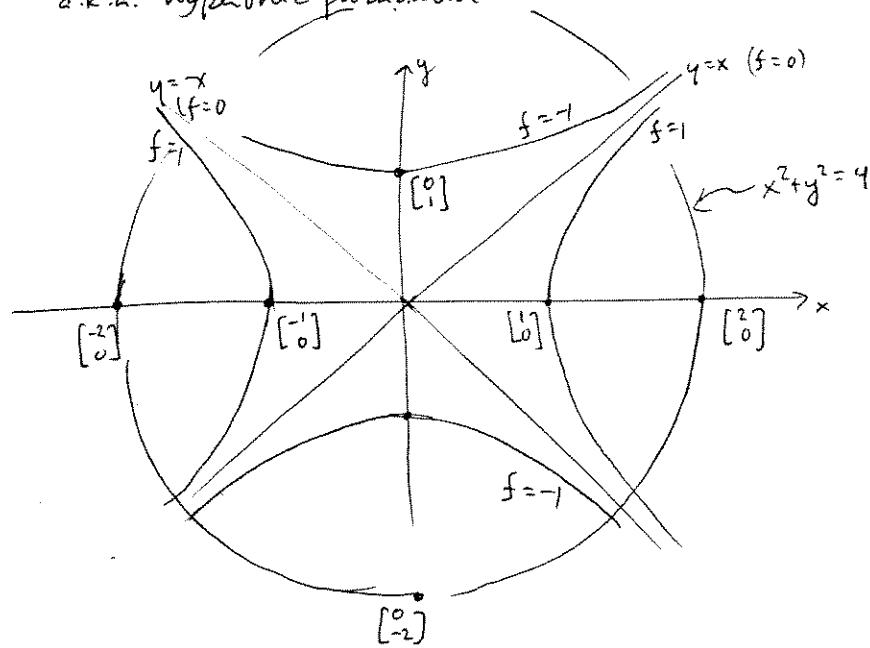


1 a) $z = x^2 - y^2$ describes a saddle surface
a.k.a. hyperbolic paraboloid

b)

c)



d) Maximize

$$f(x, y) = x^2 - y^2$$

subject to

$$g(x, y) = x^2 + y^2 = 4$$

$$\nabla f = \lambda \nabla g$$

$$\langle 2x, -2y \rangle = \lambda \langle 2x, 2y \rangle$$

$$x = 2x$$

$$x = 0$$

$$-y = 2y$$

$$y = 0$$

$$\begin{bmatrix} 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ -2 \end{bmatrix}$$

$$x \neq 0$$

$$\downarrow$$

$$\lambda = 1$$

$$\downarrow$$

$$y = 0$$

$$\downarrow$$

$$x = \pm 2$$

$$f\left(\begin{bmatrix} \pm 2 \\ 0 \end{bmatrix}\right) = 4$$

$$f\left(\begin{bmatrix} 0 \\ \pm 2 \end{bmatrix}\right) = -4$$

\uparrow
min value.

\uparrow
max value

the level curves of f are hyperbolas.

When $f > 0$ these hyperbolas open along the x -axis, and

the $f=4$ hyperbola, with vertices

at $\begin{bmatrix} \pm 2 \\ 0 \end{bmatrix}$, is the highest value

level curve to intersect the circle $x^2 + y^2 = 4$.

When $f < 0$ these hyperbolas open along the y -axis, and the lowest value level curve to intersect the circle is $f = -4$, with vertices at $\begin{bmatrix} 0 \\ \pm 2 \end{bmatrix}$.

(2)

$$2. z = f(x,y) = x^2 - y^2$$

$$\nabla f = \langle 2x, -2y \rangle$$

$$\nabla f(1,1) = \langle 2, -2 \rangle, \quad f(1,1) = 0$$

$$(a) \text{ tang plane } z = 0 + 2(x-1) - 2(y-1)$$

$$\boxed{\nabla z - 2x + 2y = 0}$$

$$(b) f(x+\Delta x, y+\Delta y) \approx f(x,y) + \underbrace{df}_{f_x \Delta x + f_y \Delta y}$$

$$\begin{matrix} x=1 \\ \Delta x=.1 \end{matrix} \quad \begin{matrix} y=1 \\ \Delta y=-.1 \end{matrix}$$

$$f(1.1, .9) \approx f(1,1) + 2(.1) - 2(-.1)$$

$$\approx .4$$

$$f(1.1, .9) = (1.1)^2 - (.9)^2 = \frac{1.21}{.81} = .4$$

(c) using tangent plane,

$$z = 0 + 2(1) - 2(-1) \text{ gives same value as df approximation.} \\ = .4 \quad (\text{this is always the case})$$

$$(d) \vec{r}(t) = \begin{bmatrix} 1 \\ t \end{bmatrix}$$

$$\frac{d}{dt} \vec{f}(\vec{r}(t)) = \nabla f(\vec{r}(t)) \cdot \vec{r}'(t)$$

$$\vec{r}'(t) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$@ t=0, \langle 2, -2 \rangle \cdot \langle 0, 1 \rangle = 10 - 8 = \boxed{2}$$

(e) in the direction of $\nabla f = \langle 2, -2 \rangle$

$$\text{i.e. } \vec{u} = \frac{1}{\sqrt{2}} \langle 1, -1 \rangle$$

3. $\vec{F}: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is

(a) continuous at \vec{x} iff $\lim_{\vec{z} \rightarrow \vec{x}} \vec{F}(\vec{z}) = \vec{F}(\vec{x})$ ($\text{or } \lim_{h \rightarrow 0} \vec{F}(\vec{x}+h) = \vec{F}(\vec{x})$)

(b) diff'ble at \vec{x} iff \exists a matrix $[\vec{F}'(\vec{x})]$ (entry $f_{ij} = \frac{\partial F_i}{\partial x_j}(\vec{x})$) s.t.

$$\vec{F}(\vec{x}+h) = \vec{F}(\vec{x}) + [\vec{F}'(\vec{x})]h + \text{error}$$

$$\text{where } \lim_{h \rightarrow 0} \frac{\text{error}}{\|h\|} = 0.$$

$$\frac{\partial}{\partial \rho} \quad \frac{\partial}{\partial \phi} \quad \frac{\partial}{\partial \theta}$$

$$4. \vec{F} \begin{bmatrix} \rho \\ \phi \\ \theta \end{bmatrix} = \begin{bmatrix} \rho \sin \phi \cos \theta \\ \rho \sin \phi \sin \theta \\ \rho \cos \phi \end{bmatrix}$$

$$[\vec{F}'] = \begin{bmatrix} \sin \phi \cos \theta & \rho \cos \phi \cos \theta & -\rho \sin \phi \sin \theta \\ \sin \phi \sin \theta & \rho \cos \phi \sin \theta & \rho \sin \phi \cos \theta \\ \cos \phi & -\rho \sin \phi & 0 \end{bmatrix} \begin{matrix} f_1 \\ f_2 \\ f_3 \end{matrix}$$