Notes on resultant and bifurcation analysis

1 The Resultant

Given two polynomials,

$$f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_0, \qquad g(x) = b_m x^m + a_{m-1} x^{m-1} + \dots + b_0, \qquad (1)$$

define the Sylvester matrix as the $(n+m)\times(n+m)$ matrix

$$S = \begin{pmatrix} a_n & a_{n-1} & a_{n-2} & \cdots & 0 & 0 & 0 \\ 0 & a_n & a_{n-1} & \cdots & & & \\ 0 & 0 & a_n & \cdots & a_1 & a_0 & 0 \\ & & & & & a_1 & a_0 \\ b_m & b_{m-1} & b_{m-2} & \cdots & 0 & & \\ 0 & b_m & b_{m-1} & \cdots & & \\ 0 & 0 & & & b_1 & b_0 & 0 \\ & & & & & b_1 & b_0 \end{pmatrix}$$
(2)

Specific example, let $f = a_1 x + a_0$, $g = b_1 x + b_0$, then

$$S = \begin{pmatrix} a_1 & a_0 \\ b_1 & b_0 \end{pmatrix}.$$
 (3)

Define the resultant of f and g as

$$R(f,g) = det(S). \tag{4}$$

The main theorem, which we are about to prove is **Theorem** Suppose $f(x) = a_n \prod_{i=1}^n (x - \xi_i)$ and $g(x) = b_m \prod_{i=1}^m (x - \eta_i)$. Then

$$R(f,g) = a_n^m b_m^n \prod_i \prod_j (\xi_i - \eta_i)$$
(5)

$$= a_n^m \prod_i g(\xi_i) \tag{6}$$

$$= (-1)^{nm} b_m^n \prod_j f(\eta_j).$$
(7)

An example:

$$f = x^2 + ax + b, \qquad g = f' = 2x + a,$$
 (8)

then

$$S = \begin{pmatrix} 1 & a & b \\ 2 & a & 0 \\ 0 & 2 & a \end{pmatrix}.$$
 (9)

and

$$det(S) = 4b - a^2 = 4f(-\frac{a}{2}).$$
(10)

Note that

$$\xi_i = \frac{1}{2}(-a \pm \sqrt{a^2 - 4b}), \qquad \eta = -\frac{a}{2},$$
(11)

so that

$$\prod_{i,j} (\xi_i - \eta_j) = -\frac{1}{4} (a^2 - 4b), \tag{12}$$

which agrees with the theorem.

Some interesting formulas:

1. Suppose $\deg(g) = k < m$. Then,

$$R_{n,m}(f,g) = a_n^{m-k} R_{n,k}(f,g)$$
(13)

This follows since $g = 0x^m + 0x^{m-1} + \dots + b_k x^k + \dots$

- 2. Suppose $\deg(f) = n$, $\deg(g) = m$, $\deg(h) = k$.
 - (a) If $m + k \le n$, then

$$R(f+gh,g) = R(f,g).$$
(14)

(b) If $n + k \le m$, then

$$R(f, g + fh) = R(f, g).$$
(15)

This follows directly from properties of determinants.

Proof of the main Theorem

We use induction on m + n. First, for n = m = 1, $f = a_1 x + a_0$, $g = b_1 x + b_0$,

$$S = \begin{pmatrix} a_1 & a_0 \\ b_1 & b_0 \end{pmatrix},\tag{16}$$

and

$$R(f,g) = a_1b_0 - b_1a_0 = a_1b_1\left(-\frac{a_0}{a_1} + \frac{b_0}{b_1}\right),\tag{17}$$

as required. The case m = 0, n = 1 works as well by setting $b_1 = 0$ in which case R(f, g) =

 $a_1g(-\frac{a_0}{a_1})$ since $g = b_0$. Now, for some n and m, suppose, without loss of generality, that $m \ge n$. Then, there is a polynomial h with $\deg(h) = m - n$ for which

$$g = hf + r, (18)$$

and $\deg(r) = k < m$. Then,

$$R(f,g) = R(f,g-hf) = R_{n,m}(f,r) = a_n^{m-k} R_{n,k}(f,r)$$
(19)

$$= a_n^{m-k} a_n^k \prod_i r(\xi_i) \tag{20}$$

$$= a_n^m \prod_i \left(g(\xi_i) - h(\xi_i) f(\xi_i) \right)$$
(21)

$$= a_n^m \prod_i g(\xi_i), \qquad (22)$$

as required. QED

1.1 The Discriminant

For any polynomial f with roots ξ_i , the discriminant is defined as

$$\Delta(f) = \prod_{i < j} (\xi_i - \xi_j)^2.$$
 (23)

A calculation: Since $f = a_n \prod_{j=1}^n (x - \xi_j)$, then $f'(\xi_i) = a_n \prod_{j \neq i}^n (\xi_i - \xi_j)$. It follows that

$$R(f, f') = a_n^{n-1} \prod_{i=1}^n f'(\xi_i)$$
(24)

$$= a_n^{n-1} a_n^n \prod_{i=1}^n \prod_{j \neq i}^n (\xi_i - \xi_j)$$
(25)

$$= a_n^{2n-1} \prod_{i < j} (x_i - x_j)(x_j - x_i)$$
(26)

$$= (-1)^{\frac{n(n-1)}{2}} a_n^{2n-1} \prod_{i < j} (x_i - x_j)^2 = (-1)^{\frac{n(n-1)}{2}} a_n^{2n-1} \Delta(f).$$
(27)

Examples:

1. For the quadratic polynomial $f = x^2 + ax + b$, f' = 2x + a,

$$R(f, f') = 4b - a^2 = -\Delta(f).$$
(28)

Obviously, if $4b = a^2$, $f = x^2 + ax + \frac{a^2}{4} = (x + \frac{a}{2})^2$ has a double root.

2. For the cubic polynomial $f = x^3 + ax + b$ (note that the quadratic term can always be eliminated with a shift of the variable x), then

$$R(f, f') = 4a^3 + 27b^2.$$
⁽²⁹⁾

The curve along which R(f, f') = 0 is the curve in parameter space along which f has a double zero. This is known as the cusp bifurcation.

2 Examples

We want to use the resultant to understand features of solutions of interesting problems.

2.1 Spruce budworm dynamics

Spruce budworm dynamics are governed by the differential equation (after a bunch of scaling)

$$\frac{dv}{dt} = \sigma v (1 - v) - \frac{v^2}{\kappa^2 + v^2} = f(v).$$
(30)

We would like to understand for what parameter values this has bistable behavior. To find double zeros of f, we calculate the resultant of the numerators of f and f', which is

$$R = k^2 \sigma (-4k^5 \sigma^6 - 8k^4 \sigma^6 - 12k^4 \sigma^5 - 4k^3 \sigma^6 + 20k^3 \sigma^5 - 12k^3 \sigma^4 + k^2 \sigma^4 - 4k^2 \sigma^3), \quad (31)$$

where $k = \kappa^2$. The zero level surface of R is shown plotted in Fig. 1(Right).

To determine cusp point we first solve for σ as a function of v

$$\sigma = \frac{v^2}{(v(1-v))(\kappa^2 + v^2)} = g(v), \tag{32}$$

and look for double roots g'(v) = 0. The necessary resultant is

$$R_{\sigma} = -32k^3(27k - 1)(k + 1)^2 \tag{33}$$

so that the cusp occurs for $\kappa = \frac{1}{\sqrt{27}}$. Similarly, solving for k,

$$\kappa^{2} = \frac{v^{2}}{\sigma v(1-v)} - v^{2} = h(v), \qquad (34)$$

and we look for double roots of h'(v) = 0. The corresponding resultant is

$$R_k = -8\sigma^3(8\sigma - 27),\tag{35}$$

from which we learn that the cusp is at $\sigma = \frac{27}{8}$.

2.2 Quorum Sensing

The equations are (after a bunch of rescaling)

$$\frac{du}{dt} = s_0 + \gamma \frac{u^2}{1+u^2} + v - u, \qquad (36)$$

$$\frac{dv}{dt} = -v + \frac{\rho}{1-\rho}(u-v). \tag{37}$$

It is not hard to determine that the steady states solutions are given by

$$\rho = -\frac{\gamma u^2 + s_0 u^2 - u^3 + s_0 - u}{(u^2 + 1)u} \equiv f(u).$$
(38)

To find regions of different behavior we look for double zeros of f'(u) = 0 and double zeros of f(u) = 0. We find that double zeros of f'(u) occur when

$$\gamma = 8s_0, \tag{39}$$

and double zeros of f occur when

$$4\gamma^3 s_0 + 12\gamma^2 s_0^2 + 12\gamma s_0^3 + 4s_0^4 \gamma^2 - 20\gamma s_0 + 8s_0^2 + 4 = 0,$$
(40)

Furthermore, the cusp intersect the straight line at $s_0 = \frac{1}{\sqrt{27}}$.

Remark: This analysis can be applied to *any* rational system of equations to (first) reduce the system of polynomials to a single polynomial of one variable and then (second) understanding the bifurcation structure of the solutions as a function of parameters, using resultant analysis.

2.3 Oscillations; Hopf Bifurcations

Resultants can also be used to find Hopf bifurcation points. The idea is as follows. For a system of equations,

$$\frac{dX}{dt} = F(X, p),\tag{41}$$

steady states are found as solutions of a polynomial equations F(X, p) = 0. Hopf bifurcation points are those for which

$$det(\frac{\partial F}{\partial X} - i\omega I) = 0 \tag{42}$$

This corresponds to two more equations (take real and imaginery parts) which must be simultaneously zero. The resultant of these two is a single polynomial in X and p. Now eliminate X using resultants to find a polynomial in p, which gives the locations of Hopf points.

2.4 Brusselator equations

Look for Hopf bifurcations for the Brusselator equations

$$u' = a - (b+1)u + vu^2, \qquad v' = bu - vu^2.$$
 (43)

Hopf bifurcation resultant analysis gives a Hopf bifurcation when R = 0, where

$$R = a(-a^2 + b - 1). (44)$$

2.5 Lorenz Equations

The Lorenz equations are

$$\frac{dx}{dt} = \sigma(y-x), \tag{45}$$

$$\frac{dy}{dt} = x(\rho - z) - y, \qquad (46)$$

$$\frac{dz}{dt} = xy - \beta z. \tag{47}$$

It is an easy matter to show that steady solutions are x = 0, and $x^2 = \rho\beta$. Further, there is a Hopf bifurcation at the nontrivial steady state provided

$$\beta \rho + \beta \sigma - \rho \sigma + \sigma^2 + \rho + 3\sigma = 0. \tag{48}$$

(determined using the resultant).

2.6 Bazykin's Equations

$$\begin{aligned} x' &= x - \frac{xy}{1+ax} - bx^2, \\ y' &= -gy + \frac{xy}{1+ax} - dy^2, \end{aligned}$$

We can find the cusp bifurcation curve to be

$$R_{cusp} = a(ag + bg - 1) + 8b.$$
(49)

Clearly, this makes sense only if g(a + b) < 1.

Similarly, the resultant analysis yields that Hopf bifurcations occur for R = 0 where

$$R \equiv a^{3}dg^{3} + a^{2}bdg^{3} + a^{3}d^{2}g + 3a^{2}bd^{2}g + 4a^{2}bdg^{2} + 3ab^{2}d^{2}g + 4ab^{2}dg^{2} + b^{3}d^{2}g - a^{3}d^{2} -a^{3}dg - 3a^{2}bd^{2} - 7a^{2}bdg - 4a^{2}bg^{2} - 2a^{2}d^{2}g - 2a^{2}dg^{2} - 3ab^{2}d^{2} - 7ab^{2}dg - 4ab^{2}g^{2} -4abd^{2}g - b^{3}d^{2} - b^{3}dg - 2b^{2}d^{2}g + a^{2}d^{2} + 2abd^{2} - 2abdg + ad^{2}g + b^{2}d^{2} + 6b^{2}dg +bd^{2}g + 4abd + 4abg + ad^{2} + adg - 4b^{2}d - 4b^{2}g + bd^{2} - bdg - 4bd - d^{2}$$

While this formula is complicated, it not difficult to make contour plots of this function



Figure 1: Top Left: Plot of f(v) for $\kappa = 0.0031$ and for selected values of σ for Eqn. (30). Top Right: plot of the zero level set, $R(\kappa, \sigma) = 0$. Bottom Left: Plot of the steady solution v as a function of the parameter σ for several different values of κ , and Bottom Right: Plot of the steady solution v as a function of κ for several values of σ .



Figure 2: Left: Plot of the steady solution v as a function of the parameter ρ for several different values of γ with $s_0 = 0.1$ for Eqns. (36)-(37). Right: plot of the zero level set, $R(\gamma, s_0) = 0$.