

Dynamical Systems for Biology -Excitability

J. P. Keener

Mathematics Department

University of Utah



Examples of Excitable Media

- B-Z reagent
- CICR (<u>Calcium Induced Calcium Release</u>)
- Nerve cells
- cardiac cells, muscle cells
- Slime mold (*dictystelium discoideum*)
- Forest Fires

Features of Excitability

- Threshold Behavior
- Refractoriness
- Recovery





Intracellular Calcium











with

 J_{RYR} Ryanodine Receptor - calcium regulated calcium channel,





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Challenge: Determine the flux terms.



Ryanodine Receptors





Ryanodine Receptors

Flux through ryanodine receptor is diffusive,

$$J_{RYR} = g_{max} P_o(c - c_{sr})$$

where $P_o = S_{10}^3$ is the open probability. To determine P_o , we must find S_{10} :

$$\frac{dS_{10}}{dt} = k_1 c S_{00} + k_{-2} S_{11} - k_{-1} S_{10} - k_2 c S_{10}$$

and so on.





If the binding sites are independent (no cooperativity), then $S_{10} = mh$, $S_{00} = (1 - m)h$, $S_{11} = m(1 - h)$, $S_{01} = (1 - m)(1 - h)$, where $\frac{dm}{dt} = \phi_m(c)(1 - m) - \psi_m(c)m$, $\frac{dh}{dt} = \phi_h(c)(1 - h) - \psi(c)h$. Furthermore, *m* is a fast variable, so can be taken to be in qss, $m = m_{\infty}(c)$.

Consequently,....



Calcium Dynamics

$$\frac{dc}{dt} = (g_{max}P_o + J_{er})(c_e - c) - J_{SERCA},$$
$$\frac{dh}{dt} = \phi_h(c)(1 - h) - \psi_h(c)h,$$

$$J_{SERCA} = V_{max} \frac{c^2}{K_s^2 + c^2},$$
$$P_o = h^3 f(c)$$





Membrane Electrical Activity





Membrane Electrical Activity



Transmembrane potential ϕ is regulated by transmembrane ionic currents and capacitive currents:

 $C_m \frac{d\phi}{dt} + I_{ion}(\phi, w) = I_{in}$ where $\frac{dw}{dt} = g(\phi, w), \quad w \in \mathbb{R}^n$

(Reminder: This is a conservation equation.)



Examples include:

- Neuron Hodgkin-Huxley model
- Purkinje fiber Noble
- Cardiac cells Beeler-Reuter, Luo-Rudy, Winslow-Jafri, Bers
- Two Variable Models reduced HH, FitzHugh-Nagumo, Mitchell-Schaeffer, Morris-Lecar, McKean, etc.)









with sodium current $I_{\rm Na}$,





with sodium current I_{Na} , potassium current I_{K} ,





with sodium current I_{Na} , potassium current I_K , and leak current I_l .



Ionic Currents

Ionic currents are typically of the form

$$I = g(\phi, t) \Phi(\phi)$$



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where $g(\phi, t)$ is the total number of open channels, and $\Phi(\phi)$ is the *I*- ϕ relationship for a single channel.



Currents

Hodgkin and Huxley found that

$$I_k = g_k n^4 (\phi - \phi_K), \qquad I_{Na} = g_{Na} m^3 h (\phi - \phi_{Na}),$$

where







Action Potential Dynamics



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Set $m = m_{\infty}(\phi)$, and set $h + n \approx N = 0.85$. This reduces to a two variable system

$$C\frac{d\phi}{dt} = \bar{g}_K n^4 (\phi - \phi_K) + \bar{g}_{Na} m_\infty^3(\phi) (N - n) (\phi - \phi_{Na}) + \bar{g}_l (\phi - \phi_L),$$

$$\tau_n(\phi) \frac{dn}{dt} = n_\infty(\phi) - n.$$





Following is a brief summary of two variable models of excitable media. The models described here are all of the form

$$\frac{dv}{dt} = f(v, w) + I$$
$$\frac{dw}{dt} = g(v, w)$$

Typically, v is a "fast" variable, while w is a "slow" variable.





The model that started the whole business uses a cubic polynomial (a variant of the van der Pol equation).

$$F(v,w) = Av(v-\alpha)(1-v) - w,$$

$$G(v,w) = \epsilon(v-\gamma w).$$

with $0 < \alpha < \frac{1}{2}$, and ϵ "small". (Remark: This model is used these days only by mathematicians.) Imagine the Possibilities

FitzHugh-Nagumo Equations





Mitchell-Schaeffer-Karma

$$C_m \frac{dv}{dt} = g_{Na} h m^2 (V_{Na} - v) + g_K (V_K - v),$$

$$\tau_h \frac{dh}{dt} = h_\infty(v) - h$$

where

$$m(v) = \begin{cases} 0, & v < 0 & h_{\infty} = 1 - f(v), \\ v, & 0 < v < 1 & , & \tau_{h} = \tau_{open} + (\tau_{close} - \tau_{open})f(v) \\ 1, & v > 1 & f(v) = \frac{1}{2}(1 + \tanh(\kappa(v - v_{gate})), \end{cases}$$



MSK Phase Portrait





Morris-Lecar

This model was devised for barnacle muscle fiber.

$$F(v,w) = -g_{ca}m_{\infty}(v)(v-v_{ca}) - g_{k}w(v-v_{k}) - g_{l}(v-v_{l}) + I_{app}$$

$$G(v,w) = \phi \cosh(\frac{1}{2}\frac{v-v_{3}}{v_{4}})(w_{\infty}(v)-w),$$





McKean

McKean suggested two piecewise linear models with F(v,w) = f(v) - w and $G(v,w) = \epsilon(v - \gamma w)$. For the first,

$$f(v) = \begin{cases} -v & v < \frac{\alpha}{2} \\ v - \alpha & \frac{\alpha}{2} < v < \frac{1+\alpha}{2} \\ 1 - v & v > \frac{1+\alpha}{2} \end{cases}$$



where $0 < \alpha < \frac{1}{2}$. The second model suggested by McKean had

$$f(v) = \begin{cases} -v & v < \alpha \\ 1 - v & v > \alpha \end{cases}$$



and $\gamma = 0$.



Features of Excitable Systems

Threshold Behavior, Refractoriness

<u>Alternans</u>

Wenckebach Patterns



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