

So much for unforced (homogeneous) spring problems. Now discuss general non-homogeneous linear DE, then in §5.6 we'll return to springs:

①

§5.5 : Finding y_p 's for $\mathcal{L}(y) = f$.

Recall, if $\mathcal{L}$ is a linear operator the general sol'n to

$$\mathcal{L}(y) = f$$

is $y = y_p + y_H$

where y_p is any particular sol'n and

y_H is the general (n-dim'l) solution to $\mathcal{L}(y) = 0$

How to find y_p 's.

Book calls the method "undetermined coefficients",

for constant coefficient linear DE's,

is really just "guessing" (but could be justified with vector space theory),
is!

example 1

$$\mathcal{L}(y) = y'' + 3y' + 4y$$

solve $\mathcal{L}(y) = 3x + 2$

try $y_p = Ax + B$

(because when you apply $\mathcal{L}$ to polys of degree ≤ 1 you get back polys of degree ≤ 1).

4 ($y_p = Ax + B$

+ 3 ($y_p' = A$

+ 1 ($y_p'' = 0$

$$\mathcal{L}(y_p) = x(4A) + 1(3A + 4B) = 3x + 2$$

$$\left. \begin{array}{l} 4A = 3 \\ 3A + 4B = 2 \end{array} \right\} \begin{array}{l} A = \frac{3}{4} \\ \frac{9}{4} + 4B = 2 \end{array}$$

$$\begin{array}{l} 4B = -\frac{1}{4} \\ B = -\frac{1}{16} \end{array}$$

$$y_p = \frac{3}{4}x - \frac{1}{16}$$

$$y_H: r^2 + 3r + 4 = 0$$

$$r = \frac{-3 \pm \sqrt{9-16}}{2} = -\frac{3}{2} \pm i\frac{\sqrt{7}}{2}$$

$$y_H(x) = e^{-3/2 x} (A \cos \frac{\sqrt{7}}{2} x + B \sin \frac{\sqrt{7}}{2} x)$$

$$y(x) = \frac{3}{4}x - \frac{1}{16} + e^{-3/2 x} (A \cos \frac{\sqrt{7}}{2} x + B \sin \frac{\sqrt{7}}{2} x)$$

example 2 $y'' - 4y = 2e^{3x}$

find y_p :

try $y_p = Ae^{3x}$

$$L(e^{3x}) = 9e^{3x} - 4e^{3x} = 5e^{3x}$$

so $L(Ae^{3x}) = 5Ae^{3x}$

||

2; $A = \frac{2}{5}$

$$y_p = \frac{2}{5}e^{3x}$$

example 3 $y'' - 4y = 10e^{2x}$

find y_p

try

oh oh. $\rightarrow$ the RHS was related to y_H . There's a way to fix your guess:

example 4 find y_p to $y'' - 4y = 4e^{3x} + 5e^{2x}$

ans: (hint: look at the 2 examples above)

(3)

guessing rules

If $L(y)$ is constant coeff. linear ^{differential} operator, what would be your first guess at the form of y_p if you wanted to solve the following, and why?

$$L(y) = 3 \cos 2x$$

$$y_p =$$

$$L(y) = 4e^{2x} \sin 3x$$

$$y_p =$$

$$L(y) = x^3 + 6x^2 - 5$$

$$y_p =$$

$$L(y) = 7e^{13x}$$

$$y_p =$$

$$L(y) = x \sin 2x$$

$$y_p =$$

Remark:

The linear algebra reason that "guessing" works: If V is finite-dim and

$L: V \rightarrow V$ has

nullspace $= \{0\}$

(only soln to $Lv = 0$ is $v = 0$), then

$Lv = f$ has a unique soln v_p .

there are special rules if $f(x) = \text{RHS}$ is related to y_H : you multiply your guess for y_p by x^s , where s is the lowest natural power making each term in your guess NOT a solution of the homog. eqn (s is the power of $r - \alpha$ in the characteristic polynomial, $p(r) = (r - \alpha)^s q(r)$).

See table page 34b, & rule 2 page 34s

more examples

$$L(y) = 7e^{-2x} + 3e^{-2x} \sin x$$

$$L = D^2 + 4D + 5I \quad (L(y) = y'' + 4y' + 5y)$$

$$p(r) = r^2 + 4r + 5 = (r+2+i)(r+2-i)$$

$$y_p = y_{p_1} + y_{p_2} =$$

$$L(y) = 7e^{-2x} + 3e^{-2x} \sin x$$

$$L(y) = y'' + 4y' + 4y$$

$$p(r) = r^2 + 4r + 4 = (r+2)^2$$

$$y_p = y_{p_1} + y_{p_2} =$$

Maple check (well, actual solutions rather than form of guess for y_p)

> with(DEtools):

> deqtn1 := diff(y(x), x, x) + 4*diff(y(x), x) + 5*y(x) = 7*exp(-2*x) + 3*exp(-2*x)*sin(x);
dsolve(deqtn1, y(x));

$$\text{deqtn1} := \frac{d^2}{dx^2} y(x) + 4 \left(\frac{d}{dx} y(x) \right) + 5 y(x) = 7e^{-2x} + 3e^{-2x} \sin(x)$$

$$y(x) = e^{-2x} \sin(x) _C2 + e^{-2x} \cos(x) _C1 - \frac{1}{2} e^{-2x} (-14 + 3 \cos(x) x)$$

> deqtn2 := diff(y(x), x, x) + 4*diff(y(x), x) + 4*y(x) = 7*exp(-2*x) + 3*exp(-2*x)*sin(x);
dsolve(deqtn2, y(x));

$$\text{deqtn2} := \frac{d^2}{dx^2} y(x) + 4 \left(\frac{d}{dx} y(x) \right) + 4 y(x) = 7e^{-2x} + 3e^{-2x} \sin(x)$$

$$y(x) = e^{-2x} _C2 + e^{-2x} x _C1 - \frac{1}{2} (-7x^2 + 6 \sin(x)) e^{-2x}$$

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If guessing won't work (maybe your linear DE is not const coeff)
there is a method, variation of parameters, that will.

illustrate method on 2nd example page 2:

$$y'' - 4y = 10e^{2x}$$

[by improved "guessing" we got

$$y_p = \frac{5}{2} x e^{2x}$$

$$y = \frac{5}{2} x e^{2x} + c_1 e^{2x} + c_2 e^{-2x}]$$

Variation of parameters: to find y_p if you have a basis $\{y_1, y_2\}$ for y_H

$$\mathcal{L}(y) = y'' + p(x)y' + q(x)y$$

$$y_H = \text{span}\{y_1, y_2\} \text{ known.}$$

to solve

$$\mathcal{L}(y) = f$$

try $y_p = u_1 y_1 + u_2 y_2$ $u_1, u_2 = \text{funs of } x$

$$\begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix} \begin{bmatrix} u_1' \\ u_2' \end{bmatrix} = \begin{bmatrix} 0 \\ f \end{bmatrix}$$

$$q(x) (y_p = u_1 y_1 + u_2 y_2)$$

$$p(x) (y_p' = u_1 y_1' + u_2 y_2' + \underbrace{u_1' y_1 + u_2' y_2}_{\text{set} = 0})$$

$$1 (\Rightarrow y_p'' = u_1 y_1'' + u_2 y_2'' + \underbrace{u_1' y_1' + u_2' y_2'}_{\text{set} = f})$$

$$\begin{bmatrix} u_1' \\ u_2' \end{bmatrix} = \frac{1}{W} \begin{bmatrix} y_2' & -y_2 \\ -y_1' & y_1 \end{bmatrix} \begin{bmatrix} 0 \\ f \end{bmatrix}$$

$$\text{so } \mathcal{L}(y_p) = u_1 \underbrace{\mathcal{L}(y_1)}_0 + u_2 \underbrace{\mathcal{L}(y_2)}_0 + f$$

$$= f$$

$$\begin{bmatrix} u_1' \\ u_2' \end{bmatrix} = \frac{1}{W} \begin{bmatrix} -y_2 f \\ y_1 f \end{bmatrix}$$

integrate to get u_1 & u_2
then get y_p .



$$y_1 = e^{2x}$$

$$y_2 = e^{-2x}$$

$$W = \begin{vmatrix} e^{2x} & e^{-2x} \\ 2e^{2x} & -2e^{-2x} \end{vmatrix} = -4$$

$$f = 10e^{2x}$$

$$u_1' = -\frac{1}{4} (-e^{-2x} 10e^{2x}) = \frac{5}{2}$$

$$u_2' = -\frac{1}{4} (e^{2x} 10e^{2x}) = -\frac{5}{2} e^{4x}$$

$$\text{take } u_1 = \frac{5}{2} x$$

$$u_2 = -\frac{5}{8} e^{4x}$$

$$y_p = u_1 y_1 + u_2 y_2$$

$$= \frac{5}{2} x e^{2x} - \frac{5}{8} e^{4x} e^{-2x}$$

$$y_p = \frac{5}{2} x e^{2x} - \frac{5}{8} e^{2x} \quad \left(\text{agrees since } -\frac{5}{8} e^{2x} \text{ is a } y_H \right)$$