

Math 2250-1
Week 8 concepts and homework, due October 19.

Recall that all problems are good for seeing if you can work with the underlying concepts; that the underlined problems are to be handed in; and that the Friday quiz will be drawn from all of these concepts and from these or related problems.

4.1-4.4 review problem:

w8.0) Consider matrix $A_{3 \times 4}$ given by

$$A := \begin{bmatrix} 1 & 3 & -2 & 0 \\ -1 & -3 & 2 & 0 \\ 2 & 6 & -3 & 4 \end{bmatrix}.$$

The reduced row echelon of this matrix is

$$\begin{bmatrix} 1 & 3 & 0 & 8 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

w8.0a) Find a basis for the homogeneous solution space $W = \{\underline{x} \in \mathbb{R}^4 \text{ s.t. } A \underline{x} = \underline{0}\}$. What the dimension of this subspace?

w8.0.b) Find a basis for the span of the columns of A , which is a subspace of \mathbb{R}^3 . What is the dimension of this subspace?

w8.0c) The dimensions of the two subspaces in parts a,b add up to 4, the number of columns of A . This is an example of a general fact, known as the "rank plus nullity theorem". To see why this is always true, consider any matrix $B_{m \times n}$ which has m rows and n columns. As in parts a,b consider the homogeneous solution space

$$W = \{\underline{x} \in \mathbb{R}^n \text{ s.t. } B \underline{x} = \underline{0}\} \subseteq \mathbb{R}^n$$

and the column space

$$V = \text{span}\{col_1(B), col_2(B), \dots, col_n(B)\} = \{B \underline{x}, \text{ s.t. } \underline{x} \in \mathbb{R}^n\} \subseteq \mathbb{R}^m.$$

Let the reduced row echelon form of B have k leading 1's, with $0 \leq k \leq n$. Explain what the dimensions of W and V are in terms of k and n , and then verify that

$$\dim(W) + \dim(V) = n$$

must hold. (The dimension of the column space V is called the rank of the matrix, and the dimension of the homogeneous solution space W is called the nullity of the matrix, which is why this is called the "rank plus nullity theorem".)

5.1

Solving initial value problems for linear homogeneous second order differential equations, given a basis for the solution space. Finding general solutions for constant coefficient homogeneous DE's by searching for exponential or other functions. Superposition for linear differential equations, and its failure for non-linear DE's.

1, 6, (in 6 use initial values $y(0) = 4, y'(0) = -2$ rather than the ones in the text), 10, 11, 12, 14 (In 14 use

the initial values $y(1) = 2, y'(1) = -4$ rather than the ones in the text.), 17, **18, 27**, 33, 39.

w8.1) In 5.1.6 above, the text tells you that $y_1(x) = e^{2x}, y_2(x) = e^{-3x}$ are two independent solutions to the second order homogeneous differential equation $y'' + y' - 6y = 0$. Verify that you could have found these two exponential solutions via the following guessing algorithm: Try $y(x) = e^{rx}$ where r is to be determined. Substitute this possible solution into the homogeneous differential equation and find the only two values of r for which $y(x)$ will satisfy the DE.

5.2 Testing collections of functions for dependence and independence. Solving IVP's for homogeneous and non-homogeneous differential equations. Superposition.

1, 2, 5, **8**, 11, 13, **16**, 21, **25**, 26

Here's a problem that integrates many of the ideas from sections 5.1-5.2, and also ties in with chapter 4:

w8.2) Consider the three functions

$$y_1(x) = \sin(2x), \quad y_2(x) = \sin\left(2\left(x - \frac{\pi}{4}\right)\right), \quad y_3(x) = \cos(2x).$$

a) Show that all three functions solve the differential equation

$$y'' + 4y = 0.$$

b) The differential equation above is a second order linear homogeneous DE, so the solution space is 2-dimensional. Thus the three functions y_1, y_2, y_3 above must be linearly dependent. Find a linear dependency. (Hint: use a trigonometry addition angle formula.)

c) Explicitly verify that every initial value problem

$$\begin{aligned} y'' + 4y &= 0 \\ y(0) &= b_1 \\ y'(0) &= b_2 \end{aligned}$$

has a solution of the form $y(x) = c_1 \sin(2x) + c_2 \cos(2x)$, and that c_1, c_2 are uniquely determined by b_1, b_2 . Use the existence-uniqueness theorem to explain why this proves that $y_1(x)$ and $y_3(x)$ are a basis for the solution space to

$$y'' + 4y = 0.$$

d) Compute the Wronskian matrix for $y_1(x), y_3(x)$. What does this matrix, evaluated at $x = 0$, have to do with the algebra related to **c**? What is the significance of the fact that the Wronskian (determinant) is non-zero at $x = 0$, in terms of knowing that c_1, c_2 are uniquely determined by b_1, b_2 ?

e) Find by inspection, particular solutions $y(x)$ to the two non-homogeneous differential equations

$$y'' + 4y = 16, \quad y'' + 4y = -8x$$

Hint: one of them could be a constant, the other could be a multiple of x .

f) Use superposition and your work from **c, e** to find the general solution to the non-homogeneous differential equation

$$y'' + 4y = 16 - 8x.$$

g) Solve the initial value problem

$$\begin{aligned} y'' + 4y &= 16 - 8x \\ y(0) &= 0 \\ y'(0) &= 0. \end{aligned}$$