

Math 2250-4

§ 3.6 Determinants

Tuesday Feb. 15.

recall: cofactor expansions for $\det$
det and elementary row ops.

$|A| \neq 0$ iff $\text{rref}(A) = I$ iff A^{-1} exists.

another magic formula

$$|AB| = |A||B|$$

(see Monday notes... not true that $|A+B| = |A| + |B|$).

today: magic formulas for A^{-1} when $|A| \neq 0$.

need: transpose of a matrix (doesn't have to be a square matrix.)

Def If $B_{m \times n} = [b_{ij}]$ then the transpose of B , B^T is defined by

$$\text{entry}_{ij}(B^T) := \text{entry}_{ji}(B) = b_{ji}$$

the effect of this is to switch rows & columns, since e.g.

$$\text{entry}_{ij}(B^T) = \text{entry}_j(\text{row}_i(B^T))$$

ii

$$\text{entry}_{ji}(B) = \text{entry}_j(\text{col}_i(B))$$

example

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

①

a chance to go
through 2008 midterm
tonight 6-7:30 pm
JTB 140

(you could also ask
abt hw due Wed.)

Theorem Recall the cofactor $C_{ij} = (-1)^{i+j} M_{ij}$

where the minor M_{ij} is the det of the $(n-1) \times (n-1)$ matrix
obtained by deleting row i and col j of A

the adjoint matrix is the
transpose of the cofactor matrix, $[C_{ij}] = \text{cof}(A)$.
i.e.

$$\text{Adj}(A) = \text{cof}(A)^T$$

then, when A^{-1} exists, it has formula

$$A^{-1} = \frac{1}{|A|} \text{adj}(A)$$

exercise 1: Show that for $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ this theorem reproduces our "magic" formula
$$A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}.$$

exercise 2 for our friend $A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 1 \\ 2 & -2 & 1 \end{bmatrix}$ we worked out $\text{cof}(A) = \begin{bmatrix} 5 & 2 & -6 \\ 0 & 3 & 6 \\ 5 & -1 & 3 \end{bmatrix}$, $|A| = 15$

What is A^{-1} ?
Check ans!

$$\text{adj}(A) = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$

(3)

exercise 3

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 1 \\ 2 & -2 & 1 \end{bmatrix}$$

$$\text{cof}(A) = \begin{bmatrix} 5 & 2 & -6 \\ 0 & 3 & 6 \\ 5 & -1 & 3 \end{bmatrix}$$

$$\text{adj}(A) = \begin{bmatrix} 5 & 0 & 5 \\ 2 & 3 & -1 \\ -6 & 6 & 3 \end{bmatrix}$$

3a) the (1,1) entry of

$$[A][\text{adj}(A)] \text{ is } 15 = 1 \cdot 5 + 2 \cdot 2 + (-1)(-6)$$

explain why this is $\det(A)$, expanded across first row3b) the (2,1) entry of $[A][\text{adj}(A)]$ is $0 \cdot 5 + 3 \cdot 2 + 1(-6) = 0$.

Notice, you used the same cofactors as in 3a).

What matrix (which uses 2 rows of A) is this the determinant of?3c) the (3,2) entry of $[A][\text{adj}(A)]$ is $2 \cdot 0 + (-2)(3) + 1(6) = 0$ What matrix (which uses 2 rows of A) is this the det of?

If you understand 3a, b, c, completely, you have just realized why

$$A(\text{adj}(A)) = \det(A) \mathbf{I} \quad \text{for every square matrix,}$$

$$\text{and so, why } A^{-1} = \frac{1}{\det A} \text{adj}(A)$$

when $\det A \neq 0$.

precisely, entry $_{ii}$ $A(\text{adj}(A)) = \sum_{j=1}^n a_{ij} c_{ij} = |A|$

$k \neq i$, entry $_{ik}$ $A(\text{adj}(A)) = \sum_{j=1}^n a_{ij} c_{kj} = \begin{vmatrix} \text{row}_1(A) \\ \vdots \\ \text{row}_i(A) \leftarrow \text{slot } k \\ \vdots \\ \text{row}_n(A) \end{vmatrix} \leftarrow \text{slot } i = 0.$

this proves the A^{-1} formula theorem!

(4)

There's a related formula for solving for individual components of $\vec{x}$, when $A\vec{x} = \vec{b}$ has unique solutions:

Cramer's rule

Let $\vec{x}$ solve $A\vec{x} = \vec{b}$ for invertible A .

$$\text{then } x_k = \frac{\begin{vmatrix} C_1 & C_2 & \dots & \vec{b} & \dots & C_n \end{vmatrix}}{|A|}$$

numerator is ^{det of} matrix obtained from A by replacing ~~row~~ column k by $\vec{b}$.

$$\begin{aligned} \text{proof: } x_k &= \text{entry}_k(A^{-1}\vec{b}) \\ &= \text{entry}_k\left(\frac{1}{|A|} \text{adj}(A)\vec{b}\right) \\ &= \frac{1}{|A|} \text{row}_k(\text{adj}(A)) \cdot \vec{b} \\ &= \frac{1}{|A|} \sum_{\ell=1}^n C_{\ell k} b_{\ell} \end{aligned}$$

this is the expansion of the det in numerator of Cramer's rule, down the k^{th} column!



exercise 4: Solve $\begin{bmatrix} 5 & -1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 7 \\ 2 \end{bmatrix}$

a) with Cramer's rule

b) with A^{-1} , using adjoint formula

Math 2250-4

Review sheet for exam 1, which is Thurs 2/17 in your section

problem session TBA

(Tuesday evening or Wed. p.m.)

Chapter 1 : Methods to solve certain 1st order DE's

integration, for $\frac{dy}{dx} = f(x)$

position, veloc, accel, when accel is a fun of t alone.

separable DE's

growth & decay (exponential)

populations, radioactive decay, Newton's law of cooling (with constant ambient temp.)

drug elimination, rumor propagation, disease spread.

NO TORRICELLI ON EXAM

linear 1st order DE's

mixing problems

slope fields and phase diagrams to understand qualitative behavior of sol's without knowing formula for solution fun.

How to draw these, especially for autonomous DE's.

Chapter 2 : Applications in depth

population models: logistic, doomsday/extinction, harvesting logistic;

understand derivations, how to find solutions (by separating variables),

how to plot slope fields & phase portraits, how to find equilibrium solutions and evaluate stability/unstability.

equilibrium sol's & stability for general 1st order autonomous DE's.

acceleration-velocity models, especially linear drag (force proportional to velocity.)

NO NUMERICAL METHODS (2.4-2.6) ON EXAM.

Chapter 3 : Linear systems and matrices

solving linear systems by creating the augmented matrix, using elementary row ops to get rref, deducing solution by back-solving.

geometric meaning of linear systems in 2 or 3 variables

Matrix algebra: addition, scalar multiplication, matrix multiplication

What algebra rules hold, and which one(s) don't.

Matrix inverses

how to compute via row operations

how to solve linear systems with the inverse matrix, if the inverse exists.

Determinants

how to compute with cofactors

how to compute with row ops

Cramer's rule

Adjoint formula for the inverse, esp. 2×2 & 3×3 cases.

Be able to ~~do~~
solve problems and
to explain key ideas