

Math 2250-1
Friday Dec. 12
Review Day

Exam is comprehensive:

10-20% { 1.1-1.5 1st order DE's
2.1-2.3 applications, equilibria & stability

15-25% { 3.1-3.6 matrix algebra & determinants
4.1-4.5, 4.7 vector space concepts

15-25% { 5.1-5.6 linear DE's & spring applications

15-20% { 10.1-10.4 Laplace transforms, applications to DE's & DE systems

15-25% { 7.1-7.4 Linear systems of DE's; tank & spring systems, conversion from DE's to 1st order system

10-25% { 6.1-6.3 eigenvalues, eigenvectors, diagonalization, discrete dynamical systems

15-25% { 9.1-9.4 nonlinear systems of DE's, equilibria, stability, linearization, phase portraits, applications,

topics overlap !!

Analytic solution methods for DE's & systems of DE's

1st order DE's: linear, separable

higher order linear DE's: general soltn = $x_h + x_p$,

how to find x_h , x_p for constant coeff DE's,

use of Euler's formula for complex exponentials,

applications to mass-spring problems

eigenvalue, eigenvector methods, + matrix computations to find $x_p(t)$ for

$$\frac{d\vec{x}}{dt} = A\vec{x} + \vec{f}(t)$$

$$\frac{d^2\vec{x}}{dt^2} = A\vec{x} + \text{const } \vec{c}$$

applications to tank & mass-spring systems.

Laplace transforms to solve linear DE's or DE systems. → You will get xeroxes

of the book covers,
i.e. basic Laplace transforms
and integrals.

Modeling: springs, spring systems, chapters 5, 7, 9

compartmental analysis (tanks)

population, velocity models, chptr 2

interacting populations, chapter 9

discrete dynamical systems, chapter 6

Geometric meaning for soltns to DE's & systems of DE's (and resulting "theorems").

slope fields, phase portraits, equilibrium soltns, stability (chapter 2)

tangent vector fields (§7.1), phase portrait analysis & linearization, chapter 9

existence/uniqueness for 1st order DE's or DE systems, or nth order DE's

dimension of solution space for homogeneous DE's or DE systems

Auxiliary tools

linear algebra

new vocabulary, vector spaces, (in)dependence, span, dim, examples, etc.

Solving linear sys kns, matrices, rref, matrix algebra, A^{-1} , dets, etc.

evals & evecs

general soltn to $L(x) = b$ when L is a linear operator: $x = x_p + x_h$

manipulating matrix & vector equations to find solutions to
systems of DE's

Final Exam Tues. Dec. 16 8-10 a.m. ①
Here, ST 104

Practice Exam and soltns is/will be posted

Review session Saturday (tomorrow)

11 a.m. - 1 p.m. JFB 103

(our Tuesday room)

(2)

We can probably touch on 70% of the cause concepts by studying the DE's in as many ways as we can think of.

$$x'' + 5x' + 4x = 0$$

$$x'' + 5x' + 4x = 3 \cos 2t$$