

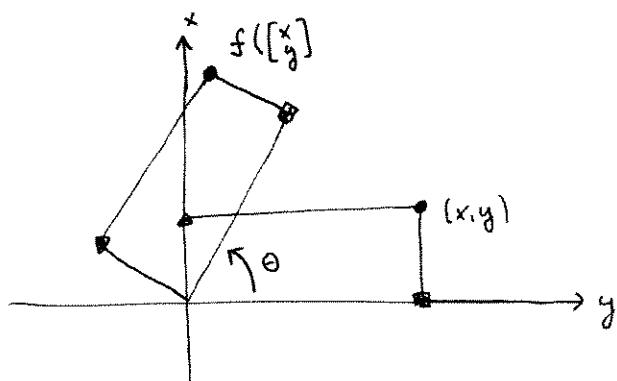
Transform Bob by affine transformations! - page 3 Fri:

$$a\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} e \\ f \end{bmatrix} = \begin{bmatrix} ax + cy + e \\ bx + dy + f \end{bmatrix} = x \begin{bmatrix} a \\ b \end{bmatrix} + y \begin{bmatrix} c \\ d \end{bmatrix} + \begin{bmatrix} e \\ f \end{bmatrix}$$

Special matrix transformations:

- rotate by θ radians counterclockwise:

(Let's work out the formula, using trig:



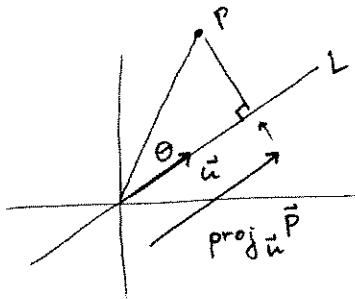
ans:

$$f\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

use this, plus a translation, to write down the formula for the rotated & translated Bob on page 3 Fri

Reflect through (across) any line L passing through the origin:

1st, recall projections from 2210 or 1260:



\vec{u} is a unit vector in dir. of L (i.e. $\|\vec{u}\|=1$)

$$\text{proj}_{\vec{u}} \vec{P} := \|\vec{P}\| \cos \theta \vec{u}$$

$$= (\vec{u} \cdot \vec{P}) \vec{u}$$

$$\begin{aligned} \text{since } \vec{u} \cdot \vec{P} &= \|\vec{u}\| \|\vec{P}\| \cos \theta \\ &= \|\vec{P}\| \cos \theta \end{aligned}$$

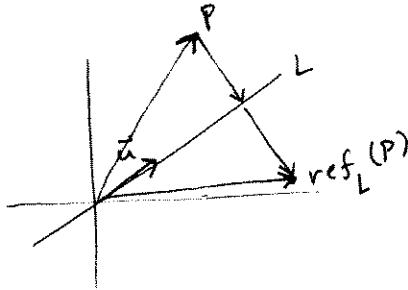
example If L is the line $y=x$

$$\vec{u} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\text{proj}_L \begin{bmatrix} x \\ y \end{bmatrix} = \left(\begin{bmatrix} x \\ y \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \right) \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{1}{2}(x+y) \\ \frac{1}{2}(x+y) \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

general formula, for $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$?

reflection thru L:



$$\text{ref}_L(\vec{P}) := \vec{P} + 2 \left[\text{proj}_L \vec{P} - \vec{P} \right]$$

$$= -\vec{P} + 2 \text{proj}_L \vec{P}$$

$$= -\vec{P} + 2(\vec{u} \cdot \vec{P}) \vec{u}$$

$$\text{ref}_L \begin{bmatrix} x \\ y \end{bmatrix} = - \begin{bmatrix} x \\ y \end{bmatrix} + 2(u_1 x + u_2 y) \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$= \begin{bmatrix} -1+2u_1^2 & 2u_1u_2 \\ 2u_1u_2 & -1+2u_2^2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= \begin{bmatrix} u_1^2 - u_2^2 & 2u_1u_2 \\ 2u_1u_2 & u_2^2 - u_1^2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

example : Check that this formula works for reflection thru the line $y=x$

$$(\text{ans: } f \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} y \\ x \end{bmatrix})$$

since $u_1^2 + u_2^2 = 1$

Compositions of matrix transformations

$$f(\vec{x}) = A_{m \times n} \vec{x} = x_1 \text{col}_1(A) + x_2 \text{col}_2(A) + \dots + x_n \text{col}_n(A) = \begin{bmatrix} \text{row}_1(A) \cdot \vec{x} \\ \text{row}_2(A) \cdot \vec{x} \\ \vdots \\ \text{row}_m(A) \cdot \vec{x} \end{bmatrix}$$

$$A(\vec{x} + \vec{y}) = A\vec{x} + A\vec{y}$$

$$A(k\vec{x}) = kA\vec{x}$$

checked Friday!

Suppose

$$g(\vec{y}) = B_{p \times m} \vec{y}$$

Then $g(f(\vec{x}))$ makes sense!

What is it?

$$\mathbb{R}^n \xrightarrow{f} \mathbb{R}^m \xrightarrow{g} \mathbb{R}^p$$

$$g(f(\vec{x})) = g(A\vec{x})$$

$$= B(x_1 \text{col}_1(A) + x_2 \text{col}_2(A) + \dots + x_n \text{col}_n(A))$$

$$= x_1 B \text{col}_1(A) + x_2 B \text{col}_2(A) + \dots + x_n B \text{col}_n(A)$$

$$= C\vec{x}$$

$$\text{where } C = \begin{bmatrix} B \text{col}_1(A) & | & B \text{col}_2(A) & | & \dots & | & B \text{col}_n(A) \end{bmatrix}$$

$$:= BA.$$

this is how we multiply matrices!

Example : Use the fact that if

you compose rotation by α with rotation by β ,
you get rotation by $\alpha + \beta$, to deduce the angle addition formulas for cos & sin!