

Recall that problems which are not underlined are good for seeing if you can work with the underlying concepts; that the underlined problems are to be handed in; and that the Friday quiz will be drawn from all of these concepts and from these or related problems. You also have a Maple/Matlab project due on September 16.

2.3: improved velocity–acceleration models:

2, 9, 10, 12: constant, or constant plus linear drag forcing

13, 14, 17, 18: quadratic drag

24, 25: escape velocity

2.4–2.6: numerical methods for approximating solutions to first order initial value problems. Your second Maple/Matlab project addresses these sections too.

2.4: 5: Euler’s method

2.5: 5: improved Euler

2.6: 5: Runge–Kutta

w4.1) Runge–Kutta is based on Simpson’s rule for numerical integration. Simpson’s rule is based on the fact that for a subinterval of length $2 \cdot h$, which by translation we may assume is the interval $-h \leq x \leq h$, the parabola $y = p(x)$ which passes through the points $(-h, y_{-1})$, $(0, y_0)$, (h, y_1) has integral

$$\int_{-h}^h p(x) \, dx = \frac{2 \cdot h}{6} \cdot (y_{-1} + 4 \cdot y_0 + y_1) . \quad (1)$$

If we write the quadratic interpolant function $p(x)$ whose graph is this parabola as

$$p(x) = a + b \cdot x + c \cdot x^2$$

with unknown parameters a, b, c then since we want $p(0) = y_0$ we solve $y_0 = a + 0 + 0$ to deduce that $a = y_0$.

w4.1a) Use the requirement that the graph of $p(x)$ is also to pass through the other two points, $(-h, y_{-1})$, (h, y_1) to express b, c in terms of h, y_{-1}, y_0, y_1 .

w4.1b) Compute $\int_{-h}^h p(x) \, dx$ for these values of a, b, c and verify equation (1) above.