

**MATH 2270-2. Final Test: Solutions.**

**Problem 1.** (10 points) Find inverse of the matrix:

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

Use any method you like.

Solution.

$$A^{-1} = \frac{1}{3} \begin{bmatrix} 1 & 2 & -1 \\ 2 & -2 & 1 \\ -1 & 1 & 1 \end{bmatrix}. \quad \square$$

**Problem 2.** (15 points) Let  $V$  be the linear space of continuous functions of one variable  $f : \mathbb{R} \rightarrow \mathbb{R}$  (with the usual operations of sum and multiplication by scalars). Let  $Z$  be the subset in  $V$  which consists of all continuous functions  $f$  which have integer values at zero (i.e., we allow  $f(0)$  to be  $0, \pm 1, \pm 2, \dots$ , but for instance  $f(0) = 0.5$  is not allowed). Determine whether or not the subset  $Z$  is a subspace in  $V$ . Justify your answer!

Solution.  $Z$  is not a subspace. For instance, take function  $f(x) = 1$ ,  $\alpha = 0.5$ . Then  $\alpha f(0) = 0.5$  is not an integer, i.e.  $\alpha f(x)$  does not belong to  $Z$ .  $\square$

**Problem 3.** (15 points) 3. [15 points] Using standard basis in  $P_2$  find matrix representation, rank, nullity and basis of the image of the linear transformation  $T : P_2 \rightarrow P_2$  which is given by the formula:

$$T(p(x)) = xp'(x) + x^2p(1).$$

Here  $p'$  denotes the derivative.

Solution.  $T(1) = 0 + x^2$ , has coordinates  $(0, 0, 1)$ . Next,  $T(x) = x + x^2$ , has coordinates  $(0, 1, 1)$ . Lastly,  $T(x^2) = 2x^2 + x^2 = 3x^2$  has coordinates  $(0, 0, 3)$ . Hence the matrix of  $T$  is

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 3 \end{bmatrix}.$$

This matrix has rank 2 and nullity 1. The basis of the image consists of the vectors  $(0, 0, 1)$  and  $(0, 1, 1)$ . Converting these vectors into polynomials we get: basis of the image of  $T$  is  $\{x^2, x + x^2\}$ .  $\square$

**Problem 4.** (10 points) Write the augmented matrix and find all solutions of the linear system:

$$\begin{cases} x_1 + x_2 + x_3 - 2x_4 = 3 \\ 2x_1 + x_2 + 3x_3 + 2x_4 = 5 \\ 3x_1 + 2x_2 + 4x_3 = 8 \end{cases}$$

Solution.  $x_1 = 2 - 2t - 4s$ ,  $x_2 = 1 + t + 6s$ ,  $x_3 = t$ ,  $x_4 = s$  are the parameters.  $\square$

**Problem 5.** (15 points) Find an orthonormal basis in the subspace  $V$  in  $\mathbb{R}^4$  spanned by the vectors

$$\begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 4 \\ 6 \\ -4 \\ 6 \end{pmatrix}.$$

Solution.  $\vec{u}_1 = \frac{1}{2}(1, 1, -1, 1)$ ,  $\vec{u}_2 = \frac{1}{2}(-1, 1, 1, 1)$ .  $\square$

**Problem 6.** (15 points) Find all eigenvalues of the matrix:

$$\begin{bmatrix} 3 & 0 & 0 \\ 1 & 2 & 0 \\ 1 & 1 & 3 \end{bmatrix}$$

For each eigenvalue find a basis of the corresponding eigenspace. Determine if the matrix is diagonalizable.

Solution. The first eigenvalue is 3, the basis of  $E_3$  is  $(0, 0, 1)$ . The second eigenvalue is 2, the basis of  $E_2$  is  $(0, -1, 1)$ . Matrix is not diagonalizable since the sum of dimensions of eigenspaces is 2 and not 3.  $\square$

**Problem 7.** (10 points) Compute the following determinant using the definition of the determinant (i.e. identify the patterns with the nonzero product of the entries, compute the  $\pm$  signs, etc.):

$$\begin{vmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{vmatrix}.$$

Solution. There is only one pattern with nonzero product, it is the product of the entries equal to 1. The pattern contains 2 inversions, hence the determinant equals  $(-1)^2 = 1$ .  $\square$

**Problem 8.** (10 points) Consider the vector space

$$V = \text{Span}\{\sin^2(t), \cos^2(t), t\}$$

with the basis:  $T = \{\sin^2(t), 1, t - 1\}$ . Compute the coordinates of the function  $2(\sin^2(t) + \cos^2(t)) - t$  with respect to the basis  $T$ .

Solution.  $2(\sin^2(t) + \cos^2(t)) - t = 0 \cdot \sin^2(t) + 1 \cdot 1 + (-1) \cdot (t - 1)$ . Hence the coordinates are  $(0, 1, -1)$ .  $\square$