

Math 2210-1
Monday 30 Aug.

HW due Wed!
Problem session tomorrow
9:40-10:30 LCB 121

1

Finish Friday notes:

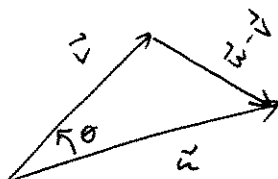
- sphere example page 3
- computational example page 3
- Do dot product page 4

hint: on exercise (III), law of cosines,
you only need to use Pythag thm once,
not twice as stated.

$$\begin{aligned} \vec{u} &= \langle u_1, u_2, u_3 \rangle \\ \vec{v} &= \langle v_1, v_2, v_3 \rangle \end{aligned} \quad \left. \vphantom{\begin{aligned} \vec{u} &= \langle u_1, u_2, u_3 \rangle \\ \vec{v} &= \langle v_1, v_2, v_3 \rangle \end{aligned}} \right\} \vec{u} \cdot \vec{v} := u_1 v_1 + u_2 v_2 + u_3 v_3$$

details of geometric property

$$\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos \theta$$



proof:

By law of cosines (see Hw)

$$|\vec{u} - \vec{v}|^2 = |\vec{u}|^2 + |\vec{v}|^2 - 2|\vec{u}||\vec{v}|\cos \theta$$

By dot product properties

$$\begin{aligned} |\vec{u} - \vec{v}|^2 &= (\vec{u} - \vec{v}) \cdot (\vec{u} - \vec{v}) \\ &= \vec{u} \cdot (\vec{u} - \vec{v}) - \vec{v} \cdot (\vec{u} - \vec{v}) \\ &= \vec{u} \cdot \vec{u} - 2\vec{u} \cdot \vec{v} + \vec{v} \cdot \vec{v} \\ &= |\vec{u}|^2 + |\vec{v}|^2 - 2\vec{u} \cdot \vec{v} \end{aligned}$$

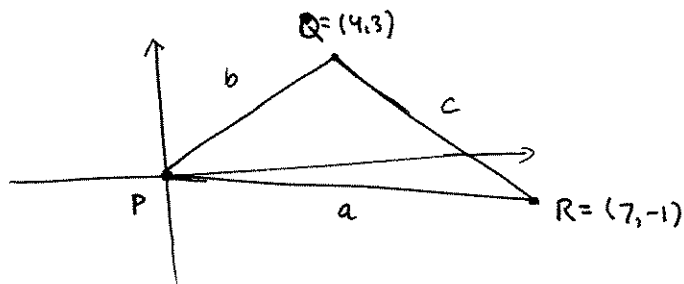
Since these eqns both express $|\vec{u} - \vec{v}|^2$, deduce

$$-2|\vec{u}||\vec{v}|\cos \theta = -2\vec{u} \cdot \vec{v} \quad \text{i.e.}$$

$$|\vec{u}||\vec{v}|\cos \theta = \vec{u} \cdot \vec{v} \quad \square$$

Examples: is $\triangle PQR$ a right triangle?

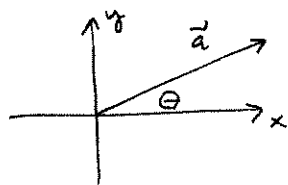
$$\begin{aligned} P &= (0,0) \\ Q &= (4,3) \\ R &= (7,-1) \end{aligned}$$



$$\begin{aligned} \vec{PQ} &= \langle 4, 3 \rangle \\ \vec{PR} &= \langle 7, -1 \rangle \\ \vec{QR} &= \langle 3, -4 \rangle \end{aligned}$$

Deduce: $\vec{u} \perp \vec{v}$ if and only if $\vec{u} \cdot \vec{v} = 0$.

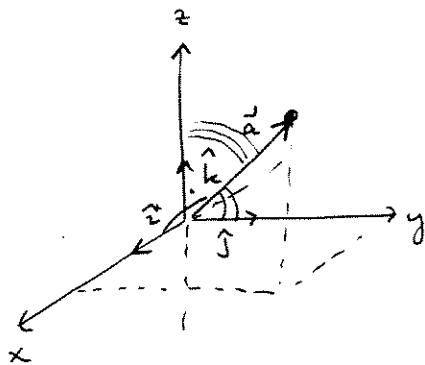
↑
perpendicular

direction angles

$$\vec{a} = \langle a_1, a_2 \rangle$$

$$\cos(\theta) = \frac{\vec{a} \cdot \vec{i}}{|\vec{a}| \cdot 1} = \frac{a_1}{|\vec{a}|}$$

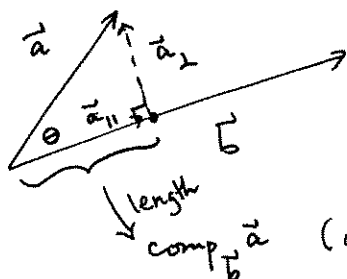
$\mathbb{R}^3$ similar $\rightsquigarrow$



$$\begin{aligned} \angle \hat{x}, \vec{a} &:= \alpha & \cos \alpha &= \frac{\vec{a} \cdot \hat{x}}{|\vec{a}| \cdot 1} = \frac{a_1}{|\vec{a}|} \\ \angle \hat{y}, \vec{a} &:= \beta & \cos \beta &= \frac{a_2}{|\vec{a}|} \\ \angle \hat{z}, \vec{a} &:= \gamma & \cos \gamma &= \frac{a_3}{|\vec{a}|} \end{aligned}$$

components and vector decomposition

↓
generalizes idea of x, y ($\hat{i}, \hat{j}$) components
or x, y, z ($\hat{i}, \hat{j}, \hat{k}$) components of vectors.



$$\begin{aligned} \text{comp}_{\vec{b}} \vec{a} & \text{ (component of } \vec{a} \text{ in direction of } \vec{b}) \\ &:= |\vec{a}| \cos \theta = \text{signed length of projection of } \vec{a} \text{ onto } \vec{b} \\ & \quad \begin{matrix} \uparrow \\ + \text{ if } \theta < \pi/2 \\ - \text{ if } \theta > \pi/2 \end{matrix} \end{aligned}$$

$$= |\vec{a}| \left(\frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|} \right)$$

$$= \vec{a} \cdot \frac{\vec{b}}{|\vec{b}|}$$

(the dot product of $\vec{a}$ with the unit vector in the $\vec{b}$ direction)

then write

$$\vec{a} = \vec{a}_{\parallel} + \vec{a}_{\perp} :$$

$$\vec{a}_{\parallel} = (\text{comp}_{\vec{b}} \vec{a}) \frac{\vec{b}}{|\vec{b}|} = \frac{\vec{a} \cdot \vec{b}}{|\vec{b}|^2} \vec{b}$$

$$\vec{a}_{\perp} = \vec{a} - \vec{a}_{\parallel}$$

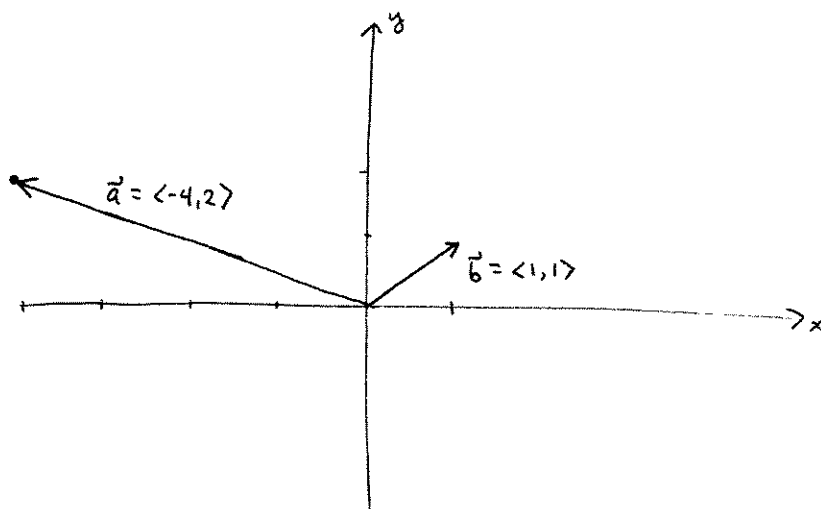
example

$$\vec{a} = \langle -4, 2 \rangle$$

$$\vec{b} = \langle 1, 1 \rangle$$

find $\text{comp}_{\vec{b}} \vec{a}$, $\vec{a}_{\parallel}$, $\vec{a}_{\perp}$

draw a picture



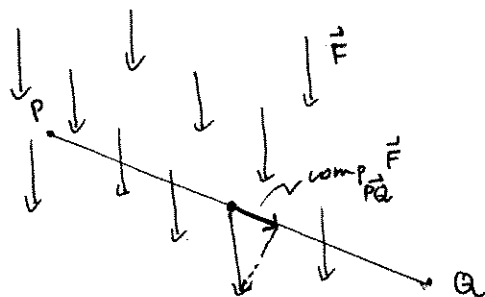
example : "Work" in physics. (see e.g. 11.2 # 56, 57)

If $\vec{F}$ is a constant force field, and if an object moves (in a straight line)

from P to Q, then

work done by the force field is

(opposite of work done by the object)



$$W := \vec{F} \cdot \vec{PQ}$$

$$= (\text{comp}_{\vec{PQ}} \vec{F}) |\vec{PQ}|$$

this generalizes examples you did in Calculus in which the force field was ~~the~~ in the direction of motion.

e.g. if $\vec{F} = -mg\vec{k}$ Object mass $g = 9.8 \text{ m/sec}^2$

height horizontal $\downarrow$

$$W = \vec{F} \cdot \vec{PQ} = (-mg\vec{k}) \cdot (h\vec{k} + \vec{T})$$

$$= -mgh.$$

§ 11.3

determinants & cross product: intro

$$\begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} := a_1 b_2 - b_1 a_2 \quad 2 \times 2 \text{ determinant}$$

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} := +a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$

3x3 det - expansion across top row.

Note the 2x2 det's are obtained by crossing out the row and column of the entry coefficient

- you can expand across any row or down any column, using the checkerboard template of $\pm$'s.

$$\begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

e.g. down column 3, you get $a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix} - b_3 \begin{vmatrix} a_1 & a_2 \\ c_1 & c_2 \end{vmatrix} + c_3 \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$

- in all cases you end up with

$$\begin{aligned} & a_1 b_2 c_3 + a_2 b_3 c_1 + a_3 b_1 c_2 \\ & - c_1 b_2 a_3 - c_2 b_3 a_1 - c_3 b_1 a_2 \end{aligned}$$

cross product

$$\vec{a} = \langle a_1, a_2, a_3 \rangle$$

$$\vec{b} = \langle b_1, b_2, b_3 \rangle$$

then $\vec{a} \times \vec{b} = \begin{pmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{pmatrix} = \vec{i} \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} - \vec{j} \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} + \vec{k} \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$

example

$$\vec{a} = \langle 2, 1, 0 \rangle$$

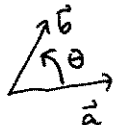
$$\vec{b} = \langle -2, 4, 0 \rangle$$

compute $\vec{a} \times \vec{b}$

verify (for this example)

(1) $\vec{a} \times \vec{b} \perp \vec{a}, \vec{b}$, and $\{\vec{a}, \vec{b}, \vec{a} \times \vec{b}\}$ are right-handed.

(2) $|\vec{a} \times \vec{b}| = |\vec{a}| |\vec{b}| \sin \theta$



$$= \langle a_2 b_3 - b_2 a_3, b_1 a_3 - a_1 b_3, a_1 b_2 - b_1 a_2 \rangle$$