

Math 2250-4

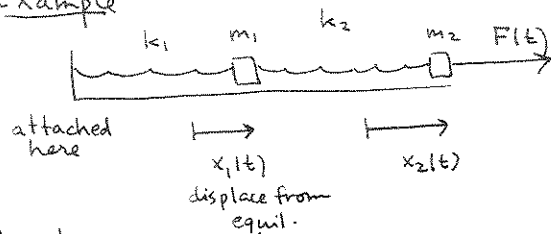
Friday 4/8

§ 7.1, hints of 7.2, 7.3.

We saw Tuesday how input-output modeling (compartmental analysis) leads to 1st order systems of DE's. So,

- What kind of DE's do we get for an interconnected mass-spring system?  
(or multiply-connected)  
RLC circuits

Example



Newton:

$$m_1 x_1''(t) = k_2 (x_2 - x_1) - k_1 x_1$$

2nd spring is stretched this much

$$m_2 x_2''(t) = -k_2 (x_2 - x_1) + F(t)$$

e.g.  $\left. \begin{array}{l} m_1 = 2 \\ m_2 = 1 \\ k_1 = 4 \\ k_2 = 2 \\ f(t) = 40 \sin 3t \end{array} \right\} \Rightarrow$

$$\left\{ \begin{array}{l} 2x_1'' = 2(x_2 - x_1) - 4x_1 = -6x_1 + 2x_2 \\ x_2'' = -2(x_2 - x_1) + 40 \sin 3t = 2x_1 - 2x_2 + 40 \sin 3t \end{array} \right.$$

$$\text{or } \begin{bmatrix} x_1'' \\ x_2'' \end{bmatrix} = \begin{bmatrix} -3 & 1 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 40 \sin 3t \end{bmatrix}$$

- What's a natural IVP for this 2nd order system of 2 linear DE's?  
(We won't solve it today - see § 7.4)

note: Any system of DE's can be converted into an equivalent system of 1st order DE's, by introducing extra unknown functions.

(1)  $\begin{cases} x_1'' = -3x_1 + x_2 \\ x_2'' = 2x_1 - 2x_2 + 40 \sin 3t \end{cases}$

let  $y_1 = x_1'$   
 $y_2 = x_2'$

solutions of (1) yield solutions of (2) and vice versa.

This correspondence is sometimes useful.

(2)

$$\begin{cases} x_1' = y_1 \\ y_1' = -3x_1 + x_2 \\ x_2' = y_2 \\ y_2' = 2x_1 - 2x_2 + 40 \sin 3t \end{cases}$$

HW for Fri. 4/15

7.1 1, 3, 5, 8, 11, 18, 21, 24, 26

7.2 5, 9, 10, 13, 14, 16, 21, 23, 25

7.3 3, 4, 6, 13, 14, 25, 30, 32, 37

use pplane (same page as dfield) for pictures. In 7.3.6 also solve with Laplace transform.

Directions for turning in HW  
this Friday 4/8, or next Friday 4/15,  
after 12:00 noon: turn HW into

Paula Tooman, front desk  
of Math office JWB 233,  
before 5:00 p.m.

NOT TO MY OFFICE

example : Study the correspondence between  $n^{\text{th}}$  order eqns or systems and  $1^{\text{st}}$  order ones : (Every system of arbitrary order DE's can be reduced to an equivalent first order system. The correspondence doesn't always go in the reverse direction)

$x = x(t)$

2<sup>nd</sup> order linear homog DE

$$x'' - x' - 2x = 0$$

$x = e^{rt}$

$$p(r) = r^2 - r - 2 = 0$$

$$(r-2)(r+1) = 0$$

$$x_H(t) = C_1 e^{2t} + C_2 e^{-t}$$

so we could immediately solve the  $1^{\text{st}}$  order system:

$$x_H(t) = C_1 e^{2t} + C_2 e^{-t}$$

$$x_H'(t) = 2C_1 e^{2t} - C_2 e^{-t}$$

$$\text{so } \begin{bmatrix} x \\ y \end{bmatrix} = C_1 e^{2t} \begin{bmatrix} 1 \\ 2 \end{bmatrix} + C_2 e^{-t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

Also, see work at right!

1<sup>st</sup> order system of 2 DE's

$$y = x'$$

$$x' = y$$

$$y' = y + 2x$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\text{try } \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = e^{\lambda t} \vec{v}$$

$$\text{for } \vec{x}'(t) = A \vec{x}$$

$$\lambda e^{\lambda t} \vec{v} = A e^{\lambda t} \vec{v}$$

$$\lambda \vec{v} = A \vec{v} \quad \vec{v} \text{ eigenvect of } A$$

$$0 = (A - \lambda I) \vec{v} \quad \text{eigenval } \lambda$$

$$\det \begin{bmatrix} -\lambda & 1 \\ 2 & 1-\lambda \end{bmatrix} = \lambda^2 - \lambda - 2 = p(\lambda)$$

does this "characteristic polynomial" look familiar?

$$= (\lambda - 2)(\lambda + 1)$$

$$\lambda = 2$$

$$\lambda = -1$$

$$\begin{array}{cc|c} -2 & 1 & 0 \\ 2 & -1 & 0 \end{array}$$

$$\begin{array}{cc|c} 1 & 1 & 0 \\ 2 & 2 & 0 \end{array}$$

$$\vec{v} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\vec{v} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

eigenbasis

$$\Rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = C_1 e^{2t} \begin{bmatrix} 1 \\ 2 \end{bmatrix} + C_2 e^{-t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

IVP  $\begin{cases} x'' - x' - 2x = 0 \\ x(0) = 2 \\ x'(0) = 1 \end{cases}$

$$\begin{aligned} C_1 + C_2 &= 2 \\ 2C_1 - C_2 &= 1 \end{aligned}$$

$$x(t) = e^{2t} + e^{-t}$$

IVP  $\begin{cases} \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \\ \begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \end{cases}$

$$\begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

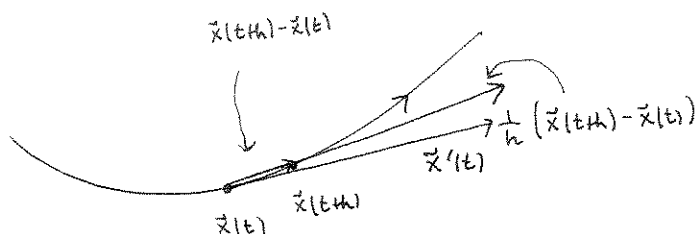
$$\begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = e^{2t} \begin{bmatrix} 1 \\ 2 \end{bmatrix} + e^{-t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

geometric interpretation of 1<sup>st</sup> order system of DEs:

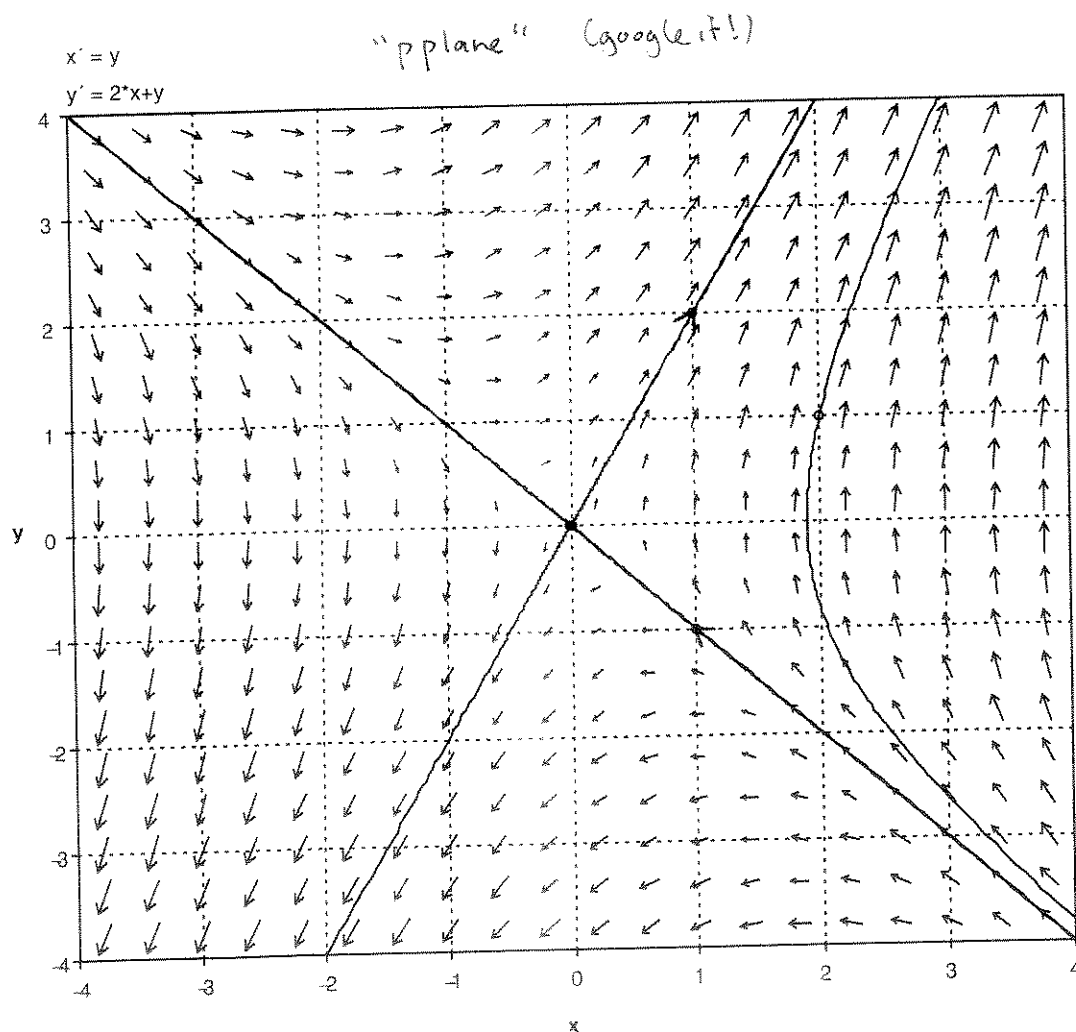
$$\text{IVP} \begin{cases} \frac{d\vec{x}}{dt} = \vec{F}(t, \vec{x}) \\ \vec{x}(t_0) = \vec{x}_0 \end{cases}$$

- Recall, if  $\vec{x}(t)$  is parametric curve in space (think particle position at time  $t$ ) then  $\vec{x}'(t)$  is the tangent (or velocity) vector:



So the IVP says you know where you start ( $\vec{x}(t_0) = \vec{x}_0$ ), and you know your velocity vector (depending on time & location)  $\rightarrow$  so you expect a unique soln

page 2 example continued :



$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 e^{2t} \begin{bmatrix} 1 \\ 2 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

( $c_1 = c_2 = 1$  if  $\begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ )

for fun, if we have time:

an example related to §6.3, applications of powers of matrices.

How google search works

I have a more in-depth explanation at

<http://www.math.utah.edu/teacherscircle/notes/2-23-2009.pdf>

see also wikipedia and

<http://www.ams.org/featurecolumn/archive/pagerank.html>

A stochastic matrix (p 38 of our text) is an  $n \times n$  matrix with all positive entries, such that the entries in each column add up to 1

e.g.  $A = \begin{bmatrix} .1 & .8 & .8 \\ .8 & .1 & .1 \\ .1 & .1 & .1 \end{bmatrix}$

Perron's theorem says any Stochastic matrix has ~~an~~ an eigenvalue  $\lambda=1$ ,  $\lambda=1$  eigenspace  $\dim=1$ , with an eigenvector  $\vec{v}$  with all positive entries. (You can scale  $\vec{v}$  so that its entries add up to 1.) All other eigenvalues of a stochastic matrix have absolute value less than 1 (if they're real), or if they're complex,  $\lambda = a+bi = \sqrt{a^2+b^2} \left( \frac{a}{\sqrt{a^2+b^2}} + \frac{ib}{\sqrt{a^2+b^2}} \right)$

thus, for all other  $\lambda$ 's,

$$\lambda^k \rightarrow 0 \text{ as } k \rightarrow \infty.$$

$$\begin{aligned} &= \cos \theta + i \sin \theta \\ &= r e^{i\theta} \text{ with } r < 1 \\ \text{so } \lambda^k &= r^k e^{ik\theta} \\ &= r^k (\cos k\theta + i \sin k\theta) \rightarrow 0 \text{ as } k \rightarrow \infty \end{aligned}$$

Thus, If  $A$  is stochastic, and is the transition matrix for a discrete dynamical system, then

$$\vec{x}_k = A^k \vec{x}_0.$$

Express  $\vec{x}_0 = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$

$\uparrow$   
 the  $\lambda=1$   
 eigenvector

$\underbrace{\hspace{10em}}$   
 the eigenvectors

(or "generalized" eigenvectors if  $A$  is not diagonalizable)

Then  $A^k \vec{x}_0 = c_1 \vec{v}_1$

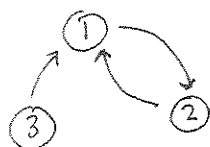
$$+ c_2 A^k \vec{v}_2 + c_3 A^k \vec{v}_3 + \dots$$

$$\begin{array}{ccc} \lambda_2^k \vec{v}_2 & \downarrow & \dots \downarrow \\ 0 & 0 & 0 \end{array} \text{ as } k \rightarrow \infty.$$

So the long-term dynamics are determined by the  $\lambda=1$  eigenvector.

# The google voting game:

Suppose that for a certain search topic there are 3 sites, and that they link (i.e. with hyperlinks) to each other as follows



Which site should be top ranked?

Initially give each site  $\frac{1}{3}$  vote, so  $\begin{bmatrix} x_0 \\ y_0 \\ z_0 \end{bmatrix} = \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \\ \frac{1}{3} \end{bmatrix}$  is # of votes for sites 1, 2, 3.

to get from stage  $k$  to stage  $k+1$   
each site splits its current votes equally among the sites it links to:  
So, in our case

votes for ① →  $x_{k+1} = 0x_k + 1y_k + 1z_k$   
 " ② →  $y_{k+1} = 1x_k + 0y_k + 0z_k$   
 " ③ →  $z_{k+1} = 0x_k + 0y_k + 0z_k$

$$\begin{bmatrix} x_{k+1} \\ y_{k+1} \\ z_{k+1} \end{bmatrix} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_k \\ y_k \\ z_k \end{bmatrix}$$

↑ how site 1 vote is split  
 ↑ how site 2 vote is split  
 ↑ how site 3 vote is split

Call this transition matrix  $B$

- column entries always add to 1
- but not all entries are non-zero.

google fudge factor: if there are  $n$  sites, and for  $\alpha = 0.15$ , make everyone give  $\frac{\alpha}{n}$  of their current vote to each site equally, and split the remaining fraction of their vote according to the original recipe.

so  $\begin{bmatrix} x_{k+1} \\ y_{k+1} \\ z_{k+1} \end{bmatrix} = (1-\alpha) \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + \frac{\alpha}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} .1 & .8 & .8 \\ .8 & .1 & .1 \\ .1 & .1 & .1 \end{bmatrix} \quad (\text{for } \alpha = .3)$   
Stochastic!

this is the matrix on page 4

With the google fudge factor, after  $k$  iterations

$$\begin{bmatrix} x_k \\ y_k \\ z_k \end{bmatrix} = \begin{bmatrix} .1 & .8 & .8 \\ .8 & .1 & .1 \\ .1 & .1 & .1 \end{bmatrix}^k \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

$\rightarrow c_1 \vec{v}_1$  ← the  $\lambda=1$  eigenvector as  $k \rightarrow \infty$

Since total vote is conserved, if  $\vec{v}_1$  is the vector with positive entries so that their sum is 1, then since the original vote totalled 1, our answer will actually be  $\vec{v}_1$ . In fact, we could have apportioned the initial vote however we wanted — as long as the initial vote totalled 1, the limit is  $\vec{v}_1$ . (So if we initially gave all the vote to site  $j$ , which is an initial vote vector

$$\vec{e}_j = \begin{bmatrix} 0 \\ \vdots \\ 1 \end{bmatrix} \text{ entry } j, \text{ the limit}$$

of  $A^k \vec{e}_j$  is  $\vec{v}_1$ , which is also the  $j^{\text{th}}$  column of the limit matrix!

The  $i^{\text{th}}$  entry of  $\vec{v}_1$  is how much vote site  $i$  ends up with — the more this number is, the higher the google rank!

> with(LinearAlgebra):

Digits := 5:

> A := Matrix(3, 3, [.1, .8, .8, .8, .1, .1, .1, .1, .1]):

x := Vector(3, 1, [1/3, 1/3, 1/3]):

map(evalf, A<sup>40</sup>.x); # map evalf so that only 5 digits are shown

map(evalf, A<sup>40</sup>):

0.47058

0.42941

0.099999

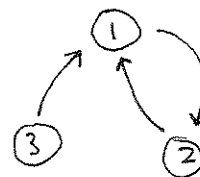
← site ① is top

← site ③ is weak

0.47059 0.47059 0.47059

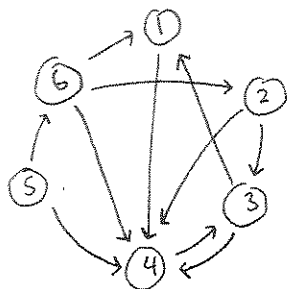
0.42941 0.42941 0.42941

0.10000 0.10000 0.10000



>  
>

A bigger example



$$B = \begin{bmatrix} 0 & 0 & \frac{1}{2} & 0 & 0 & \frac{1}{3} \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{3} \\ 0 & 0 & \frac{1}{2} & 0 & 1 & 0 \\ 1 & \frac{1}{2} & 0 & 0 & \frac{1}{2} & \frac{1}{3} \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{2} & 0 \end{bmatrix}$$

$$\alpha = 0.15$$

$$B := \begin{bmatrix} 0 & 0 & 0.5 & 0 & 0 & 0.33333 \\ 0 & 0 & 0 & 0 & 0 & 0.33333 \\ 0 & 0.5 & 0 & 1 & 0 & 0 \\ 1 & 0.5 & 0.5 & 0 & 0.5 & 0.33333 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0.5 & 0 \end{bmatrix}$$

$$goog := \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

$$A := \text{map}(\text{evalf}, (1 - \alpha) \cdot B + \frac{\alpha}{n} \cdot \text{goog});$$

$$A := \begin{bmatrix} 0.025000 & 0.025000 & 0.45000 & 0.025000 & 0.025000 & 0.30833 \\ 0.025000 & 0.025000 & 0.025000 & 0.025000 & 0.025000 & 0.30833 \\ 0.025000 & 0.45000 & 0.025000 & 0.87500 & 0.025000 & 0.025000 \\ 0.87500 & 0.45000 & 0.45000 & 0.025000 & 0.45000 & 0.30833 \\ 0.025000 & 0.025000 & 0.025000 & 0.025000 & 0.025000 & 0.025000 \\ 0.025000 & 0.025000 & 0.025000 & 0.025000 & 0.45000 & 0.025000 \end{bmatrix}$$

$$> \text{map}(\text{evalf}, A^{40});$$

$$\begin{bmatrix} 0.18476 & 0.18476 & 0.18476 & 0.18476 & 0.18476 & 0.18476 \\ 0.035093 & 0.035093 & 0.035093 & 0.035093 & 0.035093 & 0.035093 \\ 0.35216 & 0.35216 & 0.35216 & 0.35216 & 0.35216 & 0.35216 \\ 0.36735 & 0.36735 & 0.36735 & 0.36735 & 0.36735 & 0.36734 \\ 0.025000 & 0.025000 & 0.025000 & 0.025000 & 0.025000 & 0.024999 \\ 0.035625 & 0.035625 & 0.035625 & 0.035625 & 0.035624 & 0.035624 \end{bmatrix}$$

← How do you google rank the 6 sites?

other applications:  
any enclosed tank system?  
other rankings?  
(e.g. BCS football?)

actually, the google guys figured out how to page rank all  $> 10^7$  sites!