum_{i=1}^n u_i \frac{\partial f}{\partial x_i}(\vec{x}_0 + t\vec{u})$$

$$\text{so } g'(0) = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(\vec{x}_0) u_i = \nabla f(\vec{x}_0) \cdot \vec{u}. \quad \boxed{t g'(0) = \nabla f(\vec{x}_0) \cdot \vec{h}}$$

$$g''(t) = \frac{d}{dt} \sum_{i=1}^n u_i \frac{\partial f}{\partial x_i}(\vec{x}_0 + t\vec{u})$$

$$= \sum_{i=1}^n u_i \underbrace{\frac{d}{dt} \left(\frac{\partial f}{\partial x_i}(\vec{x}_0 + t\vec{u}) \right)}_{\text{chain rule again}} \sum_{j=1}^n \frac{\partial^2 f}{\partial x_j \partial x_i}(\vec{x}_0 + t\vec{u}) u_j$$

$$\text{so } g''(0) = \sum_{i,j=1}^n u_i u_j \frac{\partial^2 f}{\partial x_i \partial x_j}(\vec{x}_0)$$

$$\frac{t^2}{2} g''(0) = \sum_{i,j=1}^n \frac{\partial^2 f}{\partial x_i \partial x_j}(\vec{x}_0) h_i h_j$$

$$= \frac{1}{2} \vec{h}^T [D^2 f(\vec{x}_0)] \vec{h}$$

↑
the "Hessian"
matrix

entry $_{ij} D^2 f(\vec{x}_0)$

$$= \frac{\partial^2 f}{\partial x_i \partial x_j}(\vec{x}_0)$$

Hessian is symmetric!!

$$\bullet \quad f(\vec{x}_0 + \vec{h}) = f(\vec{x}_0) + \nabla f(\vec{x}_0) \cdot \vec{h} \\ + \frac{1}{2} \vec{h}^T [D^2 f(\vec{x}_0)] \vec{h} \\ + \text{error}$$

\vec{x}_0 is a critical point if $\nabla f(\vec{x}_0) = \vec{0}$
(necessary for local extremum).
if f is differentiable.

If $\nabla f(\vec{x}_0) = \vec{0}$, then the Hessian term

$$\frac{1}{2} \vec{h}^T [D^2 f(\vec{x}_0)] \vec{h}$$

may determine whether \vec{x}_0 is a
local extremum (over)

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Definition: An $n \times n$ symmetric matrix is positive definite iff $\vec{h}^T A \vec{h} > 0 \quad \forall \vec{h} \neq \vec{0}$
negative definite iff $\vec{h}^T A \vec{h} < 0 \quad \forall \vec{h} \neq \vec{0}$.
\ write $[A] > 0$.

Remark Let the columns of S be an orthonormal eigebasis for A

Let $\vec{h} = S \vec{h}'$ be a change of variables

Then $\vec{h}^T A \vec{h}$

$$\begin{aligned} &= \vec{h}'^T S^T A S \vec{h}' \\ &= (\vec{h}')^T \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \lambda_n \end{bmatrix} \vec{h}' = \sum_{i=1}^n \lambda_i (h'_i)^2 \end{aligned}$$

Thus A is pos.def iff all evals > 0
 A is neg def iff all evals < 0

2nd derivative test Let \vec{x}_0 be a critical pt of f , $\nabla f(\vec{x}_0) = \vec{0}$. (Let f be twice continuously diffble at \vec{x}_0 .)

Then

- a) $[D^2 f(\vec{x}_0)] > 0$ (pos def) $\Rightarrow f(\vec{x}_0)$ local min value
- b) $[D^2 f(\vec{x}_0)] < 0$ (neg def) $\Rightarrow f(\vec{x}_0)$ local max value
- c) if $[D^2 f(\vec{x}_0)]$ has both positive & negative eigenvalues then $f(\vec{x}_0)$ is neither a local max or min.
- d) $[D^2 f(\vec{x}_0)] \geq 0$ or ≤ 0 borderline

Examples (these are the ones we've been doing in the past couple lectures!)

① $f(x, y) = 2x^2 + 2y^2 + 5xy \quad @ (0,0)$

$$D^2 f(x, y) =$$

$$D^2 f(0,0) =$$

$$\begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix}$$

$$= \begin{bmatrix} 4 & 5 \\ 5 & 4 \end{bmatrix}$$

is twice the matrix
in Example 1 (no accident)!
 $\lambda_1 = 9, \lambda_2 = -1$
case (c)!

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$$\textcircled{2} \quad g(x, y) = 8x^2 - 16xy + 8y^2 \quad @ (0, 0)$$

Should get "borderline"

but you can be clever and deduce $g(0, 0) = 0$ is a non-strict local min

$$\textcircled{3} \quad h(x, y, z) = x^2 + y^2 + 2z^2 - 2xy - 4xz - 4yz \quad @ (0, 0, 0)$$

$$\textcircled{4} \quad k(x, y, z) = 5x^2 + 5y^2 + 6z^2 - 2xy - 4xz - 4yz \quad @ (0, 0, 0)$$