

Math 2270-1

Tuesday 18 Oct.

- Height-weight data by tomorrow!

- Discuss the  $A = QR$  decomposition of a matrix that we get by Gram-Schmidtting the columns of  $A$ .  
(pages 3-4 Monday).

↳ 3.3 : The "Q" matrices from a different point of view:

Def: A linear transformation  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  is called orthogonal

(we will see that ortho-normal would be a better name, but oh well...)

iff it preserves lengths of line segments, i.e. iff

$$\|T(\vec{x})\| = \|\vec{x}\| \quad \forall \vec{x} \in \mathbb{R}^n$$

sometimes these  
transformations are  
called linear  
isometries, a  
better name.

Can we characterize orthogonal transformations  $T(\vec{x}) = A\vec{x}$  in terms of the matrix  $A$ ?

Lemma If  $T(\vec{x}) = A\vec{x}$  is orthogonal, then  $T$  also preserves the dot product, i.e.  $T\vec{x} \cdot T\vec{y} = \vec{x} \cdot \vec{y} \quad \forall \vec{x}, \vec{y}$ , and hence also the angle, i.e.  $\angle \vec{x}, \vec{y} = \angle T\vec{x}, T\vec{y} \quad \forall \vec{x}, \vec{y}$ .

[you actually expect this since if triangles get mapped to congruent triangles ("SSS"), then also angles between sides will be preserved]

proof if  $\|T\vec{x}\|^2 = \|\vec{x}\|^2 \quad \forall \vec{x} \in \mathbb{R}^n$

$$\text{then } \|T(\vec{u} + \vec{v})\|^2 = \|\vec{u} + \vec{v}\|^2 \quad \forall \vec{u}, \vec{v} \in \mathbb{R}^n$$

$$(T\vec{u} + T\vec{v}) \cdot (T\vec{u} + T\vec{v}) = (\vec{u} + \vec{v}) \cdot (\vec{u} + \vec{v})$$

~~$$\|T\vec{u}\|^2 + \|T\vec{v}\|^2 + 2 T\vec{u} \cdot T\vec{v} = \|\vec{u}\|^2 + \|\vec{v}\|^2 + 2 \vec{u} \cdot \vec{v}$$~~

$$T\vec{u} \cdot T\vec{v} = \vec{u} \cdot \vec{v} \quad \forall \vec{u}, \vec{v}$$

$$\therefore \frac{T\vec{u} \cdot T\vec{v}}{\|T\vec{u}\| \|T\vec{v}\|} = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} \quad \blacksquare$$

So what orthogonal transformations are there?

(2)

Let  $T(\vec{x}) = A\vec{x}$  be orthogonal.

$$A = \begin{bmatrix} T(\vec{e}_1) & T(\vec{e}_2) & \cdots & T(\vec{e}_n) \end{bmatrix}$$

so the columns of  $A$  must be unit length (because the  $\vec{e}_i$  are & length is preserved)  
& mutually orthogonal (because  $\vec{e}_i \cdot \vec{e}_j = 0 \forall i \neq j$ )

→ the columns of  $A$  must be an orthonormal basis of  $\mathbb{R}^n$ !

e.g.  $A = \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}$

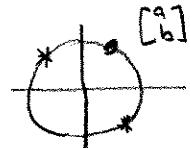
rotation

$$\begin{bmatrix} \cos \alpha & \sin \alpha \\ \sin \alpha & -\cos \alpha \end{bmatrix}$$

reflection (thru line with  $\vec{u} = \begin{bmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{bmatrix}$ )

only ones from  $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ :

$$\begin{bmatrix} a & c \\ b & d \end{bmatrix} \quad \begin{array}{l} a^2 + b^2 = 1 \\ c^2 + d^2 = 1 \\ ac + bd = 0 \end{array}$$



We just showed  $T(\vec{x}) = A\vec{x}$  orthog trans  $\Rightarrow$  cols of  $A$  are orthonormal  
(basis of  $\mathbb{R}^n$ )

Converse is true too:

Let  $A = \begin{bmatrix} \vec{w}_1 & \vec{w}_2 & \cdots & \vec{w}_n \end{bmatrix}$   $\{ \vec{w}_1, \vec{w}_2, \dots, \vec{w}_n \}$  orthonormal.

$$\begin{aligned} A\vec{x} \cdot A\vec{y} &= (x_1\vec{w}_1 + x_2\vec{w}_2 + \dots + x_n\vec{w}_n) \cdot (y_1\vec{w}_1 + y_2\vec{w}_2 + \dots + y_n\vec{w}_n) \\ &= \left( \sum_{i=1}^n x_i \vec{w}_i \right) \cdot \left( \sum_{j=1}^n y_j \vec{w}_j \right) \\ &= \sum_{i=1}^n \sum_{j=1}^n x_i y_j (\vec{w}_i \cdot \vec{w}_j) \\ &= \sum_{i=1}^n x_i y_i \quad \begin{array}{l} \text{if } j \neq i \\ = 0 \end{array} \\ &= \vec{x} \cdot \vec{y} \end{aligned}$$

so  $T(\vec{x}) = A\vec{x}$  preserves dot prod, hence also lengths,

so  $T$  is orthogonal!

Theorem  $T(\vec{x}) = A\vec{x}$  is an orthogonal transformation

if and only if the columns of  $A$  are orthonormal

We call such an  $A$  an orthogonal matrix

(3)

Example  $A = \frac{1}{2} \begin{pmatrix} 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \\ 1 & -1 & 1 & 1 \\ 1 & -1 & -1 & 1 \end{pmatrix}$  is an orthogonal matrix.

Now I will make a matrix B in which I transpose the columns of A into the rows of B:

$$B = \frac{1}{2} \begin{pmatrix} 1 & 1 & 1 & 1 \\ -1 & -1 & 1 & 1 \\ -1 & 1 & -1 & 1 \\ -1 & 1 & 1 & -1 \end{pmatrix}$$

Compute

$$BA = \frac{1}{2} \begin{pmatrix} 1 & 1 & 1 & 1 \\ -1 & -1 & 1 & 1 \\ -1 & 1 & -1 & 1 \\ -1 & 1 & 1 & -1 \end{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & -1 & -1 & -1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \end{pmatrix} = \begin{pmatrix} \end{pmatrix}$$

What do you get?

Why ???

(4)

Def Let  $A_{m \times n}$  be a matrix. The transpose matrix  $A^T$  is the  $n \times m$  matrix defined by

$$\text{entry}_{ij}(A^T) := \text{entry}_{ji}(A)$$

You may obtain the transpose by

- (a) transposing the columns of  $A$  into the rows of  $A^T$
- (b) "rows of  $A$ " "columns of  $A^T$ "
- (c) "reflecting across the diagonal"; to get  $A^T$  from  $A$

e.g.  $\text{col}_j(A) = \begin{bmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{mj} \end{bmatrix}$  (1)  $\text{row}_j(A^T) = [a_{j1}^T, a_{j2}^T, \dots, a_{jm}^T] = [a_{1j}, a_{2j}, \dots, a_{mj}]$

example  $A = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$   $A^T = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$

Theorem  $A$  is orthogonal iff  $A^T = A^{-1}$

proof:

Corollary: The rows of an orthogonal matrix are also orthonormal!

proof:  $A^T A^T = I$ !

e.g.  $\begin{bmatrix} \frac{1}{\sqrt{14}} & 0 & \frac{1}{\sqrt{182}} \\ \frac{2}{\sqrt{14}} & -\frac{3}{\sqrt{13}} & -\frac{2}{\sqrt{182}} \\ \frac{3}{\sqrt{14}} & \frac{2}{\sqrt{13}} & -\frac{3}{\sqrt{182}} \end{bmatrix} !$