

Math 2250-1  
Wednesday October 1

Exam 1 Monday!

①

1.1-1.6  
2.1-2.3  
3.1-3.6

Review session  
Saturday?

Finish determinants! §3.6; begin §4.1

Did:  $A^{-1}$  exists iff  $\text{rref}(A) = I$  iff  $\det A \neq 0$

(postpone  
§4.1 HW  
until next Friday.)  
or  
Friday afternoon?

Theorem Recall the cofactor  $C_{ij} = (-1)^{i+j} M_{ij}$

where the minor  $M_{ij}$  is the det of the  $(n-1) \times (n-1)$  matrix  
obtained by deleting row  $i$  and col  $j$  of  $A$

the adjoint matrix is the  
transpose of the cofactor matrix,  $[C_{ij}] = \text{cof}(A)$ .

i.e.  
$$\text{Adj}(A) = \text{cof}(A)^T$$

then, when  $A^{-1}$  exists, it has formula

$$A^{-1} = \frac{1}{|A|} \text{adj}(A)$$

exercise 1: Show that for  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  this theorem reproduces our "magic" formula

$$A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

exercise 2 for our friend  $A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 1 \\ 2 & -2 & 1 \end{bmatrix}$

we worked out  $\text{cof}(A) = \begin{bmatrix} 5 & 2 & -6 \\ 0 & 3 & 6 \\ 5 & -1 & 3 \end{bmatrix}$ ,  $|A| = 15$

What is  $A^{-1}$ ?  
Check ans!

$$\text{adj}(A) = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$

exercise 3

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 1 \\ 2 & -2 & 1 \end{bmatrix}$$

$$\text{cof}(A) = \begin{bmatrix} 5 & 2 & -6 \\ 0 & 3 & 6 \\ 5 & -1 & 3 \end{bmatrix}$$

$$\text{adj}(A) = \begin{bmatrix} 5 & 0 & 5 \\ 2 & 3 & -1 \\ -6 & 6 & 3 \end{bmatrix}$$

3a) the (1,1) entry of

$[A][\text{adj}(A)]$  is  $15 = 1 \cdot 5 + 2 \cdot 2 - 1(-6)$   
explain why this is  $\det(A)$ , expanded across first row

3b) the (2,1) entry of  $[A][\text{adj}(A)]$  is  $0 \cdot 5 + 3 \cdot 2 + 1(-6) = 0$ .

Notice, you used the same cofactors as in 3a).  
What matrix (which uses 2 rows of A) is this the determinant of?

3c) the (3,2) entry of  $[A][\text{adj}(A)]$  is  $2 \cdot 0 + (-2)(3) + 1(6) = 0$

What matrix (which uses 2 rows of A) is this the det of?

If you understand 3a, b, c, completely, you have just realized why

$$A(\text{adj}(A)) = \det(A) \mathbf{I} \quad \text{for every square matrix,}$$

and so, why  $A^{-1} = \frac{1}{\det A} \text{adj}(A)$  when  $\det A \neq 0$ .

precisely, entry  $_{ii}$ :  $A(\text{adj}(A)) = \sum_{j=1}^n a_{ij} C_{ij} = |A|$

$k \neq i$ , entry  $_{ik}$ :  $A(\text{adj}(A)) = \sum_{j=1}^n a_{ij} C_{kj} = \begin{vmatrix} \text{row}_1(A) \\ \vdots \\ \text{row}_i(A) \leftarrow \text{slot } k \\ \text{row}_i(A) \leftarrow \text{slot } i \\ \vdots \\ \text{row}_n(A) \end{vmatrix} = 0$

this proves the  $A^{-1}$  formula theorem!

Cramer's Rule (see below) (complete proof in yesterday's notes)

the sol'n to

$$\begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 1 \\ 2 & -2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 5 \\ 4 \end{bmatrix}$$

$$A\vec{x} = \vec{b}$$

is  $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \frac{1}{15} \begin{bmatrix} 5 & 0 & 5 \\ 2 & 3 & -1 \\ -6 & 6 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ 5 \\ 4 \end{bmatrix} =$

interpret with cofactors

$$x = \frac{1}{15} (5 \cdot 2 + 0 \cdot 5 + 5 \cdot 4)$$

↑ 1<sup>st</sup> col cofactors      ↓ RHS

$$= \frac{\begin{vmatrix} 2 & 2 & -1 \\ 5 & 3 & 1 \\ 4 & -2 & 1 \end{vmatrix}}{15}$$

$$= \frac{\begin{vmatrix} \vec{b} & \text{col}_2(A) & \text{col}_3(A) \end{vmatrix}}{|A|}$$

$$y = \frac{1}{15} (2 \cdot 2 + 3 \cdot 5 - 1 \cdot 4)$$

↑ 2<sup>nd</sup> col cofactors

$$= \frac{\begin{vmatrix} 1 & 2 & -1 \\ 0 & 5 & 1 \\ 2 & 4 & 1 \end{vmatrix}}{15}$$

$$= \frac{\begin{vmatrix} \text{col}_1(A) & \vec{b} & \text{col}_3(A) \end{vmatrix}}{|A|}$$

z =

$$x_k = \frac{\begin{vmatrix} \text{col}_1(A) & \text{col}_2(A) & \dots & \vec{b} & \dots & \text{col}_n(A) \end{vmatrix}}{|A|}$$

↳ If  $A^{-1}$  exists, and if  $A\vec{x} = \vec{b}$ ,  $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$ , then

i.e. the numerator is det of mat. obtained by replacing  $k^{\text{th}}$  column of  $A$  with  $\vec{b}$ .

exercise 4 Solve  $\begin{bmatrix} 5 & -1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 7 \\ 2 \end{bmatrix}$

a) with Cramer's rule

b) with  $A^{-1}$ , using adjoint formula

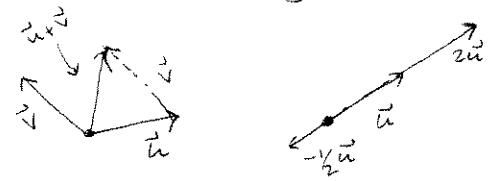
# Introduction to 4.1-4.3

(to be continued)

In chapter 4 we will continuously make use of the "linear combination form" way of writing a matrix times a vector:

$$\begin{matrix}
 \text{chapter 3} & & \text{chapter 4} \\
 \downarrow & & \downarrow \\
 \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & \dots & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} & = & \begin{bmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \\ \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n \end{bmatrix} & = & x_1 \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix} + x_2 \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix} + \dots + x_n \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix}
 \end{matrix}$$

and you will need to remember the geometric meaning of vector addition and scalar multiplication.



## example

How can you get to  $\begin{bmatrix} 1 \\ 8 \end{bmatrix}$  in  $\mathbb{R}^2$

by only moving in the  $\begin{bmatrix} 3 \\ -2 \end{bmatrix}$  and  $\begin{bmatrix} 5 \\ 1 \end{bmatrix}$  directions?

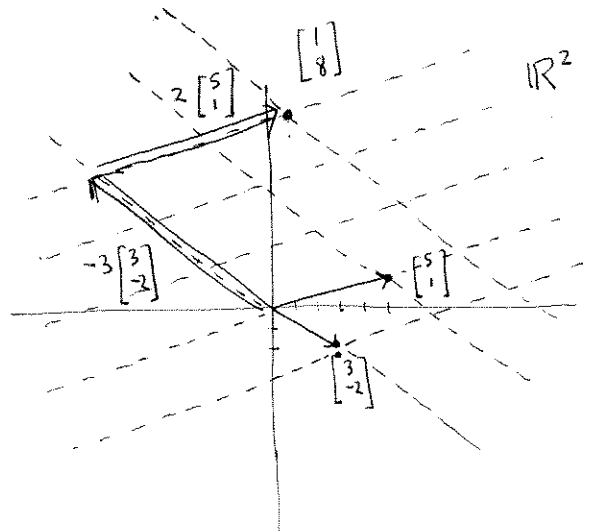
Solve

$$s \begin{bmatrix} 3 \\ -2 \end{bmatrix} + t \begin{bmatrix} 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 8 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 5 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} s \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 8 \end{bmatrix}$$

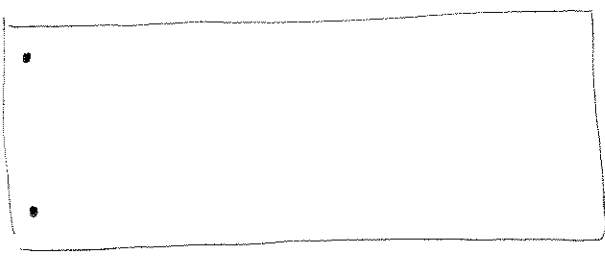
$$\begin{bmatrix} s \\ t \end{bmatrix} = \frac{1}{13} \begin{bmatrix} 1 & -5 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 8 \end{bmatrix}$$

$$= \frac{1}{13} \begin{bmatrix} -39 \\ 26 \end{bmatrix} = \begin{bmatrix} -3 \\ 2 \end{bmatrix}$$



the expression  $s \begin{bmatrix} 3 \\ -2 \end{bmatrix} + t \begin{bmatrix} 5 \\ 1 \end{bmatrix}$  is called a linear combination of  $\begin{bmatrix} 3 \\ -2 \end{bmatrix}$  and  $\begin{bmatrix} 5 \\ 1 \end{bmatrix}$

- Can we get anywhere in  $\mathbb{R}^2$  via a linear combination of  $\begin{bmatrix} 3 \\ -2 \end{bmatrix}$  and  $\begin{bmatrix} 5 \\ 1 \end{bmatrix}$ ?
- Are the linear combination coefficients (s & t) unique, if  $s \begin{bmatrix} 3 \\ -2 \end{bmatrix} + t \begin{bmatrix} 5 \\ 1 \end{bmatrix} = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$ ?



example :

$$\vec{i} = \vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{j} = \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \vec{k} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \vec{e}_3$$

these 3 vectors are often called the standard basis vectors for  $\mathbb{R}^3$

~~exam~~

$$\begin{bmatrix} 7 \\ -1 \\ 3 \end{bmatrix} = 7\vec{e}_1 - \vec{e}_2 + 3\vec{e}_3$$

- Can we express any vector in  $\mathbb{R}^3$  as a linear combination  $c_1\vec{e}_1 + c_2\vec{e}_2 + c_3\vec{e}_3$  of  $\{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$ ?
- Is this expression unique? (i.e. is there exactly 1 such expression?)

example :

$$\vec{v}_1 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} -1 \\ 1 \\ -5 \end{bmatrix}, \quad \vec{v}_3 = \begin{bmatrix} 4 \\ -1 \\ 11 \end{bmatrix}$$

- is  $\begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix}$  a linear combination of  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ ?
- is this expression (i.e. the linear combo coefficients) unique?

$$c_1 \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \\ -5 \end{bmatrix} + c_3 \begin{bmatrix} 4 \\ -1 \\ 11 \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix}$$

$$\begin{array}{ccc|c} 2 & -1 & 4 & 6 \\ 1 & 1 & -1 & 3 \\ 1 & -5 & 11 & 3 \end{array}$$

↓ rref

$$\begin{array}{ccc|c} 1 & 0 & 1 & 3 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{array}$$

$$\begin{matrix} c_3 = t \\ c_2 = 2t \\ c_1 = 3-t \end{matrix}; \quad \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$$

so, e.g.

$$\begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix} = 3\vec{v}_1$$

$$\text{or } \begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix} = 2\vec{v}_1 + 2\vec{v}_2 + \vec{v}_3 \quad (t=1)$$

$$\text{or } \begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix} = (3-t)\vec{v}_1 + 2t\vec{v}_2 + t\vec{v}_3 \quad \text{any } t$$

- Can we express any point in  $\mathbb{R}^3$  as a linear combo of  $\vec{v}_1, \vec{v}_2, \vec{v}_3$ ?
- If  $\vec{b}$  is a linear combo of  $\vec{v}_1, \vec{v}_2, \vec{v}_3$ , are the linear combo coefficients unique?

