

Recall that all problems are good for seeing if you can work with the underlying concepts; that the underlined problems are to be handed in; and that the Friday quiz will be drawn from all of these concepts and from these or related problems.

4.1-4.4 problems:

4.2: subspaces: **11, 12**

4.4: bases for subspaces: 1, **2**, 3, **4**, **6**, 15.

**w8.1)** Consider the matrix  $A_{3 \times 5}$  given by

$$A := \begin{bmatrix} 3 & 1 & -2 & -1 & 7 \\ -6 & -2 & 1 & -4 & -17 \\ -3 & -1 & 3 & 3 & -6 \end{bmatrix}$$

The reduced row echelon of this matrix is

$$\begin{bmatrix} 1 & \frac{1}{3} & 0 & 1 & 3 \\ 0 & 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

**w8.1a)** Find a basis for the homogeneous solution space  $W = \{\underline{x} \in \mathbb{R}^5 \text{ s.t. } A\underline{x} = \underline{0}\}$ . What is the dimension of this subspace?

**w8.1.b)** Find a basis for the span of the five columns of  $A$ . Note that this is a subspace of  $\mathbb{R}^3$ . Pick your basis so that it uses some (but not all!) of the columns of  $A$ .

**w8.1c)** The dimensions of the two subspaces in parts a,b add up to 5, the number of columns of  $A$ . This is an example of a general fact, known as the "rank plus nullity theorem". To see why this is always true, consider any matrix  $B_{m \times n}$  which has  $m$  rows and  $n$  columns. As in parts a,b consider the homogeneous solution space

$$W = \{\underline{x} \in \mathbb{R}^n \text{ s.t. } B\underline{x} = \underline{0}\} \subseteq \mathbb{R}^n$$

and the column space

$$V = \text{span}\{\text{col}_1(B), \text{col}_2(B), \dots, \text{col}_n(B)\} = \{B\underline{c}, \text{ s.t. } \underline{c} \in \mathbb{R}^n\} \subseteq \mathbb{R}^m.$$

Let the reduced row echelon form of  $B$  have  $k$  leading 1's, with  $0 \leq k \leq m$ . Explain what the dimensions of  $W$  and  $V$  are in terms of  $k$  and  $n$ , and then verify that

$$\dim(W) + \dim(V) = n$$

must hold.

Remark: The dimension of the column space  $V$  above is called the column rank of the matrix. The

homogeneous solution space  $W$  is often called the nullspace of  $A$ , and its dimension is sometimes called the nullity. That nomenclature is why the theorem is called the "rank plus nullity theorem". You can read more about this theorem, which has a more general interpretation, at wikipedia (although the article gets pretty dense after the first few paragraphs).

**w8.2)** Recall that because of how matrix multiplication works, column dependencies for a matrix  $A$ , i.e.

$$c_1 \text{col}_1(A) + c_2 \text{col}_2(A) + \dots + c_n \text{col}_n(A) = \mathbf{0}$$

are equivalent to homogeneous solutions  $\underline{c} = [c_1, c_2, \dots, c_n]^T$  to the matrix equation

$$A \underline{c} = \mathbf{0}.$$

As we discuss in class using the notes from Monday February 24, this implies that column dependencies in  $A$  correspond exactly to column dependencies in the reduced row echelon form of  $A$ . This fact, and the four conditions that a reduced row echelon form matrix must satisfy, means that one can deduce the reduced row echelon form of a matrix  $A$  by knowing the column dependencies of  $A$ . Thus each matrix has only one reduced row echelon form no matter the order of row operations that one uses to compute it. As an example of this fact, let a matrix  $A_{4 \times 6}$  have the following list of column dependencies:

$$\text{col}_1(A) = \mathbf{0} \text{ (i.e. column one is linearly dependent).}$$

$$\text{col}_2(A) \neq \mathbf{0} \text{ (i.e. column two is linearly independent)}$$

$$\text{col}_3(A) = 2 \text{col}_2(A)$$

$$\text{col}_4(A) \text{ is not a linear combination of } \text{col}_2(A) \text{ (i.e. not a scalar multiple)}$$

$$\text{col}_5(A) = 3 \text{col}_2(A) - \text{col}_4(A)$$

$$\text{col}_6(A) \text{ is not a linear combination of } \text{col}_2(A), \text{col}_4(A).$$

What must the reduced row echelon form of  $A$  be? Explain.

## 5.1

*Solving initial value problems for linear homogeneous second order differential equations, given a basis for the solution space. Finding general solutions for constant coefficient homogeneous DE's by searching for exponential or other functions. Superposition for linear differential equations, and its failure for non-linear DE's.*

1, 6, (in 6 use initial values  $y(0) = 10, y'(0) = -5$  rather than the ones in the text), 10, 11, 12, 14 (In 14 use the initial values  $y(1) = 1, y'(1) = 7$  rather than the ones in the text.), 17, 18, 27, 33, 39.

**w8.3a)** In 5.1.6 above, the text tells you that  $y_1(x) = e^{2x}, y_2(x) = e^{-3x}$  are two independent solutions to the second order homogeneous differential equation  $y'' + y' - 6y = 0$ . Verify that you could have found these two exponential solutions via the following guessing algorithm: Try  $y(x) = e^{rx}$  where the constant  $r$  is to be determined. Substitute this possible solution into the homogeneous differential equation and find the only two values of  $r$  for which  $y(x)$  will satisfy the DE. (See Theorem 5 in the text.)

**w8.3b)** In 5.1.10 above, the text tells you that  $y_1(x) = e^{5x}, y_2(x) = x e^{5x}$  are two independent solutions to the second order homogeneous differential equation  $y'' - 10y' + 25y = 0$ . Follow the procedure in part a of trying for solutions of the form  $y(x) = e^{rx}$ , and then use the repeated roots Theorem 6 in the text, to recover these two solutions.

*5.2 Testing collections of functions for dependence and independence. Solving IVP's for homogeneous and non-homogeneous differential equations. Superposition.*

1, 2, 5, 8, 11, 13, 16, 21, 25, 26

Here are two problems that explicitly connect ideas from sections 5.1-5.2 with those in chapter 4:

**w8.4)** Consider the 3<sup>rd</sup> order homogeneous linear differential equation for  $y(x)$

$$y'''(x) = 0$$

and let  $W$  be the solution space.

**w8.4a)** Use successive antidifferentiation to solve this differential equation. Interpret your results using vector space concepts to show that the functions  $y_0(x) = 1, y_1(x) = x, y_2(x) = x^2$  are a basis for  $W$ . Thus the dimension of  $W$  is 3.

**w8.4b)** Show that the functions  $z_0(x) = 1, z_1(x) = x - 3, z_2(x) = \frac{1}{2}(x - 3)^2$  are also a basis for  $W$ .

Hint: If you verify that they solve the differential equation and that they're linearly independent, they will automatically span the 3-dimensional solution space and therefore be a basis.

**w8.4c)** Use a linear combination of the solution basis from part b, in order to solve the initial value problem below. Notice how this basis is adapted to initial value problems at  $x_0 = 3$ , whereas for an IVP at  $x_0 = 0$  the basis in a would have been easier to use.

$$\begin{aligned}y'''(x) &= 0 \\y(3) &= 17 \\y'(3) &= 24 \\y''(3) &= 5.\end{aligned}$$

**w8.5)** Consider the three functions

$$y_1(x) = \cos(3x), \quad y_2(x) = \sin(3x), \quad y_3(x) = \sin\left(3x + \frac{\pi}{6}\right).$$

**a)** Show that all three functions solve the differential equation

$$y'' + 9y = 0.$$

**b)** The differential equation above is a second order linear homogeneous DE, so the solution space is 2-dimensional. Thus the three functions  $y_1, y_2, y_3$  above must be linearly dependent. Find a linear dependency. (Hint: use a trigonometry addition angle formula.)

**c)** Explicitly verify that every initial value problem

$$y'' + 9y = 0$$

$$y(0) = b_1$$

$$y'(0) = b_2$$

has a solution of the form  $y(x) = c_1 \cos(3x) + c_2 \sin(3x)$ , and that  $c_1, c_2$  are uniquely determined by  $b_1, b_2$ . (Thus  $\cos(3x), \sin(3x)$  are a basis for the solution space of  $y'' + 9y = 0$ : every solution  $y(x)$  has initial values that can be matched with a linear combination of  $y_1, y_2$ , but once the initial values match the solutions must agree by the uniqueness theorem, so  $y_1, y_2$  span the solution space;  $y_1, y_2$  are linearly independent because if  $c_1 \cos(3x) + c_2 \sin(3x) = y(x) \equiv 0$  then  $y(0) = y'(0) = 0$  so also  $c_1 = c_2 = 0$ .)

**d)** Find by inspection, particular solutions  $y(x)$  to the two non-homogeneous differential equations

$$y'' + 9y = 27, \quad y'' + 9y = -18x$$

Hint: one of them could be a constant, the other could be a multiple of  $x$ .

**e)** Use superposition (linearity) and your work from **c,d** to find the general solution to the non-homogeneous differential equation

$$y'' + 9y = 27 - 18x.$$

**f)** Solve the initial value problem, using your work above:

$$y'' + 9y = 27 - 18x$$

$$y(0) = 0$$

$$y'(0) = 0.$$