Name	
I.D. number	

Math 2270-2 Sample Final Exam

December 2001

This exam is closed-book and closed-note. You may not use a calculator which is capable of doing linear algebra computations. In order to receive full or partial credit on any problem, you must show all of your work and **justify your conclusions.** There are 200 points possible, and the point values for each problem are indicated in the right-hand margin. Of course, this exam counts for 30% of your final grade even though it is scaled to 200 points. Good Luck!

1) Let

4	1	-1	2
A :=	_ 1	0	1

Then $T(\mathbf{x})=A\mathbf{x}$ is a matrix map from \mathbf{R}^3 to \mathbf{R}^2 . 1a) Find the four fundamental subspaces associated to the matrix A.

(20 points)
(20 points)
(5 points)
(5 points)
(1) Find an orthonormal basis for R^3 in which the first two vectors are a basis for the rowspace of A

1c) Find an orthonormal basis for R^3 in which the first two vectors are a basis for the rowspace of A and the last vector spans its nullspace. (10 points)

2a) Exhibit the rotation matrix which rotates vectors in R^2 by an angle of α radians in the counter-clockwise direction.

(5 points) 2b) Verify that the product of an α -rotation matrix with a β -rotation matrix is an (α + β)-rotation matrix. (10 points)

3) Let T be the linear map from the complex plane to the complex plane, defined by

$$\Gamma(z) = (1+i) z$$

We can consider the complex numbers as a real vector space of dimension 2, with basis $\beta = \{1,i\}$. Find the matrix for T with respect to this basis, and explain what T does geometrically.

(10 points)

4a) Explain the procedure which allows one to convert a general quadratic equation in n-variables

$$x^T A x + B x + c = 0$$

into one without any "cross terms". Be precise in explaining the change of variables, and the justification for why such a change of variables exists.

(10 points)

4b) Apply the procedure from part (4a) to put the conic section

 $6x^{2} + 9y^{2} - 4xy + 4\sqrt{5}x - 18\sqrt{5}y = 5$

into standard form. Along the way, identify the conic section.

(20 points)

(15 points)

(15 points)

5) Let

 $C := \begin{bmatrix} 1 & -1 & 0 \\ 0 & 2 & 1 \\ 2 & 1 & 1 \end{bmatrix}$

5a) Find the inverse of C using elementary row operations.

5b) Find the inverse of C using the adjoint formula.

6a) Define what it means for a tranformation (function) T:V-->W between vector spaces to be a **linear transformation**.

(4 points) (6b) Define what it means for a set $S = \{V_1, V_2, \dots, V_n\}$ to be a **basis** for a vector space V.

6c) For a linear map T as in part (6a), define the kernel of T.

6d) Let $\beta = \{v_1, v_2, \dots, v_n\}$ be a basis for V, and let T:V-->V be linear. Explain what the matrix for T with respect to β is, and what it does.

7) Let

	-7	-6	5]
A :=	4	4	-2
	-6	-5	6

7a) Let

ſſ	1][-1][0]]
β:=	0	2	1
	2	$1 \end{bmatrix} \begin{bmatrix} 1 \end{bmatrix}$	1

be a basis for R^3. (Note these are the columns of your matrix C from #5.) Let T(x)=Ax, a linear map from R^3 to R^3. Thus A is the matrix of T with respect to the standard basis of R^3. Find the matrix of T with respect to the basis β .

(15 points)

7b) Let

$\mathbf{v}_2, \ldots \mathbf{v}_n$ to be a base
ine the kernel of T.

(3 points)

(3 points)

(5 points)

$$v := 2 \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} + \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

Compute T(v) two ways: once using the matrix for T with respect to β , and once using the matrix A. Verify that your answers agree.

(10 points)

8) True-False. Four points each (2 points for answer, two points for justification.)

(40 points)

8i) Let A be an n by n matrix. Then the equation Ax=Ay implies that x=y.

8ii) If A and B are n by n matrices, then

$$(A+B)^2 = A^2 + 2AB + B^2$$

8iii) If A is any matrix with (real entries) then the product

$$B = A^T A$$

has only real eigenvalues, and is in fact similar to a diagonal matrix.

8iv) Every set of five orthonormal vectors in \mathbf{R}^{5} is automatically a basis for \mathbf{R}^{5} .

8v) The number of linearly independent eigenvectors of a matrix is always greater than or equal to the number of distinct eigenvalues.

8vi) If the rows of a 4 by 6 matrix are linearly dependent then the nullspace is at least three dimensional.8vii) A diagonalizable n by n matrix must always have n distinct eigenvalues.

8viii) The equation

$$2x^{2} + 5xy + 3y^{2} = 1$$

defines an ellipse.

8ix) If A and B are orthogonal matrices then so is AB.

8x) If A is a square matrix and A² is singular, then so is A.