

Math 2270-1
Wed Oct 12

EXTRA!

Maple Lab meeting
will be Wed 10/19, not Mon 10/17,
next week.

Partial fractions justified via linear algebra!

We shall do the simplest case; other cases may be
treated analogously, but are technically harder.

Recall, if $q(x) = (x-r_1)(x-r_2)\dots(x-r_n)$ with all roots r_1, r_2, \dots, r_n distinct
($r_i = r_j$ only if $i=j$)

and if $\text{degree}(p(x)) \leq n-1$

Then we taught you in Calc that there are
unique constants A_1, A_2, \dots, A_n so that

$$\frac{p(x)}{(x-r_1)(x-r_2)\dots(x-r_n)} = \frac{A_1}{x-r_1} + \frac{A_2}{x-r_2} + \dots + \frac{A_n}{x-r_n}$$

WHY?

BECAUSE!

If you recombine the right side over the common denominator $q(x)$,
and equate numerators you are seeing if you can find
 A_1, A_2, \dots, A_n so that

$$p(x) = A_1 \underbrace{(x-r_2)(x-r_3)\dots(x-r_n)}_{q_1(x)} + A_2 \underbrace{(x-r_1)(x-r_3)\dots(x-r_n)}_{q_2(x)} + \dots + A_n \underbrace{(x-r_1)(x-r_2)\dots(x-r_{n-1})}_{q_{n-1}(x)}$$

$(= \frac{p}{x-r_1})$ for $x \neq r_1$ $(= \frac{p}{x-r_2})$ for $x \neq r_2$ $(= \frac{p}{x-r_n})$ for $x \neq r_n$

look in \mathbb{P}_{n-1} (polys of degree $\leq n-1$)

the question is, are $\{q_1, q_2, \dots, q_n\}$ a basis for \mathbb{P}_{n-1} ? (which is n -dim'l).

We only need to check if they are linearly independent (\Rightarrow span since $\#$ is correct)

But if

$$0 = A_1 q_1 + A_2 q_2 + \dots + A_n q_n$$

at $x=r_j \Rightarrow 0 = A_1 q_1(r_j) + A_2 q_2(r_j) + \dots + A_n q_n(r_j) = A_j q_j(r_j)$ (all others = 0)

$$\Rightarrow A_j = 0, \quad j=1, 2, \dots, n$$



Math 227D-1
Wed Oct 12

• Try some chapter 3 T-F!

11

Chapter 5: Orthogonality in \mathbb{R}^n and beyond!

recall

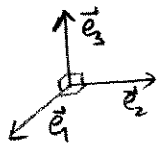
- $\vec{v}, \vec{w} \in \mathbb{R}^n$, we say \vec{v} and \vec{w} are perpendicular, ($\vec{v} \perp \vec{w}$), or orthogonal iff $\vec{v} \cdot \vec{w} = 0$
- $\|\vec{v}\| := \sqrt{\vec{v} \cdot \vec{v}}$
- $\vec{u} \in \mathbb{R}^n$ is a unit vector iff $\|\vec{u}\| = 1$
- if $\vec{v} \in \mathbb{R}^n$, $\vec{v} \neq \vec{0}$, the unit vector in the direction of \vec{v} is $\vec{u} = \frac{1}{\|\vec{v}\|} \vec{v}$.

Bases for subspaces which consist of mutually orthogonal unit vectors, are really easy to work with, so have a special name:

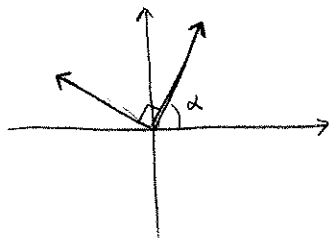
The set $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ (in \mathbb{R}^n) is called orthonormal iff $\vec{v}_i \cdot \vec{v}_j = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$.
i.e. each \vec{v}_i is unit length and $\vec{v}_i \perp \vec{v}_j$ for $i \neq j$.

examples we know

- ① standard basis $\{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\}$ for \mathbb{R}^n



- ② rotated basis $\left\{ \begin{bmatrix} \cos \alpha \\ \sin \alpha \end{bmatrix}, \begin{bmatrix} -\sin \alpha \\ \cos \alpha \end{bmatrix} \right\}$ for \mathbb{R}^2



Why orthonormal sets are good: (part 1)

(2)

Thm Let $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ be orthonormal. Then

(1) the set is linearly independent

(2) If $V = \text{span}\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$, and $\mathcal{B} = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$

then $[v]_{\mathcal{B}} = \begin{bmatrix} \vec{v} \cdot \vec{v}_1 \\ \vec{v} \cdot \vec{v}_2 \\ \vdots \\ \vec{v} \cdot \vec{v}_k \end{bmatrix}$;

in other words the linear combination coefficients

for $\vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_k \vec{v}_k$

can be computed with the dot product: $c_j = \vec{v} \cdot \vec{v}_j$

proof:

(1) Let $c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_k \vec{v}_k = \vec{0}$.

take dot product with any \vec{v}_j :

$$\underbrace{\vec{v}_j \cdot (c_1 \vec{v}_1 + \dots + c_k \vec{v}_k)}_{0+0+\dots+c_j+0+0} = \vec{v}_j \cdot \vec{0} = 0$$

$$0+0+\dots+c_j+0+0 = 0$$

$$c_j = 0 \quad ; \quad j = 1, 2, \dots, k.$$

(2) Let $c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_k \vec{v}_k = \vec{v}$

take dot prod with \vec{v}_j : this time get $c_j = \vec{v} \cdot \vec{v}_j$!

example: Consider the plane $V \subset \mathbb{R}^3$, $V = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : 2x_1 - 5x_2 + x_3 = 0 \right\}$

$\mathcal{B} = \left\{ \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \right\}$ is an orthonormal basis for V

find $\begin{bmatrix} 5 \\ 2 \\ 0 \end{bmatrix}_{\mathcal{B}}$: $\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 5/\sqrt{5} \\ 12/\sqrt{6} \end{bmatrix}$! (how)

$$\text{so } \begin{bmatrix} 5 \\ 2 \\ 0 \end{bmatrix} = \frac{5}{\sqrt{5}} \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix} + \frac{12}{\sqrt{6}} \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix} + 2 \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \quad \checkmark$$

example: $\vec{x} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ $B = \left\{ \frac{1}{3} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}, \frac{1}{3} \begin{bmatrix} 1 \\ -2 \\ 2 \end{bmatrix}, \frac{1}{3} \begin{bmatrix} -2 \\ 1 \\ 2 \end{bmatrix} \right\}$
 find $[\vec{x}]_B$:
 \vec{u} \vec{v} \vec{w}

$$\begin{bmatrix} \vec{x} \cdot \vec{u} \\ \vec{x} \cdot \vec{v} \\ \vec{x} \cdot \vec{w} \end{bmatrix} = \begin{bmatrix} \frac{1}{3}(2+4+3) \\ \frac{1}{3}(1-4+6) \\ \frac{1}{3}(-2+2+6) \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix}$$

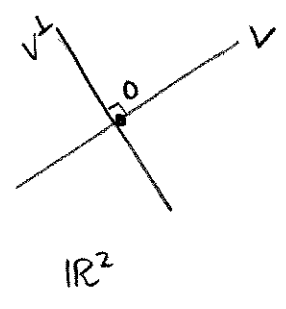
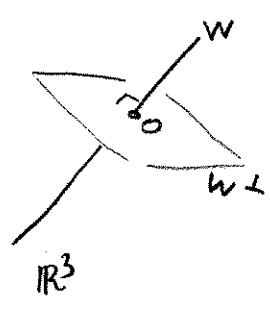
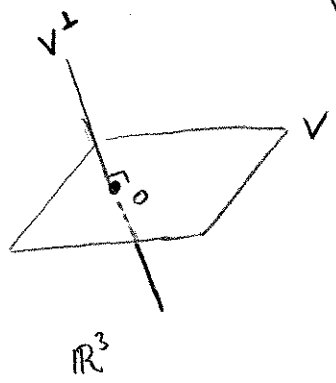
so $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} 1 \\ -2 \\ 2 \end{bmatrix} + \frac{2}{3} \begin{bmatrix} -2 \\ 1 \\ 2 \end{bmatrix}$ ✓

Why orthonormal sets are good: (part 2) They are good for projection problems

First, the notion of orthogonal complement:

Def Let $V \subset \mathbb{R}^n$ be a subspace. V^\perp , the orthogonal complement to V is defined by

$$V^\perp := \left\{ \vec{x} \in \mathbb{R}^n : \vec{x} \cdot \vec{v} = 0 \quad \forall \vec{v} \in V \right\}$$



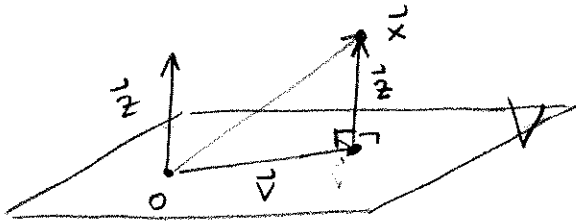
V^\perp is a subspace of \mathbb{R}^n !

- (a)
- (b)

How do you think $\dim(V)$, $\dim(V^\perp)$, and " n " are related?

④

Theorem Let $V \subset \mathbb{R}^n$ a subspace. Let $\vec{x} \in \mathbb{R}^n$. Then there is a unique decomposition $\vec{x} = \vec{v} + \vec{z}$ where $\vec{v} \in V$ and $\vec{z} \in V^\perp$.
 \vec{v} (hence $\vec{z} = \vec{x} - \vec{v}$) are easily computed using an orthonormal basis for V .
 \vec{v} is called the projection of \vec{x} onto V , $\text{proj}_V \vec{x}$.



(we projected onto lines before)

proof, which tells us how to construct the projection:

Let $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ be an orthonormal basis for V [can always find one, see §5.2]

If $\vec{x} = \vec{v} + \vec{z}$ $\vec{v} \in V, \vec{z} \in V^\perp$

$\Rightarrow \vec{x} \cdot \vec{v}_j = (\vec{v} + \vec{z}) \cdot \vec{v}_j$

* $\Rightarrow \vec{x} \cdot \vec{v}_j = \vec{v} \cdot \vec{v}_j + \vec{z} \cdot \vec{v}_j$

But by page 2 discussion, the $\vec{v} \cdot \vec{v}_j$ are the linear combination coefficients of \vec{v} , so \vec{v} must equal:

$$\vec{v} = (\vec{x} \cdot \vec{v}_1) \vec{v}_1 + (\vec{x} \cdot \vec{v}_2) \vec{v}_2 + \dots + (\vec{x} \cdot \vec{v}_k) \vec{v}_k = \sum_{j=1}^k (\vec{x} \cdot \vec{v}_j) \vec{v}_j$$

In this case \vec{z} must equal $\vec{x} - \vec{v}$

$$\vec{z} = \vec{x} - \sum_{j=1}^k (\vec{x} \cdot \vec{v}_j) \vec{v}_j$$

Is $\vec{z} \in V^\perp$?

true iff $\vec{z} \cdot \vec{v}_\ell = 0$ $\ell = 1, 2, \dots, k$

But $\vec{z} \cdot \vec{v}_\ell = (\vec{x} - \sum_{j=1}^k (\vec{x} \cdot \vec{v}_j) \vec{v}_j) \cdot \vec{v}_\ell$

$$= (\vec{x} \cdot \vec{v}_\ell) - [(\vec{x} \cdot \vec{v}_1) \vec{v}_1 + (\vec{x} \cdot \vec{v}_2) \vec{v}_2 + \dots + (\vec{x} \cdot \vec{v}_k) \vec{v}_k] \cdot \vec{v}_\ell$$

$$= (\vec{x} \cdot \vec{v}_\ell) - [0 + 0 + \dots + (\vec{x} \cdot \vec{v}_\ell) \cdot 1 + 0 + \dots + 0]$$

$$= 0!$$



example (continued from page 2) $V = \{2x_1 - 5x_2 + x_3 = 0\}$

$$B = \left\{ \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \right\}$$

Let $\vec{x} = \begin{bmatrix} 9 \\ -9 \\ -3 \end{bmatrix}$. Find $\text{proj}_V \vec{x}$

$$\begin{aligned} \text{proj}_V \vec{x} &= (\vec{x} \cdot \vec{u}) \vec{u} + (\vec{x} \cdot \vec{v}) \vec{v} \\ &= \frac{1}{\sqrt{5}} 15 \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix} + \frac{1}{\sqrt{6}} 6 \frac{1}{\sqrt{6}} \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \\ &= 3 \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 1 \\ -5 \end{bmatrix}. \end{aligned}$$

so $\vec{x} = \vec{v} + \vec{z}$

$$\begin{aligned} \vec{z} &= \vec{x} - \vec{v} \\ &= \begin{bmatrix} 9 \\ -9 \\ -3 \end{bmatrix} - \begin{bmatrix} 5 \\ 1 \\ -5 \end{bmatrix} = \begin{bmatrix} 4 \\ -10 \\ 2 \end{bmatrix} \in V^\perp \end{aligned}$$

$$[V^\perp = \text{span} \left\{ \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix} \right\}] \checkmark$$

decomposition

$$\vec{x} = \vec{v} + \vec{z}$$

$$\begin{bmatrix} 9 \\ -9 \\ -3 \end{bmatrix} = \begin{bmatrix} 5 \\ 1 \\ -5 \end{bmatrix} + \begin{bmatrix} 4 \\ -10 \\ 2 \end{bmatrix} \quad \checkmark$$

to be continued...